

Sampler algorithm for non-convex inverse problem

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The Galaxy volume

Solar systems fill $\sim 3 \cdot 10^{-10}$ of the volume of the galaxy

Most of the galaxy: empty!

Most of the galaxy: **Interstellar Medium!**

Observations of GMC: Orion B in visible frequencies



Figure: Image from Pety et al. [2016]

Observations of GMC: Orion B in visible frequencies

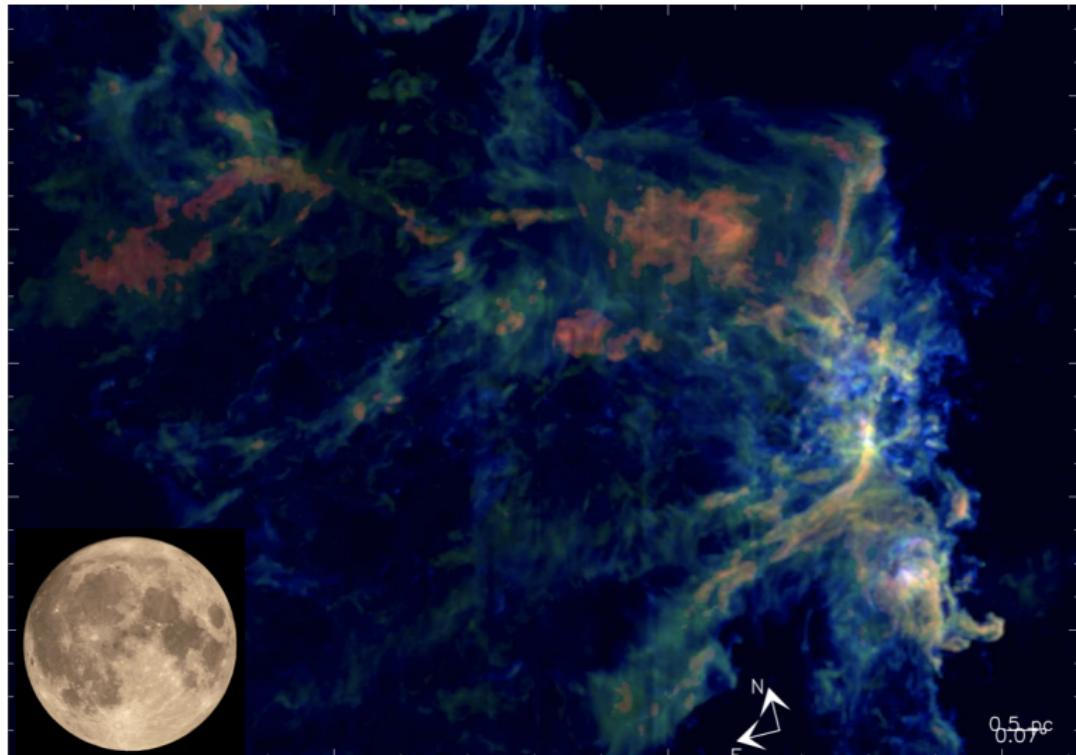


Figure: Image from Pety et al. [2016]
blue: ^{12}CO , green: ^{13}CO , red: C^{18}O

Photo-Dissociation Region (PDR)

