

f.

$$\text{Let } \vec{x}_n = [x_{n1} \ x_{n2} \ \dots \ x_{nd}] \in \mathbb{R}^d$$

$$\Rightarrow \vec{x}_n = [1 \ x_{n1} \ x_{n2} \ \dots \ x_{nd}] \in \mathbb{R}^{d+1}$$

$$\vec{x}'_n = [3 \ 3x_{n1} \ 3x_{n2} \ \dots \ 3x_{nd}] \in \mathbb{R}^{d+1}$$

For arbitrary $(\vec{x}_n, y_n) \in \{(\vec{x}_n, y_n)\}_{n=1}^N$, and assume $\text{sign}(0) = -1$

if $\text{sign}(\vec{w}_0^T \vec{x}_p) \neq y_p$, which means \vec{x}_p is the first mispredicted input

then $y_p = 1$

and

$$\vec{w}_1 = \vec{w}_0 + y_p \vec{x}_p = \vec{x}_p$$

If we further assume the second misprediction occurs at (\vec{x}_q, y_q) , then

$$\text{sign}(\vec{w}_1^T \vec{x}_q) \neq y_q$$

$$\Rightarrow \text{sign}(\vec{x}_p^T \vec{x}_q) \neq y_q$$

$$\Rightarrow \text{sign}\left([1 \ x_{p1} \ x_{p2} \ \dots \ x_{pd}] \begin{bmatrix} 1 \\ x_{q1} \\ x_{q2} \\ \vdots \\ x_{qd} \end{bmatrix}\right) \neq y_q$$

$$\Rightarrow \text{sign}\left(1 + \sum_{i=1}^d x_{pi} x_{qi}\right) \neq y_q$$

" $\vec{x}_0 \sim \vec{x}_{p-1}$ is predicted correctly by \vec{w}_0

$\therefore \text{sign}(\vec{w}_0^T \vec{x}_i) = y_i$ for $i=1 \sim p-1$

$\Rightarrow \text{sign}(\vec{w}_0^T \vec{x}_i) = y_i$

$\Rightarrow \text{sign}\left(\begin{bmatrix} 0 & 0 & \dots & 0 \end{bmatrix} \begin{bmatrix} x_{p1} \\ x_{p2} \\ \vdots \\ x_{pd} \end{bmatrix}\right) = y_i$

$\Rightarrow \text{sign}(0) = -1 = y_i$ for $i=1 \sim p-1$

" $\text{sign}(\vec{w}_0^T \vec{x}_p) \neq y_p$ as we assumed $\therefore y_p = 1$

Thus, $\vec{w}_1 = \vec{w}_0 + y_p \vec{x}_p = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} + 1 \cdot \begin{bmatrix} x_{p1} \\ x_{p2} \\ \vdots \\ x_{pd} \end{bmatrix} = \begin{bmatrix} x_{p1} \\ x_{p2} \\ \vdots \\ x_{pd} \end{bmatrix}$

Consider the same situation but replace all \vec{x}_n to \vec{x}_n' :

for \vec{x}_i' $i=1 \sim p-1$, since $\text{sign}(\vec{w}_0^T \vec{x}_i') = 1$ and y_i remain unchanged

$\therefore \vec{x}_1' \sim \vec{x}_{p-1}'$ is predicted correctly

For \vec{x}_p' , we have also have $\text{sign}(\vec{w}_0^T \vec{x}_p') = -1 \neq y_p = 1$

Therefore,

$\vec{w}_1' = \vec{w}_0' + y_p \vec{x}_p' = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} + 1 \cdot \begin{bmatrix} x_{p1} \\ x_{p2} \\ \vdots \\ x_{pd} \end{bmatrix} = \begin{bmatrix} x_{p1} \\ x_{p2} \\ \vdots \\ x_{pd} \end{bmatrix}$

" $\vec{x}_{p+1} \sim \vec{x}_{q-1}$ is predicted correctly

$\therefore \text{sign}(\vec{x}_p^T \vec{x}_i) = y_i$ for $i=p+1 \sim q-1$

We want to know if $\vec{x}_{p+1} \sim \vec{x}_q$ will be predicted correctly or not
 as $\vec{w}_1 = [3 \ x_{p1} \ \dots \ x_{pd}]^T$

$$\Rightarrow \text{sign}(\vec{w}_1^T \vec{x}_{p+1}) = \text{sign}([3 \ x_{p1} \ \dots \ x_{pd}] \begin{bmatrix} 3 \\ x_{p+1,1} \\ x_{p+1,2} \\ \vdots \\ x_{p+1,d} \end{bmatrix})$$

$$= \text{sign}(9(1 + x_{p1}x_{p+1,1} + \dots + x_{pd}x_{p+1,d}))$$

$$= \text{sign}(1 + x_{p1}x_{p+1,1} + \dots + x_{pd}x_{p+1,d})$$

$$= \text{sign}(\vec{x}_p^T \vec{x}_{p+1})$$

$$= \text{sign}(\vec{w}_1^T \vec{x}_{p+1})$$

similarly, we know that:

$$\text{sign}(\vec{w}_1^T \vec{x}_i) = \text{sign}(\vec{w}_1^T \vec{x}_i) \text{ for } i = p+1 \sim q-1$$

Thus, \vec{x}_i is predicted correctly by \vec{w}_1 for $i = p+1 \sim q-1$

Next we want to check if $\text{sign}(\vec{w}_1^T \vec{x}_q) = y_q$ or not:

$$\text{sign}(\vec{w}_1^T \vec{x}_q) = \text{sign}([3 \ x_{p1} \ \dots \ x_{pd}] \begin{bmatrix} 3 \\ x_{q1} \\ x_{q2} \\ \vdots \\ x_{qd} \end{bmatrix})$$

$$= \text{sign}(9(1 + x_{p1}x_{q1} + \dots + x_{pd}x_{qd}))$$

$$= \text{sign}(9(1 + \sum_{i=1}^d x_{pi}x_{qi}))$$

$$= \text{sign}(1 + \sum_{i=1}^d x_{pi}x_{qi})$$

$$= \text{sign}(\vec{x}_p^T \vec{x}_z)$$

$$= \text{sign}(\vec{w}_1^T \vec{x}_z)$$

Thus, if $\text{sign}(\vec{w}_1^T \vec{x}_z) \neq y_z$, then $\text{sign}(\vec{w}_1^T \vec{x}_z') \neq y_z$

Therefore, we can know that $\vec{w}_{PLA} = \vec{w}'_{PLA}$.