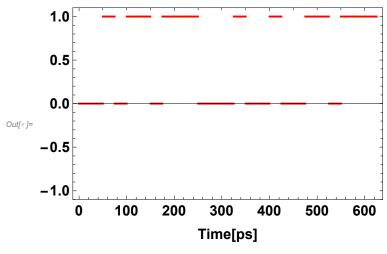
```
In[*]:= Clear["Global`*"]
    クリア
ln[-]:= L = 100; (*km*)
     bit = 25;
     \lambda = 1.55 * 10^{-6}; (*m*)
     d = 16; (*ps/km*nm*)
     c = 3 * 10^8;
     \beta 2 = \frac{d}{2 * Pi * c} \lambda^2 * 10^{-3};
     nm = 3.96; (*電気信号の実効屈折率*)
     ng = 2.19; (*光波の群屈折率*)
     c = 3 * 10^8;
     y = 38.25 * 10^{-3}; (*mm*)
    total = t[y];
     initial = 1000;
     pitch = 50 * 10^{-6}; (*um*)
     pitchmm = pitch * 10^3;
     \Delta t = pitch * (nm + ng) / (3 * 10^8);
     sumw = (total + \Delta t * initial) / \Delta t ;
     polnumber = 1 + IntegerPart[sumw] - initial;
                     整数部分
     electrodelength = N[pitch * polnumber];
                         数值
     electrodelengthmm = electrodelength * 10<sup>3</sup>;
     Print [\beta 2, "ps^2/km"]
    出力表示
     Print[total * 10<sup>12</sup>, "ps"]
    出力表示
     Print \Delta t * 10^{12}, "ps"
    出力表示
     Print[sumw, "point"]
     Print["Rev pattern is", polnumber, "point"]
     Print["electrodelength is", electrodelength * 103, "mm"]
    出力表示
     Print[electrodelengthmm, "mm"]
    出力表示
     2.03931 \times 10^{-23} \text{ps}^2/\text{km}
     784.125ps
     1.025ps
     1765.point
     Rev pattern is765point
     electrodelength is38.25mm
     38.25mm
```

```
In[*]:= (*For[i=1;j=0,i≤bit,i++,
       繰返し評価
         For [m=j; random=RandomChoice[{0,1}],j≤m+1,j=j+1,digital[j]=random]]
                         ランダムな選択
     rm=Table[digital[t], {t,1,bit}]*)
        リストを作成
     bit = 25;
     digital[1] = 0;
     digital[2] = 1;
     digital[3] = 0;
     digital[4] = 1;
     digital[5] = 1;
     digital[6] = 0;
     digital[7] = 1;
     digital[8] = 1;
     digital[9] = 1;
     digital[10] = 0;
     digital[11] = 0;
     digital[12] = 0;
     digital[13] = 1;
     digital[14] = 0;
     digital[15] = 0;
     digital[16] = 1;
     digital[17] = 0;
     digital[18] = 0;
     digital[19] = 1;
     digital[20] = 1;
     digital[21] = 0;
     digital[22] = 1;
     digital[23] = 1;
     digital[24] = 1;
     digital[25] = 1;
     rm = Table[digital[t], {t, 1, bit}]
         リストを作成
     step1[t_, i_] :=
      If[digital[i] == 1, If[i * 25 < t < (i + 1) * 25, 1, 0], If[i * 25 < t < (i + 1) * 25, 0, 0]]
     signal[t_] := signal[t] = \sum_{i=1}^{bit} step1[t, i]
     Plot[signal[t], {t, 0, bit * 25}, PlotStyle → {Red, Thick}, Frame → True,
                                        プロットスタイル 虚赤
                                                         太い
                                                                  FrameLabel \rightarrow {"Time[ps]"}, BaseStyle \rightarrow {Bold, FontSize \rightarrow 15}, PlotRange \rightarrow {-1.1, 1.1}]
      枠ラベル
                                   ベーススタイル
                                               太字 フォントサイズ
                                                                       プロット範囲
      rbit∗25
            signal[t1] * e^{-i*2*Pi*f*t1} dt1
Out[r] = \{0, 1, 0, 1, 1, 0, 1, 1, 1, 0, 0, 0, 1, 0, 0, 1, 0, 0, 1, 1, 0, 1, 1, 1, 1\}
```



