

Implementation

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Outline

- 3D distribution
- k point parallelism
- SCF loop
 - Initialization
 - iterative diagonalization
 - sum
 - mixing

FFT grids (one dimension)

- The real space grid: $x_i = \frac{i}{N}L$ with $i = 0, 1, 2, \dots, N-1$
- The reciprocal space grid: $G_i = i \frac{2\pi}{L}$
with $i = -\frac{N-1}{2}, -\frac{N-1}{2} + 1, \dots, 0, 1, \dots, \frac{N}{2}$

$$n_{max} \frac{2\pi}{L} < 2G_{cut}$$

In 3 dimensions

- Bravais and reciprocal lattices:

$$\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3 \quad \mathbf{b}_i = \frac{2\pi}{\Omega} \sum_{ijk} \epsilon_{ijk} \mathbf{a}_j \wedge \mathbf{a}_k$$

- real space grid: $\mathbf{r}_n = \sum_{i=1}^3 \frac{n_i}{N_i} \mathbf{a}_i$ with $n_i = 0, 1, 2, \dots, N_i - 1$
- reciprocal space: $\mathbf{G}_m = \sum_{i=1}^3 m_i \mathbf{b}_i$ with $m_i = -\frac{N_i+1}{2}, \dots, 0, \dots, \frac{N_i}{2}$

$$m_i^{max} |\mathbf{b}_i| < 2\sqrt{E_{cut}}$$

Gamma Trick

- Doing large calculations one uses only the gamma point $k=(0,0,0)$
- wave functions may be evaluated as real in this case for the Fourier transforms holds the equality

$$c_{-\mathbf{G}} + c_{\mathbf{G}}^*$$

This allows to store only one half of the components for each wave function.

$$\mathcal{F}_{\mathbf{G}_i} \left\{ \sum_j F(\mathbf{r}_i - \mathbf{r}_j) G(\mathbf{r}_j) \right\} = F(\mathbf{G}_i) G(\mathbf{G}_j)$$

Fourier Transform

- If one has a quantity defined in a grid in real space its FT is:

$$F(\mathbf{G}) = \sum_i F(\mathbf{r}_i) e^{-i\mathbf{G} \cdot \mathbf{r}_i}$$

- The inverse transform is:

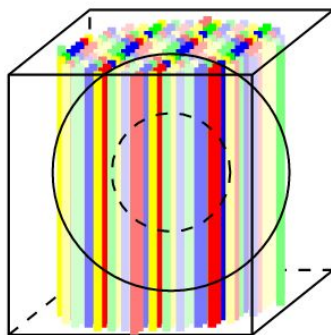
$$F(\mathbf{r}_i) = \frac{1}{N_1 N_2 N_3} \sum_j F(\mathbf{G}_j) e^{-i\mathbf{r}_i \cdot \mathbf{G}_j}$$

- Convolution

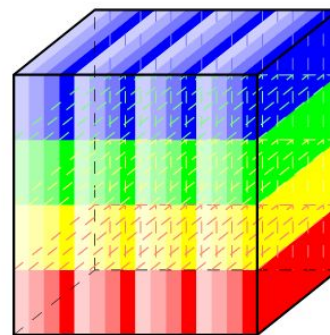
$$\mathcal{F}_{\mathbf{G}_i} \left\{ \sum_j F(\mathbf{r}_i - \mathbf{r}_j) G(\mathbf{r}_j) \right\} = F(\mathbf{G}_i) G(\mathbf{G}_i) \text{ and vice versa}$$

Data distribution

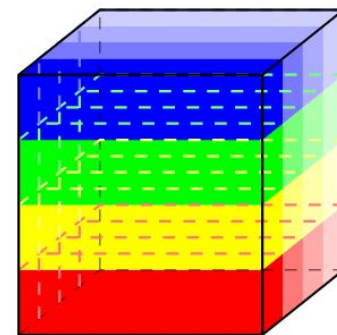
- Data in G space are distributed as sticks in the z directions
- Data in R space are distributed as z plane slices in the y direction
- At any moment a whole 1 dimensional FFT may be done in each process.



