

Problema 2

Para un

$$a < R$$

$$\rightarrow \oint \vec{B} \cdot d\vec{l} = \mu_0 \cdot I_{\text{enc}}$$

$I_{\text{enc}}$ :

$$J \neq \text{cte}$$

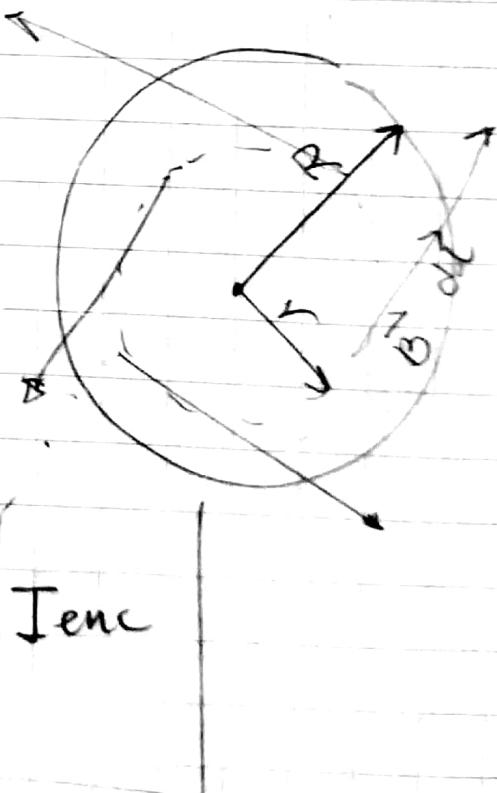
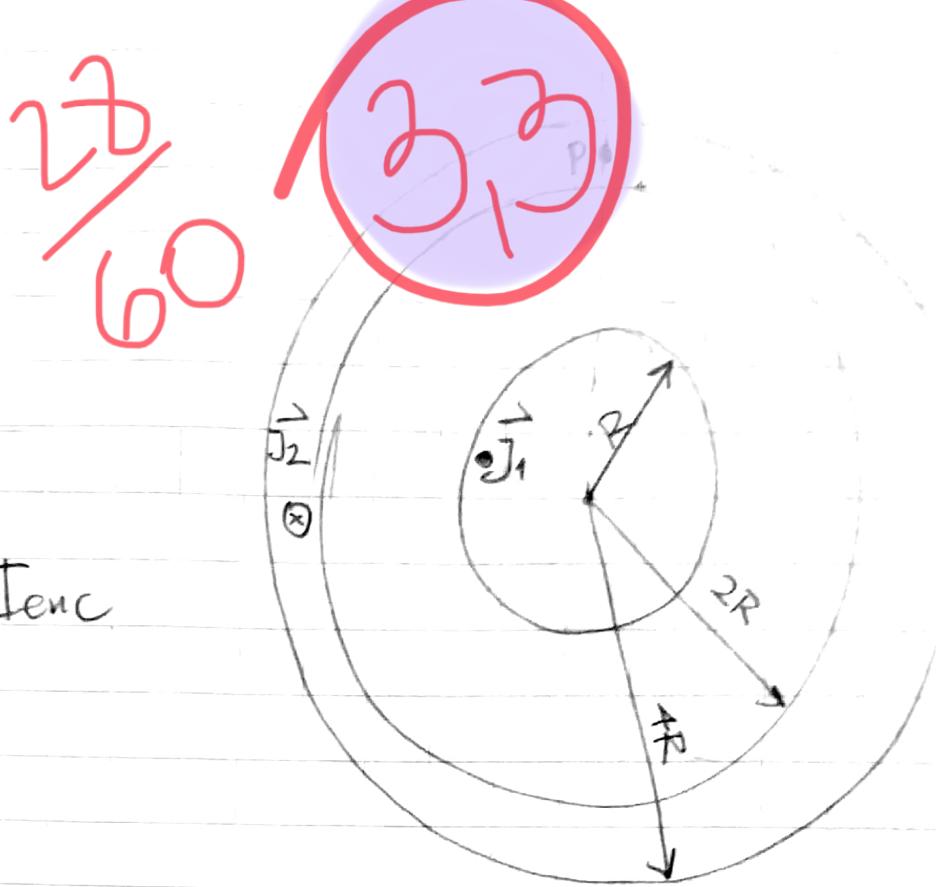
$$J_1 = A r^2 (\hat{k})$$