$$\begin{aligned} & \textit{Out}[*] = & -\frac{1}{2\,f\,\pi}\,\,\dot{\mathbb{I}}\,\,\,\mathbb{e}^{-1250\,\,\dot{\mathbb{I}}\,f\,\pi}\,\,\Big(-1\,+\,\mathbb{e}^{150\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{200\,\,\dot{\mathbb{I}}\,f\,\pi}\,+\,\mathbb{e}^{300\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{400\,\,\dot{\mathbb{I}}\,f\,\pi}\,+\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,+\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}}\,f\,\pi}\,-\,\mathbb{e}^{450\,\,\dot{\mathbb{I}$$

Plot[carrier[t], {t, 0, 600}]

プロット

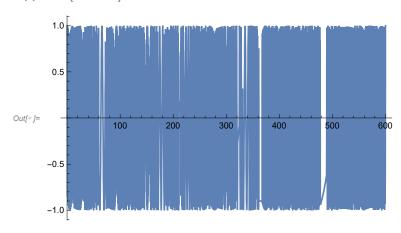
 $\label{eq:power} Plot[Evaluate[cs[t]], \{t, 0, bit * 25\}, Frame \rightarrow True, FrameLabel \rightarrow \{"Time[ps]", "Power"\}, \\$ 枠 真枠ラベル

 $\texttt{BaseStyle} \rightarrow \{\texttt{Bold}, \, \texttt{FontSize} \rightarrow \texttt{15}\}, \, \texttt{PlotRange} \rightarrow \{\texttt{-1.1}, \, \texttt{1.1}\}\,]$ 太字 フォントサイズ

ComplexExpand
$$\left[\int_{0}^{\text{bit}*25} cs[t1] * e^{-i*2*Pi*f*t1} dt1 \right]$$

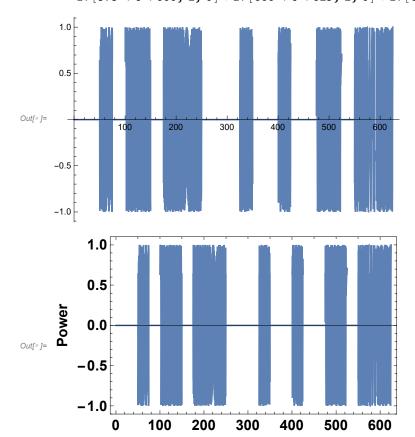
Out[*]= $\cos [400 \pi t]$

式の展開



```
Out[*]= Cos [400 π t]
```

```
 \begin{array}{l} (If[25 < t < 50, 0, 0] + If[50 < t < 75, 1, 0] + If[75 < t < 100, 0, 0] + If[100 < t < 125, 1, 0] + If[125 < t < 150, 1, 0] + If[150 < t < 175, 0, 0] + If[175 < t < 200, 1, 0] + \\ If[200 < t < 225, 1, 0] + If[225 < t < 250, 1, 0] + If[250 < t < 275, 0, 0] + \\ If[275 < t < 300, 0, 0] + If[300 < t < 325, 0, 0] + If[325 < t < 350, 1, 0] + \\ If[350 < t < 375, 0, 0] + If[375 < t < 400, 0, 0] + If[400 < t < 425, 1, 0] + \\ If[425 < t < 450, 0, 0] + If[450 < t < 475, 0, 0] + If[475 < t < 500, 1, 0] + \\ If[500 < t < 525, 1, 0] + If[525 < t < 550, 0, 0] + If[550 < t < 575, 1, 0] + \\ If[575 < t < 600, 1, 0] + If[600 < t < 625, 1, 0] + If[625 < t < 650, 1, 0]) \end{array}
```



