

## **PROFIBUS**



#### ⇒ What a fieldbus system needs to offer

- ✓ deterministic (since parallel wiring will be replaced)
- √ flexible
- √ interoperable (multi-vendor use)
- ✓ cost effective (installation, startup, service)
- ✓ reliable and safe
- √ easy to use

#### **⇒** standardization









#### **EN 50170 Volume 2**

**General Purpose Automation** 

PROFIBUS-FMS RS 485 / FO

Universal

- Large variety of applications
- Multi-master communication

**Factory Automation** 

PROFIBUS-DP RS 485 / FO

**Fast** 

- Plug and play
- Efficient and cost effective

**Process Automation** 

**PROFIBUS-PA** 

**IEC 1158-2** 

**Application Oriented** 

- Powering over the bus
- Intrinsic safety

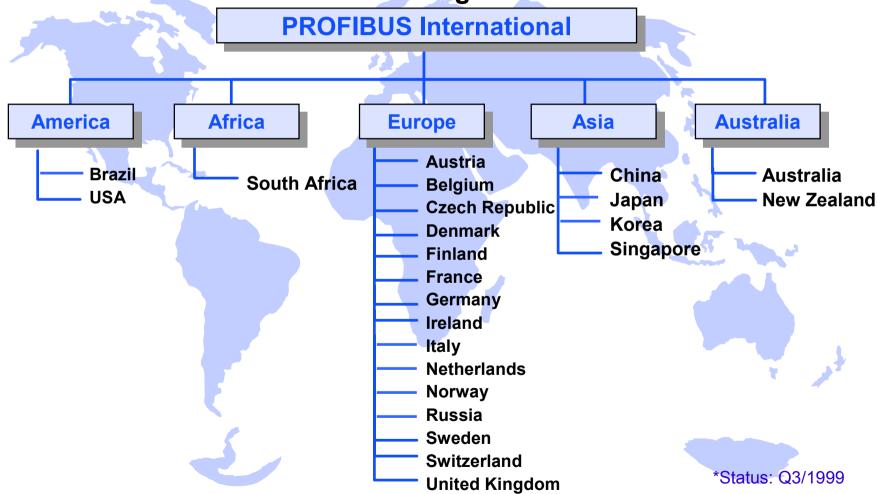




# INTERNATIONAL



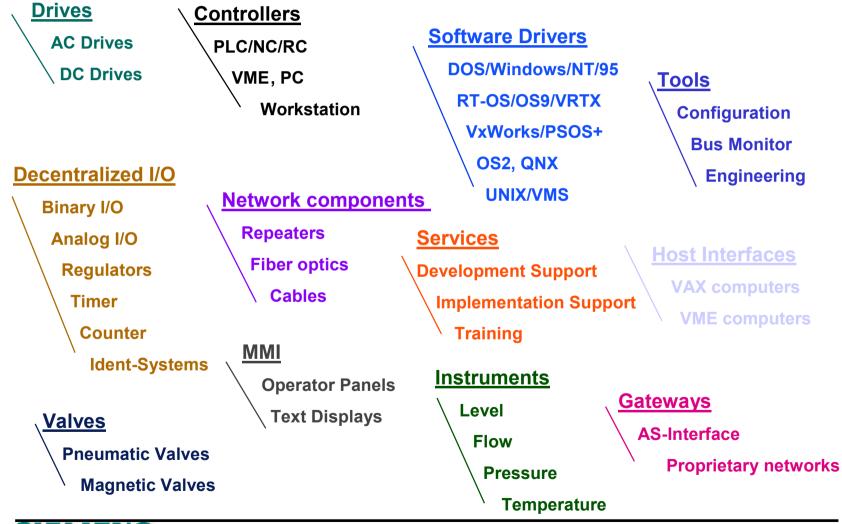
⇒ More than 900 members - 23 regional user associations





