

Lecture Slides for

INTRODUCTION TO MACHINE LEARNING

3RD EDITION

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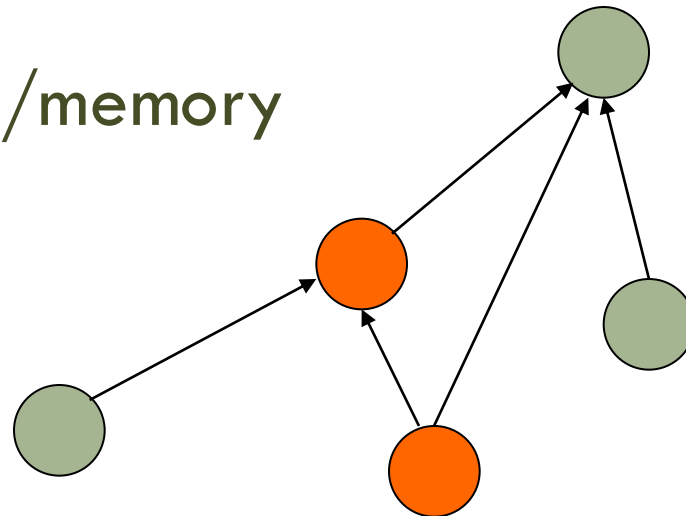
CHAPTER 11:

MULTILAYER PERCEPTRONS

Neural Networks

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- Networks of processing units (neurons) with connections (synapses) between them
- Large number of neurons: 10^{10}
- Large connectivity: 10^5
- Parallel processing
- Distributed computation/memory
- Robust to noise, failures



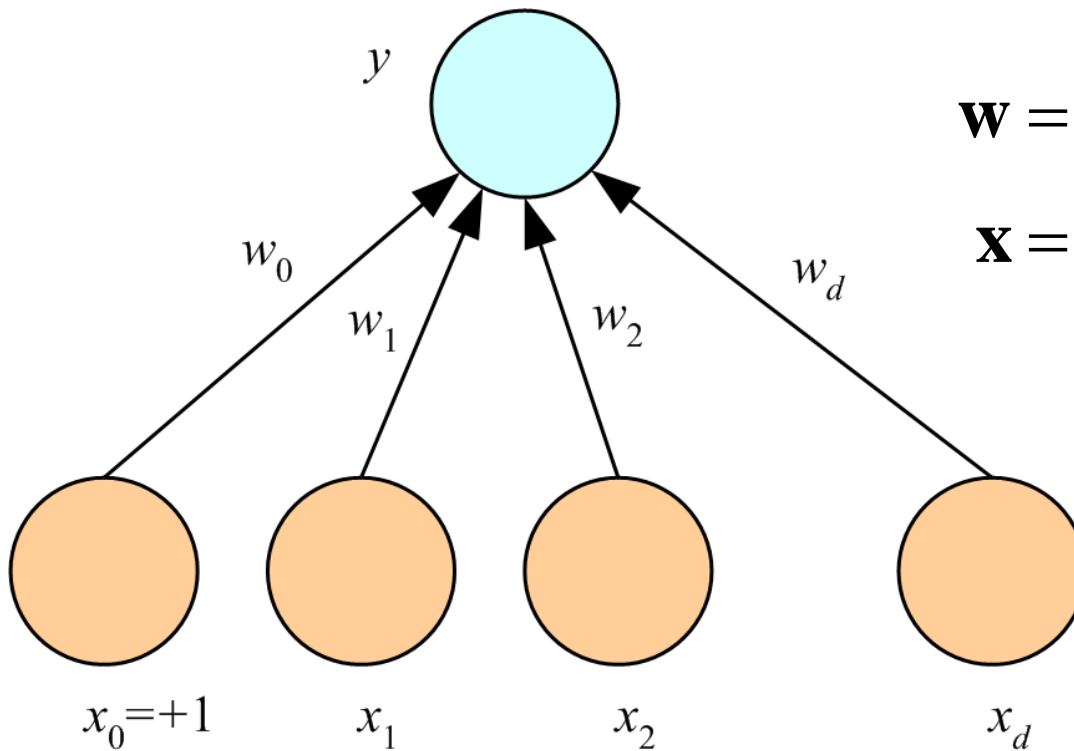
Understanding the Brain

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- Levels of analysis (Marr, 1982)
 1. Computational theory
 2. Representation and algorithm
 3. Hardware implementation
- Reverse engineering: From hardware to theory
- Parallel processing: SIMD vs MIMD
 - Neural net: SIMD with modifiable local memory
 - Learning: Update by training/experience

Perceptron

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$$y = \sum_{j=1}^d w_j x_j + w_0 = \mathbf{w}^T \mathbf{x}$$

$$\mathbf{w} = [w_0, w_1, \dots, w_d]^T$$

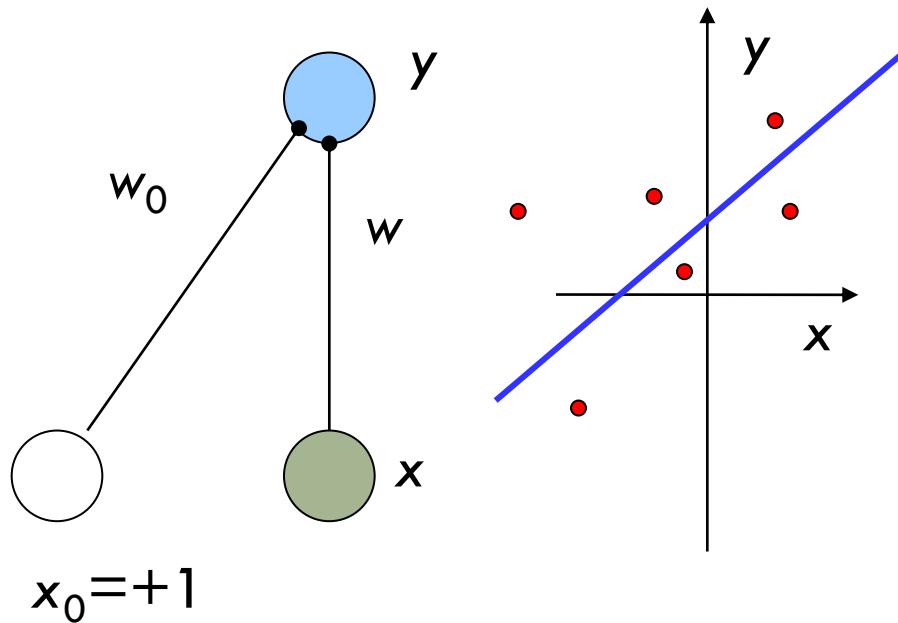
$$\mathbf{x} = [1, x_1, \dots, x_d]^T$$

(Rosenblatt, 1962)

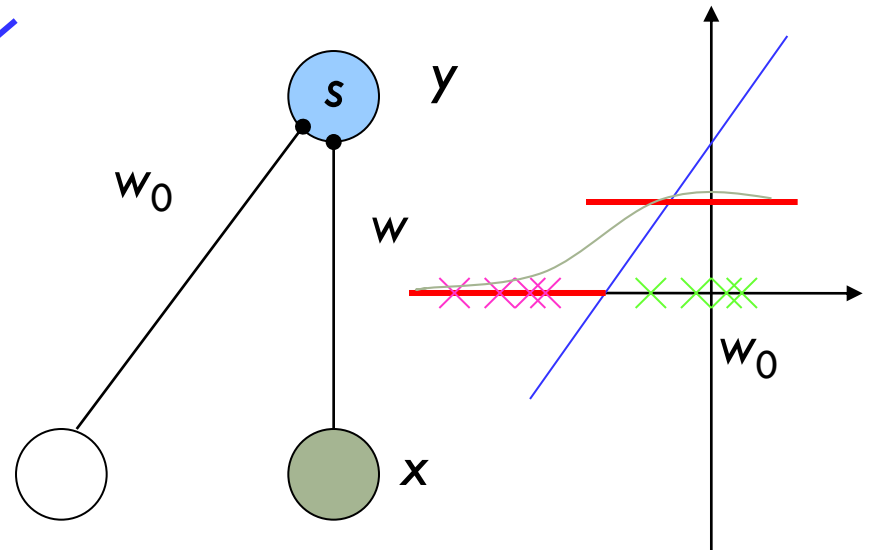
What a Perceptron Does

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□ Regression: $y = wx + w_0$



□ Classification: $y = 1 (wx + w_0 > 0)$



$$y = \text{sigmoid}(o) = \frac{1}{1 + \exp[-\mathbf{w}^T \mathbf{x}]}$$

K Outputs

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Regression:

$$y_i = \sum_{j=1}^d w_{ij} x_j + w_{i0} = \mathbf{w}_i^T \mathbf{x}$$

$$\mathbf{y} = \mathbf{W}\mathbf{x}$$

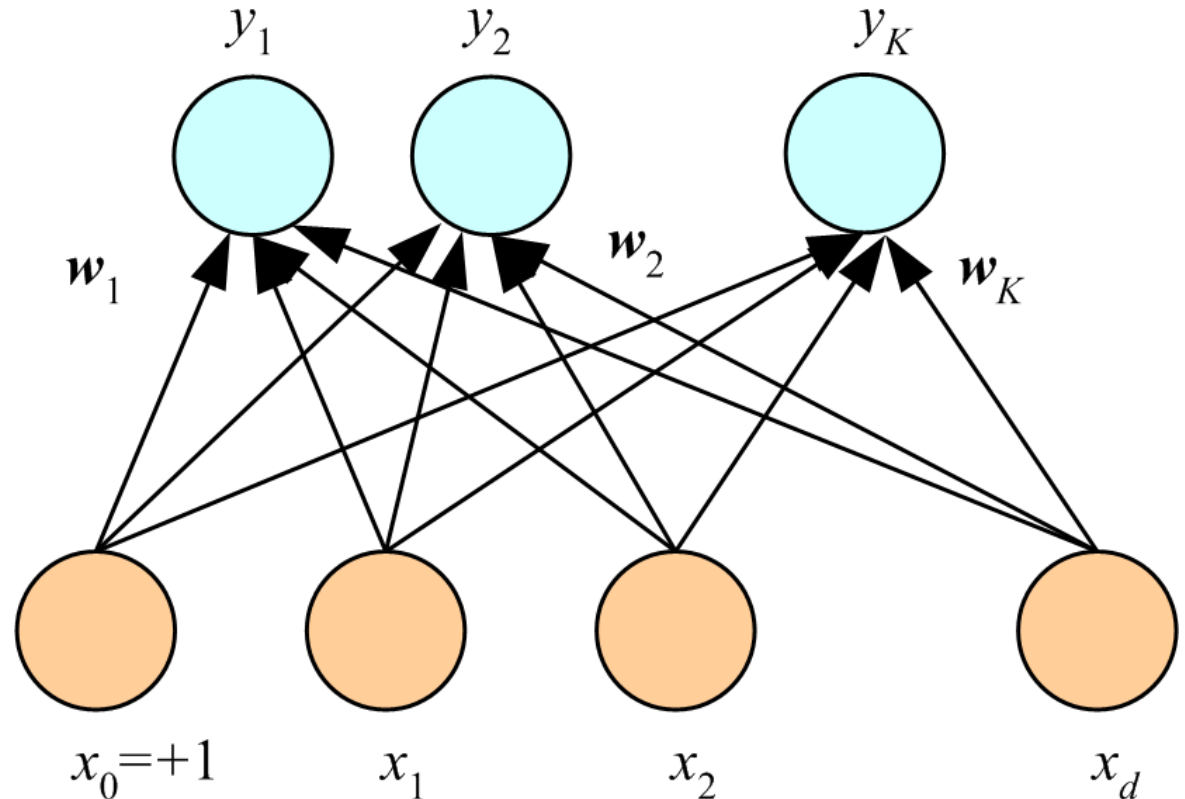
Classification:

