

# Real World Applications using Parallel Computing for Dynamic Traffic Assignment and Shortest Path Search

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- The Objective:

To implement a functional solution to take on the

Dynamic Traffic Assignment Problem  
Route Choice + Flow Propagation

In a *time and resource efficient* manner.

# Problem #1 Definition

## Dynamic Shortest Path Search Parallelisation

How to best exploit parallel computing to:

- Reduce calculation time for *individual* requests
- Achieve a high level of service

- Test Application:

VAO : Verkehrs Auskunft Österreich

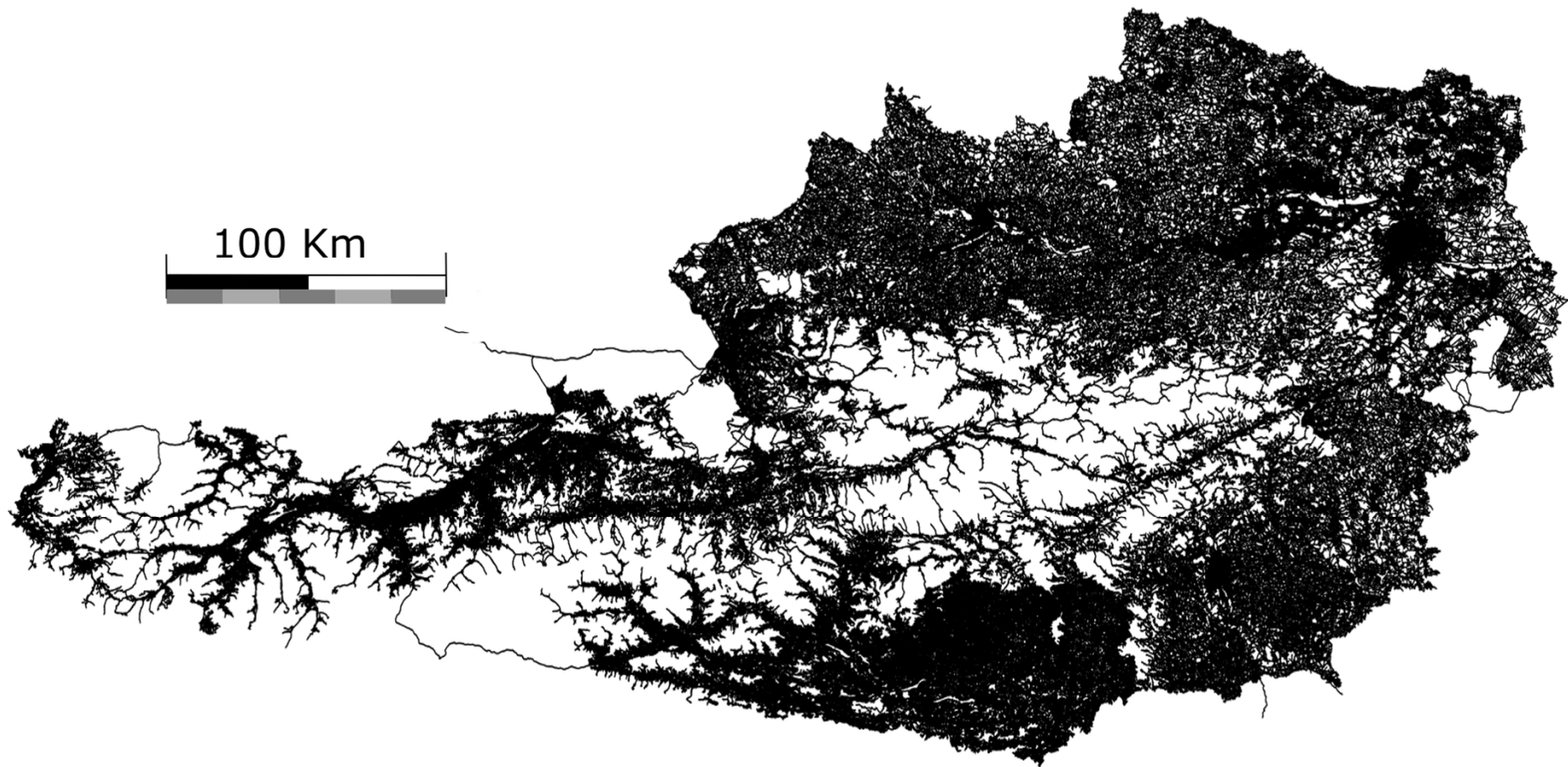
Hyperpath based Multi-modal Route planning for Austria