$$\textit{Out[s]} = \text{ in Im} \left[\int_0^{625} \mathrm{e}^{-2 \, \text{if} \, \pi \, \text{t1}} \, \text{cs[t1]} \, \, \mathrm{d}\text{t1} \right] + \text{Re} \left[\int_0^{625} \mathrm{e}^{-2 \, \text{if} \, \pi \, \text{t1}} \, \text{cs[t1]} \, \, \mathrm{d}\text{t1} \right]$$

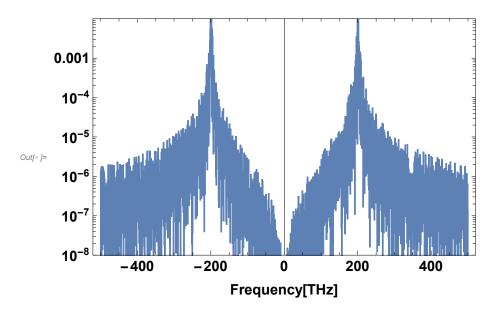
Time[ps]

If $[600 < t < 625, 1, 0] + If [625 < t < 650, 1, 0]), \{t, 0, 625\}$

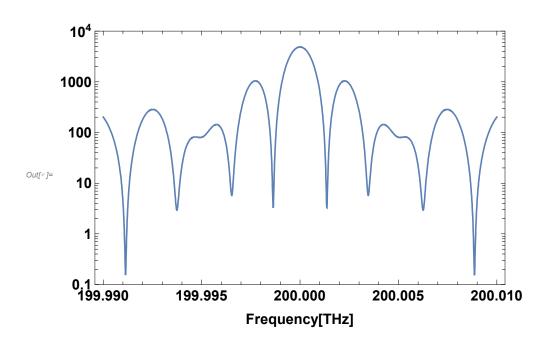
```
In[*]:= Cs[f] = ComplexExpand[FourierTransform[cs[t], t, 2 * Pi * f]]
            |式の展開 | フーリエ変換
                                                           円周率
     (*Cs[\omega]:=
            \omega (i Cos[50 \omega] -i Cos[75 \omega] +i Cos[100 \omega] -i Cos[150 \omega] +i Cos[175 \omega] -
      余弦
         i Cos[250 \omega]+i Cos[325 \omega]-i Cos[350 \omega]+i Cos[400 \omega]-i Cos[425 \omega]+
                                       余弦
                          上余弦
                                                      _余弦
         i Cos[475 ω] -i Cos[525 ω] +i Cos[550 ω] -i Cos[650 ω] -Sin[50 ω] +Sin[75 ω] -
          Sin[100 \ \omega] + Sin[150 \ \omega] - Sin[175 \ \omega] + Sin[250 \ \omega] - Sin[325 \ \omega] + Sin[350 \ \omega] -
         L正弦 L正弦 L正弦 L正弦 L正弦 L正弦
         Sin[400 \ \omega] + Sin[425 \ \omega] - Sin[475 \ \omega] + Sin[525 \ \omega] - Sin[550 \ \omega] + Sin[650 \ \omega]) *)
                   _正弦    _正弦    _正弦
     (*Plot[Re[FourierTransform[cs[t],t,\omega]],\{\omega,-100,100\}]*)
      【プロ… 【… 【フーリエ変換
     (*Plot \left[\text{Evaluate}\left[\left[\text{Re}\int_{0}^{\text{bit*25}} \cos\left[\text{t1}\right] \star e^{-i\star2\star\text{Pi*f*t1}} d\text{t1}\right]\right]\right], {f,-100,100} \] *)
```

