Estimation of the incubation time distribution for COVID-19

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Abstract

We consider smooth nonparametric estimation of the incubation time distribution of COVID-19, in connection with the investigation of researchers from the National Institute for Public Health and the Environment (Dutch: RIVM) of 88 travelers from Wuhan: Backer et al. (2020). The advantages of the smooth nonparametric approach w.r.t. the parametric approach, using three parametric distributions (Weibull, log-normal and gamma) in Backer et al. (2020) is discussed.

It is shown that the typical rate of convergence of the smooth estimate of the density is $n^{2/7}$ in a continuous version of the model, where n is the sample size. The (non-smoothed) nonparametric maximum likelihood estimator (MLE) itself is computed by the iterative convex minorant algorithm (Groeneboom and Jongbloed (2014)). All computations are available as R scripts in Groeneboom (2020a).

Keywords: incubation time, smooth nonparametric density estimation, nonparametric MLE, Weibull distribution, iterative convex minorant algorithm

Running headline: incubation time distribution

1 Introduction

Researchers from the Centre for Infectious Disease Control and Prevention of the National Institute for Public Health and the Environment (Dutch: RIVM) analyze in Backer et al. (2020) a data set of 88 travelers who are assumed to have picked up the COVID-19 virus in Wuhan. The distribution of their incubation times is estimated using certain simple distributions, like Weibull, log-normal and gamma. If the only thing we know about the start of the incubation time is that it belongs to an interval $[0, E_i]$, the log likelihood for one observation is:

$$\log \int_{t \in [0, E_i]} g(S_i - t) \, dF_i(t).$$

Here E_i would be the upper bound for the exposure interval, for which we take (looking back) 0 as the left point for the *i*th individual (see Britton and Scalia Tomba (2019)), S_i is the time where the person becomes symptomatic (note that both $S_i \leq E_i$ and $S_i > E_i$ can occur), and F_i would be the distribution function of the time of a possible contact with an infector. The exit times and times of becoming symptomatic of the 88 Wuhan travelers are shown in Table 1.

i	E_i	S_i	i	E_i	S_i
1	5	5	45	39	40
2	30	33	46	35	42
3	21	22	47	2	6
4	1	4	48	36	37
5	1	6	49	38	39
6	8	8	50	1	8
7	4	4	51	38	41
8	3	3	52	38	$\mid 41 \mid$
9	33	34	53	38	39
10	33	34	54	11	11
11	8	8	55	36	39
12	1	4	56	11	11
13	20	21	57	40	41
14	20	28	58	36	37
15	30	32	59	36	$\mid 41 \mid$
16	35	38	60	36	39
17	3	7	61	27	31

18	35	37	62	38	40
19	36	38	63	36	42
20	31	38	64	40	43
21	34	35	65	41	43
22	29	31	66	37	43
23	36	37	67	1	7
24	3	8	68	40	42
25	7	9	69	40	42
26	38	39	70	31	39
27	30	36	71	40	41
28	28	36	72	40	41
29	35	36	73	41	42
30	33	34	74	41	43
31	3	8	75	4	5
32	2	4	76	4	5
33	2	5	77	40	41
34	5	5	78	36	40
35	36	37	79	36	40
36	31	35	80	40	42
37	41	42	81	36	42
38	41	42	82	38	43
39	3	4	83	2	9
40	38	39	84	38	43
41	39	41	85	37	43
42	39	41	86	41	42
43	39	41	87	40	43
44	33	39	88	40	43

Table 1: Exit times and times of becoming symptomatic of the 88 Wuhan travelers after shifting the entrance times to 0.

It is clear that, without further assumptions, g and F_i are not identifiable. To remedy this, we assume, as in Backer et al. (2020) (see also Reich et al. (2009)), that F_i is the uniform distribution on $[0, E_i]$. If we want to use maximum likelihood, we have

to maximize

$$\sum_{i=1}^{n} \log \left\{ \int_{t=0}^{E_i} g(S_i - t) \, dt / E_i \right\},\,$$

and since the E_i do not matter in the maximization problem, we end up with the problem of maximizing

$$\sum_{i=1}^{n} \log \left\{ \int_{t=0}^{E_i} g(S_i - t) dt \right\}$$
 (1)

where q is the density of the incubation time.

So we deal with the following model. We have an exit time E_i for the exposure interval, an infection time V_i and an incubation time W_i . The time of becoming symptomatic is denoted by S_i , and S_i is assumed to be the independent sum of V_i and W_i , conditionally on E_i . Our observations are

$$(E_i, S_i, \Delta_i), \qquad i = 1, \dots, n,$$
 (2)

where n is the sample size and where the indicator Δ_i is defined by

$$\Delta_i = 1_{\{S_i \le E_i\}}, \qquad i = 1, \dots, n.$$
 (3)

Using the present notation, the log likelihood for the incubation time distribution function G becomes

$$\ell(G) = \sum_{i=1}^{n} \left[\Delta_i \log G(S_i) + (1 - \Delta_i) \log \left\{ G(S_i) - G(S_i - E_i) \right\} \right]. \tag{4}$$

Note that the time of becoming symptomatic is still in Wuhan if $\Delta_i = 1$.

