# ep\_shape\_classifier

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### 1 Classificador

Análise de Formas 2s2023

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### 2 Bibliotecas

```
[]: import gdown
     import zipfile
     import numpy as np
     from torch.utils.data import Dataset, DataLoader, random_split
     from PIL import Image
     import pathlib
     from torchvision.transforms import v2
     import torch
     import torch.nn as nn
     import time
     import matplotlib.pyplot as plt
     import albumentations as A
     from albumentations.pytorch import ToTensorV2
     from sklearn.metrics import classification_report, confusion_matrix
     from sklearn.metrics import ConfusionMatrixDisplay
     from google.colab import drive
     import shutil
```

### 3 Constantes

```
[ ]: URL_DATASET = 'https://drive.google.com/uc?id=1eL7GyBk07fInfwojAaGhSzGpKVD1KVb2'
    DATASET_NAME = 'ep_shape_dataset'
    PATH_DATASET = './ep_shape_dataset/dataset/'
    TRAIN_SPLIT = 0.85
    BATCH_SIZE = 4
    NEW_SIZE = 128
    LEARN_RATE = 1e-3
    EPOCHS = 20
    TEST_REPEAT = 5
```

## 4 Dataset gerado pelo aplicativo

```
[]: class MyDataset(Dataset):
         def __init__(self, path_dataset, aug):
             super(). init ()
             self.path_dataset = path_dataset
             self.classes = []
             for path in pathlib.Path(path_dataset).glob("*/"):
                 self.classes.append(path.name)
             self.class_number = {}
             for i, key in enumerate(self.classes):
                 self.class_number[key] = i
             self.imgs = []
             for path in pathlib.Path(path_dataset).rglob("*.jpg"):
                 self.imgs.append(path.name)
             self.aug = aug
         def __getitem__(self, i):
             x = Image.open(
                 self.path dataset +
                 '/' + self.imgs[i].split('_')[0] + '/' +
                 self.imgs[i]
             ).convert('L')
             x = np.array(x)
             aug = self.aug(image=x)
             x = aug['image']
             y = self.class_number[self.imgs[i].split('_')[0]]
             return x, y
         def __len__(self):
             return len(self.imgs)
[]: # download dataset
     gdown.download(URL_DATASET, DATASET_NAME+'.zip', quiet=False)
     with zipfile.ZipFile(DATASET_NAME+'.zip', 'r') as zip_ref:
         zip_ref.extractall(DATASET_NAME)
    Downloading...
    From: https://drive.google.com/uc?id=1eL7GyBk07fInfwojAaGhSzGpKVDlKVb2
    To: /content/ep_shape_dataset.zip
              | 270M/270M [00:01<00:00, 236MB/s]
    100%|
[]: # dataset
     train_dataset = MyDataset(PATH_DATASET, A.Compose([
         A.ToFloat(),
         A.Resize(NEW_SIZE, NEW_SIZE),
         ToTensorV2()
```

```
]))
n1 = int(len(train_dataset) * TRAIN_SPLIT)
n2 = len(train_dataset) - n1
(train_data, val_data) = random_split(train_dataset, [n1, n2])

# ensure both train and val have all the classes
train_classes = []
```

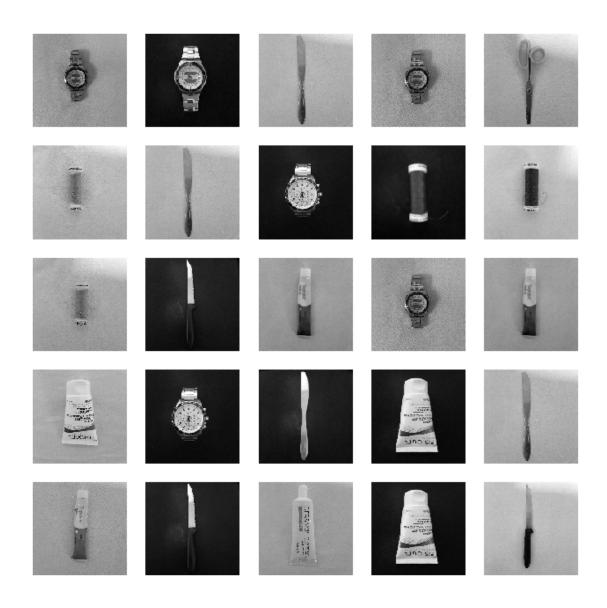
```
[]: # ensure both train and val have all the classes
     for i in range(len(train_data)):
         x, y = train_data[i]
         train_classes.append(train_dataset.classes[y])
     train_classes = list(set(train_classes))
     val_classes = []
     for i in range(len(val_data)):
         x, y = val_data[i]
         val_classes.append(train_dataset.classes[y])
     val_classes = list(set(val_classes))
     train classes.sort()
     val classes.sort()
     print(f"Classes in training dataset: {train_classes}")
     print(f"Classes in validation dataset: {val_classes}")
     if train_classes != val_classes:
         print('WARNING: train and val dont have the same classes.')
```

```
Classes in training dataset: ['creme', 'faca', 'linha', 'relogio', 'tesoura']
Classes in validation dataset: ['creme', 'faca', 'linha', 'relogio', 'tesoura']
```

```
[]: # dataloader
train_dataloader = DataLoader(train_data, BATCH_SIZE, shuffle=True)
val_dataloader = DataLoader(val_data, BATCH_SIZE)
```