$$\begin{array}{c} c_{out^{*-j-1}} \stackrel{!}{i} \left(\frac{f \cos \left[100 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2 \right) \, \pi^{3/2}} - \frac{f \cos \left[150 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2 \right) \, \pi^{3/2}} + \frac{f \cos \left[200 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2 \right) \, \pi^{3/2}} + \frac{f \cos \left[350 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2 \right) \, \pi^{3/2}} + \frac{f \cos \left[350 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2 \right) \, \pi^{3/2}} + \frac{f \cos \left[350 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2 \right) \, \pi^{3/2}} + \frac{f \cos \left[550 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2 \right) \, \pi^{3/2}} + \frac{f \cos \left[550 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2 \right) \, \pi^{3/2}} + \frac{f \cos \left[550 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2 \right) \, \pi^{3/2}} + \frac{f \cos \left[550 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2 \right) \, \pi^{3/2}} + \frac{f \cos \left[550 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2 \right) \, \pi^{3/2}} + \frac{f \cos \left[1300 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2 \right) \, \pi^{3/2}} + \frac{f \cos \left[1300 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2 \right) \, \pi^{3/2}} - \frac{f \cos \left[1300 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2 \right) \, \pi^{3/2}} + \frac{f \sin \left[150 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2 \right) \, \pi^{3/2}} - \frac{f \sin \left[200 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2 \right) \, \pi^{3/2}} + \frac{f \sin \left[500 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2 \right) \, \pi^{3/2}} - \frac{f \sin \left[500 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2 \right) \, \pi^{3/2}} + \frac{f \sin \left[500 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2 \right) \, \pi^{3/2}} - \frac{f \sin \left[500 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2 \right) \, \pi^{3/2}} + \frac{f \sin \left[500 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2 \right) \, \pi^{3/2}} + \frac{f \sin \left[500 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2 \right) \, \pi^{3/2}} - \frac{f \sin \left[500 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2 \right) \, \pi^{3/2}} + \frac{f \sin \left[500 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2 \right) \, \pi^{3/2}} - \frac{f \sin \left[500 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2 \right) \, \pi^{3/2}} + \frac{f \sin \left[500 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2 \right) \, \pi^{3/2}} - \frac{f \sin \left[500 \, f \, \pi \right]}{2 \, \sqrt{2} \, \left(-40 \, 000 \, + \, f^2$$

```
log_{s} = LogPlot[(Re[Cs[f]]^2 + Im[Cs[f]]^2), \{f, -0.5 * 10^3, 0.5 * 10^3\},
       Frame \rightarrow True, FrameLabel \rightarrow {"Frequency[THz]"},
                       枠ラベル
       BaseStyle \rightarrow {Bold, FontSize \rightarrow 15}, PlotRange \rightarrow {10^-8, 10<sup>-2</sup>}]
       【ベーススタイル 【太字 【フォントサイズ
                                                 プロット範囲
```