- Network Size:

1.1 Million Nodes

2.6 Million Arcs

- Test Network

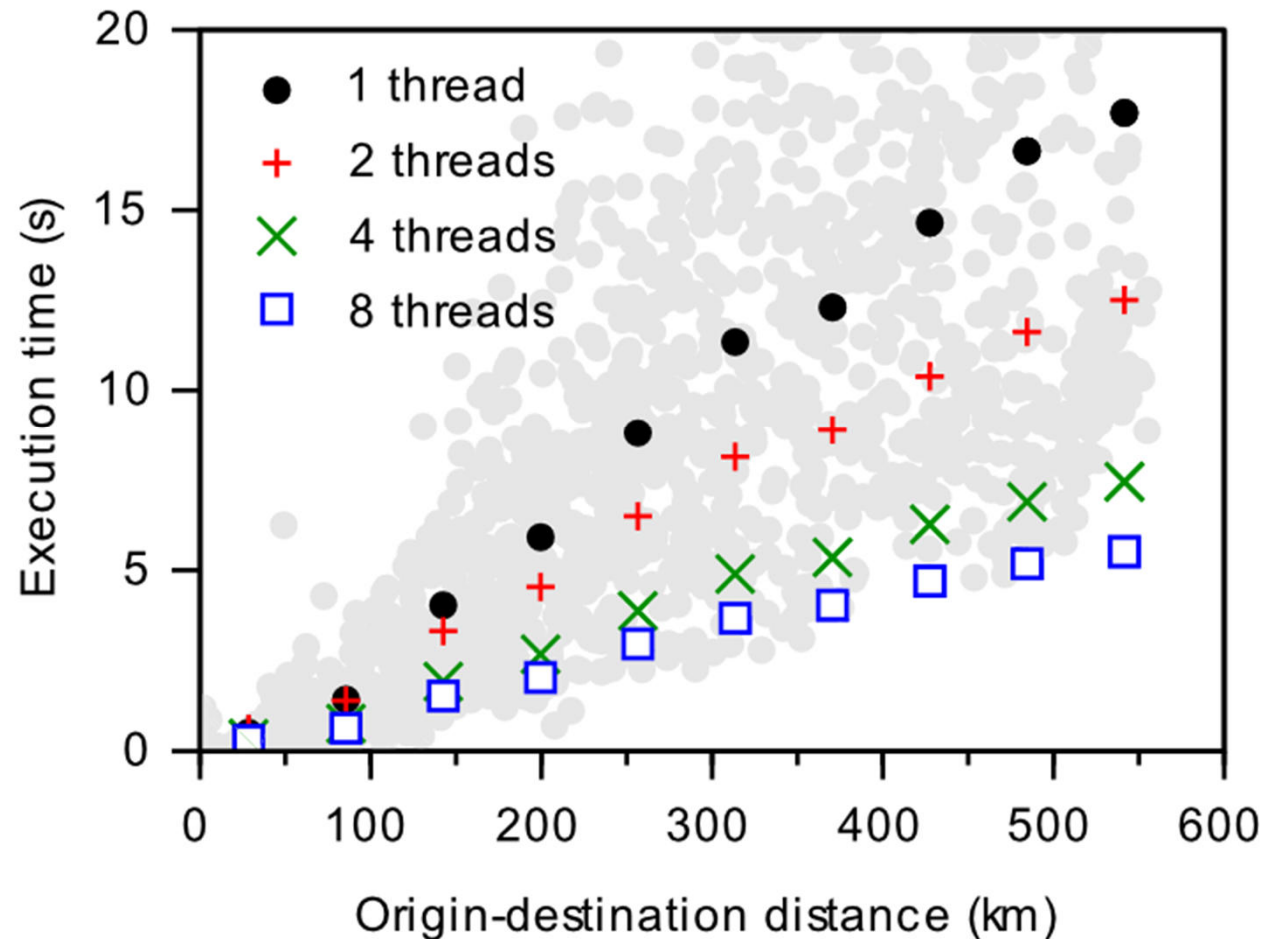


- A\* Shortest Path Algorithm:
  - ◆ Explore nodes in sequence, lower cost first
  - ◆ Similar to Dijkstra, distance as additional cost *estimate*
  - ◆ Bucket list to avoid sorting, label correcting
- Parallelisation Strategy:
  - ◆ Parallel threads extract one node each