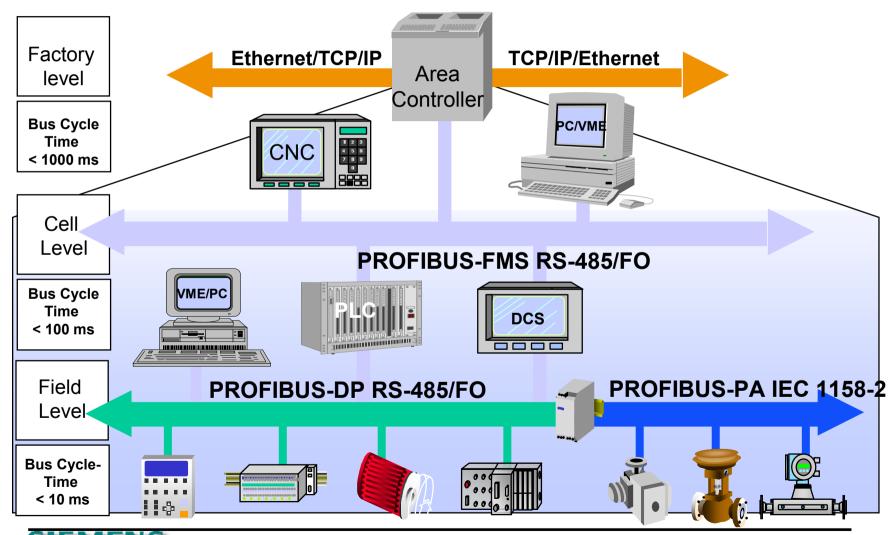
# PRODUCT Variety









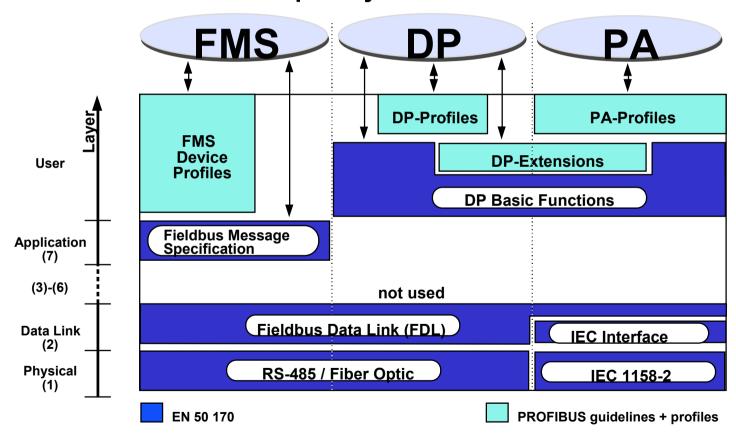




## EN 50170 - 2



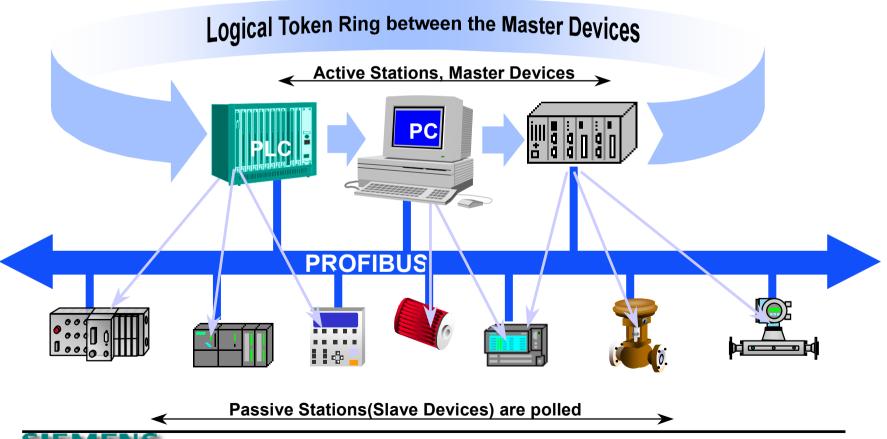
⇒ The PROFIBUS Protocol is in Accordance with the ISO/OSI Reference Model for Open Systems







□ The PROFIBUS Bus Access Method combines
 Multi-Master and Master-Slave communications







- ⇒ the PROFIBUS Bus Access Protocol (Layer 2) is identical for all three PROFIBUS variations
- ⇒ this enables transparent communication and easy combinations of FMS/DP/PA Network sections
- ⇒ Because FMS/DP use the same Physical Media (RS-485/FO), they can be combined on the same cable









#### **⇒** Hybrid Bus Access Protocol

✓ Token-Passing between Masters
Master - Slave Protocol between Master and Slaves

#### **⇒** Master

✓ active stations with the right to control the bus for a limited amount of time (Token - Hold - Time)

#### **⇒** Slave

✓ Slaves only respond on request of a Master they have no rights to control the bus







