

Digital Signal Processing SS 2024 – Exercise 2

Digital Signal Processing Tutorial

Group 23

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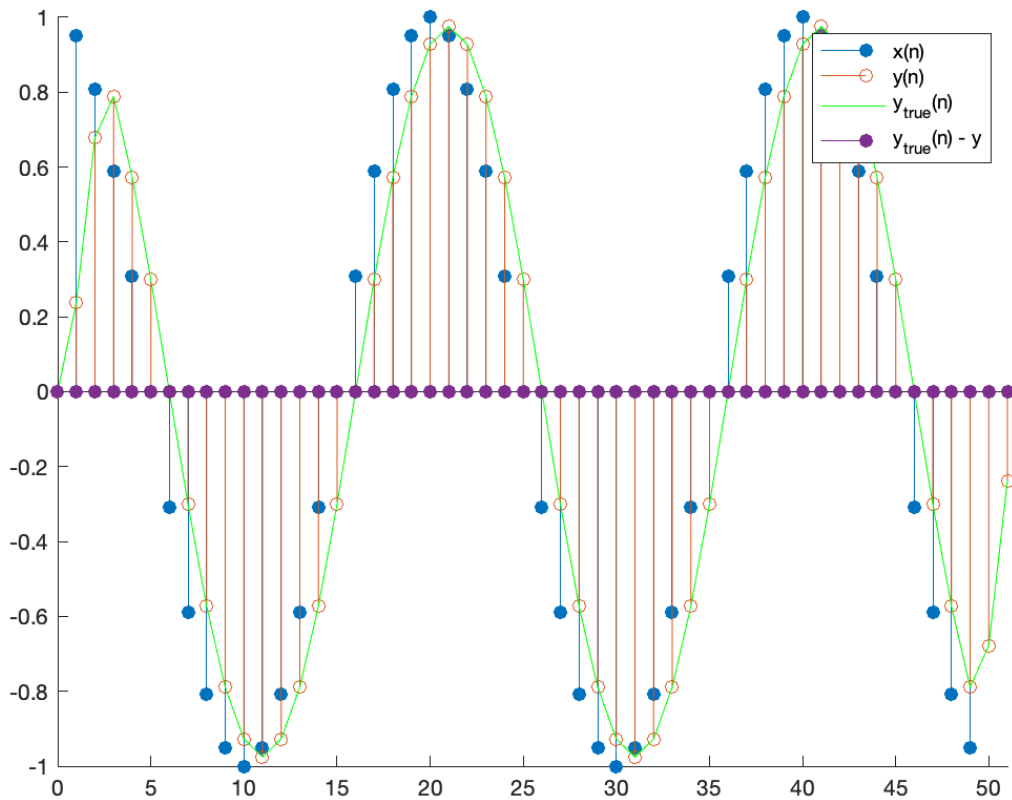
Exercise 1

Exercise 2

Exercise 3

We have the impulse response of an LTI system $h[n] = (0.25, 0.5, 0.25)$ at sample indices $n = (0, 1, 2)$. The input signal is $x[n] = \cos\left(\frac{2\pi}{20}n\right)$ for $0 \leq n < 50$.

- From the lecture: If $x[n]$ and $h[n]$ have finite lengths N_x and N_h , the length of the output signal results to $N_y = N_x + N_h - 1$. In our example we have $N_x = 50$ and $N_h = 3$, therefore we can calculate the length of the output signal L_y (N_y in the lecture) as $\underline{L_y = 52}$.
- For the actual implementation, see code `Ex03.m`. Here it was important to explicitly define $x[n]$ to be 0 outside the given range.



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- As we can see in the plot, the "true" y and our calculated y match up.