$$Im[e]$$
 = LogPlot[(Re[Cs[f]]² + Im[Cs[f]]²), {f, 1.9999 * 10^2, 2.0001 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])² + Im[Cs[f]]), {f, 1.9999 * 10^2, 2.0001 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])² + Im[Cs[f]]), {f, 1.9999 * 10^2, 2.0001 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])² + Im[Cs[f]]), {f, 1.9999 * 10^2, 2.0001 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])² + Im[Cs[f]]), {f, 1.9999 * 10^2, 2.0001 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])² + Im[Cs[f]]), {f, 1.9999 * 10^2, 2.0001 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])² + Im[Cs[f]]), {f, 1.9999 * 10^2, 2.0001 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])² + Im[Cs[f]]), {f, 1.9999 * 10^2, 2.0001 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])² + Im[Cs[f]]), {f, 1.9999 * 10^2, 2.0001 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])² + Im[Cs[f]]), {f, 1.9999 * 10^2, 2.0001 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])), {f, 1.9999 * 10^2, 2.0001 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])), {f, 1.9999 * 10^2, 2.0001 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])), {f, 1.9999 * 10^2, 2.0001 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])), {f, 1.9999 * 10^2, 2.0001 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])), {f, 1.9999 * 10^2, 2.0001 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])), {f, 1.9999 * 10^2, 2.0001 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])), {f, 1.9999 * 10^2, 2.0001 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])), {f, 1.9999 * 10^2, 2.0001 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])), {f, 1.9999 * 10^2, 2.0001 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])), {f, 1.9999 * 10^2, 2.0001 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])), {f, 1.9999 * 10^2, 2.0001 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])), {f, 1.9999 * 10^2, 2.0001 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])), {f, 1.9999 * 10^2, 2.0001 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])), {f, 1.9999 * 10^2, 2.0001 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])), {f, 1.9999 * 10^2, 2.0001 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])), {f, 1.9999 * 10^2, 2.0001 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])), {f, 1.9999 * 10^2},
 $Im[e]$ = LogPlot[(Re[Cs[f]])), {f, 1.9999



```
ln[*] := H_dis[f] := Exp[-1/2*I(f-Fc)^2*(2*pi)^2*\beta2*L]
                                虚数単位
                     指数関数
      (*FourierTransform \left[ \text{Exp} \left[ -1/2 * \text{I} \left( \omega - 2 * \text{Pi*Fc} \right) ^2 * \beta 2 * \text{L} \right] * \frac{1}{\sqrt{2 \pi} \left( -160000 \ \pi^2 + \omega^2 \right)} \omega \right] 上虚… 上円周率
         (i Cos [50 ω] - i Cos [75 ω] + i Cos [100 ω] - i Cos [150 ω] + i Cos [175 ω] - i Cos [250 ω] +
            i \cos[325 \ \omega] -i \cos[350 \ \omega] +i \cos[400 \ \omega] -i \cos[425 \ \omega] +i \cos[475 \ \omega] -i \cos[525 \ \omega] +
             i Cos[550 \omega] -i Cos[650 \omega] -Sin[50 \omega] +Sin[75 \omega] -Sin[100 \omega] +Sin[150 \omega] -

    ★
    ★

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★
    上

    ★<
            Sin[175 \ \omega] + Sin[250 \ \omega] - Sin[325 \ \omega] + Sin[350 \ \omega] - Sin[400 \ \omega] + Sin[425 \ \omega] - Sin[475 \ \omega] +
           L正弦    L正弦    L正弦    L正弦    L正弦
            Sin[525 \ \omega] - Sin[550 \ \omega] + Sin[650 \ \omega]), \omega, t, FourierParameters \rightarrow \{1, -1\} \ \star)
                                                               フーリエパラメータ
           L正弦 L正弦 L正弦
      (*Cs_dis[t]=ComplexExpand[FourierTransform[H_dis[f]*Cs[f],
                                  フーリエ変換
          f,t,FourierParameters→{1,-1}]]*)
               フーリエパラメータ
ln[*]:= (*FourierTransform \left[e^{(0.\tilde{\ }-1.0196526687420762\tilde{\ }*^{-21}i)} \left(-400\pi+\omega\right)^{2}*\frac{1}{\sqrt{2\pi}\left(-160000\pi^{2}+\omega^{2}\right)}\right]
         (π Cos [50 ω] - π Cos [75 ω] + π Cos [100 ω] - π Cos [150 ω] + π Cos [175 ω] - π Cos [250 ω] +
            i Cos[325 ω]-i Cos[350 ω]+i Cos[400 ω]-i Cos[425 ω]+i Cos[475 ω]-
             i Cos[525 \omega] +i Cos[550 \omega] -i Cos[650 \omega] -Sin[50 \omega] +Sin[75 \omega] -Sin[100 \omega] +
            Sin[150 \ \omega] - Sin[175 \ \omega] + Sin[250 \ \omega] - Sin[325 \ \omega] + Sin[350 \ \omega] - Sin[400 \ \omega] + Sin[425 \ \omega] -
           Sin[475 \ \omega] + Sin[525 \ \omega] - Sin[550 \ \omega] + Sin[650 \ \omega]), \omega, t, FourierParameters \rightarrow \{1, -1\} \mid *)
                                  |正弦 | 正弦
                                                                               フーリエパラメータ
In[@]:= (*Plot FourierTransform
        プロ・・・・フーリエ変換
         e^{(0.\text{`}-1.0196526687420762`*^-21 i)} (-400 \pi+\omega)² * \frac{1}{\sqrt{2~\pi}~\left(-160000~\pi^2+\omega^2\right)}\omega (i Cos[50 \omega] -i Cos[75 \omega] + 上余弦
             i Cos[100 ω] -i Cos[150 ω] +i Cos[175 ω] -i Cos[250 ω] +i Cos[325 ω] -i Cos[350 ω] +
                i Cos[400 ω] - i Cos[425 ω] + i Cos[475 ω] - i Cos[525 ω] + i Cos[550 ω] - i Cos[650 ω] -
               Sin[50 \ \omega] + Sin[75 \ \omega] - Sin[100 \ \omega] + Sin[150 \ \omega] - Sin[175 \ \omega] + Sin[250 \ \omega] - Sin[325 \ \omega] +
             L正弦    L正弦    L正弦    L正弦    L正弦
             Sin[350 \omega] - Sin[400 \omega] + Sin[425 \omega] - Sin[475 \omega] + Sin[525 \omega] - Sin[550 \omega] + Sin[650 \omega])
             上正弦 上正弦 上正弦
                                                                          正弦
                                                                                   上正弦 上正弦
         \omega,t,FourierParameters\rightarrow{1,-1}],{t,-100,100}]*)
              フーリエパラメータ
```