$$I_{\text{enc}} = \iint_{0 \text{ to } r} A r^2 \cdot ds$$

$$\rightarrow A \int_0^r r^2 \cdot 2\pi$$

$$\rightarrow A \cdot 2\pi \int_0^r r^2 = A \cdot 2\pi \frac{r^3}{3} = I_{\text{enc}}$$

$$\rightarrow \frac{I_{\text{enc}}}{A_{\text{enc}}} = \frac{I_T}{A_T} \Rightarrow I_{\text{enc}} = \frac{I_T \cdot A_{\text{enc}}}{A_T}$$



$$\Rightarrow \oint \vec{B} \cdot d\vec{l} = \mu_0 \cdot I_{enc}$$

$$B = \frac{\mu_0 \cdot I_{enc}}{2\pi r} = \frac{\mu_0 \cdot A / 2\pi \frac{r^3}{3}}{2\pi r} = \frac{\mu_0 \cdot Ar^2}{3}$$

\* Con Región  $R < r < 2R$  ( $I_0 = I_{enc}$ )

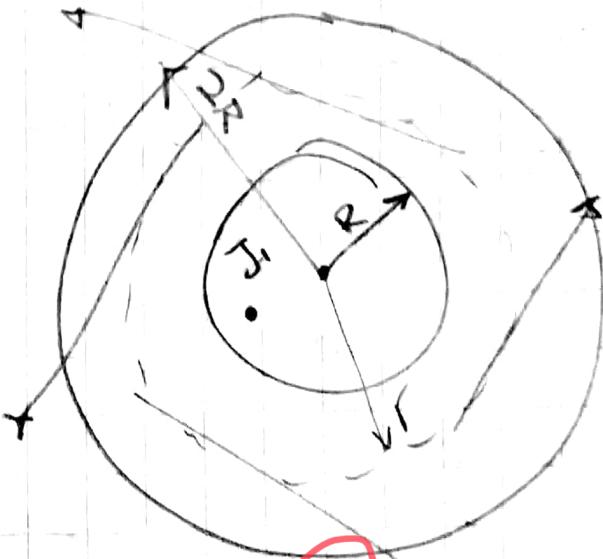
$$\oint \vec{B} \cdot d\vec{l} = \mu_0 \cdot I_{enc}$$

$I_{enc}$ :

$$\Rightarrow I_{enc} = \iint j_l \cdot ds$$

$$\Rightarrow \iint_A r^2 \cdot ds = I_{enc}$$

$$\Rightarrow A \int_0^{r_2} r^2 \int_0^{2\pi} ds = A 2\pi \int_0^{r_2} r^2 \rightarrow A \cdot 2\pi \cdot \frac{r^3}{3}$$



$$\Rightarrow \int \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{enc}} \quad | \quad I_0 = I_{\text{enc}}$$

$$\Rightarrow B = \frac{\mu_0 \cdot I_{\text{enc}}}{dl} = \mu_0 \cdot A \frac{2\pi r^{\frac{2}{3}}}{2\pi r} = \frac{\mu_0 A r^{\frac{2}{3}}}{r}$$

$$\Rightarrow B = \frac{\mu_0 A r^2}{3} \text{ (T)} \quad \text{X} \quad \text{as } r < b$$

