

# Optimization Algorithms: HW2

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## 1

We're given the following problem:

$$x_{\star} \in \arg \min_{x \in \Delta_d} f(x), \quad f(x) = - \sum_{i=1}^n w_i \log \langle a_i, x \rangle$$

where:

1.

$$x \in \Delta_d = \{x \in \mathbb{R}^d \mid x[i] \geq 0, \sum_{i=1}^d x[i] = 1\} \text{ (probability simplex)}$$

2.

$$w_i \in \mathbb{R}, w_i > 0, \sum_{i=1}^n w_i = 1$$

3.

$$a_i \in \mathbb{R}^d, a_i = \begin{bmatrix} a_i[1] \\ a_i[2] \\ \vdots \\ a_i[d] \end{bmatrix},$$
$$a_i[j] \geq 0 \quad \forall i = 1, \dots, n, j = 1, \dots, d$$
$$a_i \neq 0 \quad \forall i = 1, \dots, n$$

We're asked to show that:

$f$  is 1-smooth relative to the log-barrier, which is defined as:

$$h(x) = - \sum_{i=1}^d \log x[i]$$

*Solution.* By the following proposition <sup>1</sup>:

PROPOSITION 1.1. *The following conditions are equivalent:*  
 (a-i)  $f(\cdot)$  is  $L$ -smooth relative to  $h(\cdot)$ ;  
 (a-ii)  $Lh(\cdot) - f(\cdot)$  is a convex function on  $Q$ ;  
 (a-iii) under twice differentiability  $\nabla^2 f(x) \preceq L\nabla^2 h(x)$  for any  $x \in \text{int } Q$ ;  
 (a-iv)  $\langle \nabla f(x) - \nabla f(y), x - y \rangle \leq L \langle \nabla h(x) - \nabla h(y), x - y \rangle$  for all  $x, y \in \text{int } Q$ .

we could prove the required condition (which is (a-i), with  $L = 1$ ) by proving its equivalent condition (a-iii, with  $L = 1$ ).

First calculate  $\nabla f(x)$ :

$$\begin{aligned}\nabla f(x) &= \frac{d}{dx} \left( - \sum_{i=1}^n w_i \log \langle a_i, x \rangle \right) \\ &= - \sum_{i=1}^n w_i \cdot \frac{d}{dx} (\log \langle a_i, x \rangle) \\ &= - \sum_{i=1}^n w_i \cdot \left( \frac{a_i}{\langle a_i, x \rangle} \right) \\ &= - \sum_{i=1}^n w_i \frac{a_i}{\langle a_i, x \rangle}\end{aligned}$$

Then the Hessian of  $f$  is:

$$\begin{aligned}\nabla^2 f(x) &= \frac{d}{dx} \left( - \sum_{i=1}^n w_i \frac{a_i}{\langle a_i, x \rangle} \right) \\ &= - \sum_{i=1}^n w_i \cdot \frac{d}{dx} \left( \frac{a_i}{\langle a_i, x \rangle} \right) \\ &= - \sum_{i=1}^n w_i \cdot \left( \frac{a_i}{\langle a_i, x \rangle^2} a_i^T \right)\end{aligned}$$

Expanding the expression and writing in another form, we have:

$$\nabla^2 f(x) = - \sum_{i=1}^n \frac{w_i}{\langle a_i, x \rangle^2} a_i a_i^T \quad (1)$$

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<sup>1</sup>Relative Smooth Convex Optimization by First-Order Methods, and Applications, MIT Lecture Notes, available at: <https://dspace.mit.edu/bitstream/handle/1721.1/120867/16m1099546.pdf>, accessed: May. 9, 2025, p. 336.

Then we shall do the same to  $h(x)$

$$\begin{aligned}\nabla h(x) &= \frac{d}{dx} \left( - \sum_{i=1}^d \log x[i] \right) \\ &= \begin{bmatrix} -\frac{1}{x[1]} \\ -\frac{1}{x[2]} \\ \vdots \\ -\frac{1}{x[d]} \end{bmatrix}\end{aligned}$$

Then  $\nabla^2 h(x)$  is:

$$\begin{aligned}\nabla^2 h(x) &= \nabla \begin{bmatrix} -\frac{1}{x[1]} \\ -\frac{1}{x[2]} \\ \vdots \\ -\frac{1}{x[d]} \end{bmatrix} \\ &= \begin{bmatrix} \frac{d}{dx[1]} \left( -\frac{1}{x[1]} \right) & \frac{d}{dx[2]} \left( -\frac{1}{x[1]} \right) & \cdots & \frac{d}{dx[d]} \left( -\frac{1}{x[1]} \right) \\ \frac{d}{dx[1]} \left( -\frac{1}{x[2]} \right) & \frac{d}{dx[2]} \left( -\frac{1}{x[2]} \right) & \cdots & \frac{d}{dx[d]} \left( -\frac{1}{x[2]} \right) \\ \vdots & \vdots & \ddots & \vdots \\ \frac{d}{dx[1]} \left( -\frac{1}{x[d]} \right) & \frac{d}{dx[2]} \left( -\frac{1}{x[d]} \right) & \cdots & \frac{d}{dx[d]} \left( -\frac{1}{x[d]} \right) \end{bmatrix} \\ &= \begin{bmatrix} \frac{1}{x[1]^2} & 0 & \cdots & 0 \\ 0 & \frac{1}{x[2]^2} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \frac{1}{x[d]^2} \end{bmatrix} \tag{2}\end{aligned}$$

Observe  $\nabla^2 f(x)$  in (1), since we're given  $w_i > 0$ ,  $x \in \Delta_d$ ,  $a_i \neq 0$ , and with proposition (a-iii) only requires dealing with  $\text{int } \Delta_d$ , we can guarantee  $x[i] > 0$ , so the scalar  $\frac{w_i}{\langle a_i, x \rangle^2} > 0$ .

Also, we knew that for any  $a_i \neq 0$ ,  $a_i a_i^T$  is positive semidefinite, thus, each term in the summation is positive semidefinite, by summing up the  $n$  terms and adding a negative sign, we have  $\nabla^2 f(x) \preceq 0$  as follows:

$$\nabla^2 f(x) = - \sum_{i=1}^n \frac{w_i}{\langle a_i, x \rangle^2} a_i a_i^T \preceq 0$$

Then, since  $\nabla^2 h(x)$  is a diagonal matrix, and we're given that  $x[i] \geq 0$ , same as above, with proposition (a-iii) only requires dealing with  $\text{int } \Delta_d$ , we can guarantee  $x[i] > 0$  (so for each  $\frac{1}{x[i]}$ ), and  $\nabla^2 h(x)$  is positive definite.