$$o_i = \mathbf{w}_i^T \mathbf{x}$$

$$y_i = \frac{\exp o_i}{\sum_k \exp o_k}$$

choose C_i

if $y_i = \max_k y_k$



Training

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- Online (instances seen one by one) vs batch (whole sample) learning:
 - ▣ No need to store the whole sample
 - ▣ Problem may change in time
 - ▣ Wear and degradation in system components
- Stochastic gradient-descent: Update after a single pattern
- Generic update rule (LMS rule):

$$\Delta w_{ij}^t = \eta (r_i^t - y_i^t) x_j^t$$

Update = LearningFactor · (DesiredOutput – ActualOutput) · Input

Training a Perceptron: Regression

- Regression (Linear output):

$$E^t(\mathbf{w} | \mathbf{x}^t, r^t) = \frac{1}{2} (r^t - y^t)^2 = \frac{1}{2} [r^t - (\mathbf{w}^T \mathbf{x}^t)]^2$$

$$\Delta w_j^t = \eta (r^t - y^t) x_j^t$$

Classification

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□ Single sigmoid output

$$y^t = \text{sigmoid}(\mathbf{w}^T \mathbf{x}^t)$$

$$E^t(\mathbf{w} | \mathbf{x}^t, \mathbf{r}^t) = -r^t \log y^t - (1 - r^t) \log (1 - y^t)$$

$$\Delta w_j^t = \eta (r^t - y^t) x_j^t$$

□ $K > 2$ softmax outputs

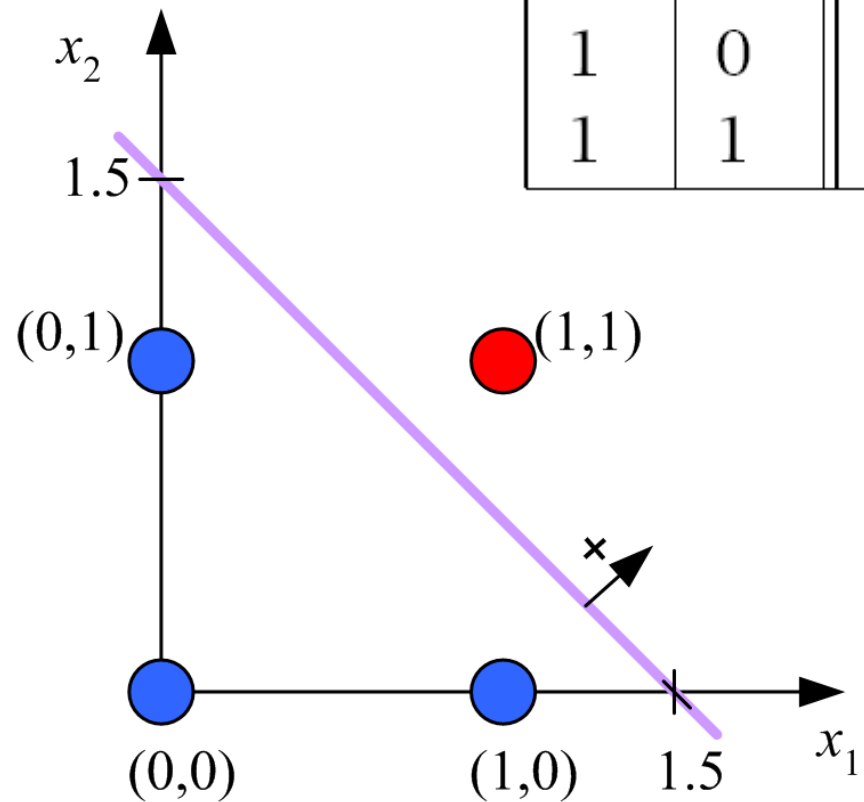
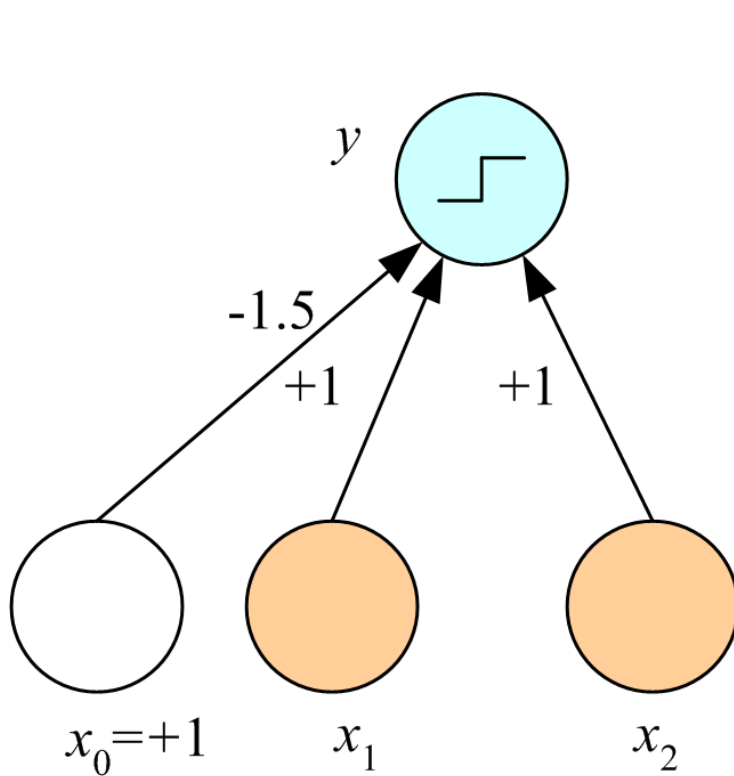
$$y^t = \frac{\exp \mathbf{w}_i^T \mathbf{x}^t}{\sum_k \exp \mathbf{w}_k^T \mathbf{x}^t} \quad E^t(\{\mathbf{w}_i\}_i | \mathbf{x}^t, \mathbf{r}^t) = -\sum_i r_i^t \log y_i^t$$

$$\Delta w_{ij}^t = \eta (r_i^t - y_i^t) x_j^t$$

Learning Boolean AND

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x_1	x_2	r
0	0	0
0	1	0
1	0	0
1	1	1



XOR

x_1	x_2	r
0	0	0
0	1	1
1	0	1
1	1	0

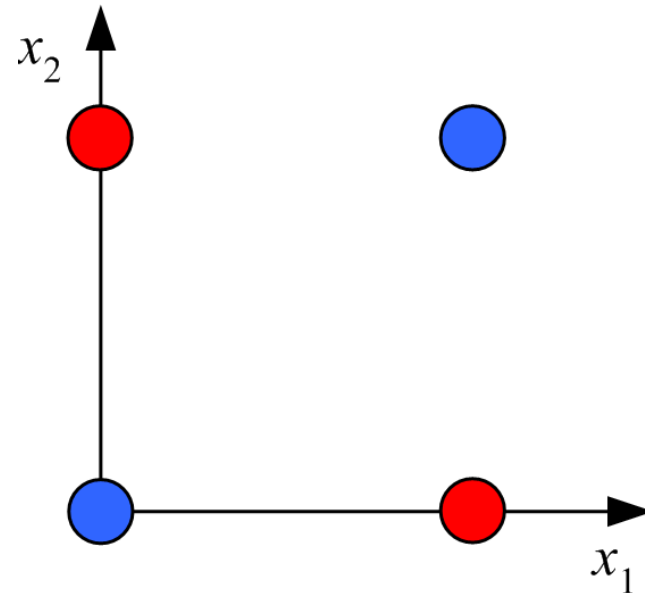
□ No w_0, w_1, w_2 satisfy:

$$w_0 \leq 0$$

$$w_2 + w_0 > 0$$

$$w_1 + w_0 > 0$$

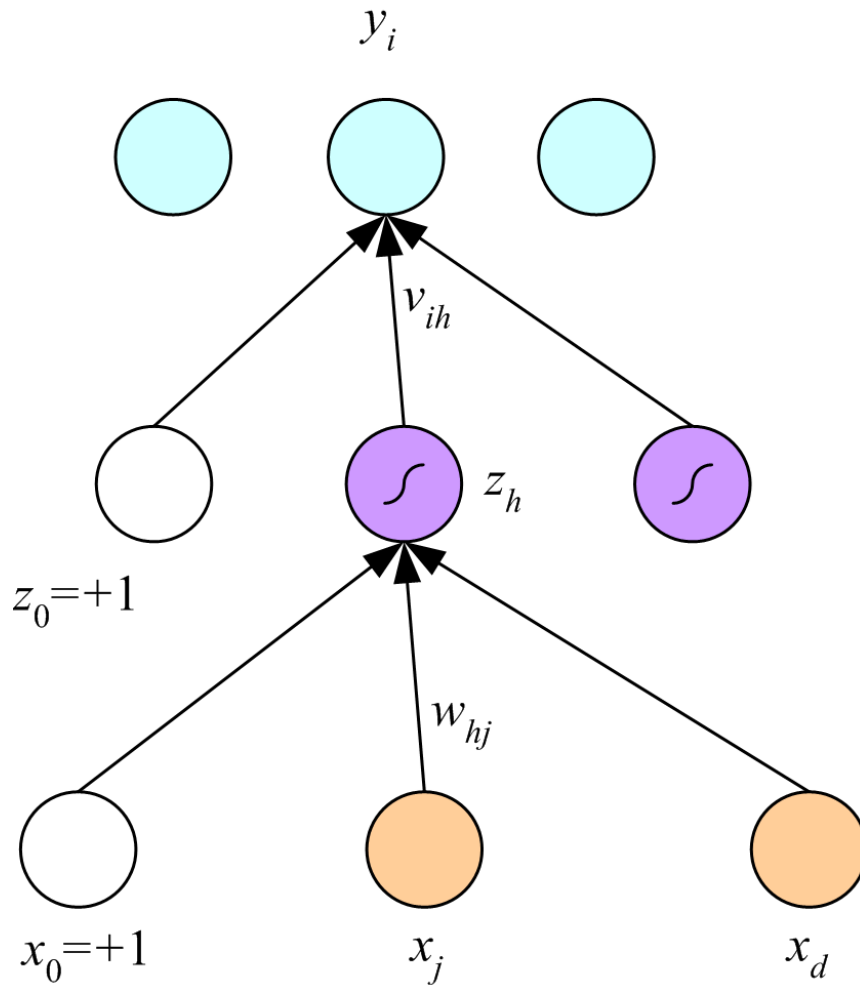
$$w_1 + w_2 + w_0 \leq 0$$



(Minsky and Papert, 1969)