- ✓ in Multi-Master Networks, the Token Passing procedure must ensure that each master has enough time to fulfill its communication tasks
- ✓ the user therefore configures the overall Target Token Rotation Time (TTR) taking into account the communication tasks of all masters
- ✓ each Master calculates the available amount of time for its communication tasks at token receipt according to the following rule:

TTH = Token Hold Time

TTR = Target Token Rotation Time

TRR = Real Token Rotation Time

TTH = TTR - TRR





# FMS, DP, PA



- ⇒ FMS stands for Fieldbus Messaging System
  - ✓ peer to peer communication
- **⇒** DP stands for Decentralized Periphery
  - √ fast data exchange
- **⇒ PA stands for Process Automation** 
  - ✓ intrinsically safe environment



# FMS/DP In Common



- ⇒ DP and FMS are based on same Layer 1 and 2:
  - ✓ DP and FMS can be operated on the same bus
  - ✓ Message header and data length are identical
  - ✓ The bus physics are identical
- ⇒ One master can service several slaves
- ⇒ Several masters can participate on the bus
- ⇒ Baudrates from 9.6 kBd up to 12 MBd are possible





# FMS/DP In Common



- ⇒ Data transmission can be between 1 and 244 bytes
- ⇒ 126 stations can be connected
- ⇒ System can consist of several segments
- ⇒ 32 stations (RS 485 drivers) per segment
- **⇒** Common components
  - ✓ Cabling, connectors, repeater, fibre optic
- **⇒** Savings in maintenance and spare parts inventory





## PA/DP In Common



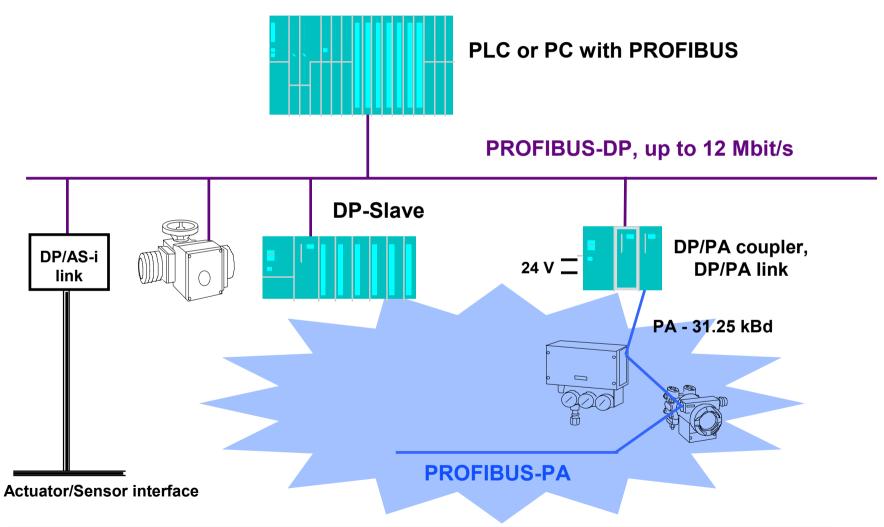
- ⇒ DP and PA are based on the same protocol definition - DP/V1 (extended DP)
  - ✓ DP and PA can use the same master systems
  - ✓ Message header and data length are identical
  - ✓ Configuration tools are the same
  - ✓ Data transmission can be between 1 and 244 bytes





# PA/DP In Common







## FMS Features



- ⇒ FMS is optimized for universal, object oriented communication of intelligent master devices at the cell level
- ⇒ FMS permits a subset of the MMS-Functions (Manufacturing Message Specification, ISO 9506)
- ⇒ A slave can be assigned to several masters
  - ✓ Several masters can write to the same slave
- Communication connections can be temporary or permanent





#### FMS Services

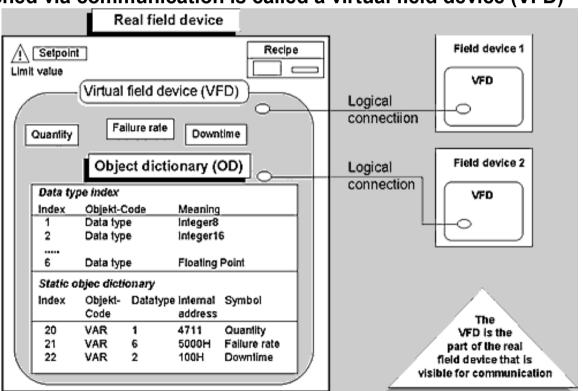


- ⇒ The FMS application layer (7) consists of the following parts:
  - ✓ The Fieldbus Message Specification (FMS) and
  - ✓ the Lower Layer Interface (LLI)
- ⇒ FMS services are a subset of the MMS services
  (MMS=Manufacturing Message Specification, ISO 9506)
  - ✓ have been optimized for field bus applications and have been expanded by functions for communication object administration and network management