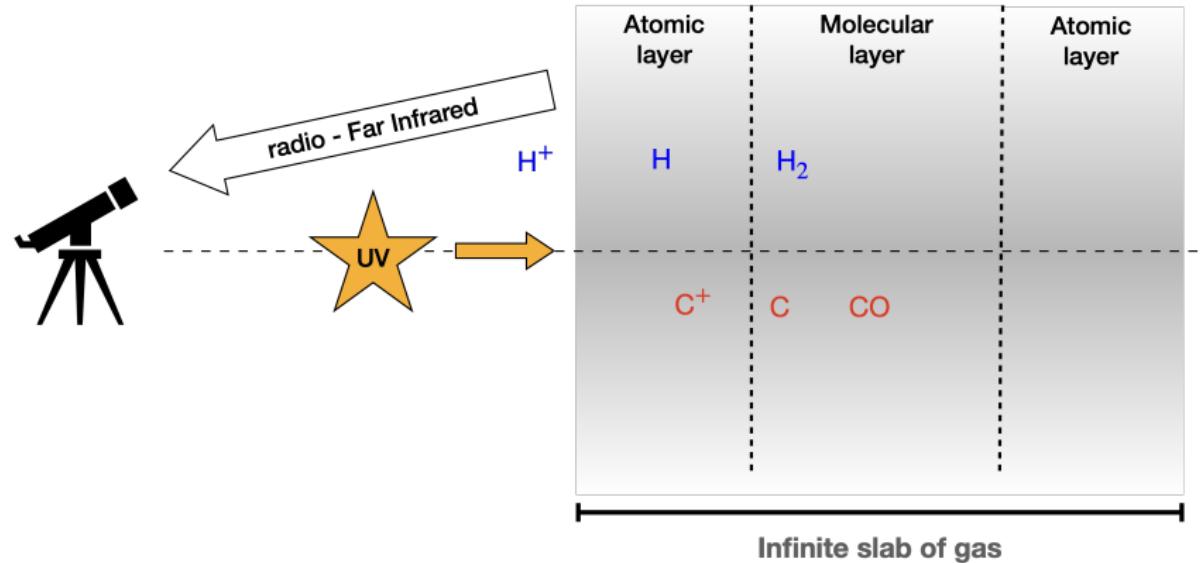


Figure: Structure of a PDR

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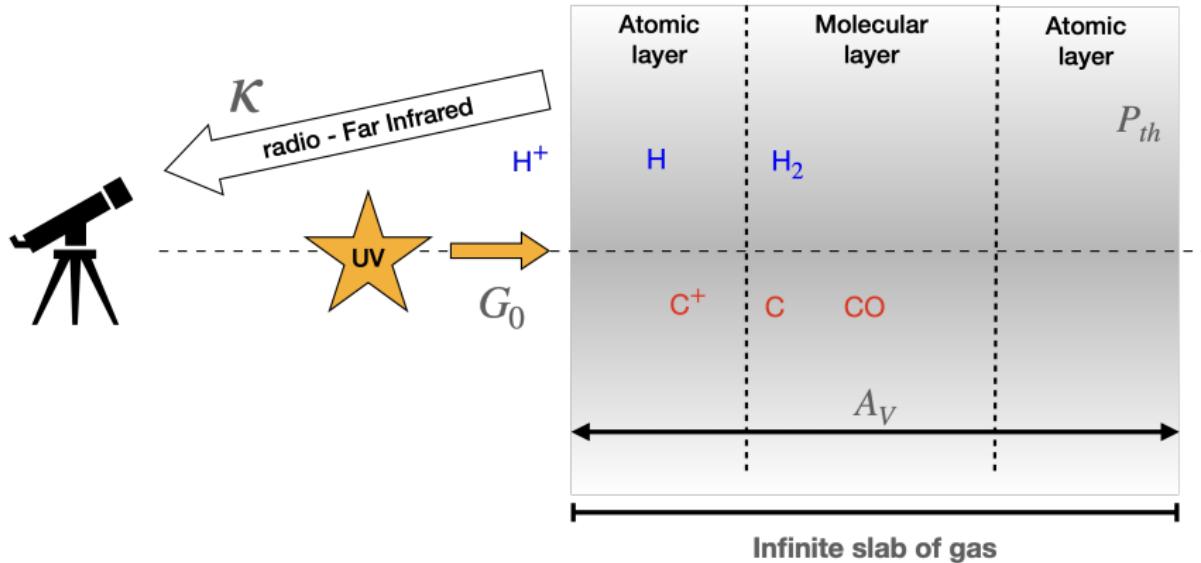
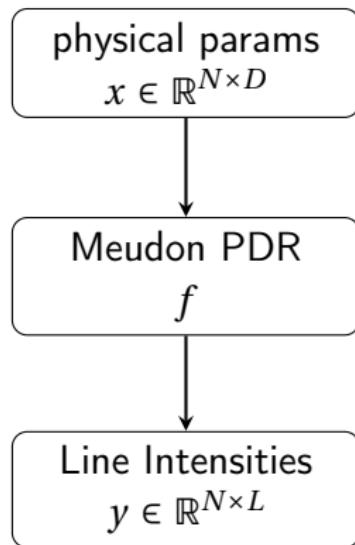