Therefore, we have:

$$\nabla^2 f(x) \preceq 1 \cdot \nabla^2 h(x) \quad \text{for any } x \in \text{int } \Delta_d$$

which means that (a-iii) is proved, and its equivalent condition (a-i) is also proved, and we have:

$f$  is 1-smooth relative to the log-barrier  $h$

■

Denote the Bregman divergence associated with  $h$  as  $D_h$ , i.e.,

$$D_h(y, x) = h(y) - [h(x) + \langle \nabla h(x), (y - x) \rangle]$$

Consider solving the optimization problem (1) by the following algorithm:

- Let  $x_1 = \begin{bmatrix} \frac{1}{d} \\ \vdots \\ \frac{1}{d} \end{bmatrix} \in \Delta_d$
- For every  $t \in \mathbb{N}$ , compute:

$$x_{t+1} \in \arg \min_{x \in \Delta_d} [\langle \nabla f(x_t), x - x_t \rangle + D_h(x, x_t)]$$

Note: I use  $\begin{bmatrix} \frac{1}{d} \\ \vdots \\ \frac{1}{d} \end{bmatrix}$  to represent the vector  $(1/d, \dots, 1/d)$  (which is the notation used in the HW spec) in the following solution.

## 2

Show that for any  $x \in \Delta_d$  and  $0 \leq \alpha < 1$ ,

$$f(x_\alpha) \leq f(x) + \frac{\alpha}{1 - \alpha}, \quad \text{where } x_\alpha = (1 - \alpha)x + \alpha \begin{bmatrix} \frac{1}{d} \\ \vdots \\ \frac{1}{d} \end{bmatrix}$$

*Solution.* From the previous subproblem, we knew that  $f$  is 1-smooth relative to the log-barrier, so we have:

$$f(y) \leq f(x) + \langle \nabla f(x), y - x \rangle + D_h(y, x) \quad \forall x, y \in \text{int } \Delta_d$$

To bound  $f(x_\alpha)$ , we first show that  $x_\alpha \in \text{int } \Delta_d$ , and then let  $y = x_\alpha$ ,  $x = x$  so that we would have:

$$f(x_\alpha) \leq f(x) + \langle \nabla f(x), x_\alpha - x \rangle + D_h(x_\alpha, x)$$

By the definition of  $x_\alpha$ , we knew that it is the convex combination of  $x$  and  $\begin{bmatrix} \frac{1}{d} \\ \vdots \\ \frac{1}{d} \end{bmatrix}$ , where  $x \in \Delta_d$  and  $\begin{bmatrix} \frac{1}{d} \\ \vdots \\ \frac{1}{d} \end{bmatrix} = x_1 \in \Delta_d$  as stated in the algorithm. Also, for

each element in  $x_\alpha$ , we have:

$$x_\alpha[i] = (1 - \alpha)x[i] + \alpha \left( \frac{1}{d} \right) \quad \forall i = 1, \dots, d$$

Since  $x[i] \geq 0$  and  $\alpha$  is strictly smaller than 1, consider the case that  $0 < \alpha < 1$ , then we have  $x_\alpha[i] > 0$  for all  $i = 1, \dots, d$ . For  $\alpha = 0$ , we have  $x_\alpha[i] = x[i] \geq 0$  for all  $i = 1, \dots, d$ , and since in order to use the previous inequality, we need  $x \in \text{int } \Delta_d$ , thus each  $x[i]$  is strictly positive, so we have  $x_\alpha \in \text{int } \Delta_d$  for  $\alpha = 0$  (and also for  $0 < \alpha < 1$ ).

$\rightarrow$  need to be true for all  $x \in \Delta_d$

Then, we have:

$$f(x_\alpha) \leq f(x) + \langle \nabla f(x), x_\alpha - x \rangle + D_h(x_\alpha, x)$$

To further simplify, we have:

$$x_\alpha - x = \left[ (1 - \alpha)x + \alpha \begin{bmatrix} \frac{1}{d} \\ \vdots \\ \frac{1}{d} \end{bmatrix} \right] - x = \alpha \left[ \begin{bmatrix} \frac{1}{d} \\ \vdots \\ \frac{1}{d} \end{bmatrix} - x \right]$$

So we could expand the following expressions:

$$\begin{aligned}
\langle \nabla f(x), x_\alpha - x \rangle &= \left\langle -\sum_{i=1}^n w_i \frac{a_i}{\langle a_i, x \rangle}, \alpha \left( \begin{bmatrix} \frac{1}{d} \\ \vdots \\ \frac{1}{d} \end{bmatrix} - x \right) \right\rangle \\
&= -\frac{\alpha}{d} \sum_{i=1}^n \frac{w_i}{\langle a_i, x \rangle} [a_i[1] \cdots a_i[d]] \begin{bmatrix} 1 - x[1] \\ \vdots \\ 1 - x[d] \end{bmatrix} \\
&= -\frac{\alpha}{d} \sum_{i=1}^n \frac{w_i}{\langle a_i, x \rangle} \left( \sum_{j=1}^d a_i[j] - \sum_{j=1}^d a_i[j]x[j] \right) \\
&= -\frac{\alpha}{d} \sum_{i=1}^n \frac{w_i}{\sum_{k=1}^d a_i[k]x[k]} \left( \sum_{j=1}^d a_i[j] - \sum_{j=1}^d a_i[j]x[j] \right) \\
&= -\frac{\alpha}{d} \sum_{i=1}^n \frac{w_i \sum_{j=1}^d a_i[j]}{\sum_{k=1}^d a_i[k]x[k]} + \frac{\alpha}{d} \sum_{i=1}^n w_i \\
&= \frac{\alpha}{d} \left( 1 - \sum_{i=1}^n w_i \sum_{j=1}^d \frac{a_i[j]}{a_i[j]x[j]} \right) \\
&= \frac{\alpha}{d} \left( 1 - \sum_{i=1}^n w_i \sum_{j=1}^d \frac{1}{x[j]} \right) \tag{1}
\end{aligned}$$