# FMS Services virtual field device (VFD).

- ⇒ The PROFIBUS-FMS communication model permits distributed application processes to be unified into a common process by using communication relationships.
  - ✓ The portion of an application process in a field device which can be reached via communication is called a virtual field device (VFD)



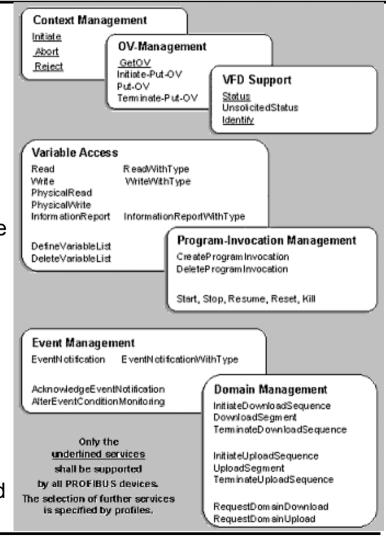




#### FMS Services



- ⇒Context Management services are for establishing and terminating logical connections.
- ⇒ Variable Access services are used to access variables, records, arrays or variable lists.
- ⇒**Domain Management** services are used to transmit large memory areas. The data must be divided into segments by the user.
- ⇒ Program Invocation Management services are used for program control.
- ⇒Event Management services are used to transmit alarm messages. These messages can also be sent as broadcast or multicast transmissions.
- ⇒VFD Support services are used for identification and status polling. They can also be sent spontaneously at the request of a device as multicast or broadcast transmissions.
- ⇒**OD** Management services are used for read and write access to the object dictionary.



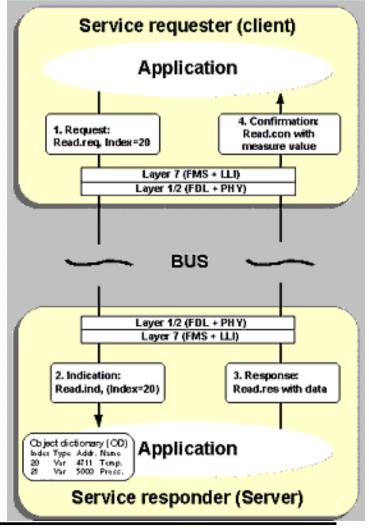




## FMS Services



- □ Confirmed services can only be used for connection-oriented communication relationships. The execution of a service is shown in Figure
- ➡ Unconfirmed services can also be used on connectionless communication relationships (broadcast and multicast). They can be transmitted with high or low priority.



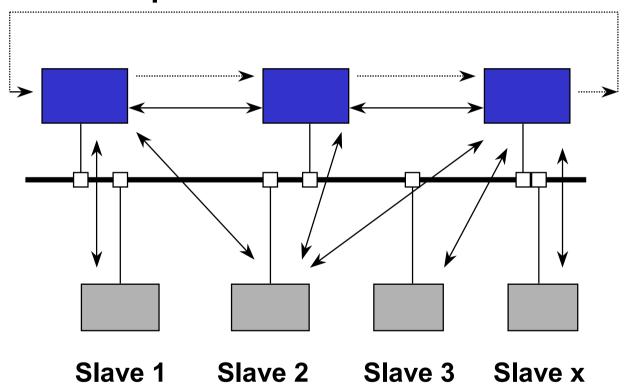




## FMS Features



## **⇒ FMS** access procedure







## PA Features



- ⇒ Based on the extended PROFIBUS-DP Protocol and IEC 1158-2 Transmission
  - ✓ Suitable to replace today's 4...20 mA Technology
  - ✓ Only two wires for data and power
  - ✓ Connects Instruments to the control system via a serial bus
  - ✓ Functional improvements plus reliable serial digital transmission
  - ✓ Control, regulation and monitoring via a simple twisted pair cable
  - ✓ A single engineering tool for all devices

