



# Functional Data Analysis

Ping-Han Huang

Arizona State University

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# Examples of FDA—CD4

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- Stochastic Process
- Second-Order Process

## fPCA

- PCA for Multivariate Data
- From PCA to fPCA
- Number of FPC
- Recovering Individual Trajectories

## Comparison

## R Demonstration

## Extensions

- FLR
- Curve Registration
- Sparse Data

## References

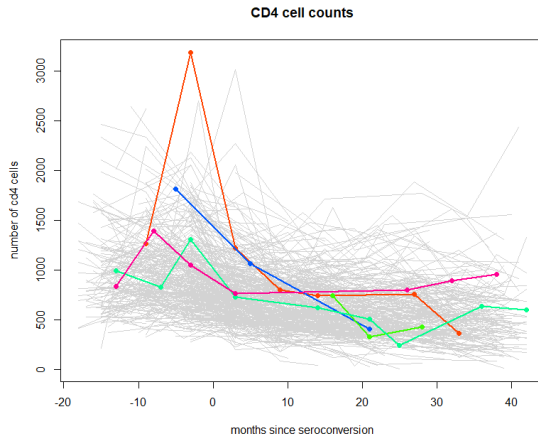


Figure 1: CD4 Data (Source: Staicu & Park, 2016)

# Examples of FDA—DTI

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## Diffusion Tensor Imaging

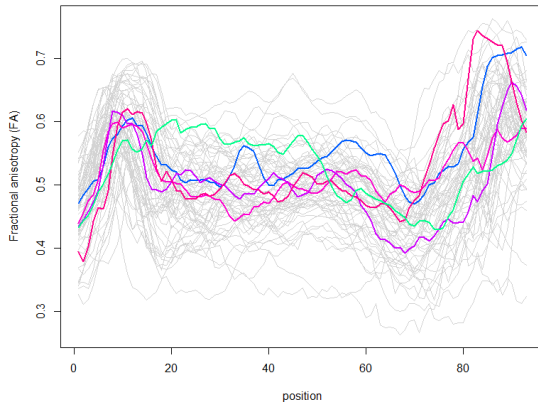


Figure 2: DTI Data (Source: Staicu & Park, 2016)

# Stochastic Process

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- Underlying random function:  $\{X(t); t \in \mathcal{T}\}$
- $m$  i.i.d. sample paths (realizations of random functions):  $\{X_i(t); t \in \mathcal{T}\}$
- Subsamples of  $m$  sample paths:  $x_i(t_{ij})$ ,  $i = 1, \dots, m$  and  $j = 1, \dots, n_i$



# Second-Order Process

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- $\{X(t); t \in \mathcal{T}\}$  is a second-order process if, for each  $t$ ,  $X(t)$  has finite second moment, i.e.,

$$E|X(t)|^2 < \infty$$

- Continuous mean function:

$$\mu_X(t) = E\{X(t)\}$$

- Continuous and nonnegative definite covariance function:

$$\Gamma_X(s, t) = \text{Cov}\{X(s), X(t)\}, \text{ for all } s, t \in \mathcal{T}$$



# Functional Principal Component Analysis (fPCA)

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- Reduce dimensionality
- Capture main modes of variation
- Express  $X(t)$  as

$$X(t) = \mu_x(t) + \sum_{k=1}^K \zeta_k \phi_k(t)$$

where  $\zeta_k$  is the  $k$ th FPC score and  $\phi_k$  is the  $k$ th eigenfunction



# PCA for Multivariate Data

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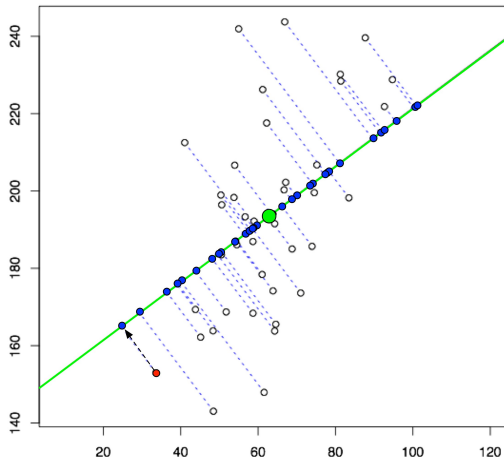


Figure 3: PCA (Source: Pachter, 2014)