By the definition of  $D_h$ , we have:

$$\begin{aligned}
D_h(x_\alpha, x) &= h(x_\alpha) - (h(x) + \langle \nabla h(x), (x_\alpha - x) \rangle) \\
&= h(x_\alpha) - \left( h(x) + \left\langle \begin{bmatrix} -\frac{1}{x[1]} \\ -\frac{1}{x[2]} \\ \vdots \\ -\frac{1}{x[d]} \end{bmatrix}, \alpha \left( \begin{bmatrix} \frac{1}{d} \\ \vdots \\ \frac{1}{d} \end{bmatrix} - x \right) \right\rangle \right) \\
&= -\sum_{i=1}^d \log x_\alpha[i] - \left( -\sum_{i=1}^d \log x[i] + \left\langle \begin{bmatrix} -\frac{1}{x[1]} \\ -\frac{1}{x[2]} \\ \vdots \\ -\frac{1}{x[d]} \end{bmatrix}, \alpha \left( \begin{bmatrix} \frac{1}{d} \\ \vdots \\ \frac{1}{d} \end{bmatrix} - x \right) \right\rangle \right) \\
&= -\sum_{i=1}^d \log x_\alpha[i] + \sum_{i=1}^d \log x[i] + \alpha \left[ -\frac{1}{x[1]} \cdots -\frac{1}{x[d]} \right] \begin{bmatrix} \frac{1-dx[1]}{d} \\ \vdots \\ \frac{1-dx[d]}{d} \end{bmatrix} \\
&= \sum_{i=1}^d (\log x[i] - \log x_\alpha[i]) - \sum_{i=1}^d \frac{\alpha}{dx[i]} + \alpha d
\end{aligned} \tag{2}$$

Combining (1) and (2), we have:

$$\begin{aligned}
&\langle \nabla f(x), x_\alpha - x \rangle + D_h(x_\alpha, x) \\
&= \frac{\alpha}{d} \left( 1 - \sum_{i=1}^n w_i \sum_{j=1}^d \frac{1}{x[j]} \right) + \sum_{i=1}^d (\log x[i] - \log x_\alpha[i]) - \sum_{i=1}^d \frac{\alpha}{dx[i]} + \alpha d \\
&=
\end{aligned}$$

■

**3**

**4**

*Solution.* We need to show that:

$$\begin{aligned}
x_{t+1} &= \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix} \oslash \left\{ \nabla f(x_t) + \begin{bmatrix} \frac{1}{x_t[1]} \\ \vdots \\ \frac{1}{x_t[d]} \end{bmatrix} + \begin{bmatrix} \lambda \\ \vdots \\ \lambda \end{bmatrix} \right\} \\
&= \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix} \oslash \begin{bmatrix} \frac{\nabla f(x_t)x_t[1]+1+\lambda x_t[1]}{x_t[1]} \\ \vdots \\ \frac{\nabla f(x_t)x_t[d]+1+\lambda x_t[d]}{x_t[d]} \end{bmatrix} \\
&= \begin{bmatrix} \frac{x_t[1]}{\nabla f(x_t)x_t[1]+1+\lambda x_t[1]} \\ \vdots \\ \frac{x_t[d]}{\nabla f(x_t)x_t[d]+1+\lambda x_t[d]} \end{bmatrix} \\
&= \begin{bmatrix} \frac{1}{\nabla f(x_t) + \frac{1}{x_t[1]} + \lambda} \\ \vdots \\ \frac{1}{\nabla f(x_t) + \frac{1}{x_t[d]} + \lambda} \end{bmatrix} \tag{*}
\end{aligned}$$

By the updating rule, we have:

$$\begin{aligned}
x_{t+1} &\in \arg \min_{x \in \Delta_d} \{ \langle \nabla f(x_t), x - x_t \rangle + D_h(x, x_t) \} \\
\rightarrow x_{t+1} &\in \arg \min_{x \in \Delta_d} \{ \langle \nabla f(x_t), x - x_t \rangle + h(x) - [h(x_t) + \langle \nabla h(x_t), x - x_t \rangle] \} \\
\rightarrow x_{t+1} &\in \arg \min_{x \in \Delta_d} \{ \langle \nabla f(x_t), x - x_t \rangle + h(x) - h(x_t) - \langle \nabla h(x_t), x - x_t \rangle \} \\
\rightarrow x_{t+1} &\in \arg \min_{x \in \Delta_d} \{ \langle \nabla f(x_t), x - x_t \rangle + h(x) - h(x_t) - \langle \nabla h(x_t), x \rangle + \langle \nabla h(x_t), x_t \rangle \} \tag{1}
\end{aligned}$$

Recall we previously derived that:

$$\nabla h(x_t) = \begin{bmatrix} -\frac{1}{x_t[1]} \\ -\frac{1}{x_t[2]} \\ \vdots \\ -\frac{1}{x_t[d]} \end{bmatrix}$$

So:

$$\langle \nabla h(x_t), x_t \rangle = \left[ -\frac{1}{x_t[1]} \cdots -\frac{1}{x_t[d]} \right] \begin{bmatrix} x_t[1] \\ \vdots \\ x_t[d] \end{bmatrix} = -\sum_{i=1}^d \frac{1}{x_t[i]} x_t[i] = -d$$



Plugging this into (1), we have:

$$x_{t+1} \in \arg \min_{x \in \Delta_d} \{ \langle \nabla f(x_t), x - x_t \rangle + h(x) - h(x_t) - \langle \nabla h(x_t), x - x_t \rangle \}$$

(Similarly,  $\langle \nabla f(x_t), x_t \rangle$  would also be a constant.)

Since we need to find the  $x$  that gives the minimum, we can drop the terms that are constant or independent of  $x$  (the Green terms), so we have:

$$x_{t+1} \in \arg \min_{x \in \Delta_d} \{ \langle \nabla f(x_t), x \rangle + h(x) - \langle \nabla h(x_t), x \rangle \}$$

Combining the inner product terms, we have:

$$x_{t+1} \in \arg \min_{x \in \Delta_d} \{ \langle \nabla f(x_t) - \nabla h(x_t), x \rangle + h(x) \}$$

Expand this equation by what we previously derived:

$$\begin{aligned} \nabla h(x_t) &= \begin{bmatrix} -\frac{1}{x_t[1]} \\ -\frac{1}{x_t[2]} \\ \vdots \\ -\frac{1}{x_t[d]} \end{bmatrix} \\ h(x) &= -\sum_{i=1}^d \log x[i] \end{aligned}$$

we have:

$$x_{t+1} \in \arg \min_{x \in \Delta_d} \sum_{i=1}^d \left( \nabla f(x_t)[i] + \frac{1}{x_t[i]} \right) x[i] - \sum_{i=1}^d \log x[i]$$

