

## Problema 2

Para un rango

$$a < R$$

$$\Rightarrow \oint \vec{B} \cdot d\vec{l} = \mu_0 \cdot I_{enc}$$

$I_{enc}$ :

$J \neq \text{cte}$

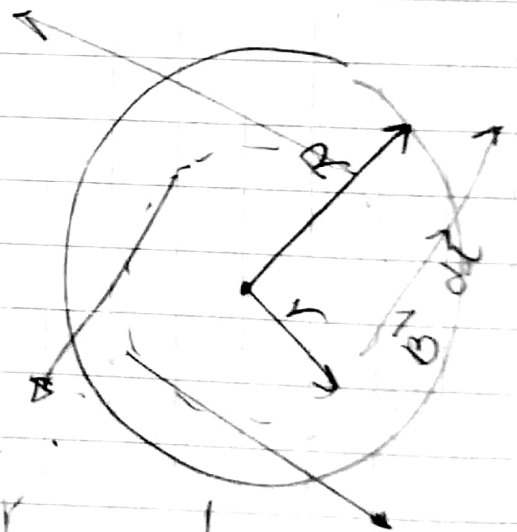
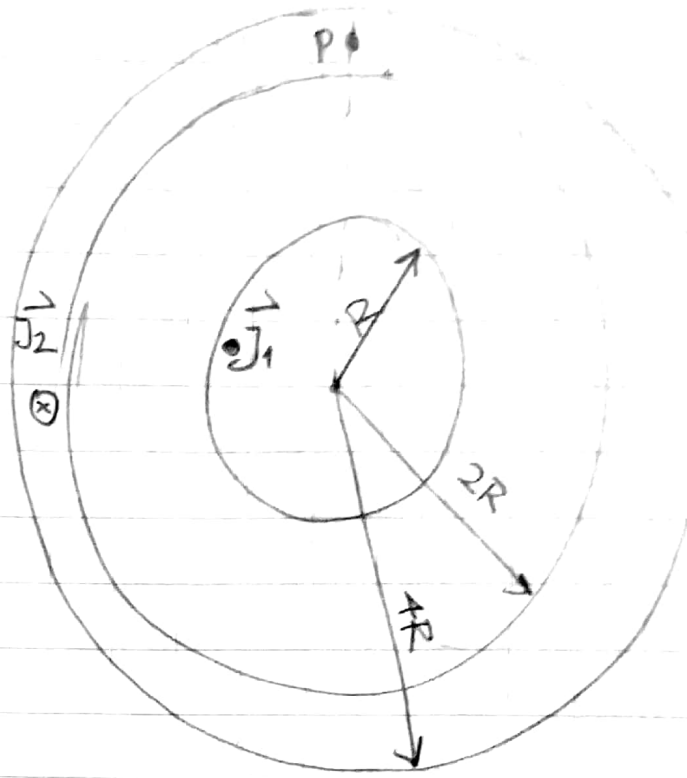
$$J_1 = A r^2 \hat{k}$$

$$I_{enc} = \int_0^R \int_0^{2\pi} A r^2 \cdot ds$$

$$\Rightarrow A \int_0^R r^2 \cdot 2\pi$$

$$\Rightarrow A \cdot 2\pi \int_0^R r^2 \Rightarrow A \cdot 2\pi \frac{r^3}{3} = I_{enc}$$

$$\Rightarrow \frac{I_{enc}}{A_{enc}} = \frac{I_T}{A_T} \Rightarrow I_{enc} = \frac{I_T \cdot A_{enc}}{A_T}$$



$$\Rightarrow \oint \vec{B} \cdot d\vec{\ell} = \mu_0 \cdot I_{enc}$$

$$B = \frac{\mu_0 \cdot I_{enc}}{d\ell} = \frac{\mu_0 \cdot A / \cancel{2\pi r} \cdot \frac{r^{\frac{3}{2}}}{3}}{\cancel{2\pi r}} \Rightarrow \frac{\mu_0 \cdot A r^2}{3}$$

\* Con Región  $R < r < 2R$  ( $I_0 = I_{enc}$ )