Figure: Structure of a PDR

Meudon PDR code: numerical simulation of a PDR

- Introduced in Le Petit et al. [2006].
- for stationary 1D slab of gas, solves:
 - 1 radiative transfer
 - 2 chemistry
 - 3 thermal balancethat are all **coupled!**



Can we infer x from y and f ?
no ground truth → with **credibility intervals**

Current state of the art in astrophysics

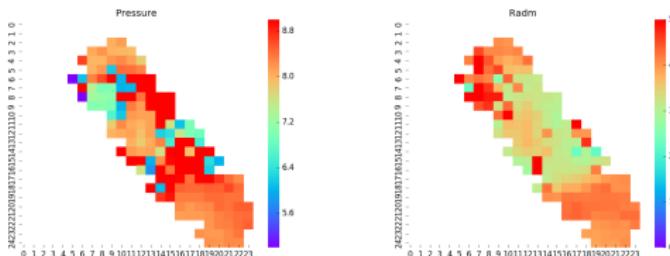
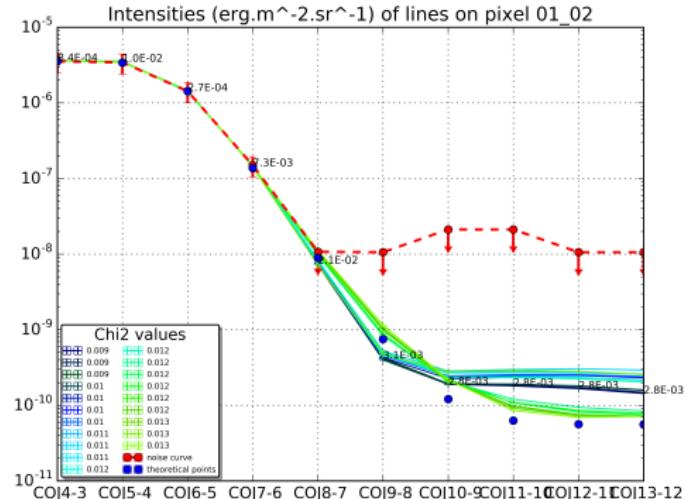


Figure: MLE maps inference

Bayesian map inversion

inference with credibility interval



a posteriori probability distribution $\mathbb{P}[x|y]$

$$\underbrace{\mathbb{P}[x|y]}_{\text{a posteriori}} \propto \underbrace{\mathbb{P}[y|x]}_{\text{likelihood}} \times \underbrace{\mathbb{P}[x]}_{\text{a priori}}$$

Complex distribution

⇒ impossible to manipulate as is
⇒ sampling with MCMC

Observation model

$$\forall n, \ell, y_{n,\ell} = \max \left\{ \omega, \epsilon_{n,\ell}^{(m)} f_\ell(x_n) + \epsilon_{n,\ell}^{(a)} \right\}$$

with

- $\epsilon_{n,\ell}^{(a)}$: additive noise (thermal, instruments)
- $\epsilon_{n,\ell}^{(m)}$: multiplicative noise (calibration error)
- ω : minimum detectable value by telescope