In order to deal with the constraint  $x \in \Delta_d$ , we can use Lagrange multiplier  $\lambda$  and write the Lagrangian as:

$$L(x, \lambda) = \sum_{i=1}^d \left( \nabla f(x_t)[i] + \frac{1}{x_t[i]} \right) x[i] - \sum_{i=1}^d \log x[i] + \lambda \left( \sum_{i=1}^d x[i] - 1 \right)$$

Then taking the derivative w.r.t.  $x[i]$  and set the result to 0 to find the optimal  $x$ , we have:

$$\frac{\partial L}{\partial x[i]} = \nabla f(x_t)[i] + \frac{1}{x_t[i]} - \frac{1}{x[i]} + \lambda = 0$$

Rearrange to solve for  $x[i]$ , we have:

$$\begin{aligned}\frac{1}{x[i]} &= \nabla f(x_t)[i] + \frac{1}{x_t[i]} + \lambda \\ \rightarrow x[i] &= \frac{1}{\nabla f(x_t)[i] + \frac{1}{x_t[i]} + \lambda}\end{aligned}$$

And this matches with (\*), which is the given updating rule. ■

## 5

We need to show that the following function is self-concordant:

$$\varphi(u) = u - \sum_{i=1}^d \log(u + \nabla f(x_t)[i] + \frac{1}{x_t[i]})$$

*Solution.* In order to show that  $\varphi(u)$  is self-concordant, since  $\varphi(u)$  is univariate, we can directly use the following definition <sup>2</sup>:

**Self-concordant for univariate functions**

A function  $f : \mathbb{R} \rightarrow \mathbb{R}$  is self-concordant on  $\mathbb{R}$  if :

$$|f'''(x)| \leq 2f''(x)^{3/2}$$

Claim:

$$|\varphi'''(u)| \leq 2\varphi''(u)^{3/2}$$

Proof: Let us define:

$$y_i := u + \nabla f(x_t)[i] + \frac{1}{x_t[i]}, \quad \forall i = 1, \dots, d$$

Then, the original function  $\varphi(u)$  can be rewritten as:

$$\varphi(u) = u - \sum_{i=1}^d \log y_i = u + \sum_{i=1}^d (-\log y_i)$$

Now we can compute the derivatives of  $\varphi(u)$ :

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<sup>2</sup>*Self-concordant function*, available at: [https://en.wikipedia.org/wiki/Self-concordant\\_function#Univariate\\_self-concordant\\_function](https://en.wikipedia.org/wiki/Self-concordant_function#Univariate_self-concordant_function), accessed: May. 29, 2025.

$$\varphi'(u) = 1 - \sum_{i=1}^d \frac{1}{y_i}$$

and the second derivative:

$$\varphi''(u) = \sum_{i=1}^d \frac{1}{y_i^2}$$

and the third derivative:

$$\varphi'''(u) = -2 \sum_{i=1}^d \frac{1}{y_i^3}$$

Now we have:

$$\begin{aligned} |\varphi'''(u)| &= 2 \sum_{i=1}^d \frac{1}{y_i^3} \\ \varphi''(u) &= \sum_{i=1}^d \frac{1}{y_i^2} \end{aligned}$$

In order to let the original definition of  $\varphi(u)$  be valid,  $y_i \in (0, \infty)$  must hold, thus, if we further define  $g(y_i) = -\log y_i$ , then

$$g : \{y_i \in \mathbb{R} \mid y_i > 0\} \rightarrow \mathbb{R}$$

, and we have:

$$\begin{aligned} g'(y_i) &= \frac{d}{dy_i}(-\log y_i) = -\frac{1}{y_i} \\ g''(y_i) &= \frac{d}{dy_i} \left( -\frac{1}{y_i} \right) = \frac{1}{y_i^2} \\ g'''(y_i) &= \frac{d}{dy_i} \left( \frac{1}{y_i^2} \right) = -\frac{2}{y_i^3} \end{aligned}$$

And we have:

$$|g'''(y_i)| = \left| -\frac{2}{y_i^3} \right| = \frac{2}{y_i^3} \leq 2 \left( \frac{1}{y_i^2} \right)^{3/2} = 2 \left( \frac{1}{y_i^3} \right)$$

Which shows that  $g(y_i)$  is self-concordant.

Then, using the following property <sup>3</sup>:

■ **Sum of self-concordant functions.** The set of self-concordant functions is closed under addition.

**Theorem 2.2.** Let  $f_1 : \Omega_1 \rightarrow \mathbb{R}$  and  $f_2 : \Omega_2 \rightarrow \mathbb{R}$  be self-concordant functions whose domains satisfy  $\Omega_1 \cap \Omega_2 \neq \emptyset$ . Then, the function  $f + g : \Omega_1 \cap \Omega_2 \rightarrow \mathbb{R}$  is self-concordant.

Since  $g(y_i)$  is self-concordant for all  $i = 1, \dots, d$ , and they have the same domain, so  $\bigcap_{i=1}^d \text{dom } g(y_i) \neq \emptyset$ , thus, their sum:

$$\sum_{i=1}^d g(y_i) = \sum_{i=1}^d (-\log y_i)$$

is also self-concordant.

Then, using another property:

■ **Addition of an affine function.** Addition of an affine function to a self-concordant functions does not affect the self-concordance property, since self-concordance depends only on the Hessian of the function, and the addition of affine functions does not affect the Hessian.

**Theorem 2.3.** Let  $f : \Omega \rightarrow \mathbb{R}$  be self-concordant function. Then, the function  $g(x) := f(x) + \langle a, x \rangle + b$  is self-concordant on  $\Omega$ .

If we let  $h(u) = u$ , then  $h$  is an affine function, then our self concordant function  $\sum_{i=1}^d (-\log y_i)$  plussing the affine function  $h$ :

$$\varphi(u) = u + \sum_{i=1}^d (-\log y_i)$$

is also self-concordant. ■

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<sup>3</sup>G. Farina, *Lecture 14A–B: Self-concordant functions*, MIT 6.7220/15.084 — Nonlinear Optimization, Apr. 16–18<sup>th</sup> 2024. Available at: [https://www.mit.edu/~gfarina/2024/67220s24\\_L14B\\_self\\_concordance/L14.pdf](https://www.mit.edu/~gfarina/2024/67220s24_L14B_self_concordance/L14.pdf), p. 4.

## 6

We're given that:

$$g_\mu(w) = \max_{v \in \mathcal{B}_\infty} \langle w, v \rangle - \frac{\mu}{2} \|v\|_2^2$$

where  $\mathcal{B}_\infty$  is the unit  $l_\infty$  norm ball.