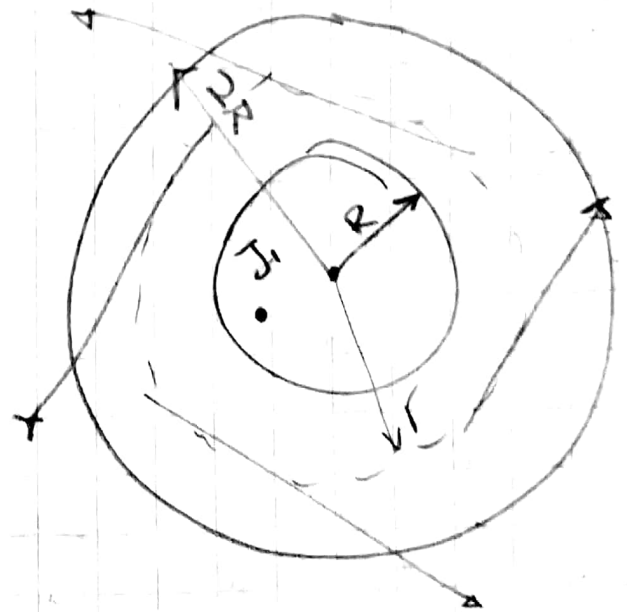
$$\oint \vec{B} \cdot d\vec{\ell} = \mu_0 I_{enc}$$

$I_{enc}$  :

$$\Rightarrow I_{enc} = \iint J_1 \cdot ds$$

$$\Rightarrow \int_0^r \int_0^{2\pi} A r^2 \cdot ds \Rightarrow I_{enc}$$

$$\Rightarrow A \int_0^r r^2 \int_0^{2\pi} ds = A 2\pi \int_0^r r^2 \Rightarrow A 2\pi \cdot \frac{r^3}{3}$$



$$\Rightarrow \oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc} \quad | \quad I_0 = I_{enc}$$

$$\Rightarrow B = \frac{\mu_0 I_{enc}}{dl} = \mu_0 \cdot \frac{A \cancel{2\pi} r^{\frac{2}{3}}}{\cancel{2\pi} r^{\frac{2}{3}}}$$

$$\Rightarrow B = \frac{\mu_0 A r^2}{3} (T) \quad \text{con} \quad ar < b$$

region  $2R < r < 4R$

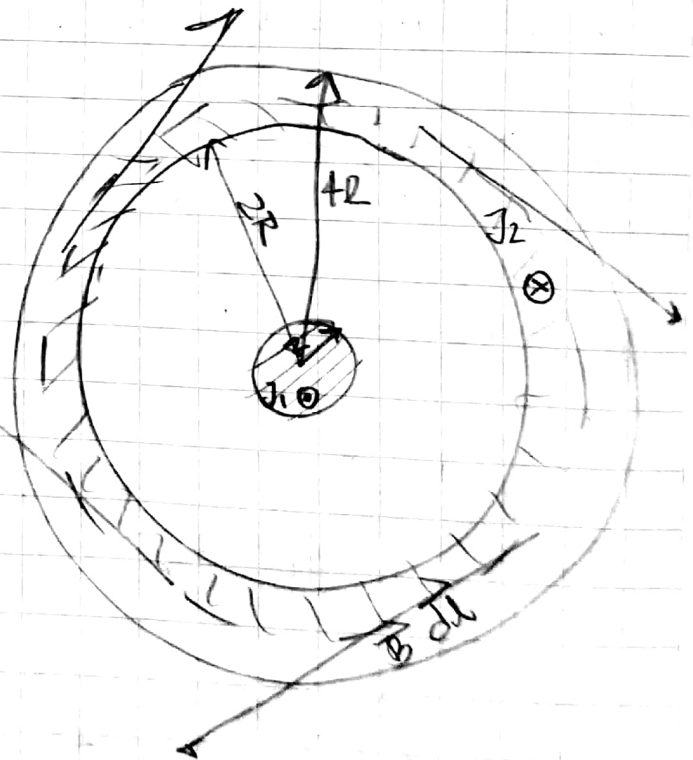
$I_{enc}$ :

$$J_2 = \frac{B}{r} - \hat{n}$$

$$J_2 \neq \text{cte} \Rightarrow I_{enc} = \iint J_2 \cdot ds$$

$$\Rightarrow \int_0^r \int_0^{2\pi} \frac{B}{r} \cdot ds$$

$$\Rightarrow B \cdot 2\pi \int_0^r \frac{1}{r} dr \Rightarrow \left[ B 2\pi \ln|r| = I_{enc} \right]$$



$$I_{TOTAL} = I_{\odot} - I_{\otimes} \Rightarrow I_{TOTAL} = A 2\pi \frac{r^3}{3} - B 2\pi \ln|r|$$

