



ÉCOLE POLYTECHNIQUE
FÉDÉRALE DE LAUSANNE

Convex recovery under linear measurements

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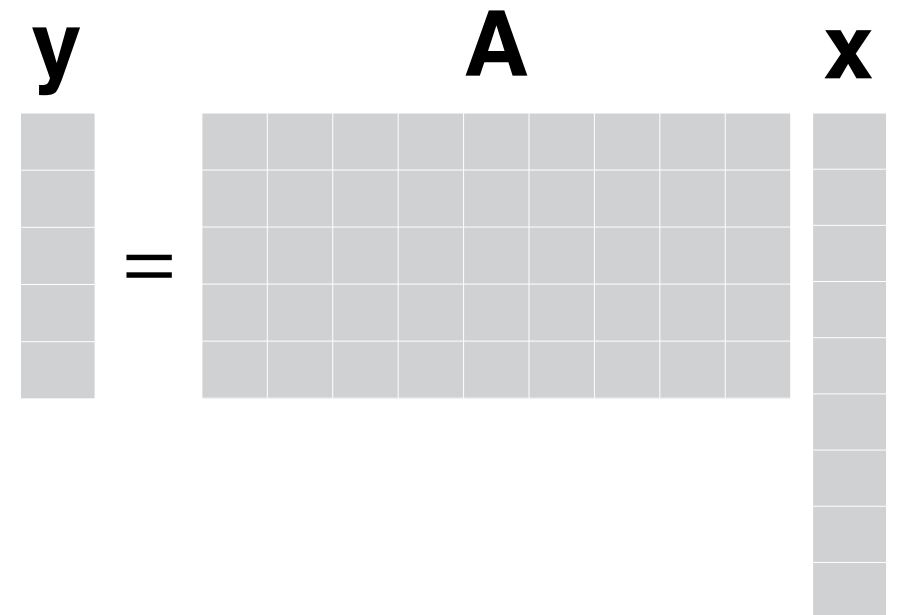


Model

Ill-posed!

$$\mathbf{y} \in \mathbb{R}^m, m < n$$

$$\mathbf{y} = \mathbf{A}\mathbf{x}$$



A diagram illustrating the equation $\mathbf{y} = \mathbf{A}\mathbf{x}$. On the left is a vertical column vector \mathbf{y} with 6 cells. To its right is an equals sign. Further right is a matrix \mathbf{A} with 6 rows and 8 columns. To the right of the matrix is a vertical column vector \mathbf{x} with 8 cells. All vectors and the matrix are represented by gray grids.