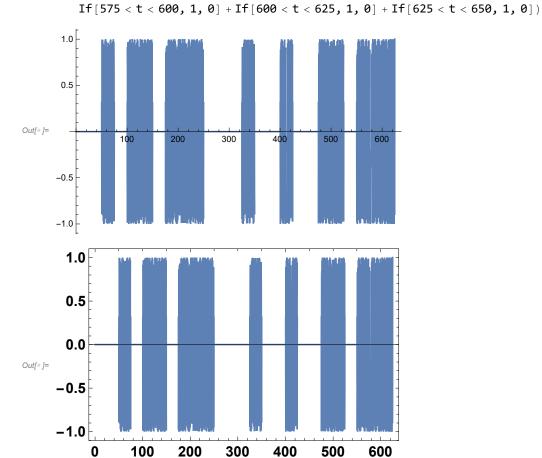
```
ln[*]:= Plot[{1/2 (Cos[x] + 1), (Cos[-x] + 1)/2}, {x, 0, 50 Pi}]
                                               プロット
                                                                                                                                                                     余弦
                                                                                                                                                                                                                                                                                                        余弦
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          円周座
                                                  1.0
                                                8.0
                                                0.6
Out[@]=
                                                  0.4
                                                  02
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       150
    | In[*]:= FC = 1;(*搬送波の周波数[THz]*)
                                                  Plot[carrier[t], {t, 0, 600}]
                                               プロット
                                                  csPM[t_] = Cos[signal[t]] Cos[2*Pi*Fc*t] - Sin[signal[t]] Sin[2*Pi*Fc*t]
                                                                                                                                                                                                                                                                                                                     余弦
                                                                                                                                                                                                                                                                                                                                                                                           円周率
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 正弦
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          正弦
                                                         1.0
                                                        0.5
Out[*]=
                                                                                                                                                     100
                                                                                                                                                                                                                                   200
                                                                                                                                                                                                                                                                                                                                                                                              400
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          600
                                                                                                                                                                                                                                                                                                                 300
                                                                                                                                                                                                                                                                                                                                                                                                                                                                               500
                                                   -0.5
                                                   -1.0
Out[\circ]= Cos[2\pi t]
                                                                      Cos\left[If[25 < t < 50,\ 0,\ 0]\right. \\ \left. + If[50 < t < 75,\ 1,\ 0]\right. \\ \left. + If[75 < t < 100,\ 0,\ 0]\right. \\ \left. + If[100 < t < 125,\ 0,\ 0,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0,\ 0,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0,\ 0,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0,\ 0,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0,\ 0,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0,\ 0,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0,\ 0,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0,\ 0,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0,\ 0,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] \\ \left. + If[100 < t < 125,\ 0]\right] 
                                                                                                        1, 0] + If [125 < t < 150, 1, 0] + If [150 < t < 175, 0, 0] + If [175 < t < 200, 1, 0] +
                                                                                              If [200 < t < 225, 1, 0] + [225 < t < 250, 1, 0] + [250 < t < 275, 0, 0] +
                                                                                              If[275 < t < 300, 0, 0] + If[300 < t < 325, 0, 0] + If[325 < t < 350, 1, 0] +
                                                                                              If[350 < t < 375, 0, 0] + If[375 < t < 400, 0, 0] + If[400 < t < 425, 1, 0] +
                                                                                              If [425 < t < 450, 0, 0] + [450 < t < 475, 0, 0] + [475 < t < 500, 1, 0] + [
                                                                                              If [500 < t < 525, 1, 0] + If [525 < t < 550, 0, 0] + If [550 < t < 575, 1, 0] +
                                                                                              If[575 < t < 600, 1, 0] + If[600 < t < 625, 1, 0] + If[625 < t < 650, 1, 0]] -
                                                            Sin[2\pi t] Sin[If[25 < t < 50, 0, 0] + If[50 < t < 75, 1, 0] + If[75 < t < 100, 0, 0] + If[75 <
                                                                                              If [100 < t < 125, 1, 0] + If [125 < t < 150, 1, 0] +
                                                                                              If [\,150 < t < 175,\, 0,\, 0\,] \,+\, If [\,175 < t < 200,\, 1,\, 0\,] \,+\,
                                                                                              If[200 < t < 225, 1, 0] + If[225 < t < 250, 1, 0] + If[250 < t < 275, 0, 0] +
                                                                                              If[275 < t < 300, \, 0, \, 0] \, + \, If[300 < t < 325, \, 0, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 325, \, 0, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[300 < t < 350, \, 1, \, 0] \, + \, If[3
                                                                                              If[350 < t < 375, \, 0, \, 0] \, + If[375 < t < 400, \, 0, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400 < t < 425, \, 1, \, 0] \, + \, If[400
                                                                                              If [\,425 < t < 450,\, 0,\, 0\,] \,+\, If [\,450 < t < 475,\, 0,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+\, If [\,475 < t < 500,\, 1,\, 0\,] \,+
                                                                                              If [500 < t < 525, 1, 0] + If [525 < t < 550, 0, 0] + If [550 < t < 575, 1, 0] +
                                                                                              If[575 < t < 600, 1, 0] + If[600 < t < 625, 1, 0] + If[625 < t < 650, 1, 0]]
```