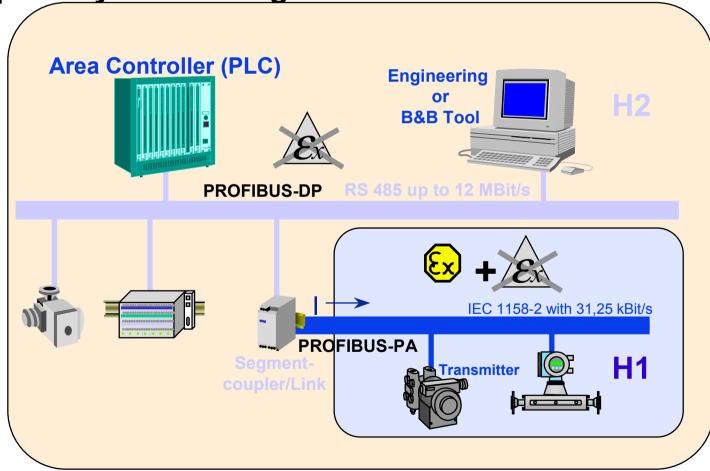




## PA Features



**Typical System Configuration with PROFIBUS-PA** 





## DP Features



- **⇒** DP communication is permanent and cyclic
- ⇒ the transmitted data is specified during the configuration (optimized data exchange)
- ⇒ only one master can write outputs (safety aspect)
- ⇒ data can be read by controlling and Class 2 master
- ⇒ acyclic data via DPV1 functions
- ⇒ alarm acknowledgment
- ⇒ fastest fieldbus system (up to 12 MBaud)
- ⇒ up to 244 byte input AND 244 byte output data per station

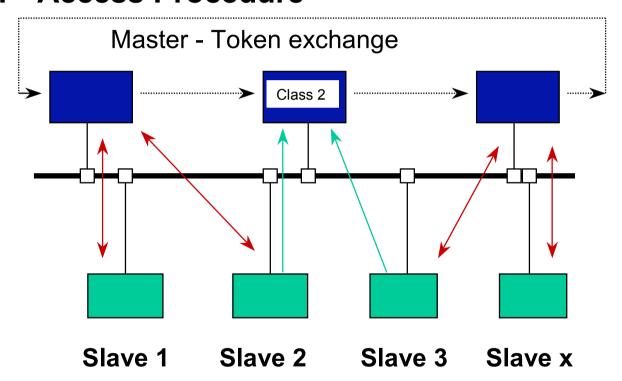




## **DP** Features



#### **⇒ DP- Access Procedure**





# Reliability-DP/FMS



- ⇒ Hamming Distance HD = 4
- ⇒ HD 4 means, that up to 3 transmission failures at a time can be detected (done by the ASICs)
  - ✓ By detecting a faulty telegram, it will be resent automatically without affecting other existing stations
- ⇒ HD 4 is a term used to describe the reliability of the data transmission on the Profibus network.
  - ✓ Special Start and End Sentinels
  - ✓ Parity Bit for Each Byte
  - ✓ Slip Free
  - ✓ According to IEC 870-5-1
  - ✓ Delimiter Synchronization







- ⇒ PROFIBUS DP/FMS wiring can be done with:
  - ✓ twisted shielded pair copper cable
  - √ fiber optic components
  - √ infrared components
- ⇒ detailed installation guideline is available PTO order no. 2.112







#### **⇒** twisted shielded pair cable

- ✓ line parameters are defined in EN 50170
- ✓ standard cable available from Belden and Siemens
- √ standard connectors available

Baudrate	Max. Segment length	Max. Expansion
9.6	1000m / 3278feet	10,000m / 32786feet
19.2	1000m / 3278feet	10,000m / 32786feet
93.75	1000m / 3278feet	10,000m / 32786feet
187.5	1000m / 3278feet	10,000m / 32786feet
500.0	400m / 1311feet	4,000m / 13114feet
1,500.0	200m / 655feet	2,000m / 6557feet
3,000.0	100m / 327feet	1,000m / 3270feet
6,000.0	100m / 327feet	1,000m / 3270feet
12,000.0	100m / 327feet	1,000m / 3270feet

max. expansion is done with 9 repeaters in a row







#### **⇒** fiber optic components

- ✓ plastic and glass fiber optic is available
- ✓ optical plugs and modules are available