region  $2R < r < 4R$

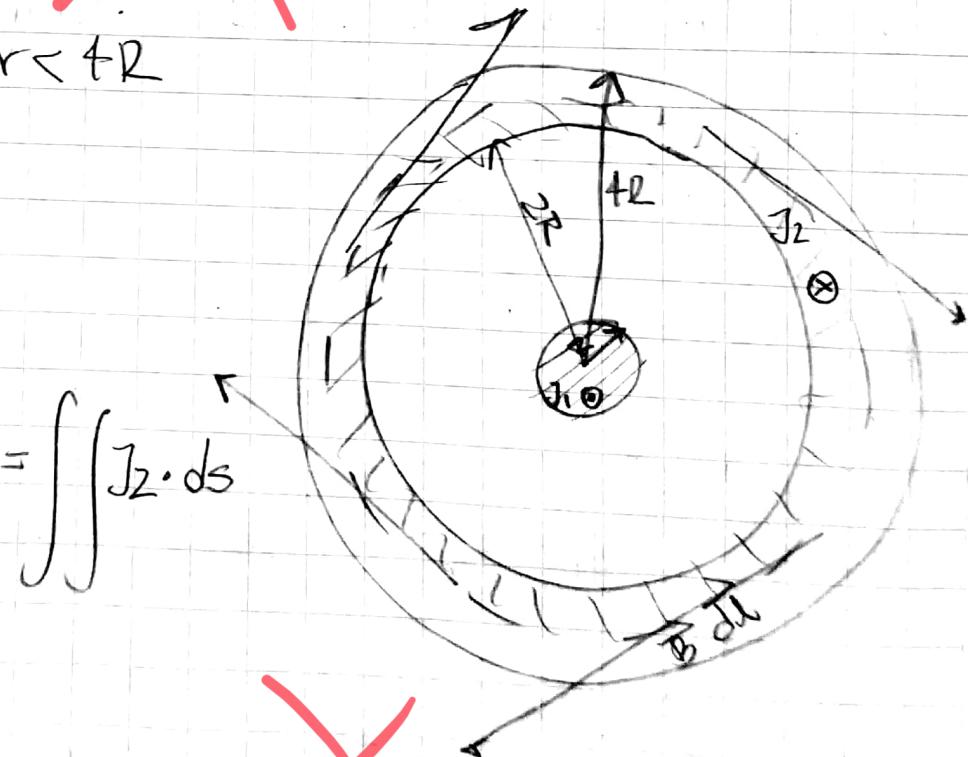
$I_{\text{enc}}$ :

$$J_2 = \frac{B}{r} - \hat{n}$$

$$J_2 \neq cte \rightarrow I_{\text{enc}} = \iint J_2 \cdot ds$$

$$\Rightarrow \iint \frac{B}{r} \cdot ds$$

$$\Rightarrow B \cdot 2\pi \int_0^r \frac{1}{r} dr = \boxed{B 2\pi \ln r = I_{\text{enc}}}$$



$$I_{\text{TOTAL}} = I_0 - I_\infty \Rightarrow I_{\text{TOTAL}} = A_2 \frac{\pi r^3}{3} - B_2 \mu \ln |r|$$

Luego

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 \cdot I_{\text{enc}} \Rightarrow B = \frac{\mu_0 I_{\text{enc}}}{dl}$$

$$\Rightarrow B = \frac{\mu_0 \cdot B_2 \mu \ln |r|}{2\pi r} = \frac{\mu_0 B \ln |r| (+)}{r}$$