The algorithms we used for analyzing the data set can be found on Groeneboom (2020a). We describe the data files given there. The original data file is data_Wuhan_tsv, which gives details on the persons in the sample and which can be found in Backer et al. (2020). This was transformed into a data file transformed_data_Wuhan.txt, consisting of three columns, giving, respectively, the arrivals in (if available) and departures from Wuhan and the time the person became symptomatic. If the arrival time was not available (possibly because the person was a Wuhan resident), this time was set to -18, which means 18 days before December 31, 2019, which is the zero on the time

scale. For traveler number 67, who apparently had a connecting flight, the duration of stay in Wuhan was changed from 0 to 1 day. This, in turn, was transformed into the input file inputdata_Wuhan.txt, where the time, spent in Wuhan, was shifted making the left point equal to zero, and consists of two columns: the first column contains the data $S_i - E_i$ (time of becoming symptomatic minus exit time from Wuhan) and S_i , time of becoming symptomatic, where all times are shifted to have entrance time zero. If the person became symptomatic in Wuhan we put E_i equal to S_i , so $S_i - E_i = 0$.

Assuming that the distribution of the possible time of infection is uniform on the exposure interval, and estimating the distribution function G by the Weibull distribution, parametrized as

$$G(x) = G_{a,b}(x) = 1 - \exp\{-bx^a\}, \qquad x > 0,$$
 (5)

we get as our maximum likelihood estimaters of the parameters a and b:

$$\hat{a} = 3.03514, \qquad \hat{b} = 0.002619.$$
 (6)

Using the Weibull maximum likelihood method, the estimate was computed by two methods. One is a very simple method using Weibull.cpp, which is used in analysis_EM.R and analysis_ICM.R, where also the nonparametric estimate to be discussed in the next sections is computed. For this "pattern search" algorithm for looking for the parameters of the Weibull distribution one does not have to compute the derivatives of the log likelihood. It is based on the Hooke-Jeeves algorithm. The other one can be found in R_Weibull_Estimation.R, where we use the R package lbfgs, and where the gradient (derivatives of the log likelihood) has to be provided.

The results obtained for the Weibull distribution approach of the two algorithms are remarkably similar. The values in (6) were produced by the R script in Groeneboom (2020a), using the Hooke-Jeeves algorithm. For a convergence proof of the Hooke-Jeeves algorithm and interesting further discussion of the pattern search algorithms, see Kolda et al. (2003) and Torczon (1997).

The aim of the present paper, however, is to draw attention to the nonparametric maximum likelihood estimator (the MLE) of the incubation time distribution, which is often also denoted by NPMLE (Nonparametric Maximum Likelihood Estimator). This is the distribution function \hat{G}_n , maximizing (4) over all distribution functions G. The problem of maximizing (4) over all distribution functions G instead of just Weibull, lognormal or gamma distribution functions is non-trivial and discussed in Section 2. We

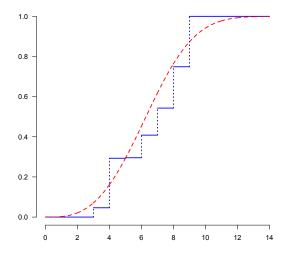


Figure 1: The nonparametric maximum likelihood estimate (MLE) \hat{G}_n of the incubation time distribution function (blue), and the MLE using the Weibull distribution (red, dashed), for the data set analyzed in Backer et al. (2020).

also discuss the smooth estimators based on the MLE, the so-called SMLE (Smoothed Maximum Likelihood Estimator) and the nonparametric density estimator, based on the MLE.

When we want to get an idea of properties of the incubation time distribution, there are (at least) three approaches.

1. We "fit" the data with a parametric distribution from a well-known family of distributions like the Weibull, log-normal or gamma distributions. The big disadvantage of this approach is that one usually does not have a good argument for choosing one of these distributions and that important aspects of the data might be completely hidden by the choice of such a distribution.

Convincing examples of this situation are given in Chapter 1 of Silverman (1986). If one fits the multimodal distribution of the eruptions of the Old Faithful Geyser in Yellowstone Park, Wyoming, by a unimodal distribution, one will only see one mode instead of the multiple modes that really are there. In that chapter also other interesting examples of how special aspects of the data are revealed by

nonparametric density estimation are given.

In fact, estimates of the simple parametric type such as the Weibull, etc. will usually be *inconsistent*: no matter how many observations one has, there will not be convergence to the right distribution. The ubiquitous appearance of the normal distribution has a completely different origin: the central limit theorem. But this reasoning will generally not apply in the same way for fitting with the Weibull, etc. distribution.

Another disadvantage which clearly shows up if people use this method (as in Backer et al. (2020)) is that one usually has to introduce several families of distributions (gamma, log-normal, Weibul ...), because there is no compelling reason to pick one of these.

2. We compute the nonparametric MLE. The result for the Wuhan data is shown in Figure 1 and the bar chart of the point masses of the MLE is shown in Figure 2 (the values of the point masses are shown in Table 2).