Logo

$$\oint \vec{B} \cdot d\vec{\ell} = \mu_0 \cdot I_{enc} \Rightarrow B = \frac{\mu_0 \cdot I_{enc}}{d\ell}$$

$$\Rightarrow B = \frac{\mu_0 \cdot \cancel{B 2\pi \ln|r|}}{\cancel{2\pi r}} = \frac{\mu_0 B \ln|r| (+)}{r}$$

Logo

$$I_{\odot} = I_{enc} \Rightarrow I_{\odot} = B 2\pi \ln|r|$$

$$\Rightarrow B = \frac{I_{\odot}}{2\pi \ln|r|} //$$

Logo resolvendo a  $R < r < 2R$

$$\Rightarrow I_{\odot} = I_{enc}$$

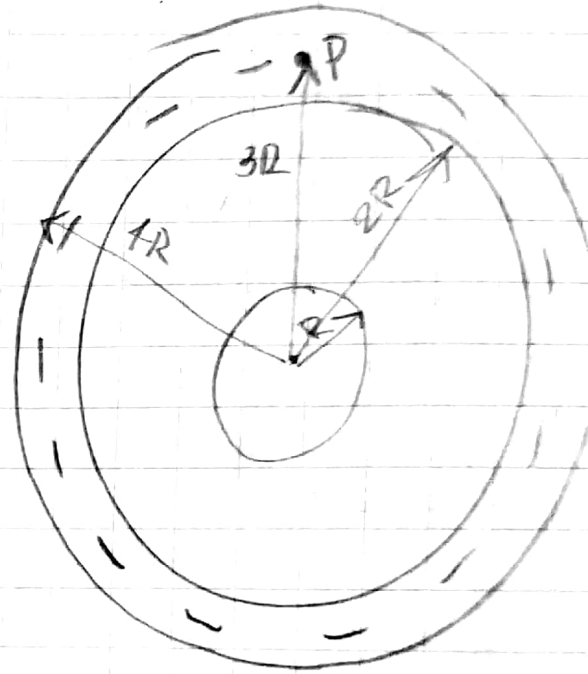
$$\Rightarrow I_{\odot} = A 2\pi \frac{r^3}{3}$$

$$3I_{\odot} = A 2\pi r^3$$

$$A = \frac{3I_{\odot}}{2\pi r^3} //$$

(B) Find  $\vec{B}_p$  in region  $r = 3R$

$$\oint \vec{B}_p \cdot d\vec{l} = \mu_0 \cdot I_{enc}$$



$$J_2 \neq \text{cte} \Rightarrow I_{enc} = \iint J_2 \cdot d\vec{s}$$

$$\Rightarrow \int_0^r \int_0^{2\pi} \frac{B}{r} ds \Rightarrow B 2\pi \int_0^r \frac{dr}{r}$$

$$\Rightarrow I_{enc} = B 2\pi \ln|r|$$

$$I_T = I_1 - I_2'$$

$$I_1 = I_{enc} \text{ de } J_1$$

$$I_{Total} = \frac{A 2\pi r^3}{3} - B 2\pi \ln|r|$$

Luego:

$$\Rightarrow \oint B_p \, dl = \mu_0 \cdot I_{enc}$$

$$\therefore B_p = \frac{\mu_0 \cdot I_{enc}}{dl}$$

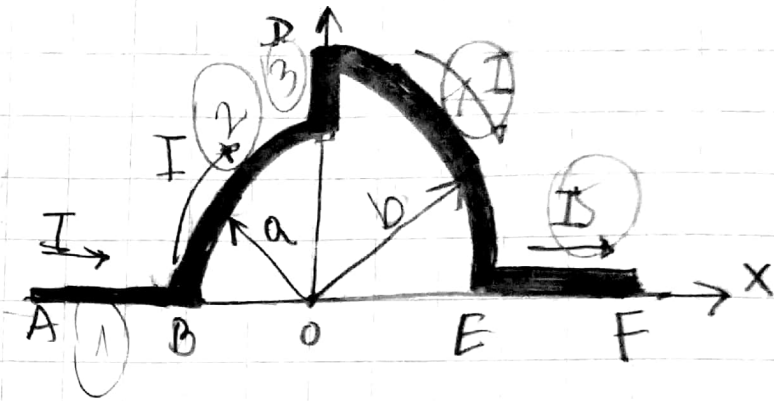
$$\Rightarrow B_p = \frac{\mu_0}{6\pi R} \left[ \frac{A 2\pi r^3}{3} - 2B\pi \ln|r| \right]$$