Multilayer Perceptrons

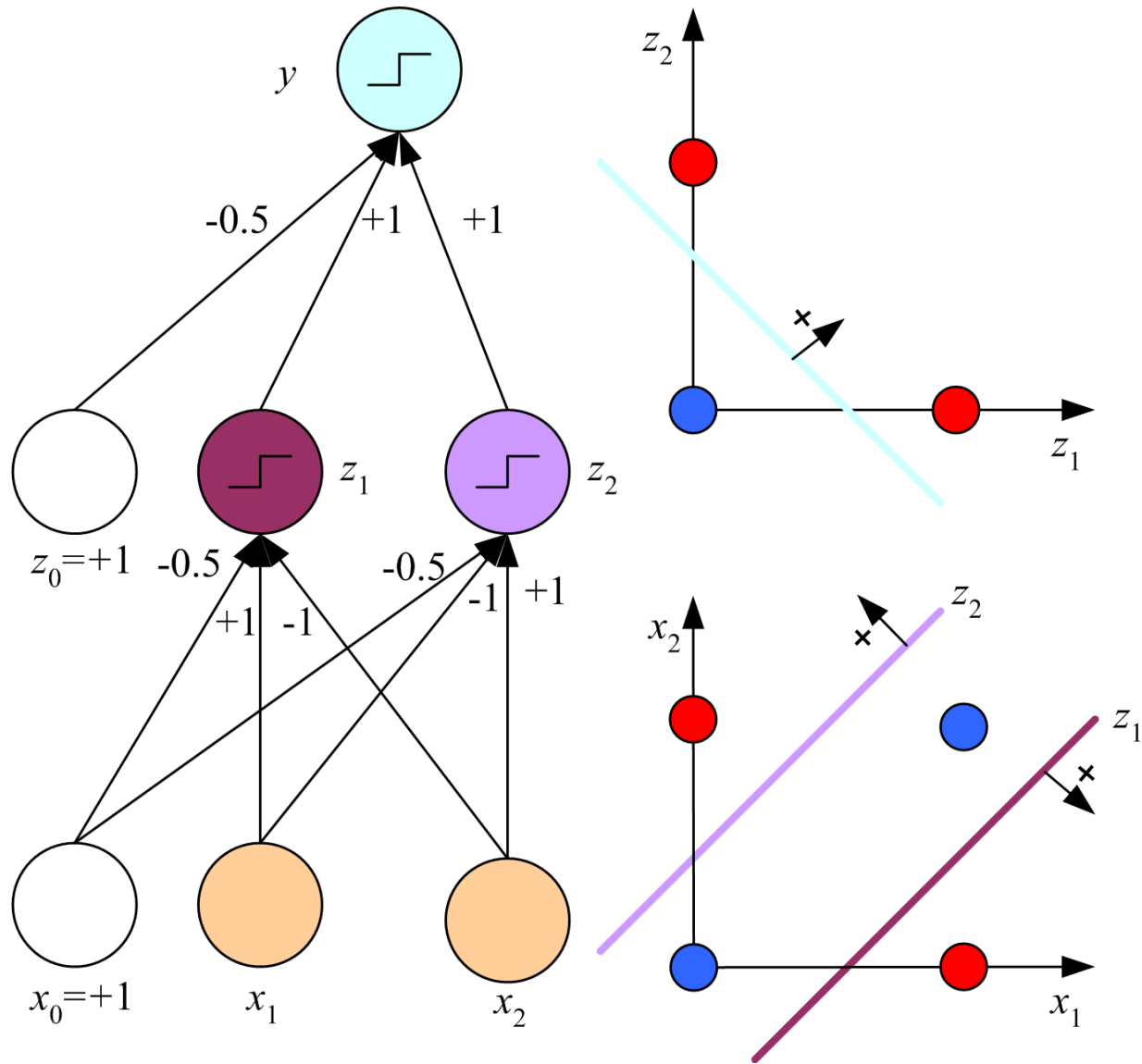
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$$y_i = \mathbf{v}_i^T \mathbf{z} = \sum_{h=1}^H v_{ih} z_h + v_{i0}$$

$$z_h = \text{sigmoid}(\mathbf{w}_h^T \mathbf{x})$$
$$= \frac{1}{1 + \exp\left[-\left(\sum_{j=1}^d w_{hj} x_j + w_{h0}\right)\right]}$$

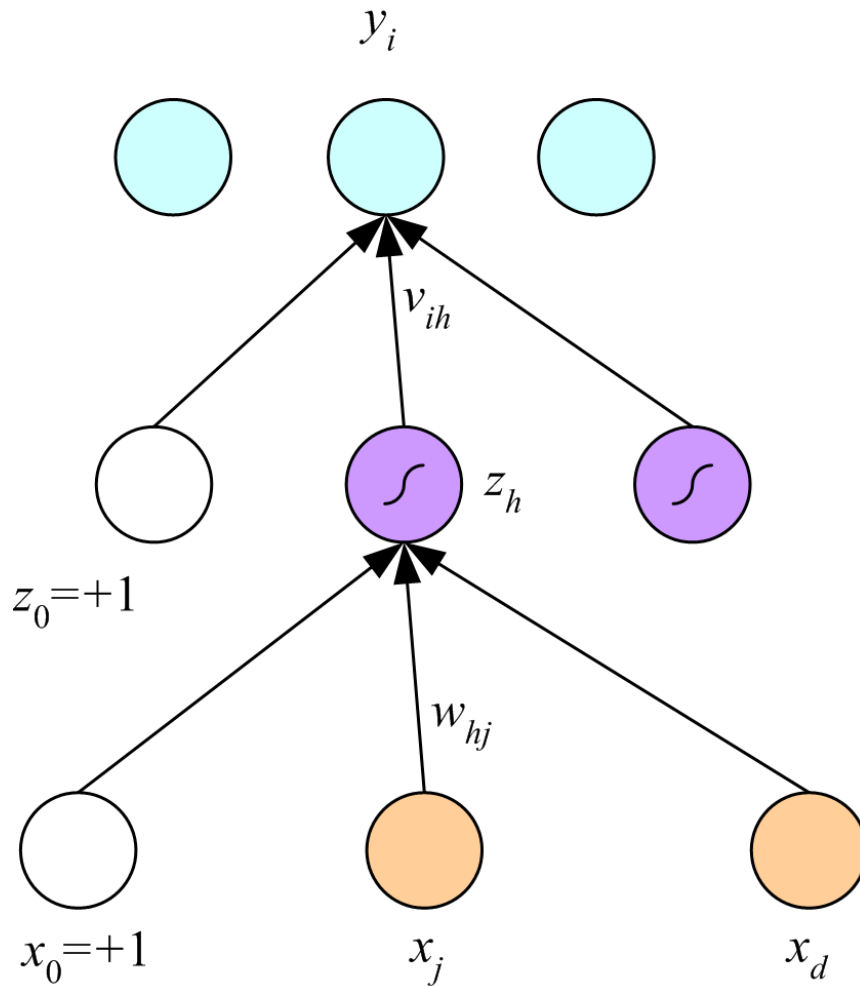
(Rumelhart et al., 1986)



$$x_1 \text{ XOR } x_2 = (x_1 \text{ AND } \sim x_2) \text{ OR } (\sim x_1 \text{ AND } x_2)$$

Backpropagation

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$$y_i = \mathbf{v}_i^T \mathbf{z} = \sum_{h=1}^H v_{ih} z_h + v_{i0}$$

$$z_h = \text{sigmoid}(\mathbf{w}_h^T \mathbf{x})$$

$$= \frac{1}{1 + \exp\left[-\left(\sum_{j=1}^d w_{hj} x_j + w_{h0}\right)\right]}$$

$$\frac{\partial E}{\partial w_{hj}} = \frac{\partial E}{\partial y_i} \frac{\partial y_i}{\partial z_h} \frac{\partial z_h}{\partial w_{hj}}$$

Regression

$$y^t = \sum_{h=1}^H v_h z_h^t + v_0$$

Forward

$$z_h = \text{sigmoid}(\mathbf{w}_h^T \mathbf{x})$$

\mathbf{x}

$$E(\mathbf{W}, \mathbf{v} | \mathcal{X}) = \frac{1}{2} \sum_t (r^t - y^t)^2$$

$$\Delta v_h = \sum_t (r^t - y^t) z_h^t$$

Backward

$$\begin{aligned} \Delta w_{hj} &= -\eta \frac{\partial E}{\partial w_{hj}} \\ &= -\eta \sum_t \frac{\partial E}{\partial y^t} \frac{\partial y^t}{\partial z_h^t} \frac{\partial z_h^t}{\partial w_{hj}} \\ &= -\eta \sum_t -(r^t - y^t) v_h \boxed{z_h^t (1 - z_h^t)} x_j^t \\ &= \eta \sum_t (r^t - y^t) v_h z_h^t (1 - z_h^t) x_j^t \end{aligned}$$

Regression with Multiple Outputs

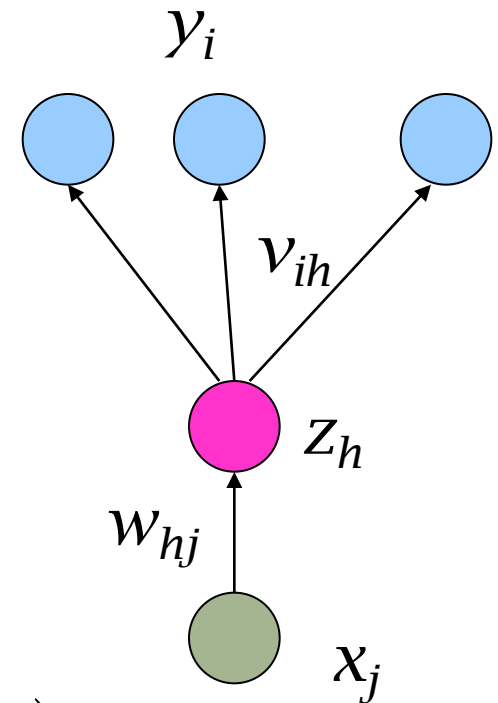
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$$E(\mathbf{W}, \mathbf{V} | \mathcal{X}) = \frac{1}{2} \sum_t \sum_i (r_i^t - y_i^t)^2$$

$$y_i^t = \sum_{h=1}^H v_{ih} z_h^t + v_{i0}$$

$$\Delta v_{ih} = \eta \sum_t (r_i^t - y_i^t) z_h^t$$

$$\Delta w_{hj} = \eta \sum_t \left[\sum_i (r_i^t - y_i^t) v_{ih} \right] z_h^t (1 - z_h^t) x_j^t$$