This is what one gets if one makes no assumptions at all about the distribution function and this is the "antipode" of the fitting with the Weibull etc. distribution. Figure 2 clearly shows a bimodal discrete density, but one wonders: is this bimodality due to chance fluctuations or is it real? Note that this discrete density is rather different from the density estimation of Silverman (1986), mentioned in point 1. In the latter case one assumes the existence of a (continuous) density with respect to Lebesgue measure instead of a discrete density.

How do we view the distribution of the incubation time? My own inclination is to assume the existence of a continuous density with respect to Lebesgue measure for the incubation time distribution and to use methods as in Silverman (1986), which entails smoothing. Which takes us to:

3. We estimate the density of the incubation time with respect to Lebesgue measure in a nonparametric way. In this case we also need an extra parameter, the smoothing parameter or bandwidth. Now one could argue (as has been done): "Ah, you objected in point 1 to the use of parametric distributions such as for example the Weibull distribution, but now you introduce a parameter again, the bandwidth!". Fair enough, but: "The bandwidth is a parameter of a totally different nature than the parameters of the Weibull distribution!". With the bandwidth one tries to mediate between the noise and the bias, something we cannot do with the nonparametric estimate, introduced in point 2. Moreover, we can do this in

a data-adaptive way, to create independence of a priori assumptions, a type of independence we cannot achieve with the estimates in point 1 above.

We must add, however, that the density estimation problem here is considerably more difficult than the density estimation problems considered in Silverman (1986). This is caused by the fact that our observations are indirect; we assume that the infection took place during the stay in Wuhan, but we do not know when. We only have an interval for this infection time. For this situation we have to use the so-called *interval censoring model*, which is for example discussed in Groeneboom and Jongbloed (2014). In fact, we have to deal with a combination of interval censoring (the infection time is contained in an interval, we cannot observe it directly) and deconvolution, since we have to extract the information from the sum of the infection time and the incubation time. For this reason we get slower rates of convergence of the density estimate: $n^{2/7}$ instead of the usual rate of convergence in density estimation, which is $n^{2/5}$ (see Silverman (1986) for the latter rate). An additional complication is that the observations are usually discretized, but we analyze in the sequel both the continuous model just described in Section 4 and the discretized model for which we cannot hope to achieve rate $n^{2/7}$ at each point.

Similar considerations hold for the SMLE, estimating the distribution function. In this case we also need a bandwidth (smaller than the bandwidth for the density estimate) and the rate will be $n^{2/5}$, which is the rate in ordinary density estimation. So in this sense the SMLE is comparable to an ordinary density estimate and the density estimate for the incubation time distribution is comparable to the ordinary estimate of the derivative of a density.

In this paper we focus on the method, described under point 3 above and give algorithms for computing the estimators. R scripts for all these methods are given in Groeneboom (2020a).

It should be noted that the asymptotic distribution of the MLE itself is unknown. In the continuous (not discretized) model it is expected to have the Chernoff limit distribution (location of the maximum of two-sided Brownian motion minus a parabola), but at present this is unknown, as it also is for the related limit distribution of the MLE in the so-called interval censoring, case 2, model (see Groeneboom and Jongbloed (2014)).

But we do not need the limit distribution of the MLE itself for deriving the (nor-

mal) limit distributions of the SMLE and density estimate, based on the MLE. As an example, we give the derivation for the limit distribution of the density estimate in the simulation model discussed in Section 4 in the appendix (Section 6).

2 Algorithms for computing the nonparametric maximum likelihood estimator

The EM iterations for the MLE maximizing (1), without making this parametric restriction, are in this case given by:

$$p'_{j} = p_{j} n^{-1} \sum_{i=1}^{n} 1_{\{j \in (S_{i} - E_{i}, S_{i}]\}} / \sum_{k \in (S_{i} - E_{i}, S_{i}]} p_{k},$$

$$(7)$$

where the ratios are zero if the denominators are zero. The implementation of this algorithm for the present situation can be found in analysis_EM.R in Groeneboom (2020a).

The EM iterations were started with the discrete uniform distribution on the 43 points $1, \ldots, 43$, which corresponds to the range of values (days) in Table 1, but withdrew its mass after 10,000 iterations to the 7 points $3, \ldots, 9$, which leads to the discrete distribution function, shown in Figure 1. A bar chart of the corresponding probability masses is shown in Figure 2. It is seen that this is a bimodal discrete probability distribution with modes at resp. 4 and 9 days, with the highest value at the second mode. This discrete probability distribution is also given in Table 2.