Signal to be recovered

(Random) measurement matrix

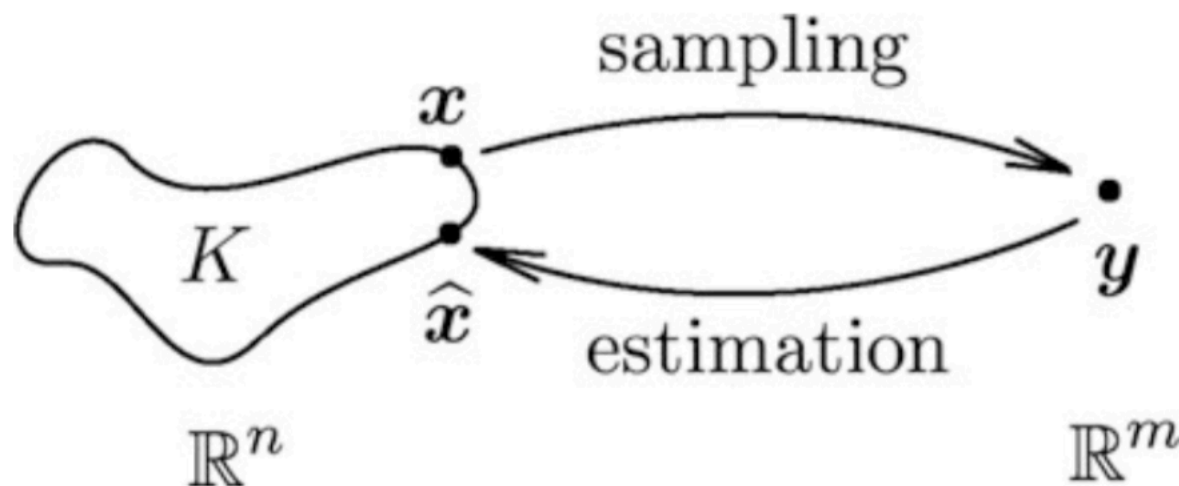
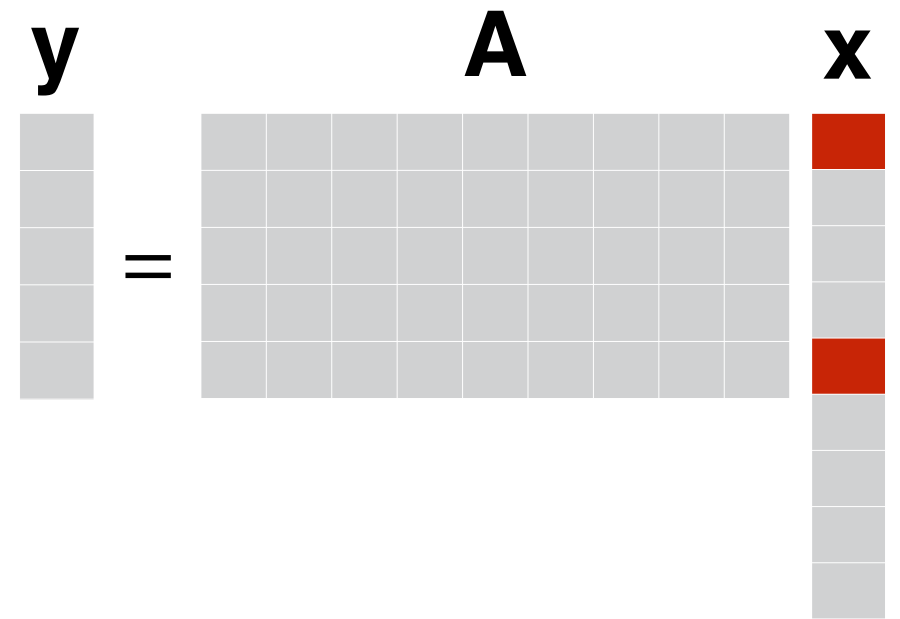
Linear measurements

Goal: recover the signal by
inverting the measurement
process

Assumptions

$$\mathbf{y} = \mathbf{A}\mathbf{x}$$

$$\mathbf{y} \in \mathbb{R}^m, m < n$$



[Vershynin, 2015]

$$\min_{\mathbf{z} \in \mathbb{R}^n} \|\mathbf{A}\mathbf{z} - \mathbf{y}\|_2^2 \text{ s.t. } \mathbf{z} \in K$$

$$\min_{\mathbf{z} \in \mathbb{R}^n} f(\mathbf{z}) \text{ s.t. } \mathbf{A}\mathbf{z} = \mathbf{y}$$

Unique recovery

$$\mathbf{y} = \mathbf{A}\mathbf{x} \longrightarrow \min_{\mathbf{z} \in \mathbb{R}^n} f(\mathbf{z}) \text{ s.t. } \mathbf{A}\mathbf{z} = \mathbf{y} \longrightarrow \mathbf{z}^* \stackrel{?}{=} \mathbf{x}$$

A.: Yes, but iff

$$\mathcal{D}(f, \mathbf{x}) := \text{cone}\{\mathbf{u} = \mathbf{z} - \mathbf{x} : f(\mathbf{z}) \leq f(\mathbf{x})\}$$