log[-]:= Plot[Evaluate[csPM[x]], {x, 45, 55}, Frame \rightarrow True, FrameLabel \rightarrow {"Time[ps]"}, プロット上評価 枠 真 枠ラベル $\texttt{BaseStyle} \rightarrow \{\texttt{Bold, FontSize} \rightarrow \texttt{15}\}, \, \texttt{PlotRange} \rightarrow \{\texttt{-1.1, 1.1}\}]$ 太字 フォントサイズ プロット範囲 1.0 0.5 0.0 Out[*]= -0.5-1.0 46 48 **50** 52 54 Time[ps] $lo[\cdot]:=$ Plot[Evaluate[csPM[x]], {x, 0, 625}, Frame \rightarrow True, FrameLabel \rightarrow {"Time[ps]"}, プロット上評価 真 BaseStyle \rightarrow {Bold, FontSize \rightarrow 15}, PlotRange \rightarrow {-1.1, 1.1}] 太字 フォントサイズ プロット範囲 1.0 0.5 0.0 Out[=]= -0.5-1.0 0 100 200 300 400 **500** 600 Time[ps]

```
ln[\circ]:= Plot[Sinc[x], {x, 0, 10}, PlotStyle \rightarrow Thick,
                                    プロットスタイル 太い
     しプロット しシンク
       ColorFunction \rightarrow Function[{x, y}, ColorData["NeonColors"][y]]]
      色関数
                                              色データ
      1.0
      0.8
      0.6
Out[ ]= 0.4
      0.2
      -0.2
      Plot3D[x+y, \{x, 0, 2\}, \{y, 0, 2\}, ColorFunction \rightarrow Function[\{x, y, z\}, Hue[z]]]
     3Dプロット
                                             色関数
||n[@]:= FC = 1;(*搬送波の周波数[THz]*)
      carrier[t] = Cos[2*Pi*Fc*t]
                     余弦
                            Plot[carrier[t], {t, 0, 600}]
     プロット
     cs[t] = signal[t] * carrier[t]
     Plot[Evaluate[cs[t]], {t, 0, bit * 25}]
     プロ… 評価
     Plot[Evaluate[cs[t]], \{t, 0, bit * 25\}, Frame \rightarrow True, FrameLabel \rightarrow {"Time[ps]"},
                                                             上真 上枠ラベル
     プロ… 上評価
                                                    枠
       BaseStyle \rightarrow {Bold, FontSize \rightarrow 15}, PlotRange \rightarrow {-1.1, 1.1}]
      ベーススタイル
                     太字 フォントサイズ
                                              プロット範囲
     ComplexExpand \left[ \int_{-\infty}^{\text{bit}*25} cs \, [t1] \, * \, e^{-i*2*Pi*f*t1} \, dt1 \right]
     式の展開
Out[\circ]= Cos[2\pi t]
      1.0
      0.5
Out[*]=
                  100
                           200
                                    300
                                              400
                                                       500
      -0.5
      -1.0
```

```
Out[\circ]= Cos[2\pi t]
```