## 1500 Requests

### Execution time:

- End user waiting time considerably reduced
- Faster, but not *exceptionally* faster
- Time vs Distance *looks* sub-linear

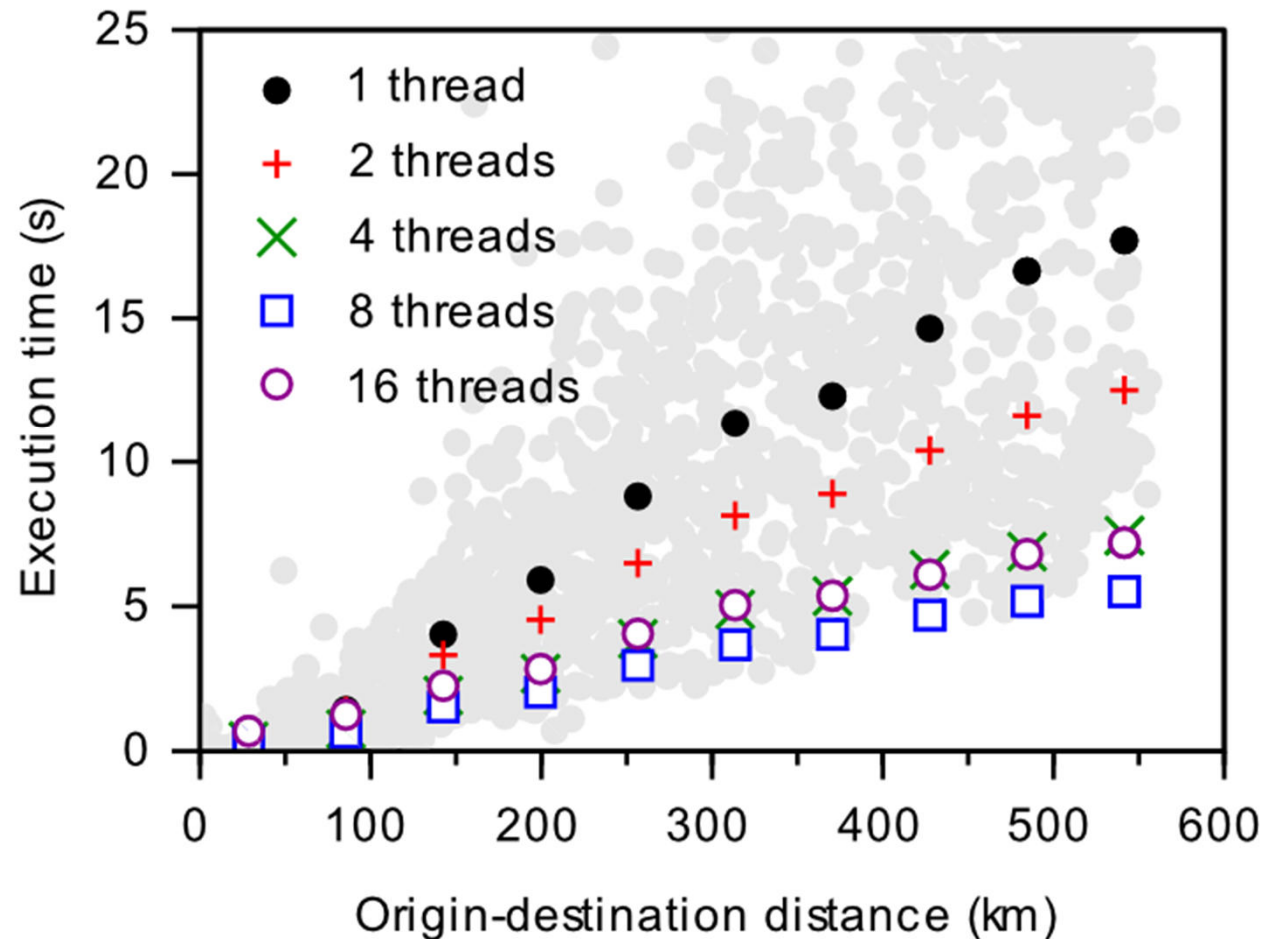




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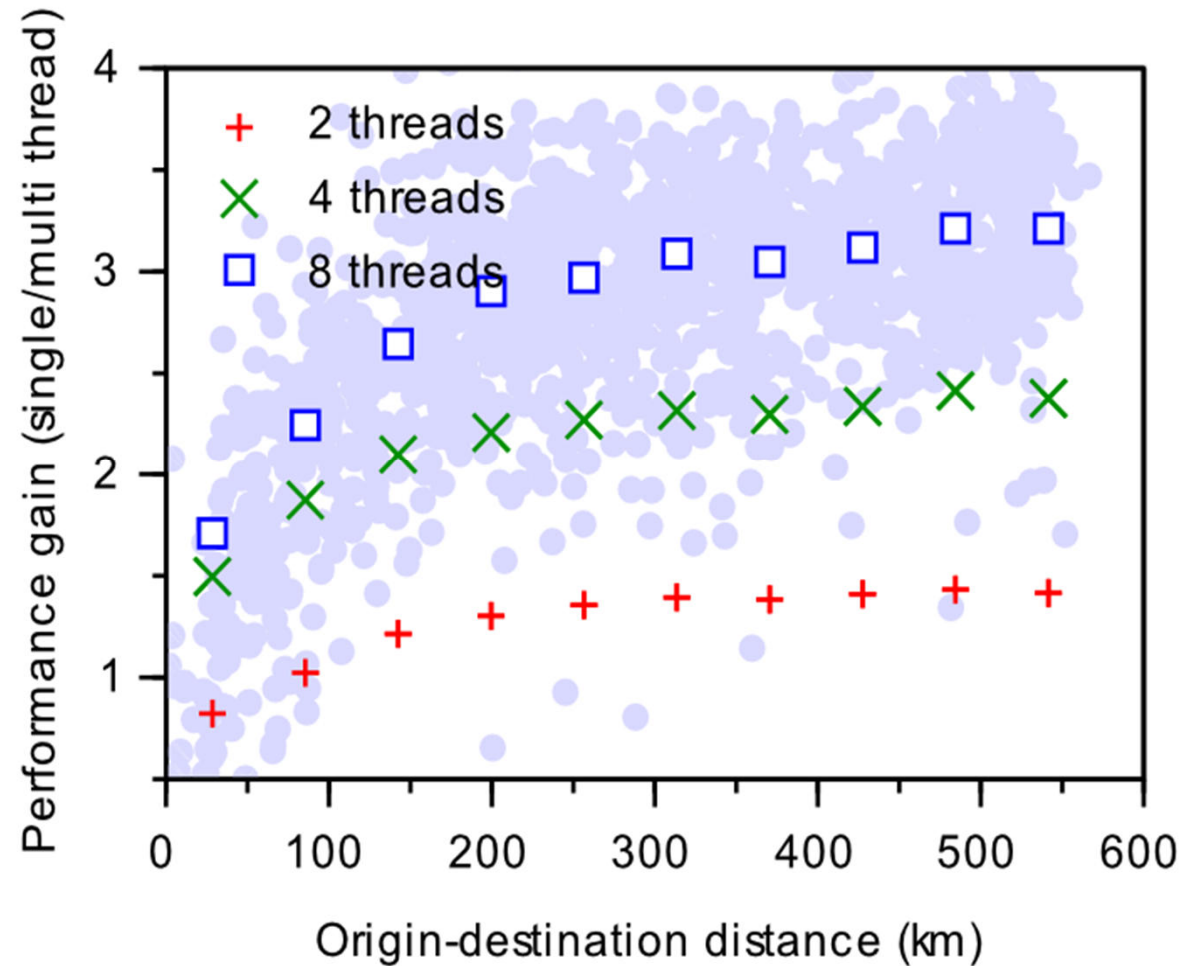
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- Time vs Distance looks sub-linear
- Gains up to 8 threads





## 1500 Requests Performance Gain:

- 8 thread performance  
2 to 4 times faster
- *Better results for  
more complex requests*



### Dynamic Traffic Assignment Parallelisation

How to best exploit parallel computing to:

- Reduce total computation time of Route Choice Model + Flow Propagation
- Achieve Real-Time compatible performance on large real-world networks

## Parallelisation Strategy

- Route Choice (DSP):
  - ◆ each DSP search is handled by a single thread
  - ◆ parallel threads carry out simultaneous path searches
  
- Flow Propagation (GLTM):
  - ◆ parallel threads compute flow splitting and redirection at individual nodes based solely on previous states
  - ◆ after processing a node, the same thread performs flow propagation on the FS and BS of that node, link by link