# PCA for Multivariate Data

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1 The data is  $\vec{X} = (X_1, \dots, X_m)^T$

2 Eigen decomposition of  $\text{Cov}(\vec{X})$  to get eigenvectors  $\Phi$  and eigenvalues  $\vec{\lambda}$

$$\text{Cov}(\vec{X}) = \Phi \Lambda \Phi^T = \sum_{m=1}^M \lambda_m \phi_m \phi_m^T$$

3 Obtain

$$\mathbf{Y} = \mathbf{P} \vec{X}_c = \sum_{m=1}^M [\phi_m^T \vec{X}_c] \phi_m$$

- $\vec{X}_c = \vec{X} - \mu_X$
- $\mathbf{P} = \Phi(\Phi^T \Phi)^{-1} \Phi^T$  is the projection matrix
- $\mathbf{Y}$  is the re-representation of the data



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■ Then we have  $\vec{X} = \mu_X + \Phi\zeta$ , where  $\zeta = \Phi^T \vec{X}_c$ .

■  $\zeta = (\zeta_1, \dots, \zeta_m)^T$

■  $\zeta_m = \phi_m^T (\vec{X} - \mu_X)$

■  $E(\zeta_m) = 0$

■  $Var(\zeta_m) = \lambda_m$

■  $Cov(\zeta_m, \zeta'_m) = 0$

■ The principal component scores are rank-ordered by their variances

# From PCA to fPCA

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## ■ Mercer's Theorem

$$\Gamma_X(s, t) = \sum_{k=1}^{\infty} \lambda_k \phi_k(s) \phi_k(t), \text{ for all } s, t \in \mathcal{T}$$

- $\lambda_k$ :  $m$ th eigenvalue of  $X(t)$
- $\phi_k(t)$ :  $m$ th eigenfunction of  $X(t)$

## ■ Karhunen-Lóeve Representation

$$X(t) = \mu_X(t) + \sum_{k=1}^{\infty} \zeta_k \phi_k(t)$$

- $\zeta_k = \int_{\mathcal{T}} [X(t) - \mu_X(t)] \phi_k(t) dt$ :  $k$ th FPC score for  $X(t)$
- $E(\zeta_k) = 0$ ,  $\text{var}(\zeta_k) = \lambda_k$ ,  $\text{cov}(\zeta_k, \zeta_{k'}) = 0$

# Number of FPC (K)

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### ■ Fraction of variation explained (FVE)

$$■ FVE = \frac{\sum_{k=1}^K \lambda_k}{\sum_{k=1}^{\infty} \lambda_k}$$

### ■ Information criteria

- AIC
- BIC

### ■ Cross validation (CV)

- Minimize the cross-validation score based on the one-curve-leave-out squared prediction error:

$$CV(K) = \sum_{i=1}^K \sum_{j=1}^{n_i} \{Y_{ij} - \hat{Y}_i^{(-i)}(T_{ij})\}^2$$

# Recovering Individual Trajectories

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After fPCA and selecting the number of FPCs, we can recover the trajectory  $\hat{X}_i(t)$  for the  $i$ th subject as

$$\hat{X}_i^K(t) = \hat{\mu}(t) + \sum_{k=1}^K \hat{\zeta}_{ik} \hat{\phi}_k(t)$$

The estimation is based on noisy observations  $\{(Y_{i1}, t_{i1}), \dots, (Y_{in_i}, t_{in_i})\}$ , where

$$Y_{ij} = X_i(t_{ij}) + \epsilon_{ij}$$



# Comparisons of LMEM and FDA

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Observed data:  $\{(Y_{i1}, t_{i1}), \dots, (Y_{in_i}, t_{in_i})\}$

- LMEM:  $Y_i = \mathbf{X}_i \vec{\beta} + \mathbf{Z}_i \vec{b}_i + \vec{e}_i$ 
  - parametric assumptions for the model
  - parametric methods for estimation
  - objective: inference
- FDA:  $Y_{ij} = X_i(t_{ij}) + \epsilon_{ij}$ 
  - no assumption for the model covariance
  - nonparametric approach for estimation
  - objective: recovering subject-specific trajectories

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## ■ Functional Linear Regression Models (FLR)