Luego

$$I_0 = I_{\text{enc}} \Rightarrow I_0 = B 2\pi \ln |r|$$

$$\Rightarrow B = \frac{I_0}{2\pi \ln |r|}$$

Luego volviendo a  $R < r < 2R$

$$\rightarrow I_0 = I_{\text{enc}}$$

$$\Rightarrow I_0 = A_2 \frac{\pi r^3}{3}$$

$$3I_0 = A_2 \pi r^3$$

$$A = \frac{3I_0}{2\pi r^3}$$

(B) lungo  $\vec{B}_p$ , region  $r = 3R$

$$\oint \vec{B}_p \cdot d\ell = \mu_0 \cdot I_{enc}$$

$$J_2 \neq \text{cte} \Rightarrow I_{enc} = \iint J_2 \cdot ds$$

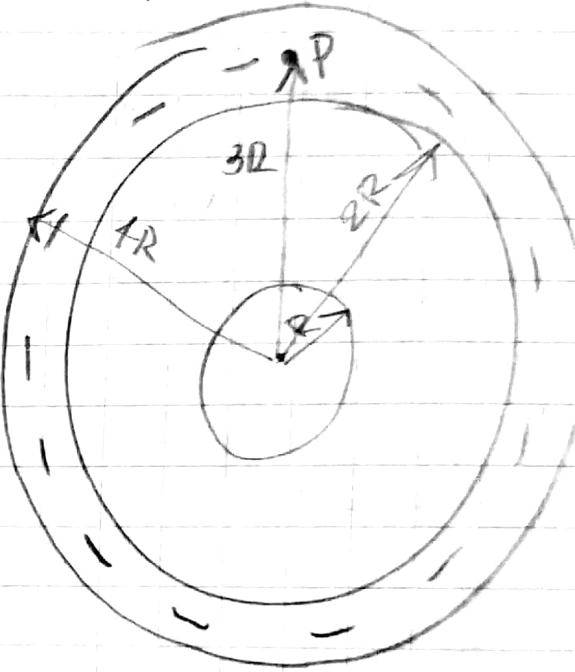
$$\Rightarrow \iint \frac{B}{r} ds \Rightarrow B 2\pi \int_0^r \frac{dr}{r}$$

$$\Rightarrow I_{enc} = B 2\pi \ln|r|$$

$$I_T = I_1 - I_2$$

$$I_1 = I_{enc} \text{ de } J_1$$

$$I_{Total} = A \frac{2\pi r^3}{3} - B 2\pi \ln|r|$$



Luego:

$$\Rightarrow \int B_p \, dl = \mu_0 \cdot F_{\text{ene}}$$

$$q. B_p = \frac{\mu_0 \cdot F_{\text{ene}}}{dl}$$

$$\Rightarrow B_p = \frac{\mu_0}{6\pi R} \left[ \frac{A z \pi r^3}{3} - 2B \pi \ln|r| \right]$$



# Problema 1

05 August 2020

Formula

$$a) B_1 = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{l} \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3}$$

i) Vect. posi.

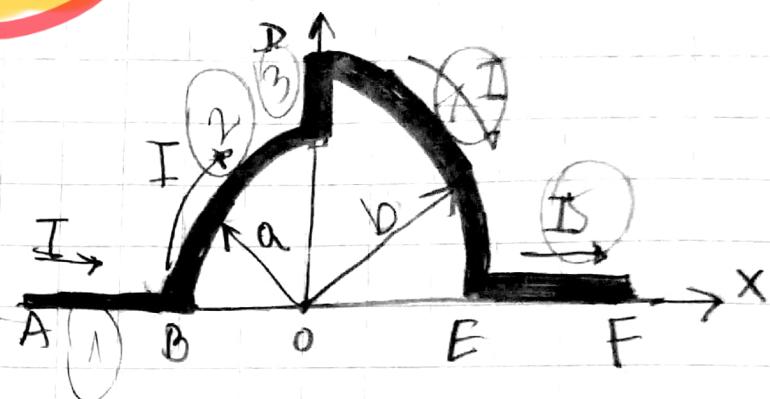
$$\begin{aligned} \vec{r} &= \vec{OC} + \vec{CP} \\ &= -x\hat{i} \quad \left. \right\} -x\hat{i} \\ \vec{r}' &= -x\hat{i} \quad \cancel{\left. \right\}} \end{aligned}$$

$$|\vec{r} - \vec{r}'| = (x^2)^{3/2}$$

$$c) d\vec{l} = dx\hat{i}$$

$$B_1 = \frac{\mu_0 I}{4\pi} \int \frac{dx\hat{i} \times (-x\hat{i})}{(x^2)^{3/2}} = 0$$

$$\vec{B}_2 = \frac{\mu_0 I}{4\pi} \int d\vec{l} \times (\vec{r} - \vec{r}')$$



i) Vector pos.