The iteration steps (7) follow from the so-called self-consistency equations, which are derived by differentiating the criterion function

$$n^{-1} \sum_{i=1}^{n} \log \left\{ \sum_{j \in (S_i - E_i, S_i]} p_j \right\} - \lambda \left\{ \sum_{j=1}^{m} p_j - 1 \right\}, \tag{8}$$

w.r.t. p_i , where in this case m=43, and λ is a nonnegative Lagrange multiplier, chosen in such a way that

$$\sum_{j=1}^{m} p_j = 1. (9)$$

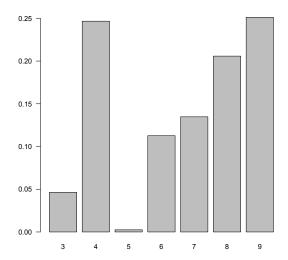


Figure 2: Bar chart of the probability masses of the nonparametric MLE

This yields

$$n^{-1} \sum_{i=1}^{n} 1_{\{j \in (S_i - E_i, S_i]\}} / \sum_{k \in (S_i - E_i, S_i]} p_k = \lambda, \qquad j = 1, \dots m,$$
(10)

and multiplying these relations with p_j and summing over j yields $\lambda = 1$, using the side condition (9). But the relations (10) only hold for the *active* (in this case 7) parameters $p_i > 0$ of the solution; in the iterations (7) the inactive parameters p_i will tend to zero. For more details, see, e.g., Groeneboom and Jongbloed (2014), Section 7.2.

Because of the monotonicity of the distribution function G, maximizing the log likelihood over all distribution functions G is an isotonic regression problem, which can be solved by specific isotonic methods. In the present case we can apply the *iterative* convex minorant algorithm, discussed in Groeneboom and Jongbloed (2014), Section 7.3.

As discussed in Section 1, the log likelihood is of type:

$$f(\boldsymbol{y}) = \sum_{i=1}^{m} k_i \log \left(G(U_i) - G(T_i) \right), \tag{11}$$

Number of days	p_i
3	0.0463850922
4	0.2466837048
5	0.0024858945
6	0.1126655228
7	0.1347501680
8	0.2058210187
9	0.2512085991

Table 2: Probability masses of the nonparametric MLE.

where k_i is the number of observations (T_i, U_i) , and where

$$(T_i, U_i) = (0, V_i + W_i) 1_{\{V_i + W_i \le E_i\}} + (V_i + W_i - E_i, V_i + W_i) 1_{\{V_i + W_i > E_i\}} \qquad i = 1, \dots, n$$
(12)

where n = 88, and where V_i is the infection time, W_i the incubation time and, as before, E_i the exit time of the travelers from Wuhan, where all observations are centred by subtracting the entrance time.

We first make the so-called preliminary reduction to reduce the problem to a maximization problem in the interior of a convex cone of type

$$\{ \boldsymbol{y} = (y_1, \dots, y_m)^T : 0 < y_1 \le \dots \le y_m \}.$$

For the Wuhan data set it can be checked that, without loss of generality, G(i) = 0, $i \leq 2$, and G(i) = 1, $i \geq 9$, since in this case values strictly between 0 and 1 can only make the likelihood smaller. If we make this preliminary reduction, the log likelihood for the ordered parameters y_i , representing the values of the distribution function G at the observation points, becomes:

$$f(\boldsymbol{y}) = \sum_{0 \le i < j \le 7} N_{ij} \log (y_j - y_i), \qquad (13)$$

where $y_i = G(i+2)$, i = 0, ..., 7, $y_0 = 0$, $y_7 = 1$, and where the triangular array (N_{ij}) ,

 $0 \le i < j \le 7$, is given by:

We have to maximize (11) under the restriction $0 < y_1 \le \cdots \le y_6$; by the preliminary reduction, we lost the additional condition $y_6 < 1$. Let $\mathbf{y} = (y_1, \dots, y_6)^T$. The (Fenchel) sufficient and necessary conditions for the solution are:

$$\sum_{j=i}^{6} \frac{\partial}{\partial y_j} f(\mathbf{y}) \le 0, \qquad i = 1, \dots, 6, \tag{14}$$

and

$$\sum_{i=1}^{6} y_i \frac{\partial}{\partial y_i} f(\mathbf{y}) = 0, \tag{15}$$

where f is defined by (11). Since the values y_i are strictly between 0 and 1, (15) can only hold if also

$$\sum_{i=1}^{6} \frac{\partial}{\partial y_i} f(\boldsymbol{y}) = 0,$$

and we can therefore turn (14) into

$$\sum_{i=1}^{i} \frac{\partial}{\partial y_j} f(\mathbf{y}) \ge 0, \qquad i = 1, \dots, 6.$$
 (16)

The resulting (nonparametric) MLE \hat{F}_n is shown in Figure 1, together with the MLE assuming that G is a Weibull distribution. The EM algorithm and the iterative convex minorant (ICM) algorithm give exactly the same solutions, but the ICM algorithm needs less iterations (106 in this case; the EM algorithm needs between 1000 and 10,000 iterations).

To compute the MLE via the iterative convex minorant algorithm, we have to construct so-called cusum (cumulative sum) diagrams. The cusum diagram consists of the point (0,0) and the points

$$\sum_{j=1}^{i} \left(w_j, \frac{\partial}{\partial y_j} f(\mathbf{y}) + w_j y_j \right), \qquad i = 1, \dots, 6,$$
(17)

where

$$w_j = -\frac{\partial^2}{\partial y_i^2} f(\mathbf{y}). \qquad j = 1, \dots, 6.$$
 (18)

At each iteration step the left derivative vector \mathbf{y}' of the greatest convex minorant of the cusum diagram is computed on the basis of the current value \mathbf{y} , and the stationary point of this iteration is the solution of the optimization problem. We perform line search in case the full step to \mathbf{y}' would not lead to improvement or would go out of bounds. For more theory, see Groeneboom and Jongbloed (2014).