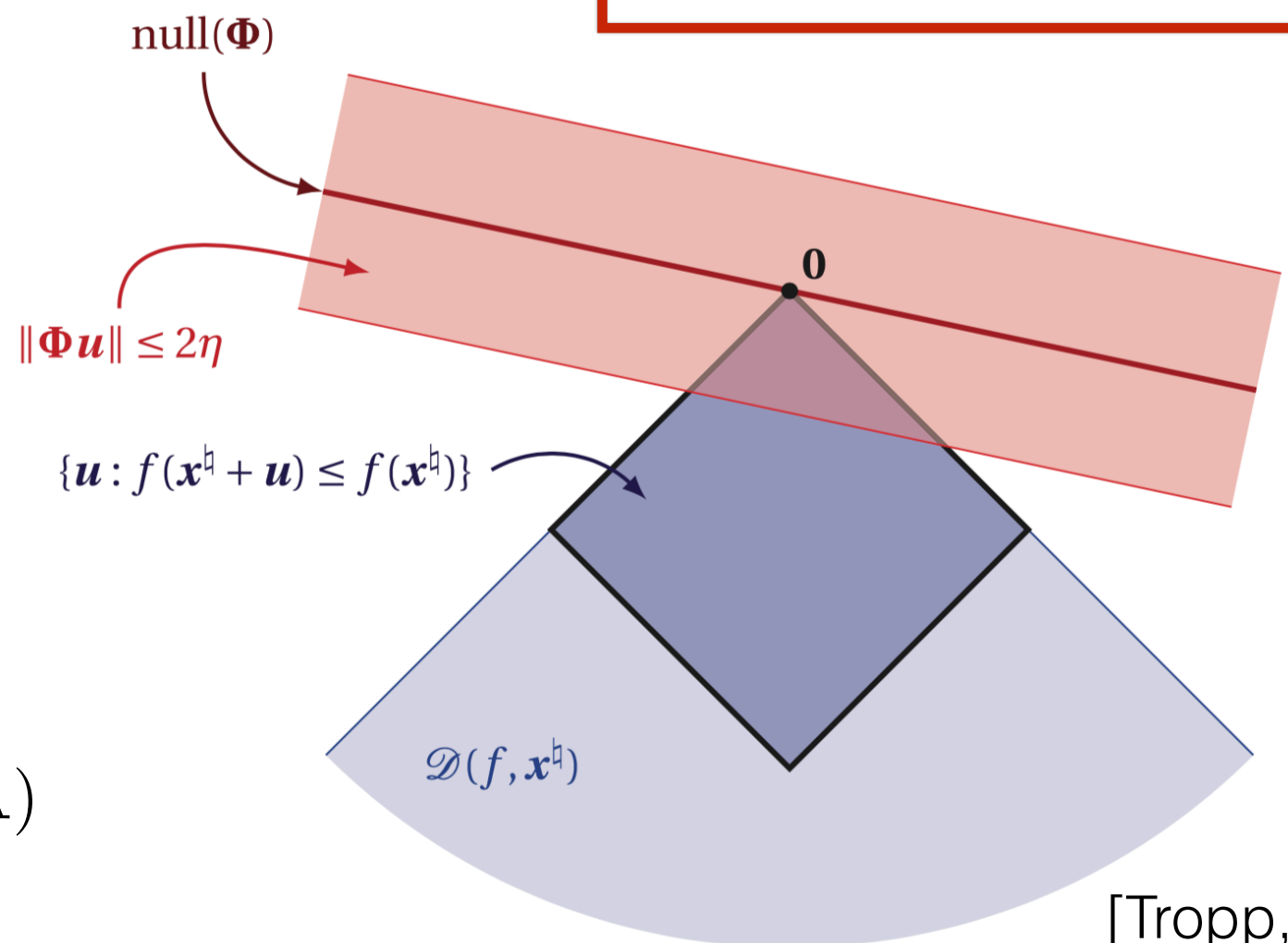
$$\mathcal{D}(f, \mathbf{x}) \cap \text{null}(\mathbf{A}) = \{\mathbf{0}\}$$

"descent cone"
vs.
"null space"

$$\mathbf{A}\mathbf{z} = \mathbf{y} = \mathbf{A}\mathbf{x}$$

$$\implies \mathbf{A}(\mathbf{z} - \mathbf{x}) = \mathbf{0}$$

$$\implies (\mathbf{z} - \mathbf{x}) \in \text{null}(\mathbf{A})$$



Equivalent condition

$$\mathbf{y} = \mathbf{A}\mathbf{x} \longrightarrow \min_{\mathbf{z} \in \mathbb{R}^n} f(\mathbf{z}) \text{ s.t. } \mathbf{A}\mathbf{z} = \mathbf{y} \longrightarrow \mathbf{z}^* \stackrel{?}{=} \mathbf{x}$$

$$\mathcal{D}(f, \mathbf{x}) \cap \text{null}(\mathbf{A}) = \{\mathbf{0}\} \longrightarrow \min_{\mathbf{z} \in \mathcal{D}(f, \mathbf{x}) \cap \mathbb{S}^{n-1}} \|\mathbf{A}\mathbf{z}\|_2^2 > 0$$

Beauty of randomness: (\mathbf{A} sub-Gaussian or "small-ball")

$$\|\mathbf{A}\mathbf{z}\|_2^2 \underset{\sim}{\geq} \sqrt{m} - w(\mathcal{D}(f, \mathbf{x}) \cap \mathbb{S}^{n-1}) - t$$

with probability at least $1 - \exp(-t^2)$, $\forall \mathbf{z} \in \mathcal{D}(f, \mathbf{x}) \cap \mathbb{S}^{n-1}$

[Tropp, 2012]

[Liaw et al., 2017]

