

thonny.org

Useful for dev on Pico MicroPython

Hackaday Europe 2024:
Digikey Presents

ROBOT CARNAGE



Basics

Paul - Workshop cat-herder and can google that for you.

James - Raspberry Jam Berlin meetup and general hardware enabler.

Schedule: <https://hackaday.io/europe2024#schedule>

10:30AM- 12.30PM: Learning about Pico-W, servos and sensors. Early testing.

DURING THE DAY: Tinker at leisure on your creation, or don't.

17:00-18:30PM: Back here for debugging and final tests/battles.

paul@pimoroni.com

<https://github.com/pimoroni/hackadayeurope2024>

This presentation and all the code/guides used.



WHAT ARE WE DOING HERE?




MAKING

MICROPYTHON

A close-up photograph of a human finger, likely the index finger, with a small, slender snake coiled around it. The snake has a dark blue body with yellow and blue markings along its sides. The background is a blurred green, suggesting an outdoor setting.

Learning some basics of 'e-z-mode' microcontroller programming



Share knowledge and encouragement to ensure everyone in the group is equally confused.

MUTUALISM

ACHTUNG!

A young child wearing a blue puffer jacket, a white knit hat, and grey pants is crouching on a paved path. The child is holding a small red and blue object, possibly a whistle or a small toy, and is looking down at a group of capybaras. Several capybaras are gathered around the child, some looking up at the child. One capybara in the foreground is eating a piece of food. The background shows a body of water and some trees.

This is a low risk workshop, however:

SAFETY THIRST!

Be careful about short circuits.

Any output can become a short and release magical smoke.

We are working with low voltage, so consequences are mild.

Double check power connections.

Beware loose wires

SAFETY THIRST!

When cutting wire, hold both pieces of wire.

The loose end can fly and you'll take your eye out.

SAFETY THIRST!

Scissors.

Be careful to not cut yourself.

Don't run with them.

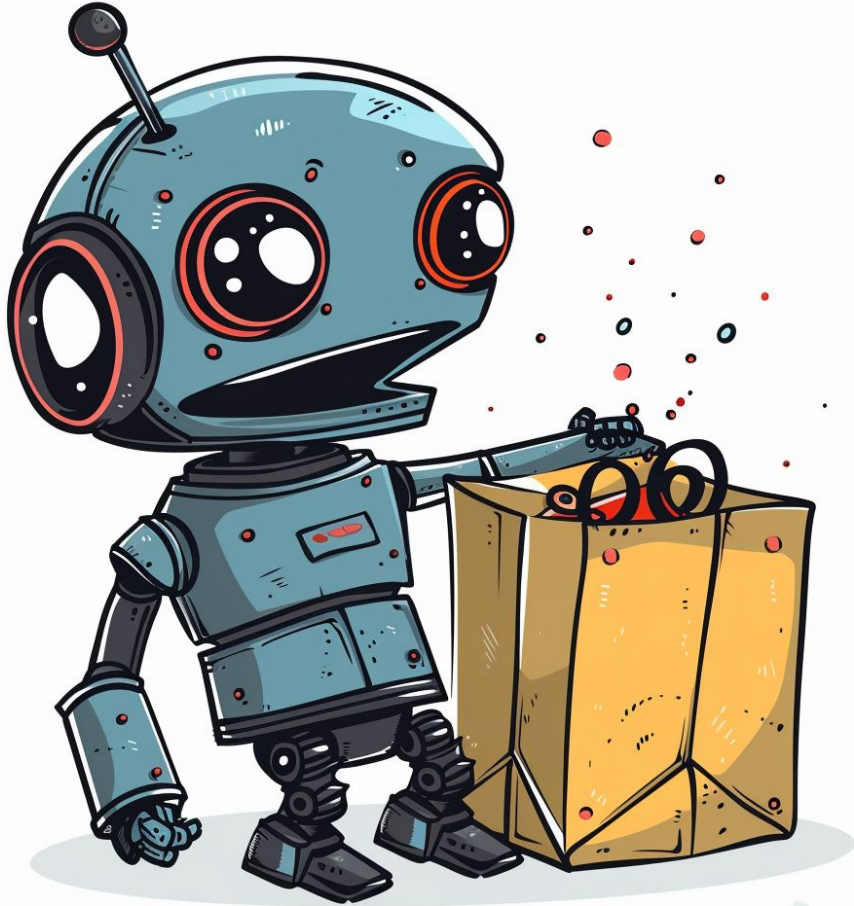
SAFETY THIRST!

Glue.

Do not huff.

Do not stick non-workshop things together.

Be nice to the Motion.Lab



**OPEN
YOUR
BAGS.**

**LET'S LOOK
AT YOUR
STUFF!**

What hardware are we using?

Raspberry Pi Pico

Continuous Rotation Servos

Time-of-Flight TOF sensor (Qwiic, Stemma QT)

Cable Ties

Laser-cut chassis

3D Printed wheels

Various craft things

Which firmware/software?

Pimoroni 'batteries included' MicroPython for Pico

Thonny - cross-platform Python/Micropython IDE

Pico (W) Basic Survival Skills

Already done: Adding MP/CP/Arduino to a Pico/Pico W

BOOTSEL

flashnuke.uf2

Thonny is a 'good enough' IDE and cross-platform

THE TRIALS

BEAUTY PAGENT - James or Paul will Judge your bot whenever you are ready.

ART SCHOOL - Draw a simple image with your bot.

ROUGH TERRAIN - Navigate an obstacle course.

SODA DELIVERY - Deliver a 330ml soda can through a maze.

PICO NOON - Robots go head-to-head to pop each others balloons.

NOT SO MUCH RULES AS GUIDELINES

You can team up in duos.

No robot size restrictions, but it has to fit in the start area.

You can retool/recode your robot between challenges.

If time allows, a second attempt at challenges is allowed to improve score.

Scoring is pretty random, but mostly fair.

Robots can be manually controlled. Extra points for automatons.

Have fun. Be kind. Be chill. Low drama.

BAT COUNTRY!

Now we go freeform!

Materials used in the workshop:

<https://github.com/pimoroni/hackadayeurope2024>

Code READMEs for sensor/servo modules:

<https://github.com/pimoroni/pimoroni-pico/tree/main/micropython/modules>

Code examples to crib from:

<https://github.com/pimoroni/pimoroni-pico/tree/main/micropython/examples>