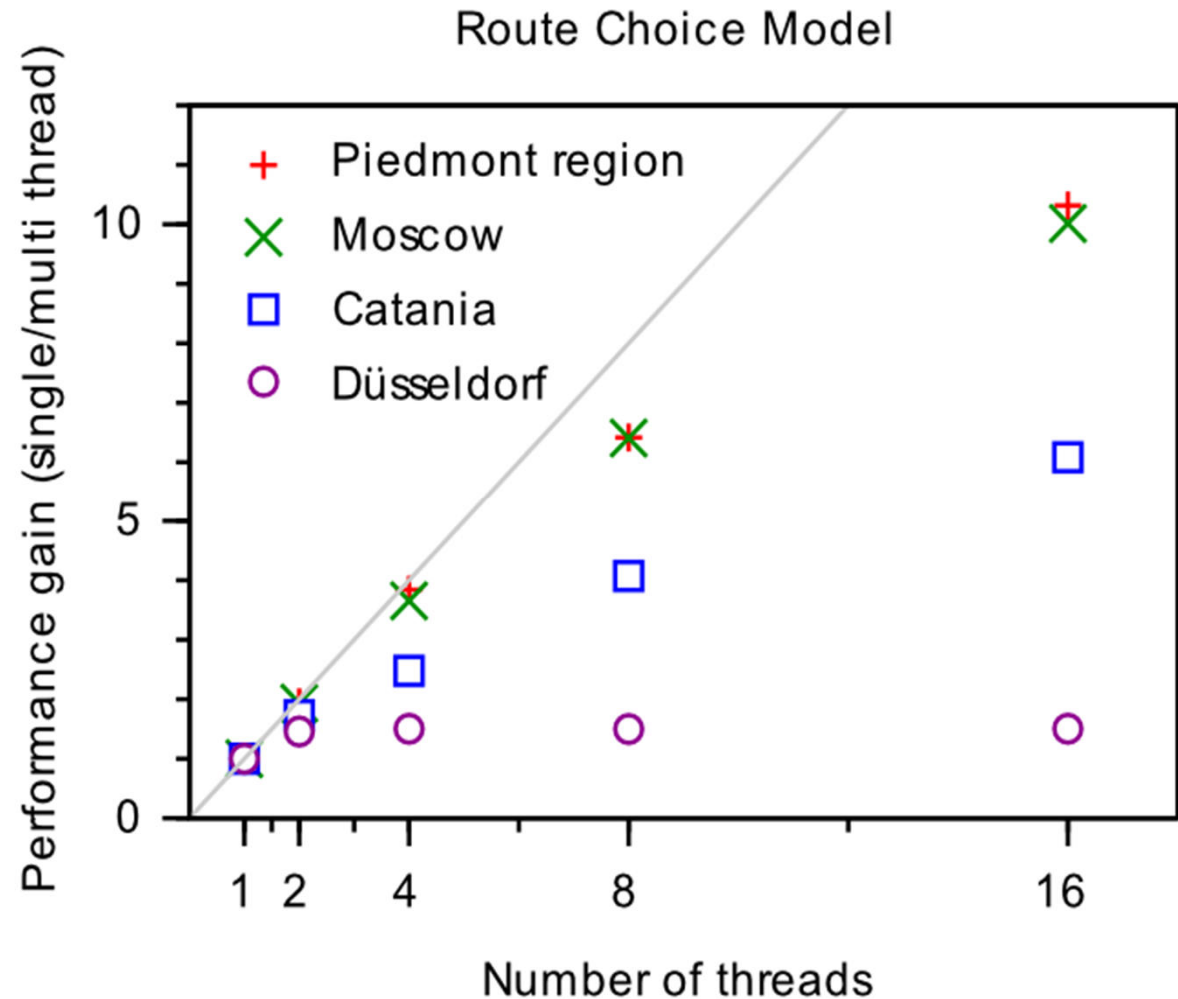
## ■ Benchmark Network Metrics

Network Metrics			
Region	N. of nodes	N. of links	N. of zones
5T-Piedimont	34606	95794	2009
Moscow	18749	46334	644
Catania	2052	6006	89
Düsseldorf South	656	1696	155

Region	Total computation time by number of threads [s]				
	1 Thr	2 Thr	4 Thr	8 Thr	16 Thr
5T-Piedimont	227	135	65	42	29
Moscow	102	57	31	18	13
Catania	7.2	4.3	2.6	1.8	1.3
Düsseldorf South	2.1	1.5	1.1	0.87	0.73

