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double getSensor(String sonars, int curr_x, int curr_y) {
    int match = 0;
    for (int y = 1; y < mundo.height - 1; y++) {
        for (int x = 1; x < mundo.width - 1; x++) {
            if (x == curr_x && y == curr_y) {
                if (mundo.grid[x][y - 1] == Integer.parseInt(Character.toString(sonars.charAt(0)))) {
                    ++match;
                }
                if (mundo.grid[x][y + 1] == Integer.parseInt(Character.toString(sonars.charAt(1)))) {
                    ++match;
                }
                if (mundo.grid[x + 1][y] == Integer.parseInt(Character.toString(sonars.charAt(2)))) {
                    ++match;
                }
                if (mundo.grid[x - 1][y] == Integer.parseInt(Character.toString(sonars.charAt(3)))) {
                    ++match;
                }
            }
            break;
        }
    }

    double result = Math.pow(sensorAccuracy, match) * Math.pow((1 - sensorAccuracy), (4 - match));
    return result;
}

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double getTransition(int action, int curr) {

    if (action == curr) {
        // Pm
        return moveProb;
    }
    return (1 - moveProb) / 4;
}

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void updateProbabilities(int action, String sonars) {
    // your code

    double sum = 0.0;
    double[][] newProbs = new double[mundo.height][mundo.width];
    for (int y = 0; y < mundo.height; y++) {
        for (int x = 0; x < mundo.width; x++) {
            newProbs[x][y] = 0.0;
        }
    }

    // Transition model
    for (int y = 1; y < mundo.height - 1; y++) {
        for (int x = 1; x < mundo.width - 1; x++) {

            if (probs[x][y] != 0.0) {
                newProbs[x][y] += getTransition(action, STAY) * probs[x][y];
            }
            if (probs[x][y-1] != 0.0) {
                newProbs[x][y - 1] += getTransition(action, NORTH) * probs[x][y];
            }
            if (probs[x][y+1] != 0.0) {
                newProbs[x][y + 1] += getTransition(action, SOUTH) * probs[x][y];
            }
            if (probs[x-1][y] != 0.0) {
                newProbs[x - 1][y] += getTransition(action, WEST) * probs[x][y];
            }
            if (probs[x+1][y] != 0.0) {
                newProbs[x + 1][y] += getTransition(action, EAST) * probs[x][y];
            }
        }
    }
}

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    }
}

// Sensor Model
for (int y = 1; y < mundo.height - 1; y++) {
    for (int x = 1; x < mundo.width - 1; x++) {
        newProbs[x][y] *= getSensor(sonars, x, y);
        sum += newProbs[x][y];
    }
}

double test = 0.0;
for (int y = 0; y < mundo.height; y++) {
    for (int x = 0; x < mundo.width; x++) {
        newProbs[x][y] = newProbs[x][y] / sum;
        test += newProbs[x][y];
    }
}

for (int y = 0; y < mundo.height; y++) {
    for (int x = 0; x < mundo.width; x++) {
        probs[x][y] = newProbs[x][y];
    }
}

myMaps.updateProbs(probs); // call this function after updating your probabilities so that the
                           // new probabilities will show up in the probability map on the GUI
}

```

I think that better understanding how transition model works would help me make progress on this lab faster. Other than that, I think everything was clear.