Initialize all v_{ih} and w_{hj} to $\text{rand}(-0.01, 0.01)$

Repeat

For all $(\mathbf{x}^t, r^t) \in \mathcal{X}$ in random order

For $h = 1, \dots, H$

$$z_h \leftarrow \text{sigmoid}(\mathbf{w}_h^T \mathbf{x}^t)$$

For $i = 1, \dots, K$

$$y_i = \mathbf{v}_i^T \mathbf{z}$$

For $i = 1, \dots, K$

$$\Delta \mathbf{v}_i = \eta(r_i^t - y_i^t) \mathbf{z}$$

For $h = 1, \dots, H$

$$\Delta \mathbf{w}_h = \eta\left(\sum_i (r_i^t - y_i^t) v_{ih}\right) z_h (1 - z_h) \mathbf{x}^t$$

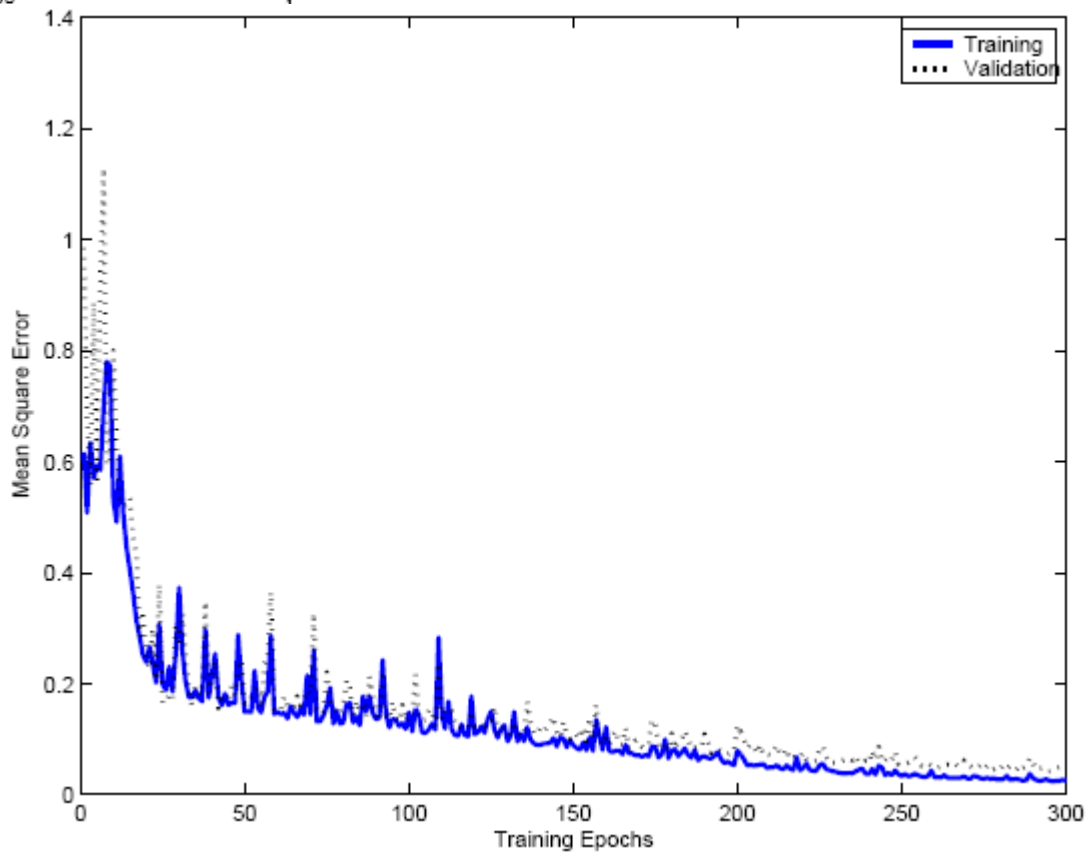
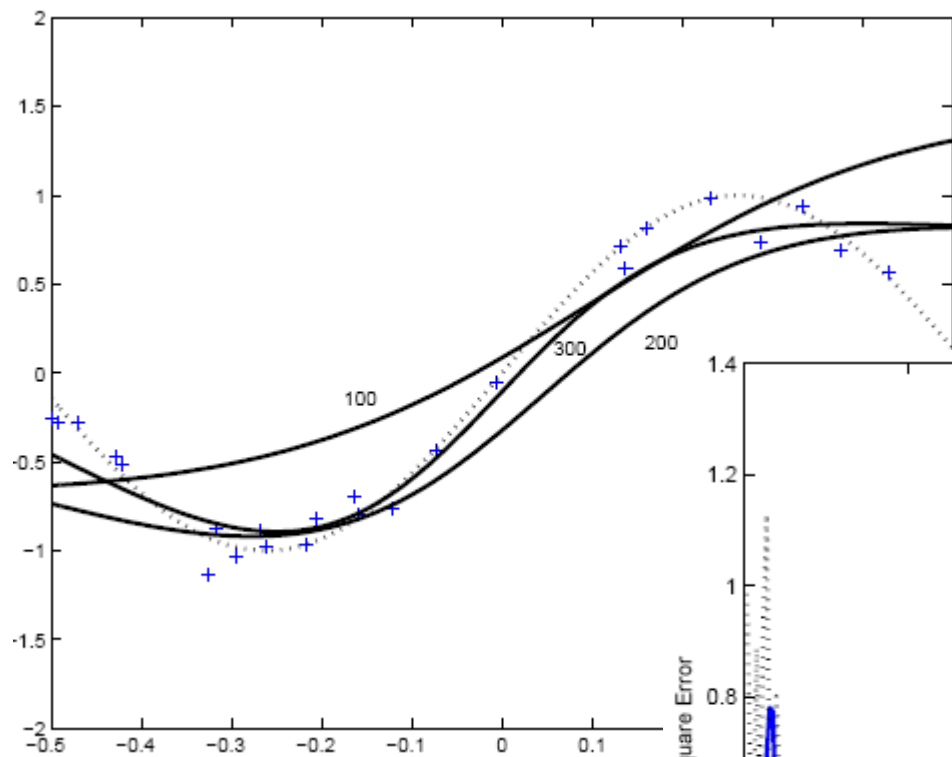
For $i = 1, \dots, K$

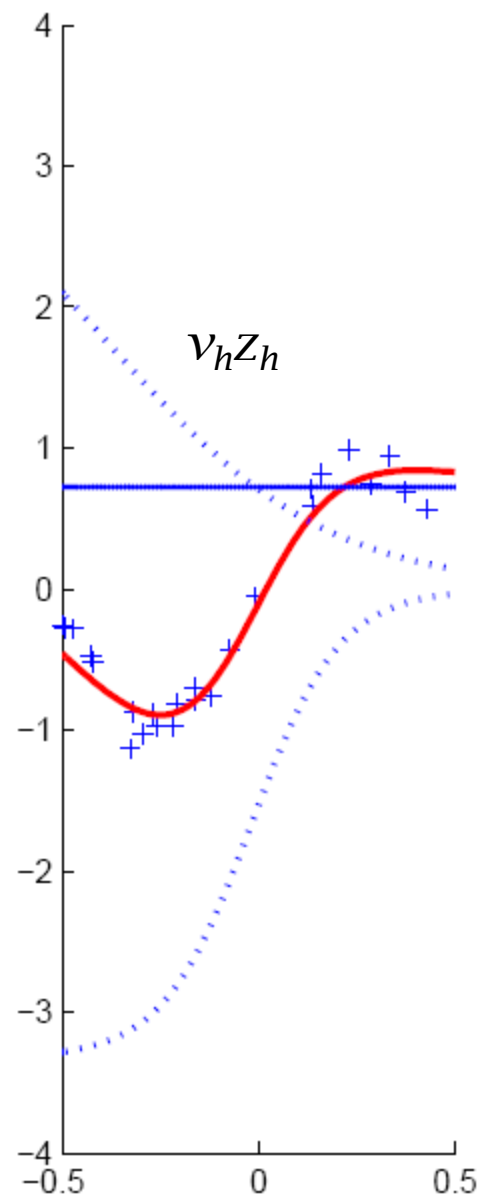
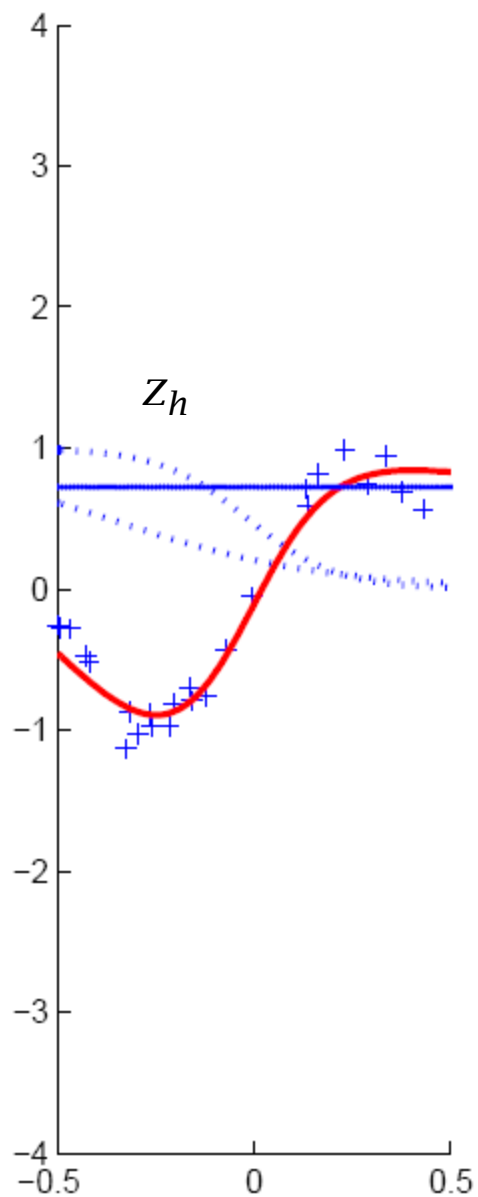
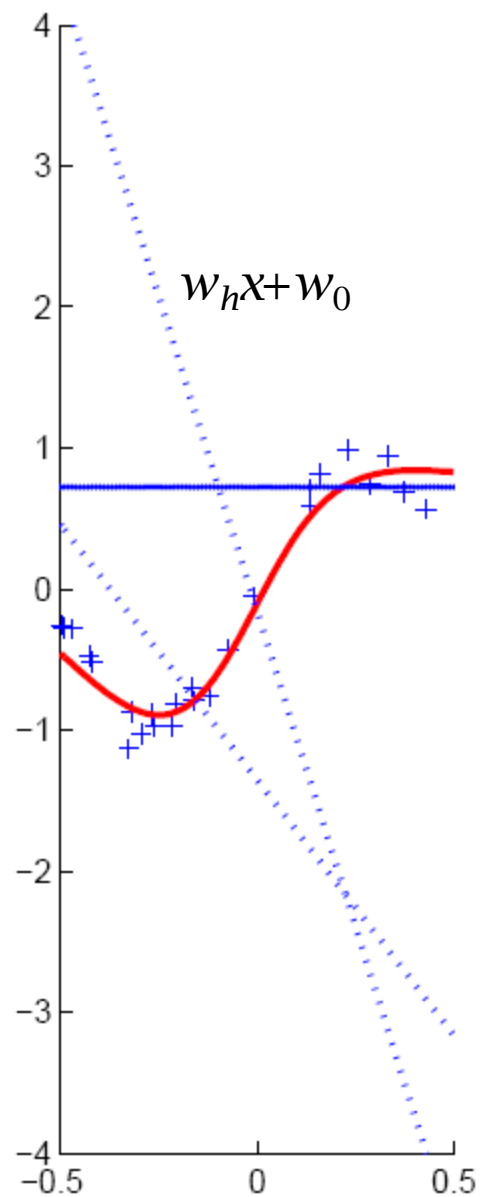
$$\mathbf{v}_i \leftarrow \mathbf{v}_i + \Delta \mathbf{v}_i$$