As in Groeneboom and Jongbloed (2014), section 1.2, we can compute the smoothed maximum likelihood estimator (SMLE) and also an estimate of the density. The SMLE is defined by

$$\tilde{G}_{nh}(t) = \int \mathbb{K}((t-y)/h) \, d\hat{G}_n(y), \tag{19}$$

where h > 0 and K is an integrated kernel

$$\mathbb{K}(x) = \int_{-\infty}^{x} K(u) \, du. \tag{20}$$

Here K is a symmetric kernel with support [-1, 1], for example the triweight kernel

$$K(u) = \frac{35}{32} (1 - u^2)^3 1_{[-1,1]}(u). \tag{21}$$

We estimate the density by

$$\tilde{g}_{nh}(t) = h^{-1} \int K((t-y)/h) \, d\hat{G}_n(y).$$
 (22)

For the present analysis we took h = 3.6 in (19) and h = 4.6 in (22); these bandwidths were chosen by a bootstrap method, explained in Section 3. The resulting estimates are shown in Figure 3.

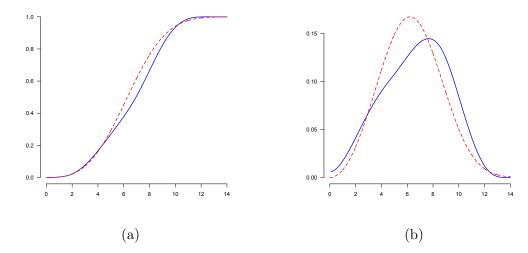


Figure 3: (a): The smoothed nonparametric maximum likelihood estimate (SMLE) of the incubation time distribution function (blue), and the MLE using the Weibull distribution (red, dashed), for the data set analyzed in Backer et al. (2020) and (b): the smoothed nonparametric maximum likelihood estimate of the incubation time density function (blue), and the MLE of the density using the Weibull distribution (red, dashed), for the data set analyzed in Backer et al. (2020).

3 Data-adaptive bandwidth choice for the density estimate and the SMLE

Let the random variables E_i with values on the integers ("days") on the interval [1, 43] represent the exit times. Furthermore, let V_i denote the (unknown) infection time, which we take, conditionally on E_i , to be uniform on $[0, E_i]$, and let W_i denote the (again unknown) incubation time. Our observations are the triples (E_i, S_i, Δ_i) , given by (2).

To determine the bandwidth h of our density estimator

$$\hat{g}_{nh}(t) = \int K_h(t-y) \, d\hat{G}_n(y), \tag{23}$$

where \hat{G}_n is the MLE of the distribution function G of the incubation time, we follow a method somewhat similar to the method used in Sen and Xu (2015).

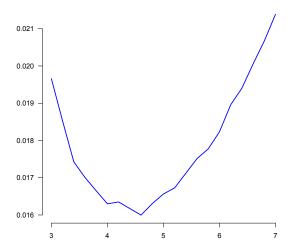


Figure 4: $\hat{MSE}_q(h)$, given by (24), as function of h.

We take B=10,000 bootstrap samples of observations (E_i, S_i^*, Δ_i^*) , corresponding to the observations (E_i, S_i, Δ_i) . The S_i^* are generated as the sums (rounded to the nearest integer) of a Uniform $(0, E_i)$ random variable V_i^* and a random variable W_i^* , generated from the density \hat{g}_{nh_0} by rejection sampling for a fixed h_0 , for which we took $h_0=4$ in the present case. The Δ_i^* are given by

$$\Delta_i^* = 1_{\{V_i^* + W_i^* \le E_i\}}.$$

Note that we keep the E_i the same as in the original sample, somewhat analogously to the procedure followed in Sen and Xu (2015), which relieves us from the duty to estimate the exit time distribution.

Next we computed

$$\hat{\text{MSE}}_g(h) = B^{-1} \sum_{h=1}^B \int \left\{ \hat{g}_{nh}^*(x) - \hat{g}_{nh_0}(x) \right\}^2 dx.$$
 (24)

The resulting loss function $\hat{MSE}_g(h)$ is shown in Figure 4, which gave as the minimizing bandwidth $\hat{h} \approx 4.6$. Taking $h_0 = 3$ in our function of reference \hat{g}_{nh_0} gave the same

minimizing value. The (approximate) independence of the starting value h_0 was also observed for the analogous bandwidth selection procedure in Sen and Xu (2015).

Similarly, we computed

$$\hat{MSE}_{G}(h) = B^{-1} \sum_{b=1}^{B} \int \left\{ \hat{G}_{nh}^{*}(x) - \hat{G}_{nh_{0}}(x) \right\}^{2} dx,$$
 (25)

as a function of h by the same bootstrap procedure, where \hat{G}_{nh}^* was computed for the bootstrap samples. The integrals were approximated by Riemann sums with step size 0.1 on the interval [0,14]. The R scripts for this procedure can again be found on Groeneboom (2020a). The method used here is called the "smoothed bootstrap", because we generate the bootstrap samples from the smooth estimate \hat{g}_{nh_0} of the density of the incubation time (added to a uniform $[0, E_i]$ random variable) instead of just resampling with replacement from the data (E_i, S_i, Δ_i) , as one would do in the ordinary bootstrap.