### ■ Scalar-on-Function Regression

$$Y_i = \alpha + \int \beta(t) X_i(t) dt + \epsilon_i$$

### ■ Function-on-Scalar Regression

$$Y_i(t) = \beta_0(t) + \sum_{j=1}^p \beta_j(t) X_{ij} + \epsilon_i(t)$$

### ■ Function-on-Function Regression

$$Y_i(t) = \beta_0(t) + \int \beta(s, t) X_i(s) ds + \epsilon_i(t)$$



# Extensions: Curve Registration

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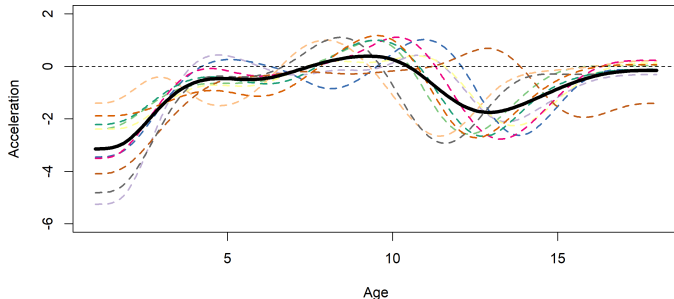
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- Phase displacement or amplitude variability in the data.
- Align the curves through time warping.





# Extensions: Curve Registration

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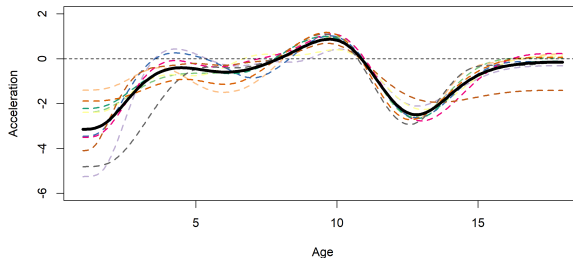
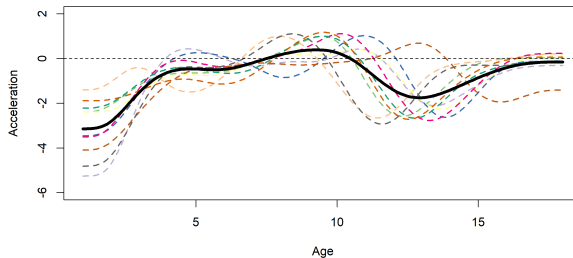
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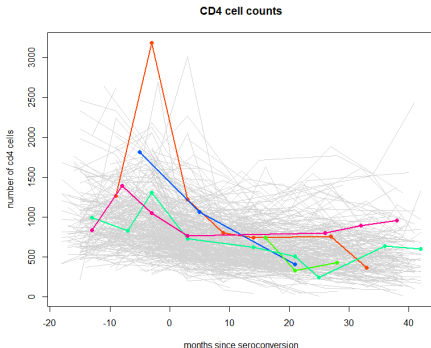
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- Principal Component Analysis through Conditional Expectation (PACE) Method for Sparse Data
- We have “sparse” data when the number of measurements per subject ( $n_i$ ) is very low.



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<https://onlinelibrary.wiley.com/doi/book/10.1002/9781118762547>
- Kokoszka, P., & Reimherr, M. (2017). Introduction to Functional Data Analysis (1st ed.). Chapman and Hall/CRC. <https://doi.org/10.1201/9781315117416>
- Ramsay, J., Hooker, G., Graves, S. (2009). Functional Data Analysis with R and MATLAB. Use R. Springer, New York, NY. <https://link.springer.com/book/10.1007/978-0-387-98185-7>

## Paper:

- Yao, F., Müller, H.-G., & Wang, J.-L. (2005). Functional data analysis for SPARSE LONGITUDINAL DATA. Journal of the American Statistical Association, 100(470), 577–590.  
<https://doi.org/10.1198/016214504000001745>
- J. S. Marron. James O. Ramsay. Laura M. Sangalli. Anuj Srivastava. "Functional Data Analysis of Amplitude and Phase Variation." Statist. Sci. 30 (4) 468 - 484, November 2015.  
<https://doi.org/10.1214/15-STS524>

## Online Lecture:

- Ana-Maria Staicu & So Young Park (2016). Short course on Applied Functional Data Analysis. Retrieved from <https://www4.stat.ncsu.edu/~staicu/FDAtutorial/index.html>
- Short course on functional data analysis. YouTube.  
<https://youtube.com/playlist?list=PLD2RXrMBJwfOEmYmYE5x1B1ARqbZrc0h9&feature=shared>

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# Thank you!