

Work Scheduling on Heterogeneous Systems

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Overview

Heterogeneous
Scheduling

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Heterogeneous
Programming

Accelerate

Scheduling

Work Plan

Questions

1 Heterogeneous Programming

2 Accelerate

3 Scheduling

4 Work Plan

5 Questions

Why Heterogeneous Programming

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- People do math, simulations, and stream processing
 - We can parallelise these!
- CPUs are becoming tiny graphics cards
- GPUs are becoming tiny CPU swarms

Why Not Heterogeneous Programming

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- Distributing work is fiddly (thesis worthy!)
- Heterogeneous code is difficult, ugly, and imperative
- Hard to compose solutions
 - If I can write an optimised GPU kernel for maps, and another for prefix sums, can I 'fuse' them together while maintaining performance?

Accelerate: An Array DSL

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- A deeply embedded domain-specific language (the domain is array computation)
- Embedded in Haskell
 - Lots of fancy type shenanigans to enforce semantics
- Solves the 'difficult, ugly, and imperative' problem
- Doesn't solve the 'distributing work' problem
 - Until recently!

Data Fission (by Newton, Holk, and McDonell)

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- Added two nodes to Accelerate: `split` and `concat`
- Arrays are fissioned after operator fusion optimisations
- Initial algorithm: fission arrays into constant number of fragments, allocate each fragment to a device

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Can we do better?

Kinds of Scheduling

Heterogeneous Scheduling

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- Static Scheduling:
 - Arrays are fissioned into constant number of work fragments
 - Fragments are scheduled on devices according to data dependency
- Dynamic Scheduling:
 - Use runtime information to choose fragmentation and device scheduling

What Has Been Tried

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Questions

- Machine learning on source code (Grewe and O'Boyle)
- Binary analysis of array indexing (Lee et. al.)
- Statically split and allocate (Newton, Holk, and McDonell)
- Runtime performance analysis (Wang et. al.)

Speedy Dynamic Scheduling

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Questions

- Devices perform differently under different workloads
- Use run-time profiling
- Do too little and you can't exploit device/workload differences
- Do too much and you get swamped by synchronisation overheads (both time and memory)
- Try something in-between!

Main Goals

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Questions

- Implement dynamic fissioning, dynamic allocation
 - New accelerate-backend-kit already set up groundwork
 - Compare scheduling algorithms
 - Investigate interaction of fission and fusion
- Small-array optimisations
- Benchmarking

Extensions

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- Improve array concatenation
- LLVM support for operations
- Device affinity for dynamic allocation algorithm

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Question Time!