A perhaps slightly unorthodox variant of the present method is the smooth bootstrap where we do not round the sums of V_i^* and W_i^* to the nearest integer, but just use them as continuous variables (for more information on the continuous model see the next session). The unorthodox aspect is that, in our bootstrap experiment, we do not recreate exactly the same situation as in our original setting, where the data are integers. In fact, we create data for the continuous model, where we can easier compare bias and variance. We tried this out for the density estimates, and it actually gave exactly the same minimizing bandwidth h = 4.6 for the least squares criterion. More research on this method is necessary, though.

4 The continuous model

Applying the method of the preceding section to the discrete data, where one only uses days on the time axis, is somewhat dubious, since, in fact, we do not have information on a finer scale, which would allow us to let the bandwidth (and therefore the bias) tend to zero. It is conceivable that we have information on a finer scale, for example the time of the outgoing flight or the time of day of becoming symptomatic. Presently both times are interval censored (where one day is the interval). We could therefore introduce another assumption, for example that the time of becoming symptomatic is uniformly distributed over a day. In any case, there seems to be enough reason to study

the continuous model, where one would have (approximately) continuous observations, and to analyze what can be expected in this case.

We define as before the indicator Δ by

$$\Delta = 1_{\{S \le E\}},\tag{26}$$

where E is again the exit time and S is the time of becoming symptomatic, and consider the following simulation experiment. E_i is uniform [0, M], the time of infection V_i is a Uniform random variable on $[0, E_i]$, conditionally on E_i , and the incubation time W_i is a truncated Weibull(a, b) distribution, where a and b have the same values as the estimates \hat{a} and \hat{b} in (6), respectively, and where the truncation interval $[0, M_1]$ is contained in the interval [0, M]. In the present simulation, we took $M_1 = 20$ and M = 30. In this way the upper bound for the observations S_i is equal to 50, which is somewhat comparable with the upper bound 43 of the observations S_i for the Wuhan travelers. This means that $S_i = V_i + W_i$, where we assume that V_i and W_i are independent, and that our observations are the triples (E_i, S_i, Δ_i) .

The MLE of the incubation time, where E_i and S_i are known, looks rather different from the MLE based on the discretized observations shown in Figure 1. An example of such an MLE is shown in Figure 5 for a sample of n = 1000. Since in this case the MLE can have more jumps, it has the possibility to be much closer to the continuous distribution function. It maximizes again expression (1), but this time the variables E_i and S_i are not discretized.

In this setup, the SMLE will, in the interior of the interval $[0, M_1]$, pointwise have the $n^{2/5}$ rate and the corresponding nonparametric density estimate the $n^{2/7}$ rate of convergence, and the pointwise limit distributions will be normal in both cases (see Section 6 of the present paper and Groeneboom and Jongbloed (2014), section 11.4). For the density estimate in the present simulation model we get the following result.

Theorem 1. Let \tilde{g}_{n,h_n} be the estimate of the density, defined by

$$\tilde{g}_{n,h_n}(t) = h^{-1} \int K((t-y)/h_n) \, d\hat{G}_n(y) = \int K_{h_n}(t-y) \, d\hat{G}_n(y),$$

where $h_n \sim cn^{-1/7}$, for some c > 0. Let the score function $\theta_{t,h,G}$ be defined by

$$\theta_{t,h,G}(e,s,\delta) = \frac{\phi(s) - \phi((s-e)_+)}{G(s) - G((s-e)_+)},\tag{27}$$

where ϕ solves the integral equation

$$\int_{e>0} e^{-1} \left[\frac{\phi(w+e) - \phi(w)}{G(w+e) - G(w)} - \frac{\phi(w) - \phi((w-e)_{+})}{G(w) - G((w-e)_{+})} \right] dH(e) = \frac{\partial}{\partial w} K_h(t-w). \tag{28}$$

defining 0/0 = 0 and letting H be the distribution function of the exit time E. Let \mathbb{P}_n be the empirical probability measure of a sample $(E_1, S_1), \ldots, (E_n, S_n)$. Then we have, taking $h = h_n \sim cn^{-1/7}$, for a c > 0, and $G = G_0$ (the underlying incubation time distribution) in (27) and (28),

$$n^{2/7} \left\{ \tilde{g}_{n,h_n}(t) - \int K_{h_n}(t-y) \, dG_0(y) \right\} = n^{2/7} \int K_{h_n}(t-y) \, d(\hat{G}_n - G_0)(y)$$

$$\xrightarrow{\mathcal{D}} N(0,\sigma^2), \tag{29}$$

where $N(0, \sigma^2)$ is a normal distribution with mean zero and variance σ^2 given by:

$$\sigma^{2} = \lim_{n \to \infty} var \left(n^{2/7} \int \theta_{t, h_{n}, G_{0}}(e, s) d\mathbb{P}_{n}(e, s) \right).$$

A sketch of the proof is given in the Appendix. In the present simulation study, G_0 is given by the truncated Weibull distribution function with parameters given by (6). For estimating the variance, we can take $G = \hat{G}_n$ and let $H = \mathbb{H}_n$ be the empirical distribution function of the E_i in (28), and solve the equation only for points w which are points of mass of $d\hat{G}_n$; in this case ϕ is a right-continuous piecewise constant function, with jumps only at the points of mass of $d\hat{G}_n$.