We need to show that  $g_\mu$  is differentiable and:

$$\nabla g_\mu(w) = \begin{cases} 1 & \text{if } w[i] \geq \mu \\ \frac{w[i]}{\mu} & \text{if } -\mu \leq w[i] \leq \mu \\ -1 & \text{if } w[i] < -\mu \end{cases}$$

*Solution.* By the definition of  $l_\infty$  norm, we have:

$$\|v\|_\infty \leq 1 \iff \max_{i=1, \dots, d} |v[i]| \leq 1$$

Then the original  $g_\mu(w)$  can be rewritten as:

$$g_\mu(w) = \max_{v \in \mathcal{B}_\infty} \sum_{i=1}^d \left( w[i]v[i] - \frac{\mu}{2} v[i]^2 \right), \quad \text{where } \|v\|_\infty \leq 1$$

Since to find the  $v$  that maximizes the above expression, we can independently find each  $v[i]$  that maximizes the component in the summation, so we can further define:

$$h_i(w[i]) = \max_{|v[i]| \leq 1} \left( w[i]v[i] - \frac{\mu}{2} v[i]^2 \right)$$

Then the original  $g_\mu(w)$  can be rewritten as:

$$g_\mu(w) = \sum_{i=1}^d h_i(w[i])$$

Now we can prove the differentiability of  $g_\mu(w)$  by proving the differentiability of each  $h_i(w[i])$ . Let:

$$f_{w[i]}(v[i]) = w[i]v[i] - \frac{\mu}{2} v[i]^2$$

Since  $w[i]v[i]$  is linear in  $v[i]$ , and the quadratic term  $-\frac{\mu}{2}v[i]^2 < 0$  (for  $\mu > 0$ ),  $f_{w[i]}(v[i])$  is concave in  $v[i]$ , which means that exists a unique  $v^*[i]$  that maximizes  $f_{w[i]}(v[i])$ , and we have:

$$\frac{d}{dv[i]} f_{w[i]}(v[i]) = w[i] - \mu v[i] = 0 \iff v[i]^* = \frac{w[i]}{\mu}$$

Thus, if we do not restrict the solution to be in the unit ball, the  $v$  that maximizes  $\langle w, v \rangle - \frac{\mu}{2} \|v\|_2^2$  is:

$$v^* = \begin{bmatrix} \frac{w[1]}{\mu} \\ \vdots \\ \frac{w[d]}{\mu} \end{bmatrix} = \begin{bmatrix} v[1] \\ \vdots \\ v[d] \end{bmatrix}$$

To further impose the restriction that  $\max_{i=1,\dots,d} |v[i]| \leq 1$ , the optimal  $v$  need to satisfy:

$$v[i] \in [-1, 1]$$

Thus, we need to project  $v[i]$  to the interval  $[-1, 1]$ , by the following definition of Euclidean projection<sup>4</sup>:

- The Euclidean projection of  $x_0$  on a rectangle  $C = \{x \mid l \preceq x \preceq u\}$  (where  $l \prec u$ ) is given by

$$P_C(x_0)_k = \begin{cases} l_k & x_{0k} \leq l_k \\ x_{0k} & l_k \leq x_{0k} \leq u_k \\ u_k & x_{0k} \geq u_k \end{cases}$$

We have:

$$\text{proj}_{[-1,1]}(v[i]) = \begin{cases} -1 & \text{if } v[i] < -1 \\ v[i] & \text{if } -1 \leq v[i] \leq 1 \\ 1 & \text{if } v[i] > 1 \end{cases}$$

or equivalently:

$$\text{proj}_{[-1,1]} \left( \frac{w[i]}{\mu} \right) = v^*(w[i]) = \begin{cases} -1 & \text{if } w[i] < -\mu \\ \frac{w[i]}{\mu} & \text{if } |w[i]| \leq \mu \\ 1 & \text{if } w[i] > \mu \end{cases} \quad (1)$$

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<sup>4</sup>S. Boyd, *Convex Optimization*, 1st ed., Cambridge University Press, Cambridge, UK, 2004, p. 399.

And this matches the given  $\nabla g_\mu(w)[i]$ .

Then getting back to the part of proving differentiability, we have  $h_i(w[i])$ :

$$\begin{aligned}
h_i(w[i]) &= \max_{|v[i]| \leq 1} \left( w[i]v[i] - \frac{\mu}{2}v[i]^2 \right) \\
&= \max_{|v[i]| \leq 1} (f_{w[i]}(v[i])) \\
&= f_{w[i]}(v^\star(w[i])) \\
&= w[i]v^\star(w[i]) - \frac{\mu}{2}(v^\star(w[i]))^2
\end{aligned} \tag{2}$$

Consider the three cases of  $\text{proj}_{[-1,1]}(v[i])$  in (1):

- Case 1:  $w[i] < -\mu$

Then  $v^\star(w[i]) = -1$ , and by plugging it into (2):

$$\begin{aligned}
h_i(w[i]) &= w[i](-1) - \frac{\mu}{2}(-1)^2 = -w[i] - \frac{\mu}{2} \\
\rightarrow h'_i(w[i]) &= \frac{d}{dw[i]} \left( -w[i] - \frac{\mu}{2} \right) = -1
\end{aligned}$$

- Case 2:  $-\mu \leq w[i] \leq \mu$

Then  $v^\star(w[i]) = \frac{w[i]}{\mu}$ , and by plugging it into (2):

$$\begin{aligned}
h_i(w[i]) &= w[i] \frac{w[i]}{\mu} - \frac{\mu}{2} \left( \frac{w[i]}{\mu} \right)^2 = \frac{w[i]^2}{\mu} - \frac{\mu}{2} \frac{w[i]^2}{\mu^2} = \frac{w[i]^2}{2\mu} \\
\rightarrow h'_i(w[i]) &= \frac{d}{dw[i]} \left( \frac{w[i]^2}{2\mu} \right) = \frac{w[i]}{\mu}
\end{aligned}$$

- Case 3:  $w[i] > \mu$

Then  $v^\star(w[i]) = 1$ , and by plugging it into (2):

$$\begin{aligned}
h_i(w[i]) &= w[i](1) - \frac{\mu}{2}(1)^2 = w[i] - \frac{\mu}{2} \\
\rightarrow h'_i(w[i]) &= \frac{d}{dw[i]} \left( w[i] - \frac{\mu}{2} \right) = 1
\end{aligned}$$

Thus, at the boundaries:

- $w[i] = \mu$

Left derivative:

$$\lim_{w[i] \rightarrow \mu^-} h'_i(w[i]) = \lim_{w[i] \rightarrow \mu^-} \frac{w[i]}{\mu} = \frac{\mu}{\mu} = 1$$

Right derivative:

$$\lim_{w[i] \rightarrow \mu^+} h'_i(w[i]) = 1$$

- $w[i] = -\mu$

Left derivative:

$$\lim_{w[i] \rightarrow -\mu^-} h'_i(w[i]) = -1$$

Right derivative:

$$\lim_{w[i] \rightarrow -\mu^+} h'_i(w[i]) = \lim_{w[i] \rightarrow -\mu^+} \frac{w[i]}{\mu} = \frac{-\mu}{\mu} = -1$$

And in the interior:

$$\begin{aligned} h'_i(w[i]) &= w[i] \frac{w[i]}{\mu} - \frac{\mu}{2} \left( \frac{w[i]}{\mu} \right)^2 \\ &= \frac{w[i]^2}{\mu} - \frac{w[i]^2}{2\mu} \\ &= \frac{w[i]^2}{2\mu} \end{aligned}$$

Which always exists and is unique.

Therefore,  $h_i(w[i])$  is differentiable, and  $g_\mu(w) = \sum_{i=1}^d h_i(w[i])$  is a sum of differentiable functions, so  $g_\mu(w)$  is also differentiable. ■



## 7

We need to further prove that  $g_\mu$  is  $\frac{1}{\mu}$ -smooth.

*Solution.* By the definition in the following image <sup>5</sup>:

**Definition 2.** Differentiable<sup>2</sup>  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  is  $L$ -smooth if and only for all  $x, y \in \mathbb{R}^n$  we have that

$$\|\nabla f(x) - \nabla f(y)\|_2 \leq L \cdot \|x - y\|_2$$

Since we have already proved that  $g_\mu(w)$  is differentiable, proving the following claim is equivalent to proving that  $g_\mu(w)$  is  $\frac{1}{\mu}$ -smooth.

Claim:

$$\|\nabla g_\mu(w_1) - \nabla g_\mu(w_2)\|_2 \leq \frac{1}{\mu} \|w_1 - w_2\|_2, \quad \forall w_1, w_2 \in \mathbb{R}^d$$

Proof: Following the notation in the previous subproblem, we have:

$$\nabla g_\mu(w) = \begin{bmatrix} \nabla g_\mu(w)[1] \\ \vdots \\ \nabla g_\mu(w)[d] \end{bmatrix}$$

Let:

$$w_1 = \begin{bmatrix} w_1[1] \\ \vdots \\ w_1[d] \end{bmatrix}, \quad w_2 = \begin{bmatrix} w_2[1] \\ \vdots \\ w_2[d] \end{bmatrix}$$

Then we have:

$$\nabla g_\mu(w_1) - \nabla g_\mu(w_2) = \begin{bmatrix} \nabla g_\mu(w_1)[1] - \nabla g_\mu(w_2)[1] \\ \vdots \\ \nabla g_\mu(w_1)[d] - \nabla g_\mu(w_2)[d] \end{bmatrix}$$

The maximum of  $\|\nabla g_\mu(w_1) - \nabla g_\mu(w_2)\|_2$  happens when:

$$\nabla g_\mu(w_1) = \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix} \quad \text{and} \quad \nabla g_\mu(w_2) = \begin{bmatrix} -1 \\ \vdots \\ -1 \end{bmatrix}$$

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<sup>5</sup>A. Sidford, *MS&E 213 / CS 269O: Chapter 2 — Smooth Functions*, Stanford University, Oct. 17, 2020. Available at: [https://web.stanford.edu/~sidford/courses/20fa\\_opt\\_theory/sidford\\_mse213\\_2020fa\\_chap\\_2\\_smoothness.pdf](https://web.stanford.edu/~sidford/courses/20fa_opt_theory/sidford_mse213_2020fa_chap_2_smoothness.pdf), p. 2.

which implies that:

$$w_1[i] \geq \mu, w_2[i] \leq -\mu \quad \forall i = 1, \dots, d \quad (1)$$

and we'll have:

$$\|\nabla g_\mu(w_1) - \nabla g_\mu(w_2)\|_2 = \left\| \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix} - \begin{bmatrix} -1 \\ \vdots \\ -1 \end{bmatrix} \right\|_2 = 2\sqrt{d}$$

Under the condition in (1), if we want to find the minimum of  $L\|w_1 - w_2\|_2$ , we can set  $w_1[i] = \mu$  and  $w_2[i] = -\mu$  for all  $i = 1, \dots, d$ , and we'll have:

$$L\|w_1 - w_2\|_2 = L \left\| \begin{bmatrix} \mu \\ \vdots \\ \mu \end{bmatrix} - \begin{bmatrix} -\mu \\ \vdots \\ -\mu \end{bmatrix} \right\|_2 = L\sqrt{4\mu^2 d} = L2\mu\sqrt{d}$$

Thus, we can set  $L = \frac{1}{\mu}$ , and we'll have:

$$\|\nabla g_\mu(w_1) - \nabla g_\mu(w_2)\|_2 = 2\sqrt{d} \leq 2\sqrt{d} = \frac{1}{\mu} 2\mu\sqrt{d} = \frac{1}{\mu} \|w_1 - w_2\|_2$$

■

## 8

We're asked to show that:

$$g_\mu(w) \leq g(w) \leq g_\mu(w) + \frac{\mu d}{2}$$

*Solution.* Since  $g(w)$  is defined as  $\|w\|_1$ , it is equivalent to show that:

$$g_\mu(w) \leq \|w\|_1 = \sum_{i=1}^d |w[i]| \leq g_\mu(w) + \frac{\mu d}{2}$$

We prove this by showing the two inequalities separately.

