

Bootstrapping Multi-atlas Hippocampal Segmentation with MAGeT-Brain

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Abstract

Neuroimaging research often relies on automated anatomical segmentations of MR images of the brain. Current multi-atlas based approaches provide accurate segmentations of brain images by propagating manually derived segmentations of specific neuroanatomical structures to unlabelled data. These approaches often rely on a large number of such manually segmented atlases that take significant time and expertise to produce. We present an algorithm for the automatic segmentation of the hippocampus that minimizes the number of atlases needed while still achieving similar accuracy to multi-atlas approaches.

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1 Introduction

The hippocampus is of particular interest to many researchers because it is implicated in forms of brain dysfunction such as Alzheimer’s disease (Sabuncu et al., 2011) and schizophrenia (Narr et al., 2004; Karnik-Henry et al., 2012), and has functional significance in cognitive processes such as learning and memory (den Heijer et al., 2012; Scoville and Milner, 2000). For many research questions involving magnetic resonance imaging (MRI) data accurate identification of the hippocampus and its subregions is a necessary first step to better understand the individual neuroanatomy of subjects.

Currently, the gold standard for neuroanatomical segmentation is manual delineation by an expert human rater. This is problematic for hippocampal segmentation for several reasons. First, manual segmentation takes a significant investment of time and expertise (Hammers et al., 2003) which may not be readily available to researchers or clinicians. Second, the amount of data produced in neuroimaging experiments increasingly exceeds the capacity for identification of specific neuroanatomical structures by an expert manual rater. Third, the true definition of hippocampal anatomy in MR images is disputed (Geuze et al., 2004), as evidenced by efforts to create a unified segmentation protocol (Jack et al., 2011).

Compounding each of these problems is the significant neuroanatomical variability in the hippocampus throughout the course of aging, maturation, and neuropsychiatric disorders (Sabuncu et al., 2011; Gogtay et al., 2006; Narr et al., 2002). The result is that existing hippocampal atlases available to a researcher may not accurately represent neuroanatomy of a specific population under study. Additionally, in the course of a research or clinical study, it may be necessary to make adjustments to hippocampal definition as a means of hypothesis testing. For example, Poppenk (Poppenk and Moscovitch, 2011) found that subdividing the hippocampus into anterior and posterior regions resulted in a predictive relationship between volume difference of those regions and recollection memory performance. Making such modifications to a set of MRI data segmentations requires additional manual effort.

Automated segmentation techniques do not require human intervention but do require *a priori* anatomical information to guide segmentations. In this paper we focus on methods that use manually segmented MRI atlases as anatomical priors, as these methods achieve some of the best automated hippocampal segmentation accuracies to-date. This technique was first developed using a single atlas prior (known as single-atlas, or model-based, segmentation) (??). Volumetric image registration is used to estimate a fit between the

neuroanatomy of an atlas and target images. Labelling of the target image is achieved by applying the resulting transformation to the atlas labels to bring them into the target image space (*label propagation*). This method is limited in accuracy by the introduction of estimation errors in registration and partial volume effects in label resampling, and errors introduced when the anatomy of the atlas is unrepresentative of the target anatomy.

Multi-atlas segmentation techniques address these limitations by combining segmentation information from a series of expertly segmented atlases (Heckemann et al., 2006, 2011; Collins and Pruessner, 2010; ?; Aljabar et al., 2009; Leung et al., 2010; Wolz et al., 2010). Each atlas image is registered to a target image, and label propagation is performed to produce several labellings of the target image (one from each atlas). A *label fusion* technique, such as voxel-wise voting, is used to merge these labels into a definitive segmentation for the target. In addition, *atlas selection* techniques are often used to exclude atlases from label fusion that are dissimilar to a target image in order to reduce error from unrepresentative anatomy (Aljabar et al., 2009). Cross-correlation or normalised mutual information of image intensities are common measures of image similarity used in atlas selection.