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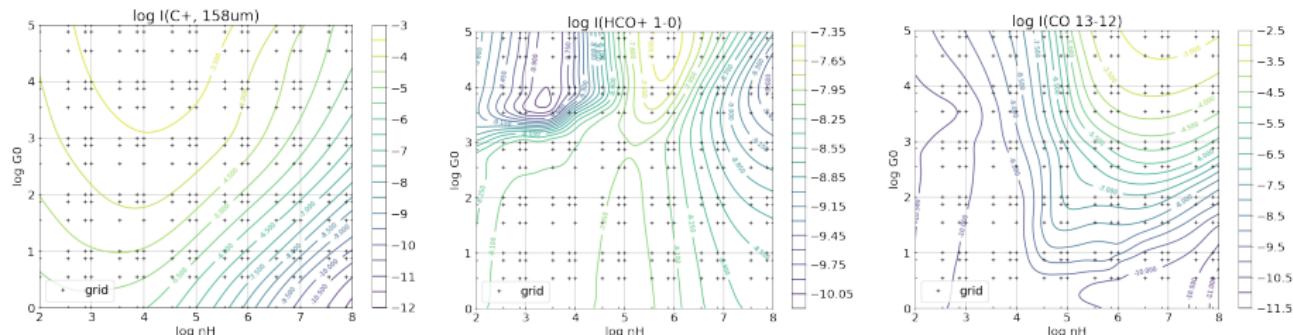


Figure: f_ℓ for some lines ℓ , for 1 pixel

Including a priori information

a *priori* information on x :

- spatial regularization: L2 penalty on image Laplacian
- f_ℓ : estimated from a grid
 - **constraint of belonging to a cube** (convex enveloppe of grid)
 - ⚠ non smooth prior ⚡ but can be tempered with a smooth penalty

Sampler

smooth prior + smooth likelihood \Rightarrow smooth posterior
classic **MCMC algorithm** (e.g., MALA) OK

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Final sampler : random combination of these two kernels

Illustration: Gaussian Mixture in a square

Illustration that our algorithm explores interesting **local minima** :

- mixture of 20 gaussians
- with constraint $x \in [-10, 10] \times [-10, 10]$

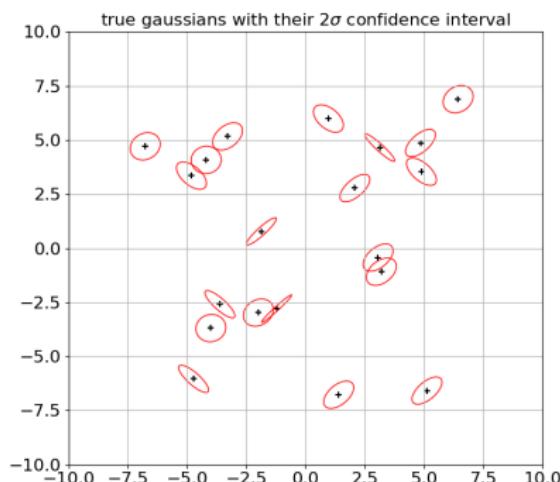
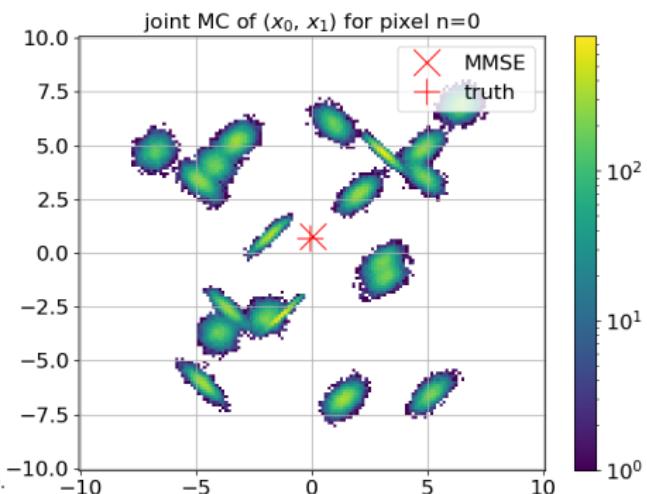
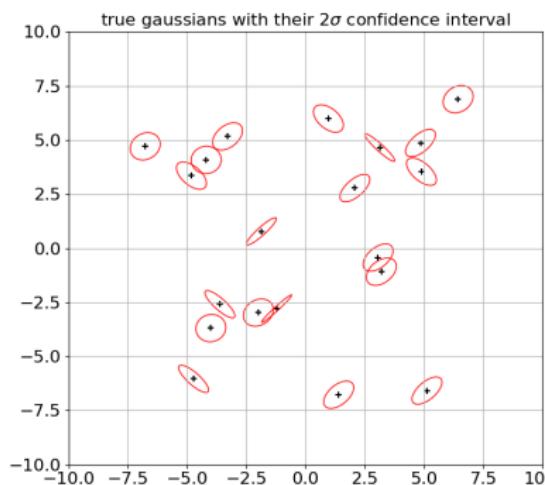