For $h = 1, \dots, H$

$$\mathbf{w}_h \leftarrow \mathbf{w}_h + \Delta \mathbf{w}_h$$

Until convergence





Two-Class Discrimination

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- One sigmoid output y^t for $P(C_1 | \mathbf{x}^t)$ and $P(C_2 | \mathbf{x}^t) \equiv 1 - y^t$

$$y^t = \text{sigmoid} \left(\sum_{h=1}^H v_h z_h^t + v_0 \right)$$

$$E(\mathbf{W}, \mathbf{v} | \mathcal{X}) = - \sum_t r^t \log y^t + (1 - r^t) \log (1 - y^t)$$

$$\Delta v_h = \eta \sum_t (r^t - y^t) z_h^t$$

$$\Delta w_{hj} = \eta \sum_t (r^t - y^t) v_h z_h^t (1 - z_h^t) x_j^t$$

$K > 2$ Classes

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$$o_i^t = \sum_{h=1}^H v_{ih} z_h^t + v_{i0} \quad y_i^t = \frac{\exp o_i^t}{\sum_k \exp o_k^t} \equiv P(C_i | \mathbf{x}^t)$$

$$E(W, \mathbf{v} | \mathcal{X}) = - \sum_t \sum_i r_i^t \log y_i^t$$

$$\Delta v_{ih} = \eta \sum_t (r_i^t - y_i^t) z_h^t$$

$$\Delta w_{hj} = \eta \sum_t \left[\sum_i (r_i^t - y_i^t) v_{ih} \right] z_h^t (1 - z_h^t) x_j^t$$

Multiple Hidden Layers

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- MLP with one hidden layer is a **universal approximator** (Hornik et al., 1989), but using multiple layers may lead to simpler networks

$$z_{1h} = \text{sigmoid}(\mathbf{w}_{1h}^T \mathbf{x}) = \text{sigmoid}\left(\sum_{j=1}^d w_{1hj} x_j + w_{1h0}\right), h = 1, \dots, H_1$$

$$z_{2l} = \text{sigmoid}(\mathbf{w}_{2l}^T \mathbf{z}_1) = \text{sigmoid}\left(\sum_{h=1}^{H_1} w_{2lh} z_{1h} + w_{2l0}\right), l = 1, \dots, H_2$$

$$y = \mathbf{v}^T \mathbf{z}_2 = \sum_{l=1}^{H_2} v_l z_{2l} + v_0$$

Improving Convergence

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□ Momentum

$$\Delta w_i^t = -\eta \frac{\partial E^t}{\partial w_i} + \alpha \Delta w_i^{t-1}$$

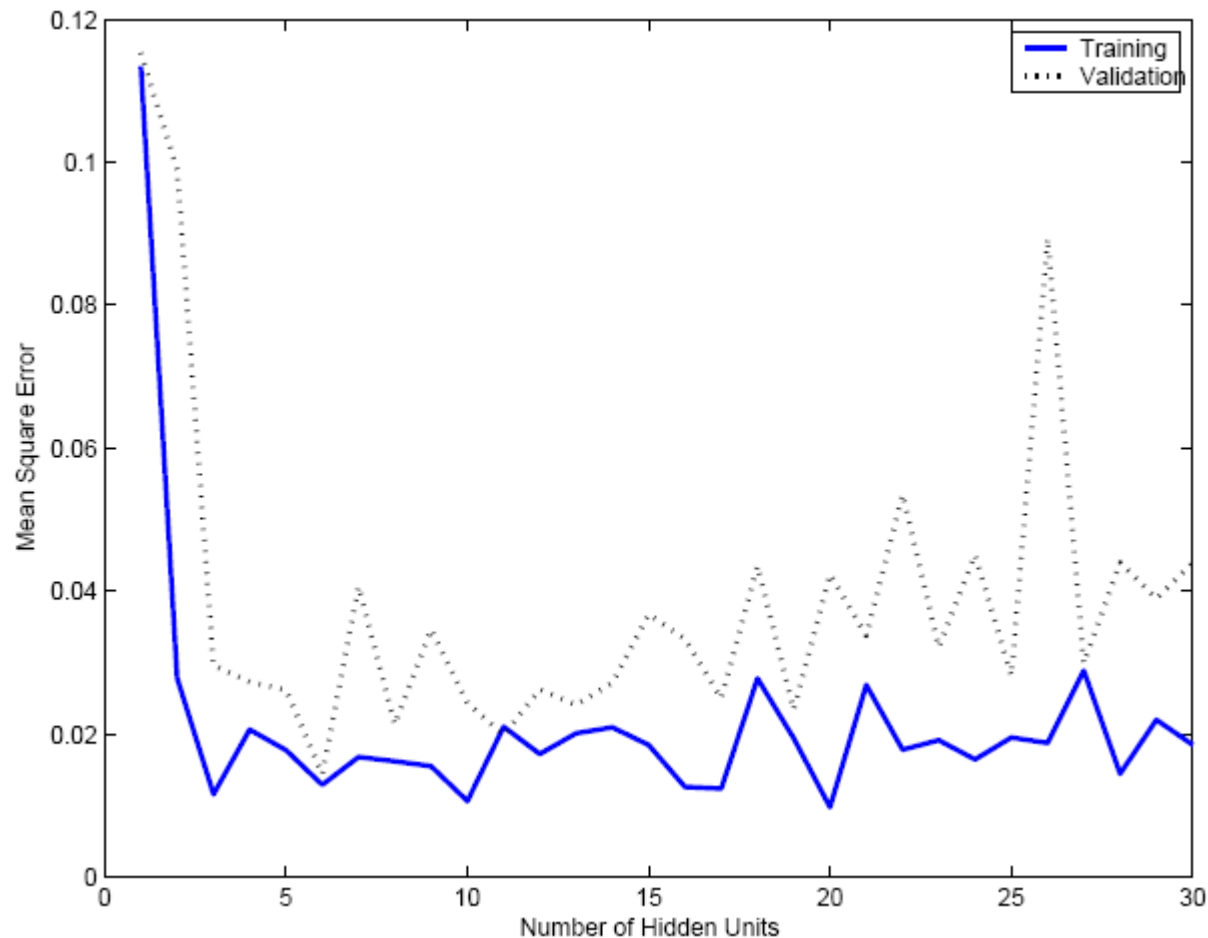
□ Adaptive learning rate

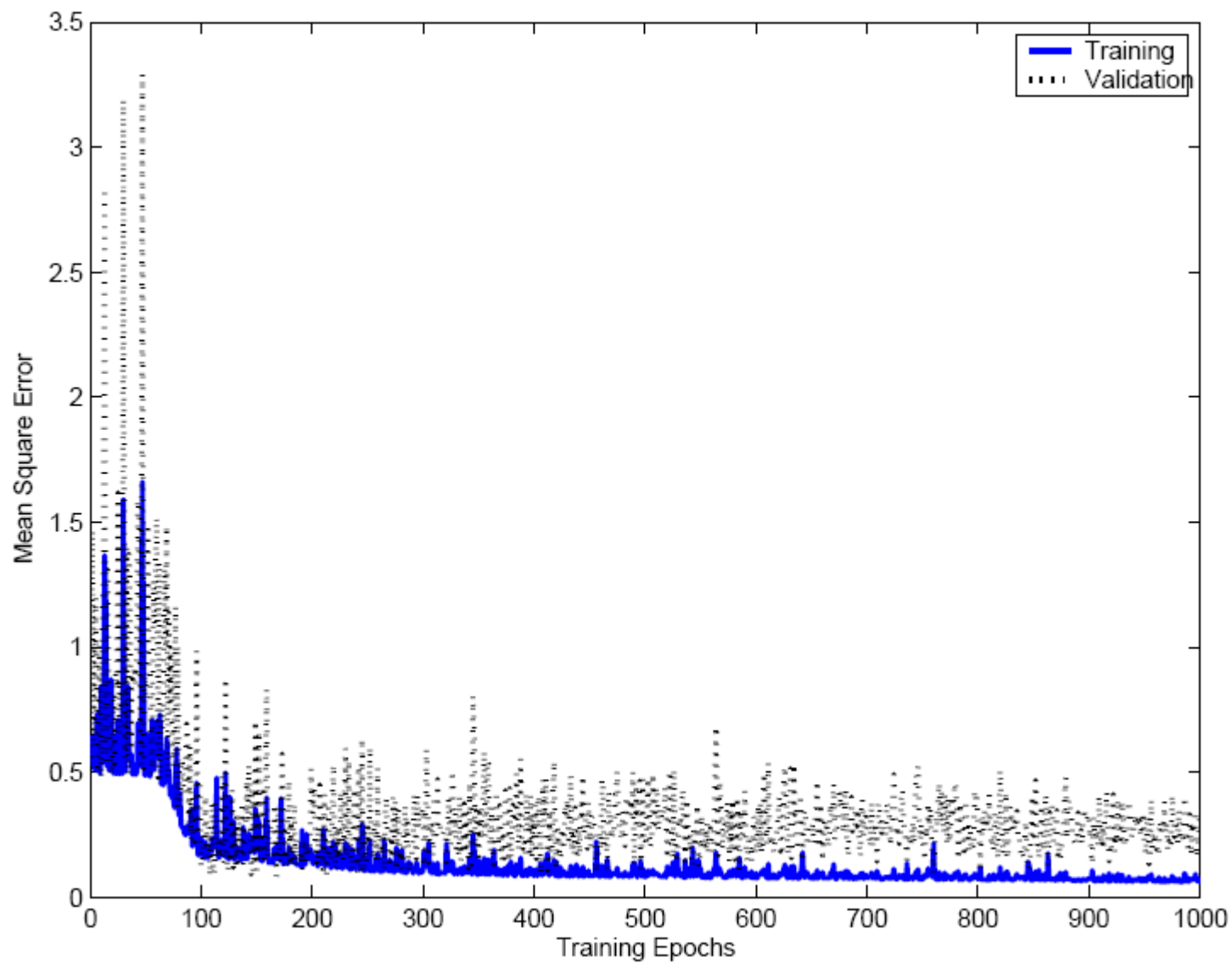
$$\Delta \eta = \begin{cases} +a & \text{if } E^{t+\tau} < E^t \\ -b\eta & \text{otherwise} \end{cases}$$