- $g_\mu(w) \leq g(w)$

Since the dual norm of  $\|\cdot\|_1$  is  $\|\cdot\|_\infty$ , we can rewrite the one norm  $\|w\|_1$  as <sup>6</sup>:

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<sup>6</sup>S. Boyd, *Convex Optimization*, 1st ed., Cambridge University Press, Cambridge, UK, 2004, p. 637.

$$g(w) = \|w\|_1 = \sup\{w^T v \mid \|v\|_\infty \leq 1\}$$

Compared with the definition of  $g_\mu(w)$ , we have:

$$g_\mu(w) = \max_{v \in \mathcal{B}_\infty} \langle w, v \rangle - \frac{\mu}{2} \|v\|_2^2$$

Since  $\mu$  is positive, and the square of a two norm  $\|v\|_2^2$  is always non-negative, the term  $\frac{\mu}{2} \|v\|_2^2$  is always non-negative, thus:

$$g_\mu(w) = \max_{v \in \mathcal{B}_\infty} \langle w, v \rangle - \frac{\mu}{2} \|v\|_2^2 \leq \sup\{w^T v \mid \|v\|_\infty \leq 1\} = g(w)$$

- $\underline{g(w) \leq g_\mu(w) + \frac{\mu d}{2}}$

Observe that:

$$g(w) = \|w\|_1 = \sum_{i=1}^d |w[i]| = [w[1] \cdots w[d]] \begin{bmatrix} \text{sign}(w[1]) \\ \vdots \\ \text{sign}(w[d]) \end{bmatrix} = \langle w, \text{sign}(w) \rangle$$

where  $\text{sign}(w)$  is the sign function, which is defined as:

$$\text{sign}(w[i]) = \begin{cases} 1 & \text{if } w[i] > 0 \\ -1 & \text{if } w[i] \leq 0 \end{cases}$$

Then let:

$$v^* = \arg \max_{v \in \mathcal{B}_\infty} \langle w, v \rangle = \text{sign}(w)$$

Since for all elements in  $\text{sign}(w)$ , its value is either 1 or  $-1$ ,  $\text{sign}(w) \in \mathcal{B}_\infty$ .

Thus, we can write:

$$\begin{aligned} g_\mu(w) &= \langle w, \text{sign}(w) \rangle - \frac{\mu}{2} \|\text{sign}(w)\|_2^2 \\ &= g(w) - \frac{\mu}{2} \cdot d \end{aligned}$$

And we can get the following inequality:

$$\begin{aligned} g_\mu(w) &= \max_{v \in B_\infty} \langle w, v \rangle - \frac{\mu}{2} \|v\|_2^2 \\ &\geq \langle w, v^* \rangle - \frac{\mu}{2} \|v^*\|_2^2 \\ &= g(w) - \frac{\mu}{2} d \end{aligned}$$

Therefore:

$$\begin{aligned} g_\mu(w) &\geq g(w) - \frac{\mu}{2} d \\ \rightarrow g(w) &\leq g_\mu(w) + \frac{\mu d}{2} \end{aligned}$$

■

## 9

*Solution.* We're given:

$$F = f + \lambda g$$

Claim:

$$F(w_{T+1}) - F(w_\star) \leq \frac{\lambda \sqrt{d}}{2\sqrt{T}} (\|w_1 - w_\star\|_2^2 + 1) + \frac{L\|w_1 - w_\star\|_2^2}{2T}$$

Proof:

Let us define:

$$F_\mu(w) = f(w) + \lambda g_\mu(w)$$

which is a little bit different from the original  $F$  in the problem statement by replacing  $g_\mu(w)$  with  $g(w)$ .

In the solution process, I aimed to use the following theorem <sup>7</sup>:

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<sup>7</sup>Lecture 6 of *10-725: Optimization*, taught by Ryan Tibshirani at Carnegie Mellon University in Fall 2013. Scribed by Micol Marchetti-Bowick. URL: <https://www.stat.cmu.edu/~ryantibs/convexopt-F13/scribes/lec6.pdf>, p. 6-1

**Theorem 6.1** Suppose the function  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  is convex and differentiable, and that its gradient is Lipschitz continuous with constant  $L > 0$ , i.e. we have that  $\|\nabla f(x) - \nabla f(y)\|_2 \leq L\|x - y\|_2$  for any  $x, y$ . Then if we run gradient descent for  $k$  iterations with a fixed step size  $t \leq 1/L$ , it will yield a solution  $f^{(k)}$  which satisfies

$$f(x^{(k)}) - f(x^*) \leq \frac{\|x^{(0)} - x^*\|_2^2}{2tk}, \quad (6.1)$$

Thus we need to prove the differentiability, convexity, and smoothness of  $F_\mu(w)$ .

$F_\mu(w)$  differentiable:

We're given that  $f$  is differentiable, and in the previous problem 6, we have proved that  $g_\mu(w)$  is differentiable, thus  $F_\mu(w)$  is differentiable.

$F_\mu(w)$  convex:

We're given that  $f$  is convex, so it remained to show that  $g_\mu(w)$  is convex.

$$g_\mu(w) = \max_{v \in B_\infty} \langle w, v \rangle - \frac{\mu}{2} \|v\|_2^2$$

Since  $\langle w, v \rangle - \frac{\mu}{2} \|v\|_2^2$  is affine, it is convex, and taking the maximum of a convex function is convex, thus  $g_\mu(w)$  is convex.

With both  $f$  and  $g_\mu(w)$  being convex, and the operations of addition and multiplication by a constant preserve convexity,  $F_\mu(w)$  is convex.

$F_\mu(w)$  smooth:

We're given that  $f$  is  $L$ -smooth, and in the previous problem 7, we have proved that  $g_\mu(w)$  is  $\frac{1}{\mu}$ -smooth, thus by the definition of  $L$ -smoothness <sup>8</sup>:

**Definition 2.** Differentiable<sup>2</sup>  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  is  $L$ -smooth if and only for all  $x, y \in \mathbb{R}^n$  we have that

$$\|\nabla f(x) - \nabla f(y)\|_2 \leq L \cdot \|x - y\|_2$$

we have:

$$\begin{aligned} \|\nabla f(w_1) - \nabla f(w_2)\|_2 &\leq L\|w_1 - w_2\|_2 \\ \|\nabla g_\mu(w_1) - \nabla g_\mu(w_2)\|_2 &\leq \frac{1}{\mu}\|w_1 - w_2\|_2 \end{aligned} \quad (1)$$

We then take gradient to the definition of  $F_\mu(w)$ :

<sup>8</sup>A. Sidford, *MS&E 213 / CS 269O: Chapter 2 — Smooth Functions*, Stanford University, Oct. 17, 2020. Available at: [https://web.stanford.edu/~sidford/courses/20fa\\_opt\\_theory/sidford\\_mse213\\_2020fa\\_chap\\_2\\_smoothness.pdf](https://web.stanford.edu/~sidford/courses/20fa_opt_theory/sidford_mse213_2020fa_chap_2_smoothness.pdf), p. 2.