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Toy case 1: Time Series Inversion

$$y_{n,\ell} = \epsilon_{n,\ell}^{(m)} f(x_n) + \epsilon_{n,\ell}^{(a)} \text{ with } f: x \in \mathbb{R} \mapsto e^x, \sigma_a = 1, \sigma_m \sim 10\%$$

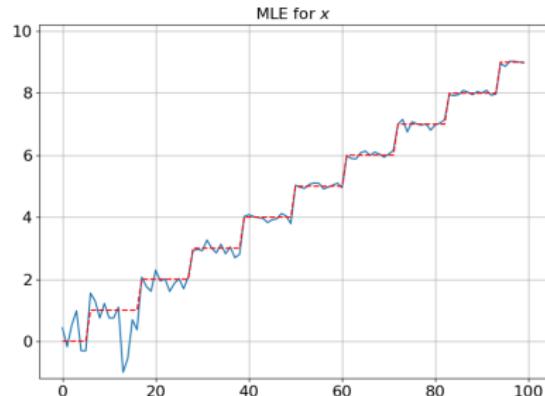
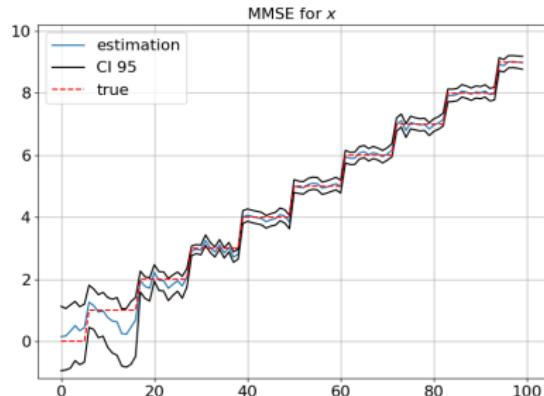
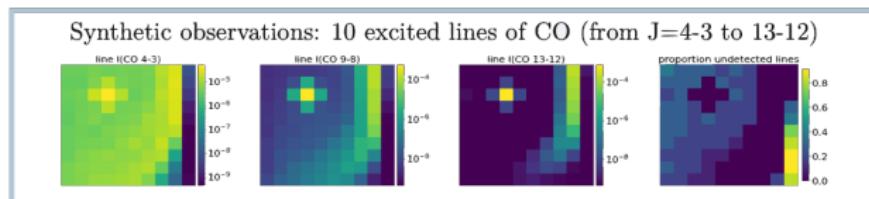
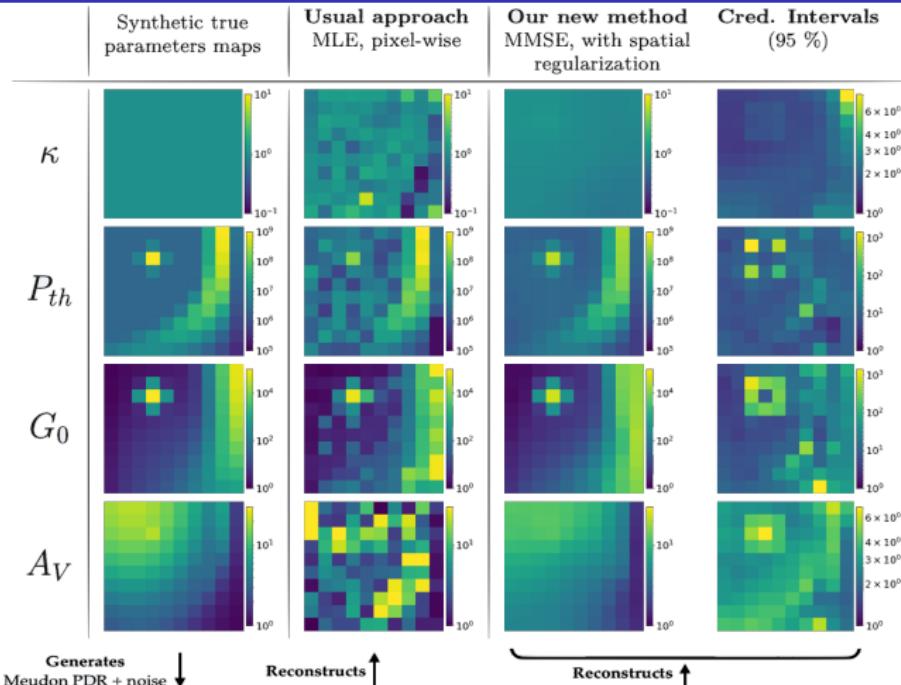