Overfitting/Overtraining

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Number of weights: $H(d+1) + (H+1)K$

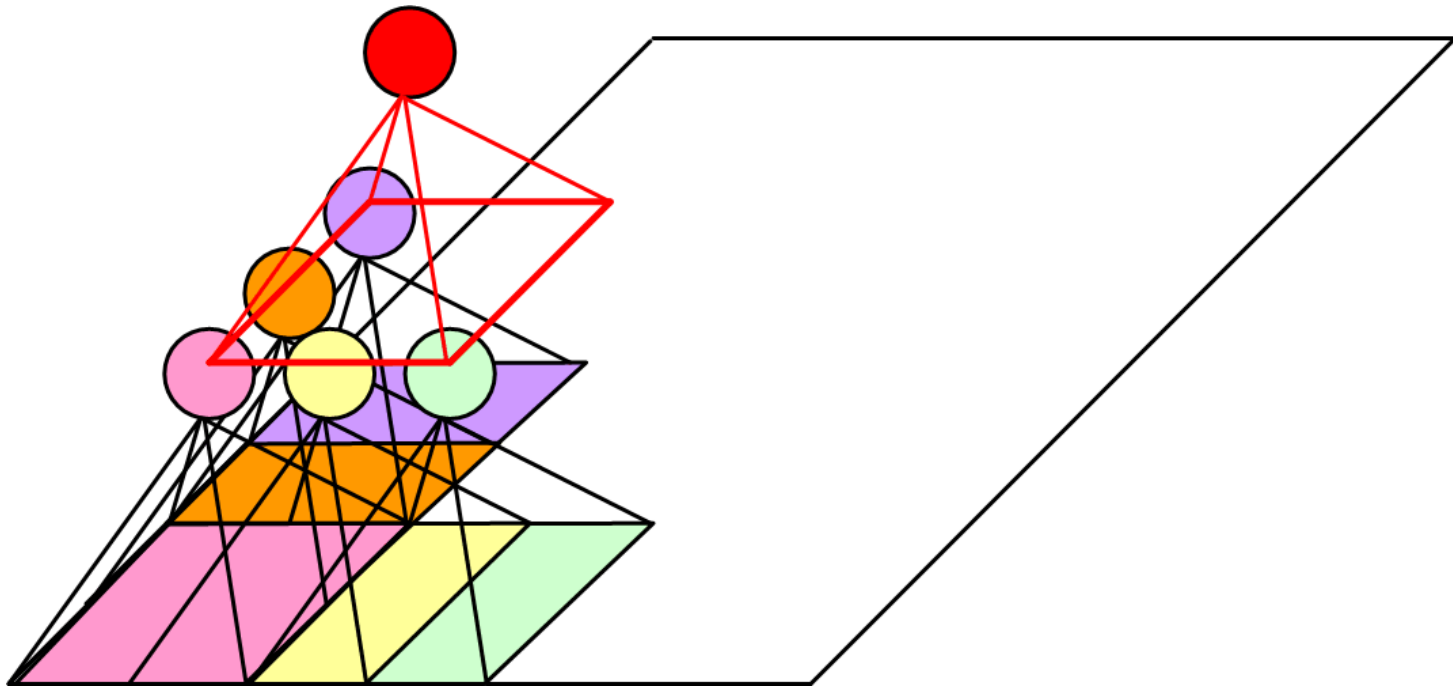




Structured MLP

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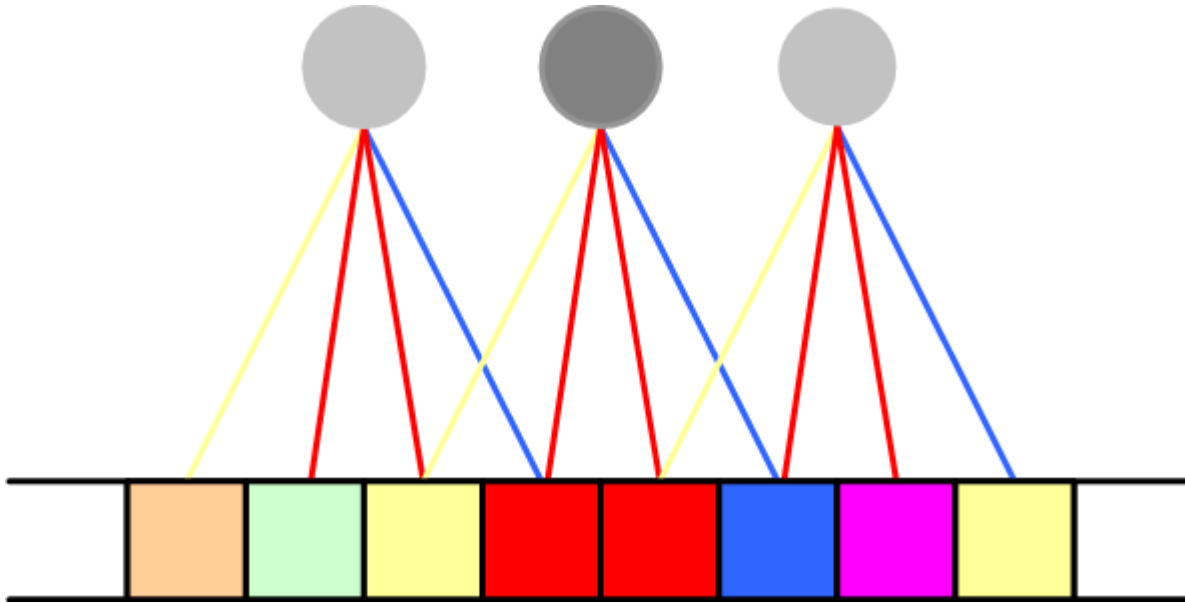
- Convolutional networks (Deep learning)



(Le Cun et al, 1989)

Weight Sharing

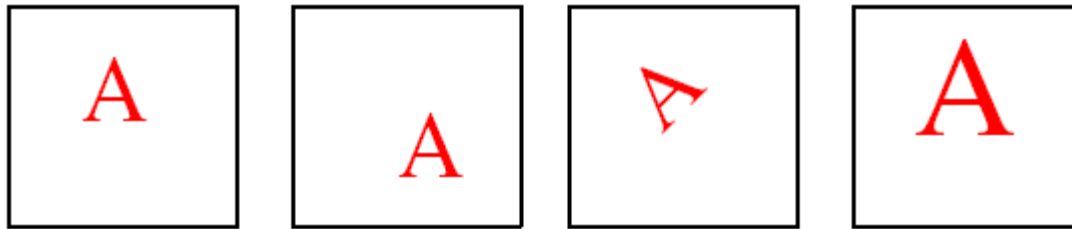
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Hints

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- Invariance to translation, rotation, size



- Virtual examples (Abu-Mostafa, 1995)
- Augmented error: $E' = E + \lambda_h E_h$

If x' and x are the “same”: $E_h = [g(x | \theta) - g(x' | \theta)]^2$

Approximation hint:

$$E_h = \begin{cases} 0 & \text{if } g(x | \theta) \in [a_x, b_x] \\ (g(x | \theta) - a_x)^2 & \text{if } g(x | \theta) < a_x \\ (g(x | \theta) - b_x)^2 & \text{if } g(x | \theta) > b_x \end{cases}$$

Tuning the Network Size

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□ Destructive

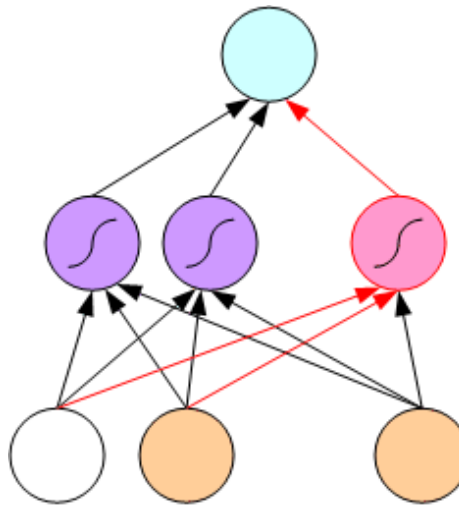
Weight decay:

$$\Delta w_i = -\eta \frac{\partial E}{\partial w_i} - \lambda w_i$$

$$E' = E + \frac{\lambda}{2} \sum_i w_i^2$$

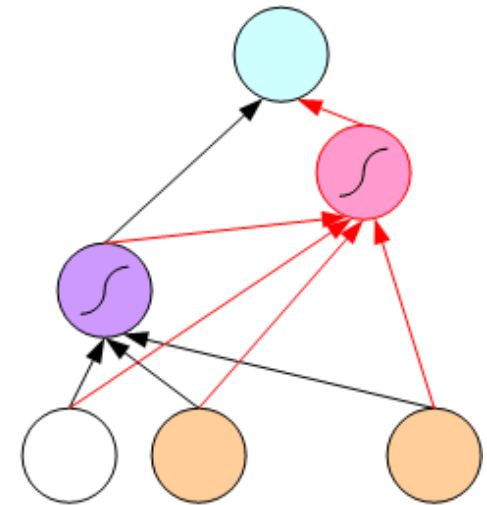
□ Constructive

Growing networks



Dynamic Node Creation

(Ash, 1989)