$$\vec{r} = 0$$

$$\vec{r}' = a \cos \theta \hat{i} + a \sin \theta \hat{j}$$

$$|\vec{r} - \vec{r}'| = -a \cos \theta \hat{i} - a \sin \theta \hat{j}$$

$$= -a \omega t \cos \theta \hat{i} + \sin \theta \hat{j}$$

$$a = a$$

3

→ *decreasing*

ii)  $d\ell = ad\theta$

$$d\vec{\ell} = ad\theta = (\cos(\theta - \pi/2) \hat{i} - \sin(\theta - \pi/2) \hat{j})$$

$$d\vec{\ell} = ad\theta (\sin \theta \hat{i} - \cos \theta \hat{j})$$

$$\begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a \sin \theta d\theta & -a \cos \theta d\theta & 0 \\ -a \cos \theta & -a \sin \theta & 0 \end{vmatrix} \Rightarrow \begin{aligned} \hat{k} & (-a \sin^2 \theta d\theta - a \cos^2 \theta d\theta) \\ & \Rightarrow -a^2 d\theta \hat{k} \end{aligned}$$

hiergo

$$\vec{B}_2 = \frac{\mu_0 I}{4\pi} \left[ -\frac{d\vec{d}\hat{n}}{a^3} \right] \frac{-\mu_0 I \hat{k}}{4\pi a} \left[ \pi - \frac{\pi}{2} \right]$$

$\frac{\pi}{2}$

$$\Rightarrow -\frac{\mu_0 I}{8a} \hat{k}(T)$$

3

c)  $\vec{B}_3 = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{l} \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3}$

i) Vector pos.

$$\vec{r} = 0 \quad (\vec{r} - \vec{r}') = y \hat{j}$$

$$\vec{r}' = y \hat{j}$$

ii)  $d\vec{l} = dy \hat{j}$

hiergo =  $0 < y \leq v$

3

$$B_3 = \frac{\mu_0 I}{4\pi} \int_b^c \frac{dy \uparrow \times (l - y \uparrow)}{y^3} = 0$$

$B_3$  igual que  $B_2$  con signo contrario:

$$B_3 = 0.$$

3

$B_T$

vector posic.

$$\rightarrow r = o\hat{x} + o\hat{y}$$

3  
deformado

$$\vec{r} = b(\cos \theta \hat{x} + \sin \theta \hat{y})$$

$$|\vec{r} - \vec{r'}| = \sqrt{-b \cos \theta \hat{x} - b \sin \theta \hat{y}}$$

$$a = b^3$$

$$i) dL = b \Rightarrow (\sin \theta \hat{x} - \cos \theta \hat{y}) = dL = \vec{J}L \times \vec{r} - \vec{r'}$$

$r$	$\hat{x}$	$\hat{y}$	$\Rightarrow -\left(2b^2\right) \hat{k}$
$b \sin \theta \hat{x}$	$-b \cos \theta \hat{y}$	$0$	$\hat{d}\theta$
$-b \cos \theta \hat{x}$	$-b \sin \theta \hat{y}$	$0$	

$$B_4 = \frac{\mu_0 I}{4\pi} \int_{-\frac{2b^2 k}{b^3}}^{\frac{\pi}{2}} d\hat{k} \Rightarrow \frac{-2\mu_0 I}{4\pi b} \int_0^{\frac{\pi}{2}} d\hat{k} \alpha(\hat{k})$$

$$\Rightarrow \frac{-\mu_0 I}{4b} R(\tau) \quad \cancel{R(\tau)} \quad \cancel{I}$$