This means that we can apply the same techniques as in Groeneboom and Hendrickx (2017b) and the R-package Groeneboom and Hendrickx (2017a), and for example compute pointwise bootstrap confidence intervals for the density. The bandwidth was determined by taking bootstrap samples of size m = 50, using bandwidths of size $cm^{-1/7}$ and using the optimal constant \hat{c} over the east squares criterion in the bandwidth $\hat{c}n^{-1/7} = 3.51991$, where n = 1000, for the density in the original sample, where we compare with the density estimate with bandwidth h = 3 in the original sample. This follows the procedure shown in the vignette of the R-package Groeneboom and Hendrickx (2017a). For the motivation for taking bootstrap samples of a smaller sample size, see Groeneboom and Hendrickx (2017b). The method goes back to Hall (1990). Since we have a simulation model here, we can also compute the real minimizing h, in a comparison with the truncated Weibull density. This yielded h = 3.4 in the present

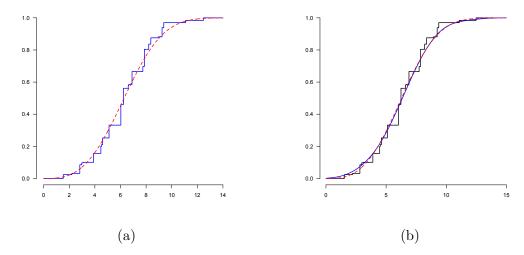


Figure 5: (a): The nonparametric maximum likelihood estimate (MLE) \hat{G}_n of the incubation time distribution function (blue) for a sample of size n=1000, and the truncated Weibull distribution function (red, dashed) with parameters a and b, in the simulation model where the variables are not discretized. (b): The MLE (black) and the SMLE (blue), for the same sample, and the truncated (on $[0, M_1]$) Weibull distribution function (red, dashed). The bandwidth of the SMLE is h=3.

case, which is a value not far from the bandwidth found by the bootstrap sampling. In the pictures of this section, we took h = 3.4.

The bootstrap 95% confidence intervals for the density are shown for a sample of size n=1000 in Figure 7. These computations can again be checked on Groeneboom (2020a). For these intervals just 1000 bootstrap samples were taken, resampling with replacement from the original sample of triples (E_i, S_i, Δ_i) , computing the density estimate again in the bootstrap samples and determining the 2.5% and 97.5% percentiles of the values of the density estimates in the 1000 bootstrap samples. To get really good intervals it is probably necessary to use an asymptotic pivot though, based on Theorem 1. This matter is subject to further investigation.

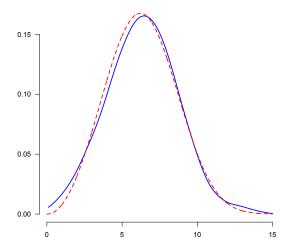


Figure 6: The nonparametric estimate of the density of the incubation time (blue, solid), based on a sample of size n = 1000, based on the truncated Weibull distribution, where we use bandwidth h = 3.4. The red dashed curve is the truncated Weibull density with parameters a and b of (6).

5 Concluding remarks

We offered an alternative nonparametric approach to the estimation of the incubation time distribution which was estimated by parametric methods in Backer et al. (2020) for a data set of travelers from Wuhan. In this way we do not have to choose a parametric distribution, like the Weibull, log-normal or gamma, as in Backer et al. (2020), but compute a nonparametric maximum likelihood estimate instead which does not need the arbitrary choice of parameters at all.

However, to give a smooth estimate of the distribution function and (continuous) density, we have to choose a bandwidth parameter. For this choice a smoothed bootstrap approach was suggested. We also considered the model where the observations are not discretized and discussed rates of convergence, bootstrap confidence intervals and a limit theorem in that case. The present paper can be considered to be the technical companion of the column Groeneboom (2020b). All numerical computations are given as R scripts in Groeneboom (2020a).

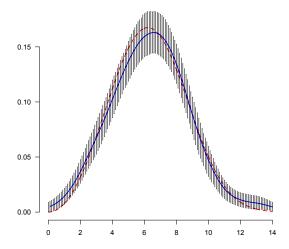


Figure 7: Density estimate (blue) and pointwise bootstrap 95% confidence intervals for the density of the incubation time distribution for a sample of size n=1000 (same sample as in Figures 5 and 6). The truncated Weibull density is given by the red dashed curve.

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6 Appendix

Using the notation of p. 330 of Groeneboom and Jongbloed (2014), we define the score function $\theta_{t,h,G}$ by:

$$\theta_{t,h,G}(e,s) = E[a(W)|(E,S) = (e,s)] = \frac{\int_{w \in ((s-e)_+,s]} a(w) dG(w)}{G(s) - G((s-e)_+)}$$
(30)

We assume $G_0(M_1) = 1$, where G_0 is the distribution function of the incubation time and M_1 is the upper bound of the support of the distribution (taken to be $M_1 = 20$ in

the simulations).