Cascade Correlation

(Fahlman and Lebiere, 1989)

Bayesian Learning

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- Consider weights w_i as random vars, prior $p(w_i)$

$$p(\mathbf{w} | \mathcal{X}) = \frac{p(\mathcal{X} | \mathbf{w})p(\mathbf{w})}{p(\mathcal{X})} \quad \hat{\mathbf{w}}_{MAP} = \arg \max_{\mathbf{w}} \log p(\mathbf{w} | \mathcal{X})$$

$$\log p(\mathbf{w} | \mathcal{X}) = \log p(\mathcal{X} | \mathbf{w}) + \log p(\mathbf{w}) + C$$

$$p(\mathbf{w}) = \prod_i p(w_i) \text{ where } p(w_i) = c \cdot \exp \left[-\frac{w_i^2}{2(1/2\lambda)} \right]$$

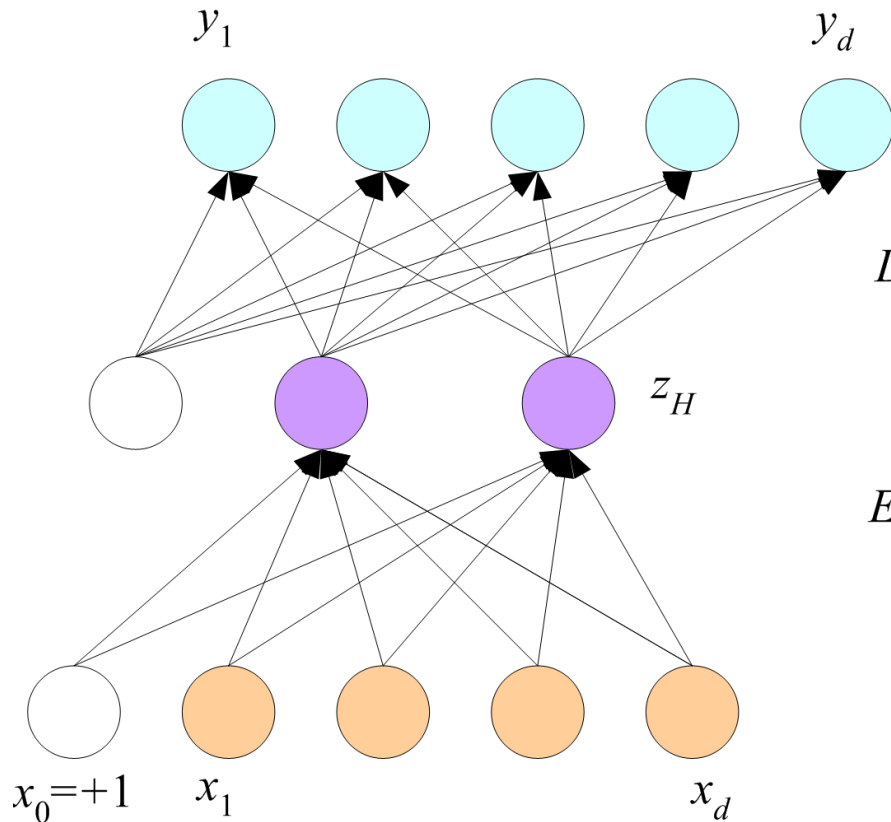
$$E' = E + \lambda \|\mathbf{w}\|^2$$

- Weight decay, ridge regression, regularization
cost = data-misfit + λ complexity

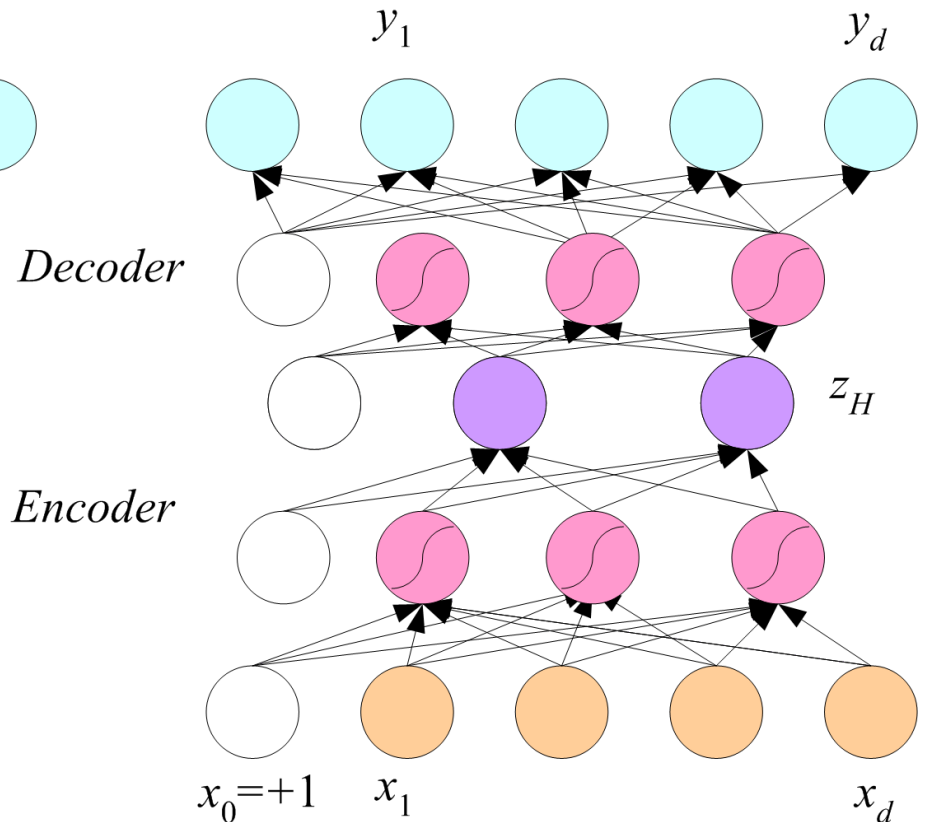
More about Bayesian methods in chapter 14

Dimensionality Reduction

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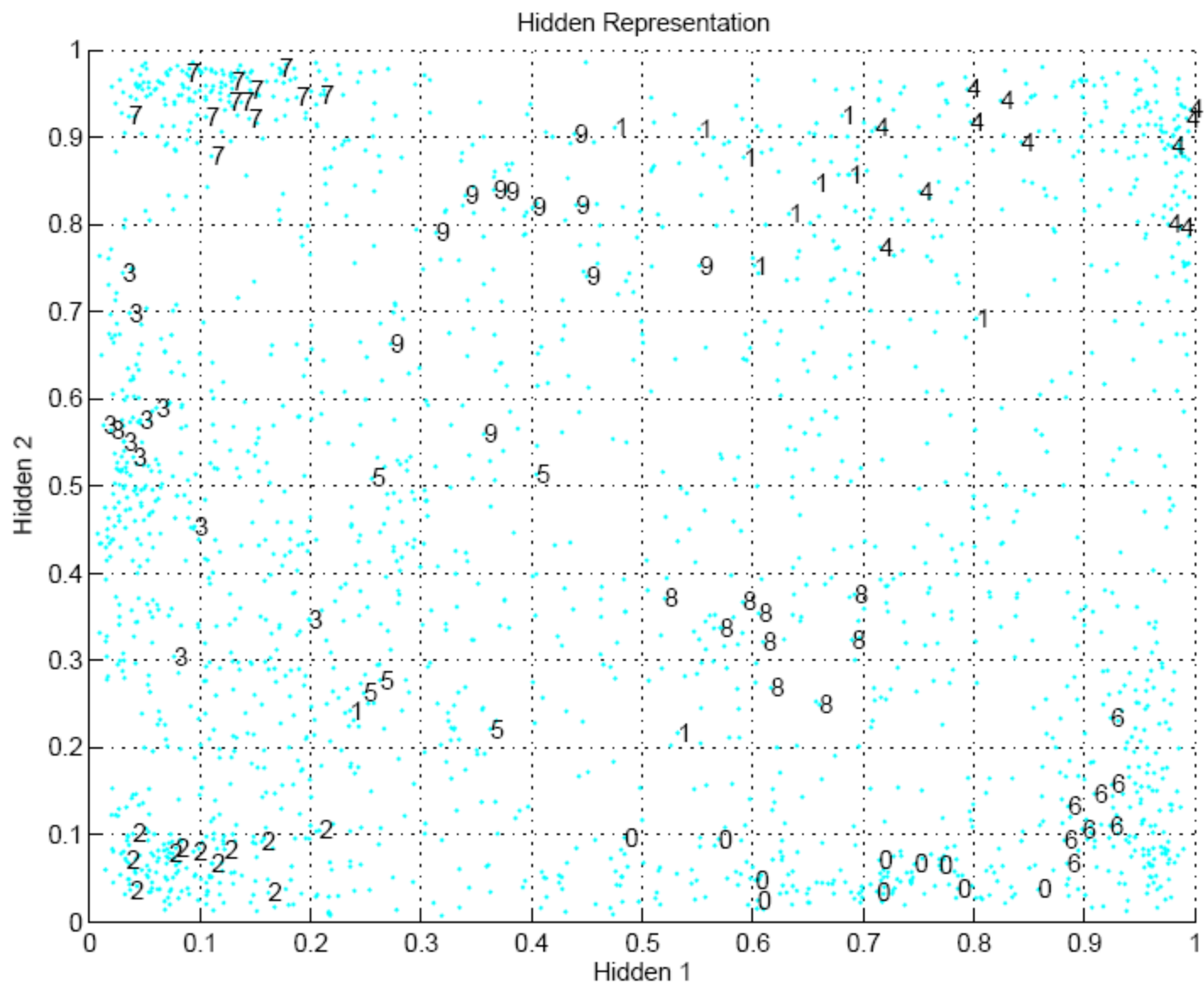


