

# INT3404E 20 - Image Processing: Homeworks 2

Đỗ Mạnh Dũng

## 1 The result of the function grayscale\_image

### 1.1 Source code

Listing 1: Code of grayscale\_image() function

```
def grayscale_image(image):  
    height, width = image.shape[:2]  
    img_gray = np.zeros((height, width), dtype=np.uint8)  
    for i in range(height):  
        for j in range(width):  
            B = image[i, j, 0]  
            G = image[i, j, 1]  
            R = image[i, j, 2]  
  
            gray_value = 0.299 * R + 0.587 * G + 0.114 * B  
  
            img_gray[i, j] = gray_value  
  
    return img_gray
```

### 1.2 Input

- Input:
  - image: a Numpy array containing the image data
- Algorithm:
  - Get the dimension of the image
  - Create a Numpy array with the same dimension as the image this will be used to stored the new grayscale image
  - Convert each pixel of an original image to a grayscale image using the following formula for each pixel:

$$p = 0.299 * R + 0.587 * G + 0.114 * B$$

### 1.3 Output

- Return the converted image



Figure 1: Grayscale Image

## 2 The result of the function flip\_image

### 2.1 Source code

Listing 2: Code of flip\_image() function

```
def flip_image(image):  
    return cv2.flip(image, 1)
```

### 2.2 Input

- Input:
  - image: A Numpy array containing the image data
- Algorithm:
  - Use function : `cv2.flip(image, 1)`
    - \* image The data of the image
    - \* flipCode = 1 Specify that the image will be flipped along the y-axis

## 2.3 Output

- Return the flipped image:



Figure 2: Flipped Grayscale Image

## 3 The result of the function rotate\_image

### 3.1 Source code

Listing 3: Code of rotate\_image() function

```
def rotate_image(image, angle):  
    height, width = image.shape[:2]  
    rotation_matrix = cv2.getRotationMatrix2D((width / 2, height / 2), angle, 1)  
    rotated_image = cv2.warpAffine(image, rotation_matrix, (width, height))  
    return rotated_image
```

### 3.2 Input

- Input:
  - image: A Numpy array containing the image data
  - angle: The rotation angle with a numeric value.

- Algorithm:
  - Extract the image dimension
  - The `cv2.getRotationMatrix2D()` function is used to compute the rotation matrix for the given angle around the center of the image.
  - Apply the rotation defined by the rotation matrix `rotation_matrix` to the original image using the function `cv2.warpAffine()`. The argument `(width, height)` specifies the size of the output image.

### 3.3 Output

- Return the rotated image:



Figure 3: Rotated Grayscale Image