Multi-atlas methods have been very successfully applied to hippocampal segmentation. Collins et al. found near-manual segmentation performance using an atlas library of 80 T1-weighted atlas images from the ICBM152 dataset, the ANIMAL nonlinear registration algorithm, normalised mutual information as an atlas selection similarity metric, and majority vote for label fusion (Collins and Pruessner, 2010). The Alzheimer’s Disease Neuroimaging Initiative (ADNI) is a commonly used benchmarking dataset of MR images of controls and patients with MCI or Alzheimer’s (see Methods for more information on the ADNI dataset). Leung et al. tuned parameters for registration and label fusion to the segmentation of ADNI1 1 year dataset of images with an atlas library of 55 images (Leung et al., 2010). The MAPER whole brain segmentation algorithm (Heckemann et al., 2006, 2011), using 30 atlases, on all ADNI1 baseline images (Heckemann et al., 2011). Lotjonen et al. use images from the ADNI1 baseline dataset and 30 atlases with a proprietary non-linear registration method based on intensity differences, and post-processing step using a graph cuts algorithm to optimise fused segmentations against a spatial intensity prior (?).

The LEAP algorithm is an elegant modification to the basic multi-atlas strategy (Wolz et al., 2010). The atlas library is grown, beginning with a set of manually labelled atlases, and successively incorporates unlabelled target images after being labelled using multi-atlas techniques. The sequence in which target images are labelled is chosen so that the similarity between the atlas images and the target images is minimised at each step, effectively allowing for deformations between very dissimilar images to be broken up into sequences of smaller deformations. With an atlas library of 30 MR images, LEAP was used to segment the ADNI1 baseline dataset, achieving a mean Dice score of 0.85 with manual segmentations.

While not purely multi-atlas techniques, there are several important algorithms for hippocampal segmentation that inform our approach. The popular FreeSurfer application’s whole brain segmentation algorithm uses a probabilistic atlas of anatomical and tissue classes along with spatial constraints for class labels encoded using a Markov random field model (Fischl et al., 2002). When segmenting hippocampal subfields, FreeSurfer employs a Bayesian inference algorithm using a probabilistic atlas of anatomical classes as a prior, and a likelihood model of how those classes translate into MR image intensities, both trained on manual segmentations of high resolution MR images (?). Yushkevitch et al. describe a semi-automated method for hippocampal subfield segmentation of focal T2 images(?). The unlabelled MR image must be manually partitioned into ‘head’, ‘body’ and ‘tail’, and then multi-atlas methods are used to segment the image. Finally, an AdaBoost-based bias correction classifier is trained on texture, spatial location, and intensities of manual segmentations and is applied to fix mislabelled voxels.

Aside from the algorithmic choices used in multi-atlas segmentation, it is natural to ask about how the features of the atlases themselves impact the resulting segmentations. As noted, by choosing atlases ranked most similar to a target image by voxel intensity profile, segmentation accuracy is improved, suggesting that neuroanatomical similarity plays a strong role (Aljabar et al., 2009). Carmichael et al. explored this directly and found that when using only one atlas the important factors leading to improved accuracy are that the atlas have neuroanatomical features that match the target, and that the atlas segmentation use the same protocol as the gold-standard (Carmichael et al., 2005). Nestor et al. found that hippocampal segmentation protocols that include more dorsal white-matter and posterior anatomy tended to produce higher overlap and better accuracy at distinguishing disease classes in the ADNI1 1 year dataset (Nestor et al., 2012). These results suggest both atlas library neuroanatomy and delineation protocol play a significant role in the

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resulting segmentation.

Considered along with our earlier discussion on the difficulty of producing manual segmentations of MR images and the need for adaptable segmentation definitions in order to conduct research, this presents a real problem of labour and expertise when using existing multi-atlas segmentation methods which rely on relatively large atlas libraries (typically between 30 and 80 atlases). Indeed, it may be especially prohibitive to use these methods in situations where producing a single atlas is challenging (e.g. histology-based atlases, or atlases from very high resolution images). In this paper we address the problem of producing accurate segmentations using small numbers of manually segmented atlases.

Our algorithm, called MAgE-T-Brain (*Multiple Automatically Generated Templates*), is an extension to the basic multi-atlas-based segmentation schema(?). Principally, we explore the possibility of using a small atlas library to bootstrap a much larger *template library* composed of images taken from the target population. The template library is then used to segment the targets in a similar fashion to basic multi-atlas segmentation: by label propagation and label fusion. The intuition driving this approach is that by generating a template library we leverage the unique neuroanatomy of target population on hand to initialize the segmentation process and improve accuracy over direct propagation from the atlas library to unlabelled targets while also using fewer manually segmented atlases.