Exercise 4

a) See Ex04.m for the full code, here I show only the function `dtft`:

```
function X = dtft(x, n, w)
    % DTFT Computes Discrete-time Fourier transform
    % @param    x: finite duration sequence over n
    % @param    n: sample position vector
    % @param    w: frequency location vector
    % @return    X: DTFT values computed at w frequencies

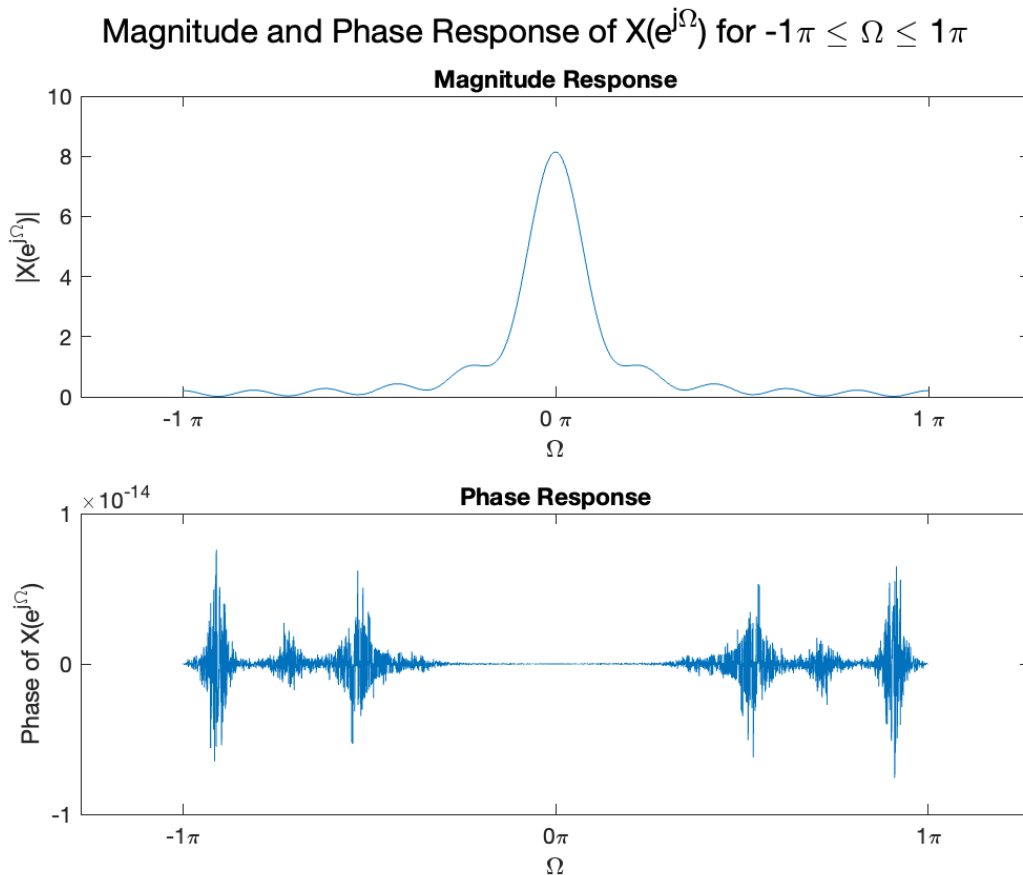
    X = x * exp(-1j .* n' * w);

end
```

We call the function via `X = dtft(@x, n, w)`, where

- $x(n) = ((0.8).^{\text{abs}(n)}) .* (u(n+10) - u(n-11))$ with $u(n) = 1.*(n \geq 0)$
- $n = -10:10$
- $w = \text{linspace}(\Omega * -\pi, \Omega * \pi, 1000)$ for $\Omega = 1$

b) What I can observe on the y-axis of the phase response plot is that the phase response for the settings described above is very small, in fact less than 10^{-14} .



c) If we change Ω from $\Omega = 1$ to $\Omega = 5$, we can see that the magnitude response has peaks and troughs at multiples of π . We can also see that the phase response seems to be mirrored and flipped around the y-axis (graphic on next page).

Magnitude and Phase Response of $X(e^{j\Omega})$ for $-5\pi \leq \Omega \leq 5\pi$