- noise immune
- **potential difference independent**
- longer distances (up to 20 miles)
- redundant operating is possible
- line, ring and star configuration







#### **⇒** infrared components

- ✓ wireless linking of devices in close-up ranges
- ✓ communication with moving devices
- ✓ communication with changing devices
- √ noise immune
- ✓ ground independent

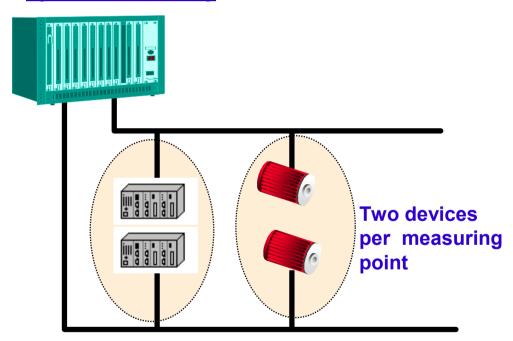




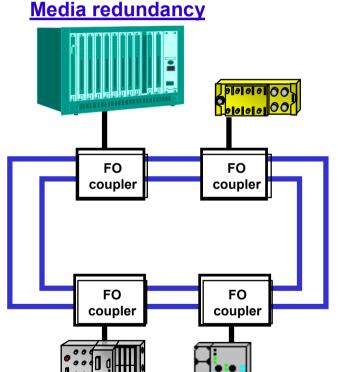


#### ⇒ Redundancy Improves System Reliability

#### **System redundancy**



Several interfaces enable redundant systems



Fiber optic segments enable redundant wiring







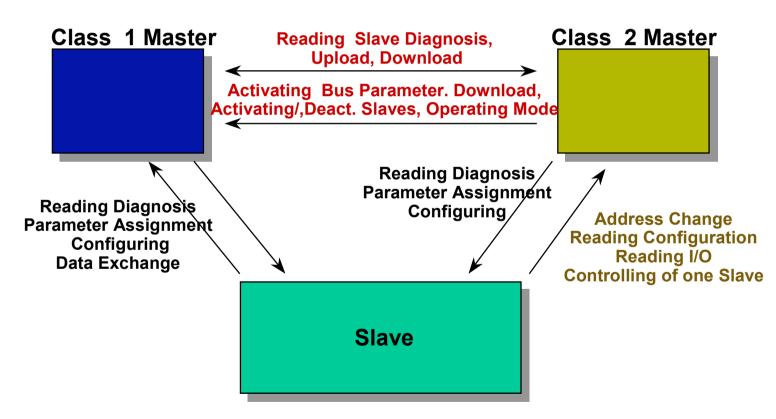
- ⇒ class 1 master -
  - ✓ central controller which exchanges data with the connected I/O devices (slaves)
  - ✓ determines the baudrate
  - √ handles the Token
  - ✓ several class1 masters are permitted, typical devices are PLC, PC
- ⇒ class 2 master -
  - ✓ diagnostic and startup tool, typically a configuration tool
  - √ can control one slave at a time
- ⇒ slave station -
  - ✓ passive station which acknowledges messages or answers per request







#### ⇒ master- master, master- slave communication



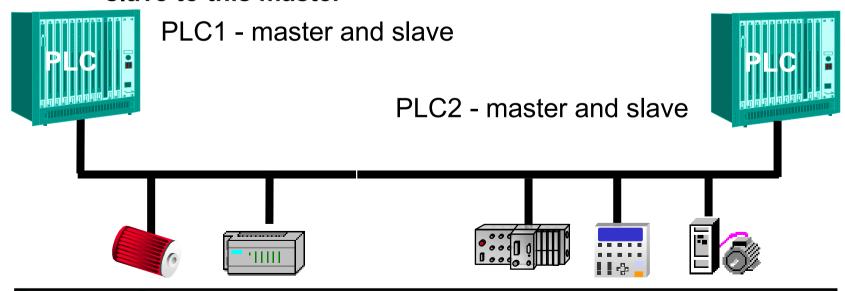
a device can consist of multiple functions, e.g... class1 and class2, class1 and slave