The insight of generating a template library is not new. Heckemann et al. compared “indirect” segmentation – taking a single atlas and propagating the labels to intermediate targets before fusing them in a target image space – to multi-atlas segmentation and found that the indirect approach performed worse (Heckemann et al., 2006). In this paper we continue the same line of investigation but explore the performance when using multiple atlases as well as the effect of different registration and fusion methods.

The LEAP algorithm (Wolz et al., 2010), described above, is another example of indirect segmentation previously explored. LEAP proceeds by iteratively segmenting unlabelled images most similar to the atlas library images and then incorporating the labelled images into the atlas library for future iterations. The novelty explored in our current work is to demonstrate the viability of achieving comparable segmentation accuracy using the basic multi-atlas schema and using significantly fewer manually created atlases.

In previous work (?), we applied MAgE-T-Brain to segmentation of the human striatum, globus pallidus, and thalamus using a single histologically-derived atlas. The contribution of the present work is to extend our approach to the human hippocampus and perform a series of experiments to rigorously validate the method. First, we conduct an extensive cross-validation of MAgE-T-Brain and basic multi-atlas segmentation on a subset of the ADNI1 dataset to assess the accuracy of MAgE-T-Brain under various parameter settings (number of atlases and templates, registration and fusion methods). With the best performing parameter configuration discovered above, we estimate MAgE-T-Brain intra-rater reliability by segmenting separately acquired T1 images of the atlas subjects. For this experiment, we use the Winterburn atlases: digital hippocampal subfield segmentations of five in-vivo high-resolution (300u isotropic) T1-weighted MR scans(?). To validate MAgE-T-Brain in a real world situation, we segment the entire ADNI1 Complete 1Yr dataset and compare our segmentations to established automated and manual segmentations. Additionally, to ensure MAgE-T-Brain accuracy across disease categories, we also compare MAgE-T-Brain segmentations to manual segmentations of 139 first episode schizophrenic patients.

2 Methods

2.1 MAgE-T-Brain Algorithm

In this paper we will be making a distinction between an atlas and a template – typically these terms are used roughly interchangeably. The term *atlas* is taken to refer to two image volumes: an intensity image (*atlas image*) and a corresponding manual segmentation image (*atlas labels*). *Template* refers more generically to any image and corresponding labelling, manual or computed, when it is *used as* a model in the segmentation of another image. The terms *atlas library* and *template library* mean a set of such images. Additionally, we will use the terms *target* to refer to an intensity image for which we would like an segmentation.

The simplest form of multi-atlas segmentation combines labellings derived from several atlases by way of label fusion (Heckemann et al., 2006, 2011). We will refer to this as *basic multi-atlas segmentation*. The schema as for this method is as follows:

1. An atlas library and set of target images are given as input. The atlas library is used as a template library in the following steps;
2. Each atlas intensity image is nonlinearly registered to each target intensity image;
3. Label images from each atlas are propagated via the resulting transformations to the target image space; and
4. the resulting labels are fused to produce a single, definitive segmentation.

The particular registration and voting method used are left unspecified.

MAGeT-Brain is best understood as an extension of the basic multi-atlas segmentation schema. Instead of using the atlas library to directly label the target images, a subset of the input images are selected as template images and then labelled. The choice of targets used in the template library can be made to reflect the neuroanatomy or demographics of the target set as a whole (for instance, by sampling equally from cases and controls). Once the template library images have been chosen, a truncated version of basic multi-atlas segmentation is used to label the template library images without performing label fusion. Instead, each template image receives multiple labellings: one from each atlas image. A second round of basic multi-atlas segmentation uses the template library to segment the entire set of target images (including those images used in the template library). Label fusion in this final step fuses all labels from all templates. To summarize, figure 1 describes the MAGeT-Brain algorithm in pseudocode.

Source code for MAGeT-Brain can be found at <http://github.com/pipitone/MAGeTbrain>.

Algorithm 1 Pseudocode for the MAGeT-Brain algorithm

```

function BASICMULTIATLASSEGMENTATION(Templates, Subjects)
  for all target do
    for all template do
      propagate all labels for template to target space
      store target labels
    end for
    fuse target labels
  end for
end function

function MAGETBRAIN(Subjects, Atlases, n)
  for  $i = 1 \rightarrow n$  do
    choose a target to be used as a template
    propagate labels from each atlas to template space
    store the template with all of its labels
  end for
  MultiAtlas(Templates, Subjects)
end function

```

2.2 Subjects

Our experiments use three distinct subject datasets.