Table: Estimation Summary

| estimator | MSE | SNR |
|-----------|------|------|
| MMSE | 3.6 | 28.8 |
| MLE | 10.5 | 24.1 |

Astrophysical Toy case: Map Inversion



Application to NGC 7023 (1 pixel)

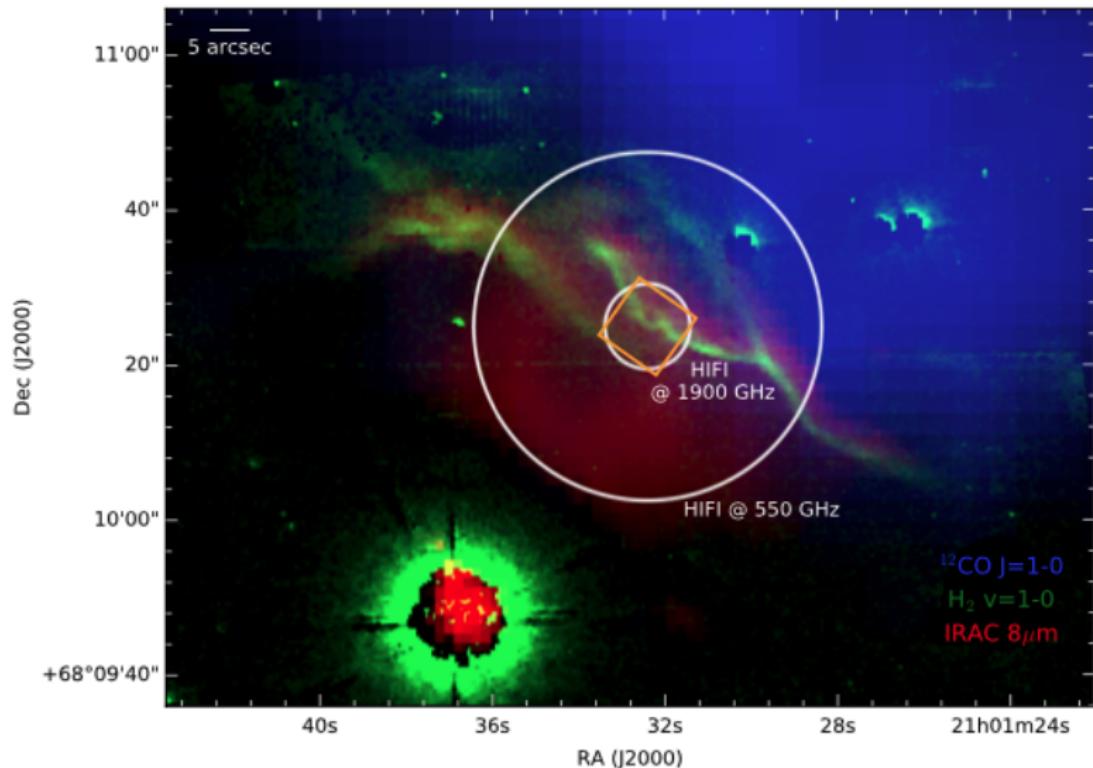
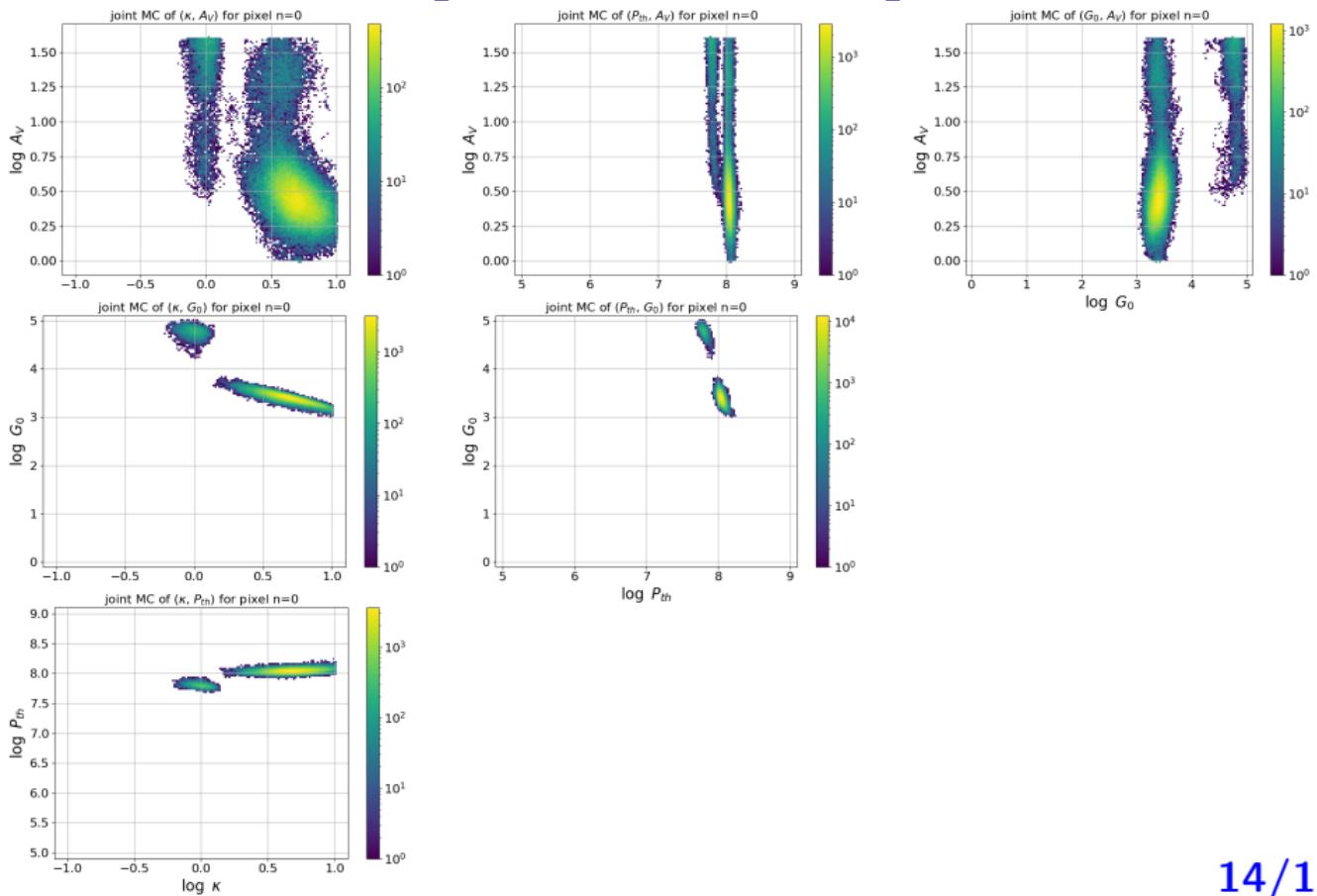


Figure: from Joblin et al. [2018]

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Summary

- Definition of a MCMC sampler with
 - 1 P-MALA kernel to tackle regularity issues
 - 2 MTM kernel to tackle the non-log-concavity of the posterior
- Evaluation of the method on toy data
- Application to real world data

Thank you for your attention!



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