### 5 Visualizando o dataset

```
[]: fig, ax = plt.subplots(5, 5, figsize=(8,8))
   idx = np.random.randint(len(train_dataset), size=(5, 5))
   for i in range(5):
        for j in range(5):
            x, _ = train_dataset[idx[i,j]]
            ax[i,j].imshow(x[0,:,:], interpolation='none', cmap='gray')
            ax[i,j].axis('off')
   plt.show()
```



# $6 \mod (CNN + FCs)$

```
[]: class MyNet(nn.Module):
    def __init__(self, n_classes):
        super().__init__()
        self.cnn = nn.Sequential(
            nn.Conv2d(1, 5, 3, 1, 1),
            nn.ReLU(),
            nn.MaxPool2d(2, 2),
            nn.Conv2d(5, 10, 3, 1, 1),
            nn.ReLU(),
            nn.ReLU(),
            nn.MaxPool2d(2, 2)
```

## 7 Treinamento e validação

```
[]: def train(model, device, train_dataloader, val_dataloader, lr=LEARN_RATE,
               epochs=EPOCHS):
         # optimizer
         opt = torch.optim.Adam(model.parameters(), lr)
         # loss function
         loss_fn = nn.NLLLoss()
         # history
         hist = {
             'train_loss': [],
             'train_accuracy': [],
             'val_loss': [],
             'val_accuracy': [],
             'time': None
         }
         print('Starting training...')
         start_time = time.time()
         for epoch in range(epochs):
             print(f"EPOCH {epoch+1}/{epochs}")
             # training
             model.train()
             train_loss = 0
             train_hits = 0
             for (x, y) in train_dataloader:
                 (x, y) = (x.to(device), y.to(device))
                 x_hat = model(x)
                 loss = loss_fn(x_hat, y)
                 opt.zero_grad()
```

```
loss.backward()
        opt.step()
        train_loss += loss
        train_hits += (x_hat.argmax(1) == y).type(torch.float).sum()
    train_loss = train_loss / len(train_dataloader.dataset)
    train_accuracy = train_hits / len(train_dataloader.dataset)
    hist['train_loss'].append(train_loss.item())
    hist['train_accuracy'].append(train_accuracy.item())
    # validation
    with torch.no grad():
        model.eval()
        val loss = 0
        val_hits = 0
        for (x, y) in val_dataloader:
            (x, y) = (x.to(device), y.to(device))
            x_hat = model(x)
            loss = loss_fn(x_hat, y)
            val_loss += loss
            val_hits += (x_hat.argmax(1) == y).type(torch.float).sum()
        val_loss = val_loss / len(val_dataloader.dataset)
        val_accuracy = val_hits / len(val_dataloader.dataset)
        hist['val_loss'].append(val_loss.item())
        hist['val_accuracy'].append(val_accuracy.item())
end_time = time.time()
hist['time'] = end_time - start_time
print(f'Training finished in {end_time - start_time:.0f}s.')
return hist
```

```
[]: # free memory
torch.cuda.empty_cache()

# create model and send to device
model = MyNet(len(train_dataset.classes))
device = torch.device('cuda' if torch.cuda.is_available() else 'cpu')
model.to(device)

# train
hist = train(model, device, train_dataloader, val_dataloader)

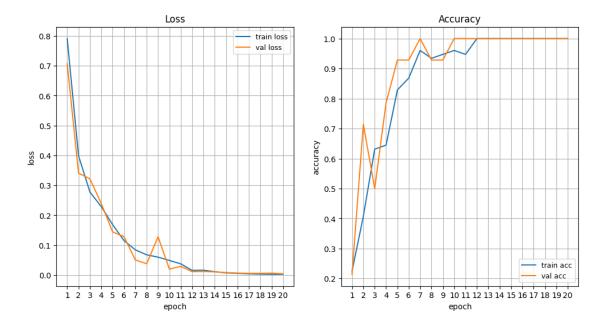
# save model
torch.save(model.state_dict(), 'ep_shape_model.pth')
```

Starting training... EPOCH 1/20 EPOCH 2/20

```
EPOCH 3/20
EPOCH 4/20
EPOCH 5/20
EPOCH 6/20
EPOCH 7/20
EPOCH 8/20
EPOCH 9/20
EPOCH 10/20
EPOCH 11/20
EPOCH 12/20
EPOCH 13/20
EPOCH 14/20
EPOCH 15/20
EPOCH 16/20
EPOCH 17/20
EPOCH 18/20
EPOCH 19/20
EPOCH 20/20
Training finished in 176s.
```