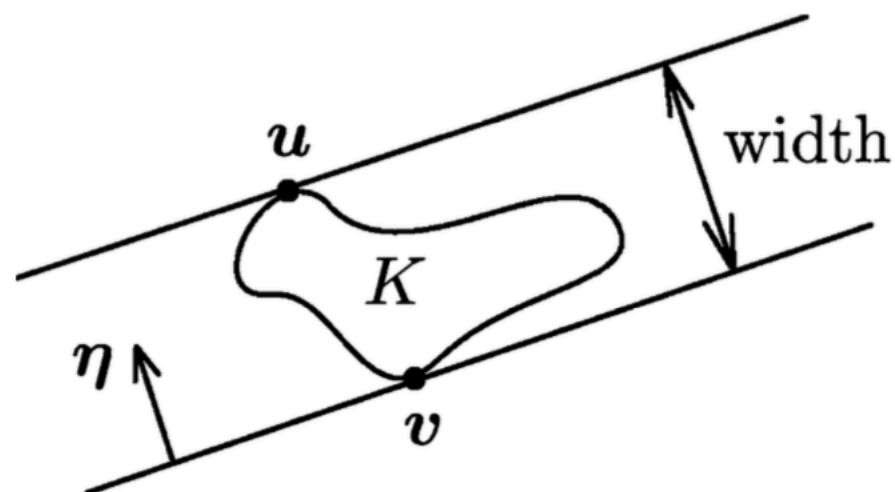
"Gaussian width" 

Gaussian mean width

$$\mathbf{y} = \mathbf{A}\mathbf{x} \longrightarrow \min_{\mathbf{z} \in \mathbb{R}^n} f(\mathbf{z}) \text{ s.t. } \mathbf{A}\mathbf{z} = \mathbf{y} \longrightarrow \mathbf{z}^* \stackrel{?}{=} \mathbf{x}$$

$$\|\mathbf{A}\mathbf{z}\|_2^2 \underset{\sim}{\geq} \sqrt{m} - w(\mathcal{D}(f, \mathbf{x}) \cap \mathbb{S}^{n-1}) - t$$

$$w(K) = \mathbb{E} \sup_{\mathbf{u} \in K} \langle \mathbf{u}, \eta \rangle, \quad \eta \sim \mathcal{N}(0, I)$$



So what?

- Singular values of random matrices

$$K = \mathbb{S}^{n-1} \quad \sigma(\mathbf{A}) \in [\sqrt{m} - C\sqrt{n}, \sqrt{m} + C\sqrt{n}]$$

- Johnson-Lindenstrauss lemma

$$K = X - X, |X| < \infty \quad \left| \frac{\|\mathbf{A}\mathbf{x}\|_2}{\sqrt{m}} - 1 \right| \leq \frac{C\sqrt{\log |X|}}{\sqrt{m}}$$

- Intersection of a set K by a random subspace L

$$L = \text{null}(\mathbf{A}) \quad \text{rad}(L \cap K) \leq \frac{Cw(L)}{\sqrt{m}}$$

- Exact recovery in compressed sensing

$$K = B_{\ell_1} \quad m \geq Cs \log(n/s)$$

Summary

$$\mathbf{y} = \mathbf{A}\mathbf{x} \longrightarrow \min_{\mathbf{z} \in \mathbb{R}^n} f(\mathbf{z}) \text{ s.t. } \mathbf{A}\mathbf{z} = \mathbf{y} \longrightarrow \mathbf{z}^* \stackrel{?}{=} \mathbf{x}$$

Sub-Gaussian? "Small-ball"?

Then,

$$m \gtrsim \left(w(\mathcal{D}(f, \mathbf{x}) \cap \mathbb{S}^{n-1}) + t \right)^2$$

Guarantees unique recovery with probability at least

$$1 - \exp(-t^2)$$

Atomic norms are great!
[Chandrasekaran et al., 2012]

Thank you

Q & A

References

- [1] R. Vershynin, “Estimation in high dimensions: a geometric perspective,” in Sampling theory, a renaissance, Birkhauser/Springer, Cham, 2015, pp. 3–66.
- [2] V. Chandrasekaran, B. Recht, P. A. Parrilo, and A. S. Willsky, “The Convex Geometry of Linear Inverse Problems,” Found Comput Math, vol. 12, no. 6, pp. 805–849, Oct. 2012.
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- [4] Y. Plan and R. Vershynin, “The generalized lasso with non-linear observations,” IEEE Transactions on Information Theory, vol. 62, no. 3, pp. 1528–1537, Mar. 2016.