Defining, as in for example the interval censoring model,

$$\phi(u) = \int_{y \le u} a(y) \, dG(y),$$

we get:

$$\theta_{t,h,G}(e,s) = \frac{\phi(s) - \phi((s-e)_{+})}{G(s) - G((s-e)_{+})},\tag{31}$$

where we define 0/0 = 0. Note that ϕ is absolutely continuous w.r.t. G and that $\phi(s) = 0$, $s \ge M_1$, since we assume, as usual, $a \in L_2^0(G)$, where $L_2^0(G)$ is the space of square integrable functions f w.r.t. dG, with the property $\int f(x) dG(x) = 0$.

The adjoint of the conditional expectation operator, defined in (30) is given by

$$E[b(E,S)|W=w] = \int_{e>0} e^{-1} \int_{s \in (w,w+e)} b(e,s) \, ds \, dH(e), \tag{32}$$

where H is the distribution function of E.

This gives the following equation for $\theta_{t,h,G}$:

$$E\left[\theta_{t,h,G}(E,S)|W=w\right] = \int_{e>0} e^{-1} \int_{s\in(w,w+e)} \frac{\phi(s) - \phi((s-e)_{+})}{G(s) - G((s-e)_{+})} \, ds \, dH(e)$$

$$= K_{h}(t-w) - \int K_{h}(t-y) \, dG(y), \tag{33}$$

where w is a point where the density of G is positive (where we have to distinguish the discrete and continuous model).

Note that, letting \mathbb{H}_n be the empirical distribution function of the E_i , this leads to the following sample version of the equation:

$$\int_{e>0} e^{-1} \int_{s \in (w, w+e)} \frac{\phi(s) - \phi((s-e)_{+})}{\hat{G}_{n}(s) - \hat{G}_{n}((s-e)_{+})} ds d\mathbb{H}_{n}(e)
= K_{h}(t-w) - \int K_{h}(t-y) d\hat{G}_{n}(y),$$
(34)

where we evaluate this for point of mass w of \hat{G}_n and a piecewise constant function ϕ which only has jumps at the points of mass w of \hat{G}_n .

This leads to

$$n^{2/7} \int K_h(t-y) \, d(\hat{G}_n - G_0)(y) \sim n^{2/7} \int \theta_{t,h,G_0}(e,s) \, (\mathbb{P}_n - P_0) \, (e,s), \tag{35}$$

where θ_{t,h,G_0} is defined by (31), where $G = G_0$, the underlying distribution function of the incubation time, and ϕ is the solution of the equation (33) and satisfies $\phi(M_1) = 0$. Moreover, (35) would imply:

$$n^{2/7} \int K_{h_n}(t-y) d(\hat{G}_n - G_0)(y) \xrightarrow{\mathcal{D}} N(0, \sigma^2), \tag{36}$$

where

$$\sigma^{2} = \lim_{n \to \infty} \operatorname{var} \left(n^{2/7} \int \theta_{t,h_{n},G_{0}}(e,s) d\mathbb{P}_{n}(e,s) \right)$$
$$= \lim_{n \to \infty} \operatorname{var} \left(n^{2/7} \int \tilde{\theta}_{t,h_{n},\tilde{G}_{n}}(e,s) d\mathbb{P}_{n}(e,s) \right),$$

if $n^{1/7}h_n \to c > 0$ and $\tilde{\theta}_{t,h_n,\hat{G}_n}$, where

$$\tilde{\theta}_{t,h,\hat{G}_n}(e,s) = \frac{\tilde{\phi}_n(s) - \tilde{\phi}_n((s-e)_+)}{\hat{G}_n(s) - \hat{G}_n((s-e)_+)},$$
(37)

and $\tilde{\phi}_n$ solves the equation (34) in ϕ , where we abandon the interpretation as a conditional expectation for $\tilde{\theta}_{t,h,\hat{G}_n}$.

By differentiating w.r.t. w, we find that $\theta_{t,h,G}$ is also the solution of the equation

$$\int_{e>0} e^{-1} \left[\frac{\phi(w+e) - \phi(w)}{G(w+e) - G(w)} - \frac{\phi(w) - \phi((w-e)_{+})}{G(w) - G((w-e)_{+})} \right] dH(e) = \frac{\partial}{\partial w} K_h(t-w).$$
 (38)

We can also consider the corresponding equation for the MLE $\hat{G}_n = G$ and the empirical distribution function $\mathbb{H}_n = H$ instead:

$$\int_{e>0} e^{-1} \left[\frac{\phi(w+e) - \phi(w)}{\hat{G}_n(w+e) - \hat{G}_n(w)} - \frac{\phi(w) - \phi((w-e)_+)}{\hat{G}_n(w) - \hat{G}_n((w-e)_+)} \right] d\mathbb{H}_n(e) = \frac{\partial}{\partial w} K_h(t-w),$$
(39)

for the points of mass w of $d\hat{G}_n$, where we define 0/0 = 0.

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