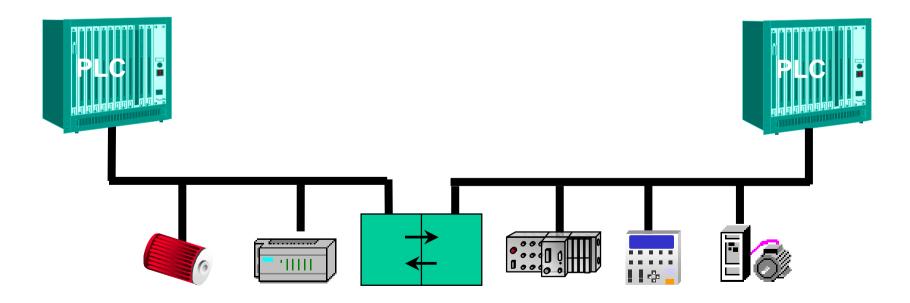
- ⇒ A device can consist of multiple functions, e.g... class1
  and class2, class1 and slave, which allows:
  - ✓ a simple master master communication via the master slave combination
  - ✓ whenever one master has the token the other PLC can be a slave to this master







- ⇒ Master Master communication by using a DP-DP gateway
  - ✓ combination of two mono master systems
  - ✓ simple data exchange between the two masters up to 244 byte



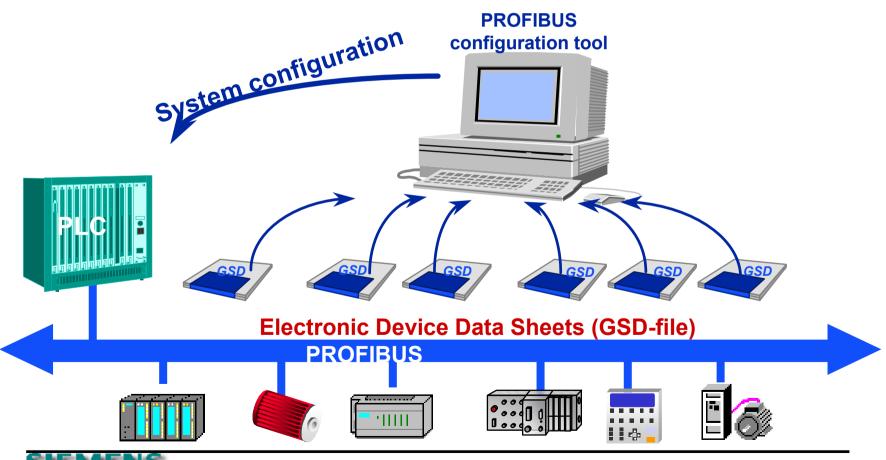




# Interoperability



#### **⇒** Open Configuration permits Plug and Play





#### Device Description



#### **⇔** GSD file

- ✓ each slave or master class 1 device on PROFIBUS DP needs to have a device description file, the characteristic of each PROFIBUS-DP device is described in the GSD-File
- ✓ the GSD-file contains all device specific parameters e.g.:
  - × Supported Baudrate
  - Supported Message Length
  - Number of input / output data
  - Meaning of diagnostic messages
  - Options for modular devices e.g. which are available
- √ text file (ASCII-format)
- ✓ each configuration tool relates to the GSD information





#### Device Description



- ✓ GSD-Files are created by the device vendors
- ✓ the PROFIBUS Trade Organization provides an GSD-Editor which makes it very easy to create GSD-Files
- ✓ the GSD-Editor contains a GSD-Checker which guarantees
  the conformance of the GSD-Files to the PROFIBUS
  standard
- ✓ a library of GSD-Files is provided at the PROFIBUS web page: http://www.profibus.com





#### Device Description



#Profibus_DP	(M)	
:< P R M -T e x t_ D e f_ L is t>	(0)	
Prm Text =		Parameter text (O)
 F n d D nm T F v/4		
E n d P rm T E x t	1	
; <ext-user_prm_data_def_list></ext-user_prm_data_def_list>	(0)	
ExtUserPrm Data =		A system and the system of the
		ext. user parameter data (O)
E n d E x t U s e r P r m D a t a	1	
; <unit_definition_list></unit_definition_list>	(M)	
GSD_Revision=1		mandatary gaparal data (M)
Vendor_Name=		mandatory general data (M)
	†	
;Slave specific data	(M)	
Freeze_mode_supported=		apparia alaya data (M)
		generic slave data (M)
	<b>-</b>	
;U ser_ P rm _ data	1	
;U n it_ d ia g n o s tic	+	device related slave data (O)
<u> </u>	1	
		J
;< M odule _ D e finition _ List	(M)	
Module =	T /	✓ I/O definition (M)
E n d M o d u le		



