

Multi-agent Cooperative Patrolling of Designated Points on Graphs

Akitoshi Kawamura Hideaki Noshiro

June 30, 2017

In *patrolling* problems, one or more mobile agents move around in a given region and try to cooperate so that every point in the region is visited sufficiently often.

References

- [1] K. Chen, A. Dumitrescu, and A. Ghosh. On fence patrolling by mobile agents. In *Proc. 25th Canadian Conference on Computational Geometry (CCCG)*, 2013.
- [2] S. Coene, F. C. R. Spieksma, and G. J. Woeginger. Charlemagne’s challenge: the periodic latency problem. *Operations research*, 59(3), pp. 674–683, 2011.
- [3] J. Czyzowicz, L. Gąsieniec, A. Kosowski, and E. Kranakis. Boundary patrolling by mobile agents with distinct maximal speeds. In *Proc. 19th Annual European Symposium on Algorithms (ESA)*, LNCS 6942, pp. 701–712, 2011.
- [4] A. Kawamura and M. Soejima. Simple strategies versus optimal schedules in multi-agent patrolling. In *Proc. Ninth International Conference on Algorithms and Complexity (CIAC)*, LNCS 9079, pp. 261–273, 2015.