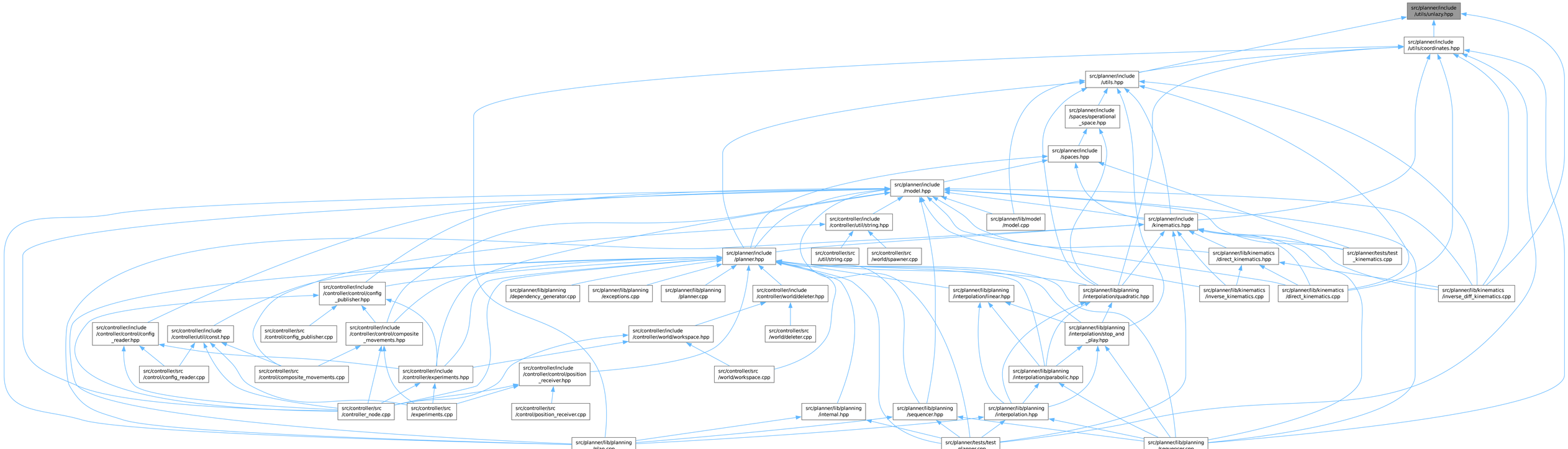
src/planner/include /utils/unlazy.hpp
src/planner/include /utils/coordinates.hpp
src/planner/include /utils.hpp
src/planner/include /spaces/operational _space.hpp
src/planner/include /spaces.hpp
src/planner/include /model.hpp
src/controller/include /controller/util/string.hpp
src/planner/lib/model /model.cpp
src/planner/include /kinematics.hpp
src/planner/include /planner.hpp
src/controller/src /util/string.cpp
src/controller/src /world/spawner.cpp
src/planner/lib/kinematics /direct_kinematics.hpp
src/planner/tests/test _kinematics.cpp
src/controller/include /controller/control/config _publisher.hpp
src/planner/lib/planning /dependency_generator.cpp
src/planner/lib/planning /exceptions.cpp
src/planner/lib/planning /planner.cpp
src/controller/include /controller/world/deleter.hpp
src/planner/lib/planning /interpolation/linear.hpp
src/planner/lib/planning /interpolation/quadratic.hpp
src/planner/lib/kinematics /inverse_kinematics.cpp
src/planner/lib/kinematics /direct_kinematics.cpp
src/planner/lib/kinematics /inverse_diff_kinematics.cpp
src/controller/include /controller/control/config _reader.hpp
src/controller/include /controller/util/const.hpp
src/controller/src /control/config_publisher.cpp
src/controller/include /controller/control/composite _movements.hpp
src/controller/include /controller/world/workspace.hpp
src/controller/src /world/deleter.cpp
src/planner/lib/planning /interpolation/stop_and _play.hpp
src/controller/src /control/config_reader.cpp
src/controller/src /control/composite_movements.cpp
src/controller/include /controller/experiments.hpp
src/controller/include /controller/control/position _receiver.hpp
src/controller/src /world/workspace.cpp
src/planner/lib/planning /interpolation/parabolic.hpp
src/controller/src /controller_node.cpp
src/controller/src /experiments.cpp
src/controller/src /control/position_receiver.cpp
src/planner/lib/planning /internal.hpp
src/planner/lib/planning /sequencer.hpp
src/planner/lib/planning /interpolation.hpp
src/planner/lib/planning /plan.cpp
src/planner/tests/test _planner.cpp
src/planner/lib/planning /sequencer.cpp