#### **DP** Interactions



#### DP Extended

- ⇒ Why DP extended?
  - ✓ the requirements of the process industry are included
  - ✓ selecting and changing parameters of a field device from several DP-Masters, e.g., CPU, PG or HMI Devices
    - × provides for higher flexibility in operation
  - ✓ Interrupts from Field Devices, e.g.. for diagnostics, have to be accepted by the DP-Master
    - \* allows for greater security
  - ✓ time stamping of events, e.g., for interrupts, accurate history of special events
  - ✓ additional data formats are necessary for transmitting data, e.g., floating-point-radix





#### DP Extended



## New extended PROFIBUS-DP-Standard

#### **DP-Extension**

- Additional acyclic messages between Master and Slave by reading and writing of data blocks
- Acknowledgment of field device interrupts
- Time synchronization for an exact time stamping
- Extension of data types, floating-point-radix

**PROFIBUS-DP-Standard!** 

→ every station that handles the DP-extensions must meet the previous PROFIBUS-DP-Standard-Functions!





#### DP Extended



- ⇒ Acyclic communication connections between Class 1
   Master and Slave via Slave SAP 51
  - ✓ Read data set (DDLM\_Read)
  - ✓ Write data set (DDLM\_Write)
  - ✓ Acknowledge alarms (DDLM\_Alarm\_Ack)
  - ✓ Only the master that parameterized and configured the slave can utilize the SAP 51 for these services also
  - ✓ Alarm can only be acknowledged by the Class 1 Master via SAP 51 (access protection)





#### DP Extended

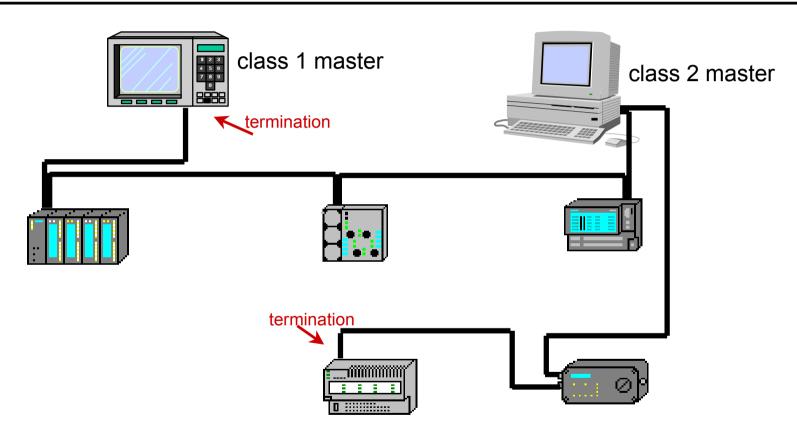


- ⇒ Acyclic communication relations between Class 2
  Master and Slave via SAP 0...49
  - ✓ Initiate (MSAC2\_Initiate) SAP 49
  - ✓ Abort (MSAC2\_Abort)
  - ✓ Read Data Set (MSAC2\_Read)
  - ✓ Write Data Set (MSAC2\_Write)
  - ✓ Data Transport (MSAC2\_Data\_Transport)



#### Network Setup









#### PROFES PIC certification



#### ⇒ How to certify a device!

- Vendor applies for an ID number from PROFIBUS International (PI) for his device
- Vendor develops the PROFIBUS device and writes a GSD file

# Applies for Certification test at any PROFIBUS Test Lab NO Test passed ? YES

Vendor receives two test reports and can apply for a certificate via PI



**CERTIFICATE** 







### Profibus & Ethernet



 ⇒ The PROFIBUS User Organization is currently working on the implementation of universal concepts for vertical integration on the basis of Ethernet TCP/IP

Physical Profiles	Communication Profiles	Application Profiles
Ethernet	Ag	PA (Process Automation)
RS-485	Deve looments	Encoder
IEC 1158-2	PROFInet	PROFIdrive (Motion Control)
Fiber Optics		PROFIsafe (Fail Safe)
	PROFIBUS EN 50170	





#### **PROFInet**



- ⇒ Automation object model according to the Microsoft COM/DCOM standard
- ⇒ Object handling in engineering and HMI: Microsoft OLE, ActiveX
- □ Integration of existing unchanged PROFIBUS bus segments and PROFIBUS based devices