$$\nabla F_\mu(w) = \nabla f(w) + \lambda \nabla g_\mu(w)$$

with triangle inequality, and replace (1) in, we have:

$$\begin{aligned} \|\nabla F_\mu(w_1) - \nabla F_\mu(w_2)\|_2 &= \|\nabla f(w_1) + \lambda \nabla g_\mu(w_1) - \nabla f(w_2) - \lambda \nabla g_\mu(w_2)\|_2 \\ &= \|\nabla f(w_1) - \nabla f(w_2) + \lambda \nabla g_\mu(w_1) - \lambda \nabla g_\mu(w_2)\|_2 \\ &\leq \|\nabla f(w_1) - \nabla f(w_2)\|_2 + \lambda \|\nabla g_\mu(w_1) - \nabla g_\mu(w_2)\|_2 \\ &\leq L\|w_1 - w_2\|_2 + \frac{\lambda}{\mu}\|w_1 - w_2\|_2 \\ &= \left(L + \frac{\lambda}{\mu}\right)\|w_1 - w_2\|_2 \end{aligned}$$

Thus we have derived that  $F_\mu(w)$  is  $L + \frac{\lambda}{\mu}$ -smooth.

Thus we can use the theorem above and get:

$$F_\mu(w_{T+1}) - F_\mu(w_\star) \leq \frac{\left(L + \frac{\lambda}{\mu}\right)\|w_1 - w_\star\|_2^2}{2T}$$

From problem 8, we have proved that:

$$g_\mu(w) \leq g(w) \leq g_\mu(w) + \frac{\mu d}{2}$$

so we have:

$$\begin{aligned} g(w_{T+1}) &\leq g_\mu(w_{T+1}) + \frac{\mu d}{2} \\ g_\mu(w_\star) &\leq g(w_\star) \quad (\text{or } -g(w_\star) \leq -g_\mu(w_\star)) \end{aligned}$$

and we could finally derive:

$$\begin{aligned}
F(w_{T+1}) - F(w_\star) &= f(w_{T+1}) + \lambda g(w_{T+1}) - f(w_\star) - \lambda g(w_\star) \\
&\leq f(w_{T+1}) + \lambda \left( g_\mu(w_{T+1}) + \frac{\mu d}{2} \right) - f(w_\star) - \lambda (g_\mu(w_\star)) \\
&= f(w_{T+1}) + \lambda (g_\mu(w_{T+1})) + \frac{\lambda \mu d}{2} - f(w_\star) - \lambda (g_\mu(w_\star)) \\
&= F_\mu(w_{T+1}) - F_\mu(w_\star) + \frac{\lambda \mu d}{2} \\
&\leq \frac{\left( L + \frac{\lambda}{\mu} \right) \|w_1 - w_\star\|_2^2}{2T} + \frac{\lambda \mu d}{2} \\
&= \frac{L \|w_1 - w_\star\|_2^2}{2T} + \frac{\frac{\lambda}{\mu} \|w_1 - w_\star\|_2^2}{2T} + \frac{\lambda \mu d}{2} \\
&= \frac{L \|w_1 - w_\star\|_2^2}{2T} + \frac{\lambda \left( \frac{1}{\mu} \|w_1 - w_\star\|_2^2 + T \mu d \right)}{2T} \tag{*}
\end{aligned}$$

By setting  $\mu = \frac{1}{\sqrt{Td}}$ , we have:

$$\begin{aligned}
F(w_{T+1}) - F(w_\star) &\leq \frac{L \|w_1 - w_\star\|_2^2}{2T} + \frac{\lambda \left( \frac{1}{\mu} \|w_1 - w_\star\|_2^2 + T \mu d \right)}{2T} \\
&= \frac{L \|w_1 - w_\star\|_2^2}{2T} + \frac{\lambda \left( \sqrt{Td} \|w_1 - w_\star\|_2^2 + T \frac{1}{\sqrt{Td}} d \right)}{2T} \\
&= \frac{L \|w_1 - w_\star\|_2^2}{2T} + \frac{\lambda \left( \sqrt{Td} \|w_1 - w_\star\|_2^2 + \sqrt{Td} \right)}{2T} \\
&= \frac{L \|w_1 - w_\star\|_2^2}{2T} + \frac{\lambda \sqrt{Td} (\|w_1 - w_\star\|_2^2 + 1)}{2T} \\
&= \frac{L \|w_1 - w_\star\|_2^2}{2T} + \frac{\lambda \sqrt{d} (\|w_1 - w_\star\|_2^2 + 1)}{2\sqrt{T}}
\end{aligned}$$

Which is the required bound. ■

## 10

*Solution.* If we want to get a tighter bound using accelerated gradient descent and choose other value of  $\mu$ , we should take the derivative w.r.t.  $\mu$  and set it to 0 to get the optimal  $\mu$ :

$$\begin{aligned}
& \frac{d}{d\mu} \left( \frac{\left(L + \frac{\lambda}{\mu}\right) \|w_1 - w_\star\|_2^2}{2T} + \frac{\lambda\mu d}{2} \right) = 0 \\
& \rightarrow \frac{(-\lambda) \|w_1 - w_\star\|_2^2}{2T\mu^2} + \frac{\lambda d}{2} = 0 \\
& \rightarrow \frac{\lambda d}{2} = \frac{\lambda \|w_1 - w_\star\|_2^2}{2T\mu^2} \\
& \rightarrow d = \frac{\|w_1 - w_\star\|_2^2}{T\mu^2} \\
& \rightarrow \mu^2 = \frac{\|w_1 - w_\star\|_2^2}{Td} \\
& \rightarrow \mu = \sqrt{\frac{\|w_1 - w_\star\|_2^2}{Td}} \\
& \rightarrow \mu = \sqrt{\frac{\|w_1 - w_\star\|_2^2}{Td}}
\end{aligned}$$

Substitute  $\mu = \sqrt{\frac{\|w_1 - w_\star\|_2^2}{Td}}$  into (\*), we have:

$$\begin{aligned}
F(w_{T+1}) - F(w_\star) & \leq \frac{L\|w_1 - w_\star\|_2^2}{2T} + \frac{\lambda \left( \frac{1}{\mu} \|w_1 - w_\star\|_2^2 + T\mu d \right)}{2T} \\
& = \frac{L\|w_1 - w_\star\|_2^2}{2T} + \frac{\lambda \left( \frac{1}{\sqrt{\frac{\|w_1 - w_\star\|_2^2}{Td}}} \|w_1 - w_\star\|_2^2 + T\sqrt{\frac{\|w_1 - w_\star\|_2^2}{Td}} d \right)}{2T}
\end{aligned}$$

■