Algorithm $Extend(x_{near}, x_{rand}, S)$

- (* Finds a point close to x_{rand} that is in ϵ -neighbourhood of x_{near} *)respecting the kinodynamic constraints
- 1. $x_{new} \leftarrow arg \max_{a \in A} ||x x_{rand}||_J x_{new} x_{near}||$ is within kinematic bounds and action a_{max} which generated x_{new} is within the acceleration bounds
- 2. $(r, x_{new}) \leftarrow MDP(x_{near}, a)$
- 3. return $(x_n ew, a, r)$
- End of Algorithm