# Problema 1

05 August 2020

Formula

$$a) B_1 = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{l} \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3}$$



i) vect. posi.

$$\vec{r} = 0\hat{i} + a\hat{j} \quad \left. \begin{array}{l} \\ \\ \end{array} \right\} -x\hat{i}$$

$$\vec{r}' = x\hat{i}$$

$$|\vec{r} - \vec{r}'| = (x^2)^{3/2}$$

$$c) d\vec{l} = dx\hat{i}$$

$$B_1 = \frac{\mu_0 I}{4\pi} \int \frac{dx\hat{i} \times (-x\hat{i})}{(x^2)^{3/2}} = 0$$

$$\vec{B}_2 = \frac{\mu_0 I}{4\pi} \int d\vec{l} \times (\vec{r} - \vec{r}')$$

i) Vector pos.

$$\vec{r} = 0$$

$$\vec{r}' = a \cos \theta \hat{i} + a \sin \theta \hat{j}$$

$$(\vec{r} - \vec{r}') = -a \cos \theta \hat{i} - a \sin \theta \hat{j}$$

$$= -a \omega T \theta \hat{i} + \sin \theta \hat{j}$$

$$= a$$

ii)  $dl = a d\theta$

$$d\vec{l} = a d\theta = (\cos(\theta - \pi/2) \hat{i} - \sin(\theta - \pi/2) \hat{j})$$

$$d\vec{l} = a d\theta (\sin \theta \hat{i} - \cos \theta \hat{j})$$

$$\begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a \sin \theta & -a \cos \theta & 0 \\ -a \cos \theta & -a \sin \theta & 0 \end{vmatrix} \Rightarrow \hat{k} (-a^2 \sin^2 \theta - a^2 \cos^2 \theta) \Rightarrow -a^2 d\theta \hat{k}$$



luego

$$\vec{B}_2 = \frac{\mu_0 I}{4\pi} \int_{\pi/2}^{\pi} \frac{d\vec{\ell} \times \hat{r}}{a^3} = \frac{-\mu_0 I \hat{k}}{4\pi a} \left[ \pi - \pi/2 \right]$$

$$\Rightarrow \frac{-\mu_0 I \hat{k}(\pi)}{8a}$$

$$c) \vec{B}_3 = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{\ell} \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3}$$

e) vector pos.

$$\vec{r} = 0 \quad (\vec{r} - \vec{r}') = y^3$$

$$\vec{r}' = y \hat{j}$$

$$ii) d\vec{\ell} = dy \hat{j}$$

$$\text{luego} = b < y < c$$

$$B_z = \frac{\mu_0 I}{4\pi} \int_b^c \frac{dy \hat{j} \times (-y \hat{j})}{y^3} = 0$$

$B_z$  igual que  $B_z$  con signo contrario :-

$$B_z = 0.$$

$B_z$  :

i vector posic.

$$\vec{r} = r\hat{e}_r + r\hat{e}_\theta$$

$$\vec{r}' = b(\cos\theta\hat{e}_r + \sin\theta\hat{e}_\theta)$$

$$|\vec{r} - \vec{r}'| = -b\cos\theta\hat{e}_r - b\sin\theta\hat{e}_\theta$$

$$u = b^3$$

$$i) d\vec{L} = b d\theta (\sin\theta\hat{e}_r - \cos\theta\hat{e}_\theta) = d\vec{L} = \vec{r}' \times \vec{r} - \vec{r}$$

$$\begin{vmatrix} \hat{e}_r & \hat{e}_\theta & \hat{k} \\ b\sin\theta & -b\cos\theta & 0 \\ -b\cos\theta & -b\sin\theta & 0 \end{vmatrix} \Rightarrow -(2b^2)\hat{k}$$

$$B_4 = \frac{\mu_0 I}{4\pi} \int \frac{-2b^2 d\theta}{b^3} \Rightarrow \frac{-2\mu_0 I}{4\pi b} \int_0^{\pi/2} d\theta(\hat{k})$$

$$\Rightarrow \frac{-\mu_0 I}{4b} \hat{R}(T)$$