Linear



Nonlinear

Autoencoder networks



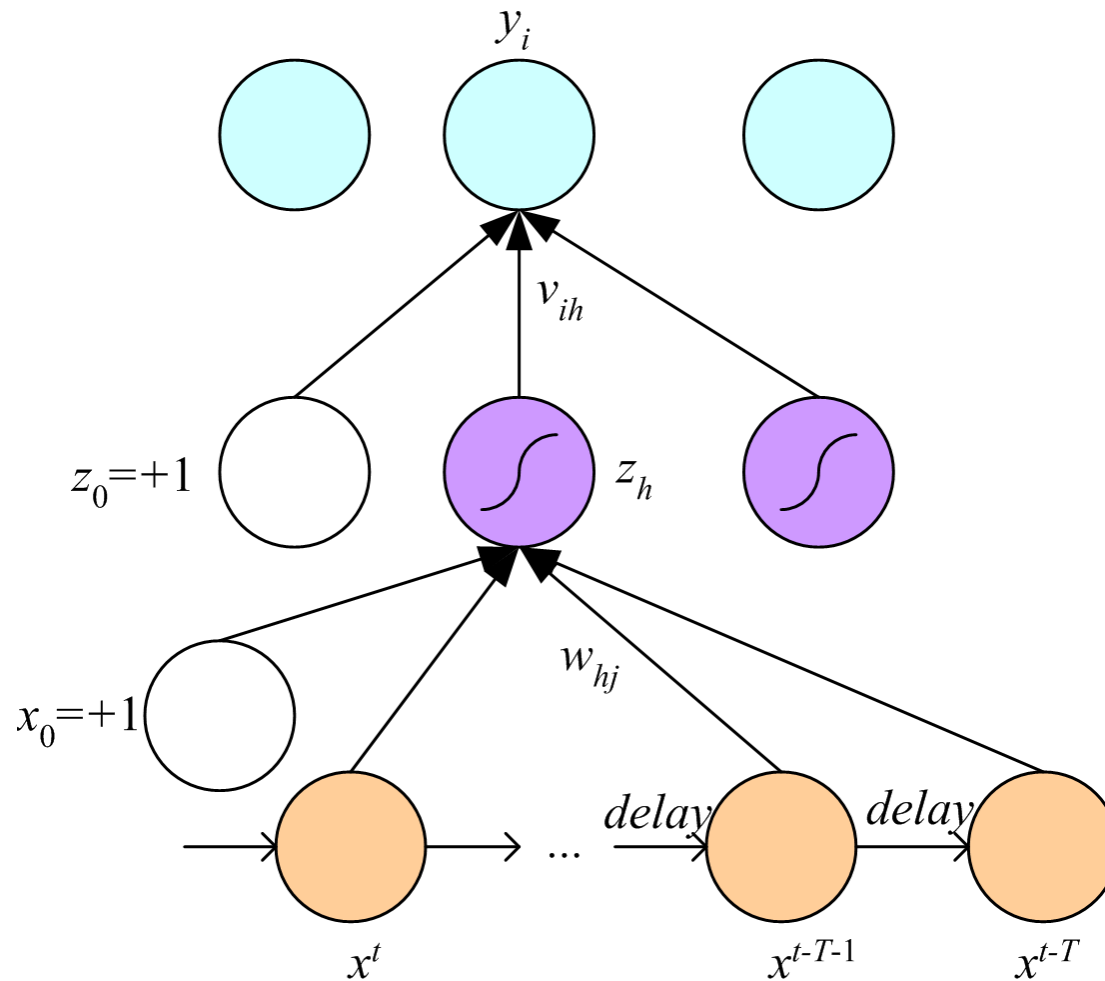
Learning Time

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- Applications:
 - ▣ Sequence recognition: Speech recognition
 - ▣ Sequence reproduction: Time-series prediction
 - ▣ Sequence association
- Network architectures
 - ▣ Time-delay networks (Waibel et al., 1989)
 - ▣ Recurrent networks (Rumelhart et al., 1986)

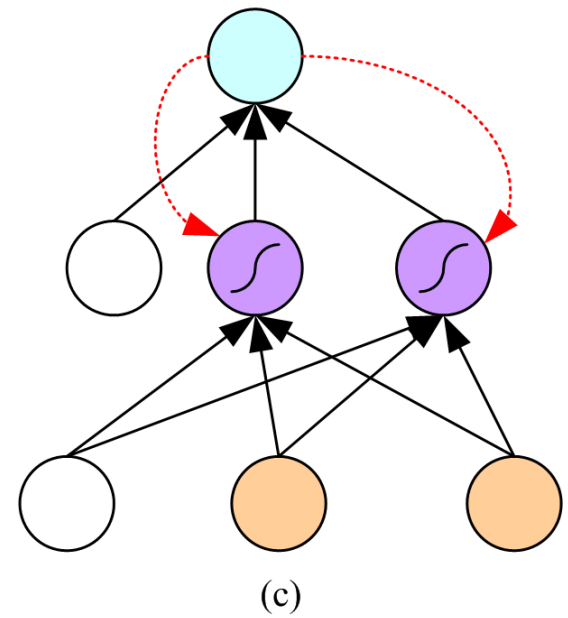
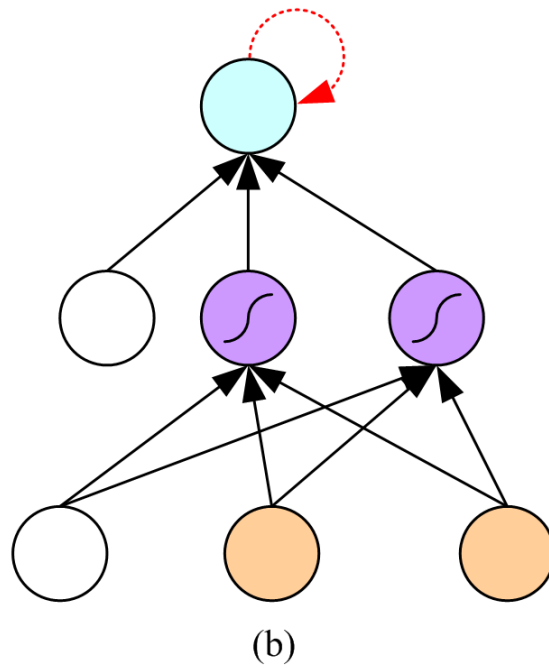
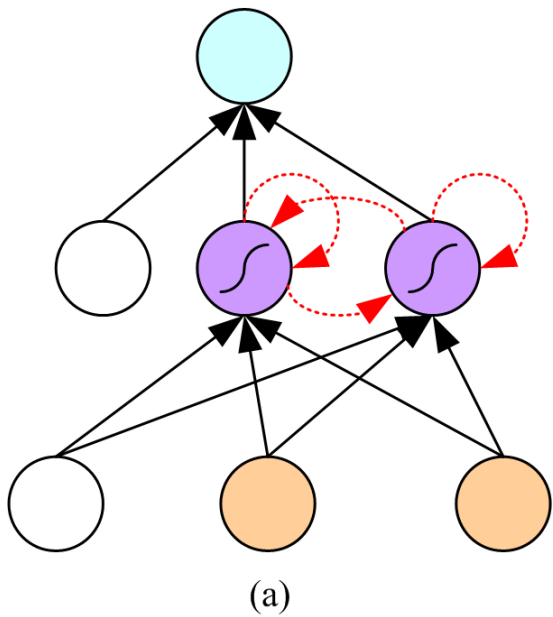
Time-Delay Neural Networks

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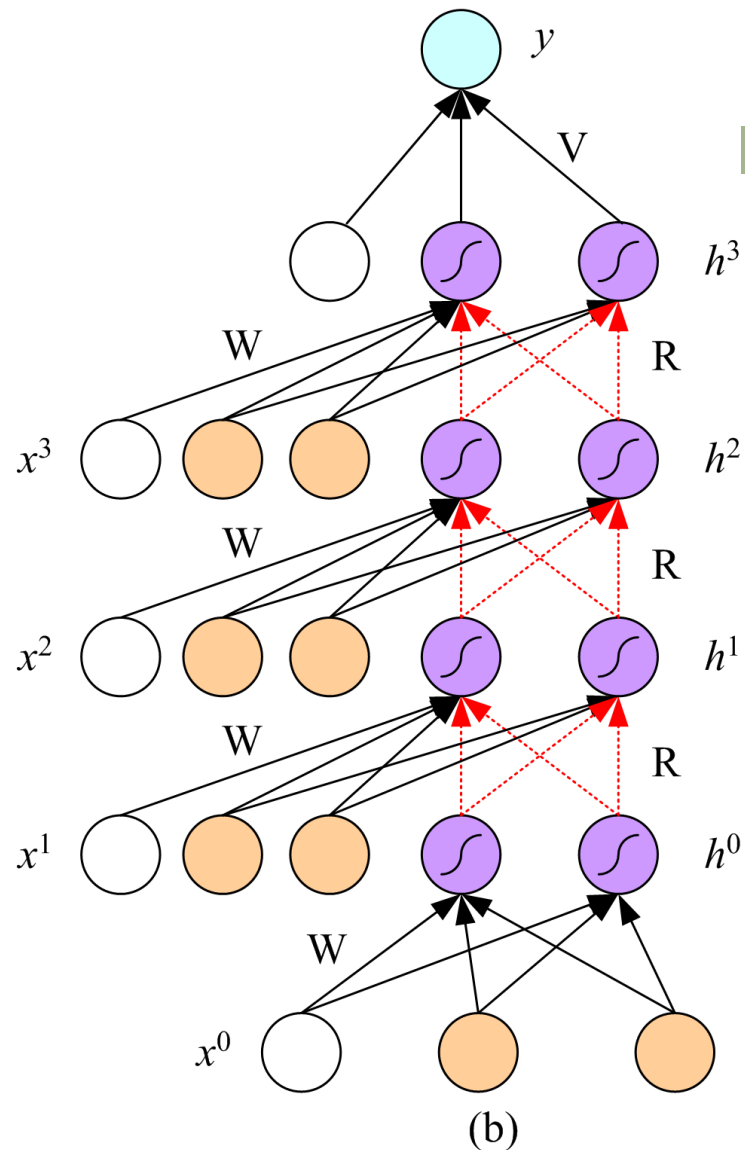
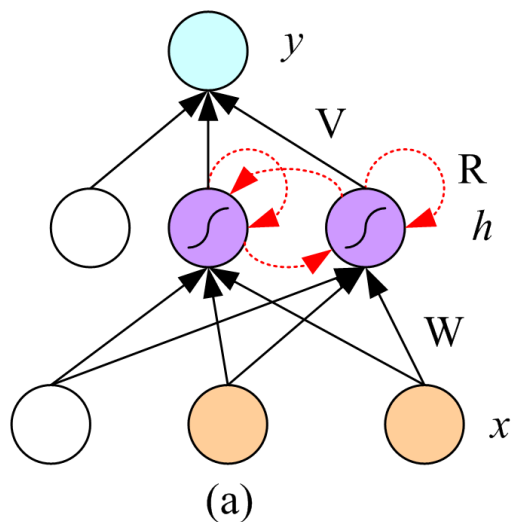
Recurrent Networks

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Unfolding in Time

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Deep Networks

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- Layers of feature extraction units
- Can have local receptive fields as in convolution networks, or can be fully connected
- Can be trained layer by layer using an autoencoder in an unsupervised manner
- No need to craft the right features or the right basis functions or the right dimensionality reduction method; learns **multiple layers of abstraction** all by itself given a lot of data and a lot of computation
- Applications in vision, language processing, ...