$$\begin{matrix} F(G_x, G_y, G_z) \\ F(G_x, G_y, R_z) \end{matrix}$$



$$\begin{matrix} F(G_x, G_y, G_z) \\ F(G_x, R_y, R_z) \end{matrix}$$



$$\begin{matrix} F(G_x, G_y, G_z) \\ F(R_x, R_y, R_z) \end{matrix}$$

K point parallelism

- Each k point has its own block of Hamiltonian restricted to the space spanned by the $|k+G\rangle$ vectors. Each block may be diagonalized autonomously
- It is possible to parallelize the diagonalization so that a pool of processors diagonalizes a set of k -points
- the k point parallelism is selected using the option $-nk = \langle \text{number of pools} \rangle$
- How to choose an optimal value for nk ?
 - Each pool needs to have a sufficient number of processors to perform the FFTs efficiently
 - k parallelism increases the required memory
 - k parallelism is linear so the more pools the faster
 - obviously you can't use more pools than the number of k -points

SCF loop: initialization

- Generates the \mathbf{G} vectors and sets up the k-point mesh
- Read the pseudopotentials and initializes $V_{\text{loc}}(\mathbf{r})$ and V_{nonloc} in G space (V_{nonloc} is made by separable Kleinmann-Bylander projectors)
- Generates (or read from file) initial wave functions and charge density

SCF loop: iterative diagonalization

- The KS Hamiltonian in plane waves basis is too large to be memorized and diagonalized directly.
- It is just an operator made by:
 - Kinetic energy (in G space)
 - V_{loc} in R space
 - V_{nonloc} in G space (sometimes in real space)
- To compute the eigenfunctions and the eigenvalues we keep in memory only the trial wave functions and their image through H

$$\{ |\psi_i\rangle, \hat{H}\psi_i \}$$

SCF: loop diagonalization

- Davidson diagonalization
- We have an initial base of trial wfc and compute the matrix of H in this space

$$H_{ij}^{dav} = \langle \psi_i | H | \psi_j \rangle$$

- We diagonalize it and compute the residuals:

$$H^{dav} |\phi_i^{dav}\rangle = \epsilon_i^{dav} |\phi_i^{dav}\rangle \quad |\Delta_i\rangle = (H - \epsilon_i^{dav}) |\phi_i^{dav}\rangle$$

- We now expand our trial basis adding the residuals

SCF loop: davidson diagonalization

- Compute the new ϵ_i^{dav} , ϕ_i^{dav} and Δ_i
- reiterate the procedure until $|\Delta_i|^2 < threshold$ for all the eigenfunctions
- the final values of ϵ_i^{dav} and ϕ_i^{dav} are our calculated eigenvalues and eigenfunctions
- This procedure involves the diagonalization of a matrix which can become very large. For systems with many bands one need to use parallel linear algebra routines
- the parallelism for diagonalization is controlled in pw with the flag `-nd` or `-ndiag`, as it uses scalapack ndiag must be set to some perfect square integer lower than the number of processors.

SCF loop: sum

- Now we compute the new charge density and augmentation charges (if you using USPP or PAW)

$$n_v(\mathbf{r}) = \sum_{n,\mathbf{k}} \phi_{n,\mathbf{k}}^* \phi_{n,\mathbf{k}} + \sum_{ij} \rho_{ij} Q_{ij}(\mathbf{r}) \quad \rho_{ij} = \sum_{n,\mathbf{k}} \langle \phi_{n,\mathbf{k}} | \beta_i \rangle \langle \beta_j | \phi_{n,\mathbf{k}} \rangle$$

- This is done with a sum on the k points, if symmetry is used each k points contributes also for its symmetry equivalent points, these quantities must also be symmetrized.

SCF loop: mixing

- The new charge is mixed with the old one:
 - Broyden method is based on Quasi Newton optimization, it can be less or more aggressive it is regulate by the Beta mixing_beta parameter
 - Thomas Fermi uses the dielectric permittivity to compute the new charge density

References

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