(If[25 < t < 50, 0, 0] + If[50 < t < 75, 1, 0] + If[75 < t < 100, 0, 0] + If[100 < t < 125, 1, 0] $0] \; + \; If[125 < t < 150,\; 1,\; 0] \; + \; If[150 < t < 175,\; 0,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\; 1,\; 0] \; + \; If[175 < t < 200,\;$ $If[\,200 < t < 225,\, 1,\, 0\,] \,+\, If[\,225 < t < 250,\, 1,\, 0\,] \,+\, If[\,250 < t < 275,\, 0,\, 0\,]$ $If[275 < t < 300, \, 0, \, 0] \, + \, If[300 < t < 325, \, 0, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[325 < t < 350, \, 1, \, 0] \, + \, If[3$ If[350 < t < 375, 0, 0] + If[375 < t < 400, 0, 0] + If[400 < t < 425, 1, 0] +If[425 < t < 450, 0, 0] + If[450 < t < 475, 0, 0] + If[475 < t < 500, 1, 0] + $If[500 < t < 525, \, 1, \, 0] \, + \, If[525 < t < 550, \, 0, \, 0] \, + \, If[550 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[500 < t < 575, \, 1, \, 0] \, + \, If[5$



$$\textit{Out[$^\sigma$]$= $\dot{\text{I}}$ Im} \left[\int_0^{625} \mathrm{e}^{-2\,\dot{\text{I}}\,f\,\pi\,t\,1} \,c\,s\,[\,t\,1\,] \,\,\mathrm{d}t\,1 \right] \,+\, Re \left[\int_0^{625} \mathrm{e}^{-2\,\dot{\text{I}}\,f\,\pi\,t\,1} \,c\,s\,[\,t\,1\,] \,\,\mathrm{d}t\,1 \right]$$

Time[ps]