## 1 DTA Iteration Route Choice Phase

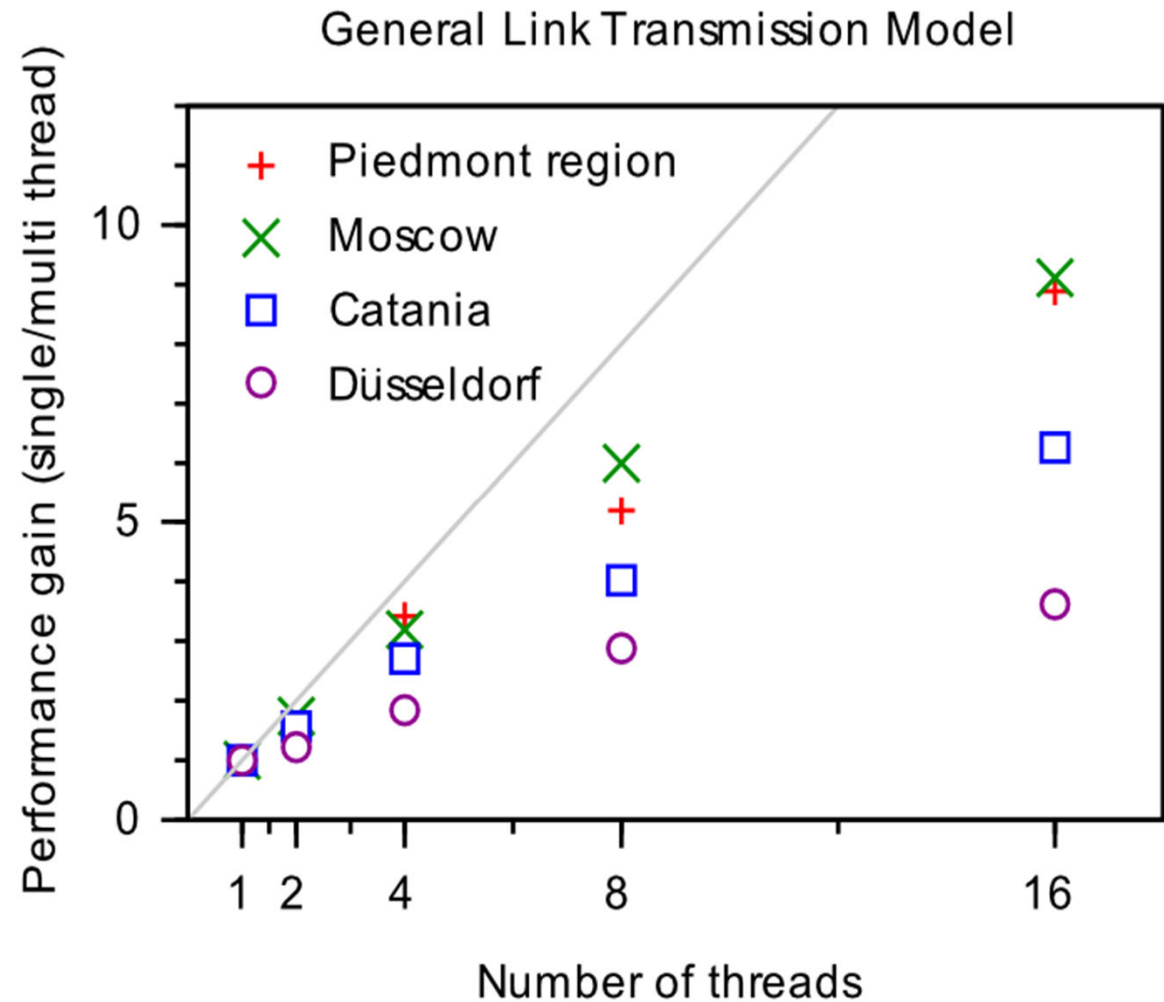
- Gains nearly linear for 2 and 4 threads
- Best results for larger networks
- MUCH more efficient than parallelised A\*
- Saturation onset is considerably delayed



## 1 DTA Iteration

### Flow Propagation Phase

- Gains sub-linear but still very significant
- Best results for larger networks



- Complete DTA Iteration Results:
  - ◆ Route Choice + Flow Generation + Flow Propagation
  - ◆ Simulation horizon 75 minutes
  - ◆ Time step 12 seconds

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18%

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...on an AMD Opteron 6272  
16 core CPU @2.1GHz - 128GB RAM

Thank you for your attention