```
??
                                     M\ddot{U}(t)+C\dot{U}(t)+KU(t)=F(t)
                (1)
??
                                      U(0) = {}^{0}U\dot{U}(0) = {}^{0}\dot{U}
                                                                      ??\beta?\theta???
                                                                      ??M, C, KF(t)tU(t)(\cdot)\dot{U}(t), \ddot{U}(t)
                                     \dot{U}(t) = V(t)??
                                     \dot{U}(t)\dot{V}(t) = \mathbf{0}\mathbf{I} - M^{-1}K - M^{-1}CU(t)V(t) + \mathbf{0}M^{-1}F(t)
                                     U(0) = {}^{0}UV(0) = {}^{0}\dot{U}
                                    {\bf ^{'}OI^{1}????}
                                     \ddot{u}(t) + 2\xi\omega\dot{u}(t) + \omega^2 u(t) = f(t)

\begin{array}{c}
(5) \\
\xi, \omega f(t) u(t) \\
?
\end{array}

\begin{cases}
\dot{y}_1(t) = \lambda_2 y_1(t) + f(t)\dot{y}_2(t) = \lambda_1 y_2(t) + f(t) \\
\lambda_{1,2} = -\xi \omega \pm j\sqrt{1 - \xi^2}\omega
\end{cases}

   (7)
j = \underbrace{\sqrt{-10}}_{\xi < 10} \le \underbrace{1u(t)y_1(t), y_2(t)}_{\xi < 10}
(4) = \dot{u}(t) - \underbrace{1}_{\xi < 10} = \dot{u}(t) - \underbrace{1}_{\xi < 10}
                  (8) \{ y_1(t) = \dot{u}(t) - \lambda_1 u(t) y_2(t) = \dot{u}(t) - \lambda_2 u(t) \}
                                     u(t) = -\frac{y_1(t) - y_2(t)}{\lambda_1 - \lambda_2}
                                      \lambda_{1,2}y_{1,2}(t)u(t)
                                     y(t_0) = 0
        \dot{y}(t) = f(y, t)
(10)
                                     t \in [0,T][0,T]
                                     [0,T] = \bigcup_{n=0}^{N-1} [t_n, t_{n+1}]

\begin{array}{c}
\Delta t = \\
t_{n+1} - \\
t_n t_n t_{n+1} \\
??k?
\end{array}

                                     \alpha_0^{t+\Delta t}y + \alpha_1^{t}y + \dots + \alpha_k^{t+(1-k)\Delta t}y = \Delta t[\beta_0 f(t^{t+\Delta t}y, t_{n+1} + \beta_1 f(t^{t}y, t_n) + \dots + \beta_k f(t^{t+(1-k)\Delta t}y, t_{n+1-k})]
          (12)
       \sum_{i=0}^{k} \{\alpha_i^{t+(1-i)\Delta t} y + \Delta t \beta_i f(t^{t+(1-i)\Delta t} y, t_{n+1-i})\} = 0
(13)
         \ddot{y} = f(\dot{y}(t), y(t), t) = g_0 y(t) + g_1 \dot{y}(t) + h(t)
(14)
```

 $^{n+1/2}y =$

```
t + \Delta t \ddot{U} t +
                                                                                                    ^{\Delta t}_{^{t+\Delta t}\! \ddot{U} \overset{.}{\div}}
                                                                                                        C^{t+\Delta t}\!\widetilde{\dot{U}}+

\begin{array}{l}
C^{t+\Delta t}U + \\
K^{t+\Delta t}\tilde{U} = \\
t^{t+\Delta t}\tilde{U} = \\
t^{t+\Delta t}\dot{U} = \\
t^{t+\Delta 

\begin{aligned}
t + \Delta t & U = t\dot{U} + \\
(2\theta_1 - \frac{3}{2}) t \ddot{U} \Delta t + \\
(\frac{3}{2} - \theta_1)^{t + \Delta t} \ddot{U} \Delta t \\
t + \Delta t \tilde{U} & = t \\
t & T + 
\end{aligned}

\begin{aligned}
t & \stackrel{t+\Delta t}{U} = \\
t & \stackrel{t}{U} + \\
\theta_1 & \stackrel{t}{U} \Delta t + \\
\frac{1}{4} & (2 - \\
\frac{1}{\theta_1^2}) & \stackrel{t}{U} \Delta t^2 + \\
\end{aligned}

                                                                                                                \frac{1}{4\theta_1^2}t + \Delta t\ddot{U}\Delta t^2

\begin{array}{ccc}
4\theta_1^2 & \overleftarrow{\Box} & \overleftarrow{\Box} \\
t + \Delta t \widetilde{\overrightarrow{U}} & t + \Delta t \widetilde{\overrightarrow{U}} & t + \Delta t \widetilde{\overrightarrow{U}} \\
t + \Delta t \overrightarrow{U} & = & \overleftarrow{\Box}
\end{array}

\begin{array}{l}
t + \Delta t U = t \dot{U} + t
                                                                                                         \theta_1^{(2)} t + \Delta t \ddot{U} \Delta t 
 t + \Delta t U = 
                                                                                                    \frac{1}{4\theta_1^2} t \ddot{U} \Delta t^2
                                                                                                                                                                                                                 \theta_1
                                                                                                ?
??a
                                                                                                        (90)^{\underbrace{t+\Delta t}_{t-1}}U =
                                                                                                        \lambda_2^t \ddot{U} \Delta t^2 +
                                                                                                        \lambda_3 \Delta \ddot{U} \Delta t^2
t + \Delta t \dot{U} =
                                                                       \begin{array}{l} \lambda_{3}\Delta\psi \Delta t \\ t+\Delta t\dot{U} = \\ \dot{t}\dot{U} + \\ \lambda_{4}{}^{t}\dot{U}\Delta t + \\ \lambda_{5}\Delta\dot{U}\Delta t \\ t+\Delta t\dot{U} = \\ \dot{U} + \\ \Delta U \\ \dagger \\ \Delta I = \\ \lambda_{i}, i = \\ \lambda_{i}, i = \\ 1, 2, \cdots, 5 \\ \dagger \\ \dagger \\ t+\Delta t\dot{U} = \\ \dot{t}\dot{U} + \\ \dot{U} + \\
                                                                                                    t\dot{U} + \Delta t\ddot{U} + \Delta t\ddot{U}
                                                                                                \frac{\Delta t^2}{t^2} t + \Delta t U
t + \Delta t \dot{U} = \frac{3}{2\Delta t} t + \Delta t U - \frac{2}{\Delta t} U + \frac{1}{2\Delta t} U + \frac{1}{2\Delta t} t - \Delta t U
t + \frac{1}{2\Delta t} \Delta t ??
                                                                                                        M^{t+\Delta t} \ddot{U} + C^{t+\Delta t} \dot{U} + K^{t+\Delta t} U = {}^{t+\Delta t} F
                                                                                                        \overset{\prime}{U}\dot{U} = \frac{3}{2\Delta t}(^{\Delta t}U - ^0\!U) - \frac{1}{2}{}^0\dot{U} + \frac{\Delta t}{4}{}^0\ddot{U}
(92)?\beta =
```