Pieter van Zutven

Journal

2013 Identification and parameter estimation of robotic systems with series elastic actuation

P.W.M. van Zutven and H. Nijmeijer

ASME Journal of Dynamic Systems, Measurement and Control

2013 Foot placement indicator for balance of planar bipeds with point feet

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International Journal of Advanced Robotic Systems

Conference

2013 Model parameter estimation of humanoid robots using static contact force

Linköping measurements

Sweden J.A.J. Baelemans, P.W.M. van Zutven and H. Nijmeijer

Proceedings of the IEEE International Symposium on Safety Security and Rescue

Robotics

2013 Qualitative validation of humanoid robot models through balance recovery side-

Karlsruhe stepping experiments

Germany T.M. Assman, P.W.M. van Zutven and H. Nijmeijer

Proceedings of the IEEE International Conference on Robotics and Automation

2012 Balance of humanoid robots by proper foot placement

Pensacola P.W.M. van Zutven and H. Nijmeijer

USA Proceedings of the Dynamic Walking Conference

2012 Foot placement for planar bipeds with point feet

Saint Paul P.W.M. van Zutven, D. Kostić, and H. Nijmeijer

USA Proceedings of the IEEE International Conference on Robotics and Automation

2010 On the stability of bipedal walking

Darmstadt P.W.M. van Zutven, D. Kostić, and H. Nijmeijer

Germany Simulation, Modeling and Programming for Autonomous Robots

2010 Parameter identification of robotic systems with series elastic actuators

Bologna P.W.M. van Zutven, D. Kostić, and H. Nijmeijer

Italy 8th IFAC Symposium on Nonlinear Control Systems

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Robocup

2013 Eindhoven

the Netherlands

Tech United Eindhoven RoboCup adult size humanoid team description 2013 P.W.M. van Zutven, T.M. Assman, J. Caarls, C. Çilli, T.P.M. Boshoven, E. Ilhan, J.A.J. Baelemans, D.J.F. Heck, M.P.A. Spoelstra and H. Nijmeijer Proceedings of RoboCup 2013 Symposium Papers and Team Description Papers

2012

Mexico

Mexico-City

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2010 Singapore Singapore

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