#### 8 Loss chart

```
[]: # loss chart
     fig, ax = plt.subplots(1, 2, figsize=(12, 6))
     ax[0].plot(np.arange(1, EPOCHS + 1), hist['train_loss'], label='train_loss')
     ax[0].plot(np.arange(1, EPOCHS + 1), hist['val_loss'], label='val loss')
     ax[0].set_title("Loss")
     ax[0].set ylabel('loss')
     ax[0].set_xlabel('epoch')
     ax[0].legend(fontsize=9, loc='upper right')
     ax[0].set_xticks(np.arange(1, EPOCHS + 1, 1))
     ax[0].grid(True)
     ax[1].plot(np.arange(1, EPOCHS + 1), hist['train_accuracy'], label='train acc')
     ax[1].plot(np.arange(1, EPOCHS + 1), hist['val_accuracy'], label='val acc')
     ax[1].set_title("Accuracy")
     ax[1].set_ylabel('accuracy')
     ax[1].set_xlabel('epoch')
     ax[1].legend(fontsize=9, loc='lower right')
     ax[1].set_xticks(np.arange(1, EPOCHS + 1, 1))
     ax[1].grid(True)
     plt.show()
```



### 9 Teste com dados aumentados

```
[]: def test(model, device, dataloader):
         print('Starting test...')
         y_true = []
         y_pred = []
         start_time = time.time()
         with torch.no_grad():
             model.eval()
             test_hits = 0
             for _ in range(TEST_REPEAT):
                 for (x, y) in dataloader:
                     (x, y) = (x.to(device), y.to(device))
                     x_hat = model(x)
                     y_pred.extend(x_hat.argmax(1).cpu().numpy())
                     y_true.extend(y.cpu().numpy())
         end_time = time.time()
         y_pred = np.array(y_pred)
         y_true = np.array(y_true)
         labels = dataloader.dataset.classes
         print(f'Test finished in {end_time - start_time:.0f}s.')
         print(classification_report(y_true, y_pred, target_names=labels))
         print()
         cm = confusion_matrix(y_true, y_pred, normalize='true')
         disp = ConfusionMatrixDisplay(cm, display_labels=labels)
```

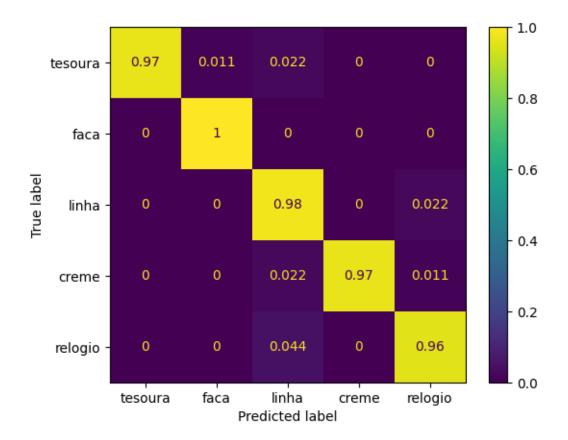
```
disp.plot()
plt.show()
```

```
[]: # dataset
     test_dataset = MyDataset(PATH_DATASET, A.Compose([
         A.ToFloat(),
         A.ShiftScaleRotate(shift_limit=0, scale_limit=0.2, rotate_limit=0),
         A.ColorJitter(hue=0, p=1),
         A.Blur(p=1),
         A.Resize(NEW_SIZE, NEW_SIZE),
         ToTensorV2()
     ]))
     # dataloader
     test_dataloader = DataLoader(test_dataset, BATCH_SIZE)
     # model
     model = MyNet(len(test_dataset.classes))
     model.to(device)
     model.eval()
     model.load_state_dict(torch.load('ep_shape_model.pth', map_location=device))
     # free memory
     torch.cuda.empty_cache()
     test(model, device, test_dataloader)
```

Starting test...

Test finished in 116s.

	precision	recall	f1-score	support
	-			
tesoura	1.00	0.97	0.98	90
faca	0.99	1.00	0.99	90
linha	0.92	0.98	0.95	90
creme	1.00	0.97	0.98	90
relogio	0.97	0.96	0.96	90
accuracy			0.97	450
macro avg	0.97	0.97	0.97	450
weighted avg	0.97	0.97	0.97	450



```
[]: # free model
del model
torch.cuda.empty_cache()
```

## 10 Upload do modelo

```
[]: drive.mount('/content/drive')
    shutil.copy("ep_shape_model.pth","/content/drive/MyDrive")
```

Drive already mounted at /content/drive; to attempt to forcibly remount, call drive.mount("/content/drive", force\_remount=True).

[]: '/content/drive/MyDrive/ep\_shape\_model.pth'