2.2.1 ADNI1 1.5T Complete 1Yr Dataset

Clinical, demographic and pre-processed T1-weighted MRI were downloaded by the authors from the ADNI1 database (adni.loni.ucla.edu) between March 2012 and August 2012. The image dataset download was the "ADNI1:Complete 1Yr 1.5T" standardized dataset available from ADNI ¹ (Wyman et al., 2012). This image collection contains uniformly preprocessed images which have been designated to be the "best" after quality control. All images were acquired using 1.5T scanners (General Electric Healthcare, Philips Medical Systems or Siemens Medical Solutions) at multiple sites using the protocol described in (?). Representative 1.5T imaging parameters were TR = 2400ms, TI = 1000ms, TE = 3.5ms, flip angle = 8°, field of view = 240 x 240mm, a 192 x 192 x 166 matrix (x, y, and z directions) yielding a voxel resolution of 1.25 x 1.25 x 1.2 mm³. Clinical and demographic data are shown in table ??.

¹ <http://adni.loni.ucla.edu/methods/mri-analysis/adni-standardized-data/>

Table 1: ADNI1 1.5T Complete 1Yr dataset demographics

	N	CN N = 585	LMCI N = 936	AD N = 405	Combined N = 1926
Age at baseline Years	1926	72.4 75.8 78.5	70.5 75.1 80.4	70.1 75.3 80.2	71.1 75.3 79.8
Sex : Female	1926	48% (279)	35% (329)	49% (198)	42% (806)
Education	1926	14 16 18	14 16 18	12 15 17	13 16 18
Ethnicity : Unknown	1926	2% (9)	1% (6)	1% (3)	1% (18)
Not Hisp/Latino		97% (570)	97% (909)	99% (402)	98% (1881)
Hisp/Latino		1% (6)	2% (21)	0% (0)	1% (27)
CDR-SB	1918	0.0 0.0 0.0	1.0 1.5 2.5	3.5 4.5 6.0	0.0 1.5 3.0
ADAS 13	1902	5.67 8.67 12.33	14.67 19.33 24.33	24.67 30.00 35.33	10.67 18.00 25.33
MMSE	1924	29 29 30	25 27 29	20 23 25	25 27 29

a b c represent the lower quartile a , the median b , and the upper quartile c for continuous variables.
 N is the number of non-missing values.
Numbers after percents are frequencies.

For a subset of ADNI1 images, labels of the left and right hippocampi are available (herein referred to as SNT labels). Semi-automated hippocampal volumetry was carried out using a commercially available high dimensional brain mapping tool (Medtronic Surgical Navigation Technologies, Louisville, CO), that has previously been validated and compared to manual tracing of the hippocampus (Hsu et al., 2002). Measurement of hippocampal volume is achieved first by placing manually 22 control points as local landmarks for the hippocampus on the individual brain MRI data: one landmark at the hippocampal head, one at the tail, and four per image (i.e., at the superior, inferior, medial and lateral boundaries) on five equally spaced images perpendicular to the long axis of the hippocampus. Second, fluid image transformation is used to match the individual brains to a template brain (Christensen et al., 1997). The pixels corresponding to the hippocampus are then labeled and counted to obtain volumes. This method of hippocampal voluming has a documented reliability of an intraclass coefficient better than .94 (Hsu et al., 2002).

2.2.2 Schizophrenic First Episode Patients

All patients were recruited and treated through the Prevention and Early Intervention Program for Psychoses (PEPP-Montreal), a specialized early intervention service at the Douglas Mental Health University Institute in Montreal, Canada. People aged 15-30 years from the local catchment area suffering from either affective or non-affective psychosis who had not taken antipsychotic medication for more than one month with an IQ above 70 were consecutively admitted as either in- or out-patients. Of those treated at PEPP, only patients aged 18 to 30 years with no previous history of neurological disease or head trauma causing loss of consciousness were eligible for the neuroimaging study; only those suffering from schizophrenia spectrum disorders were considered for this analysis. For complete program details see Malla et al. (?).

Scanning was carried out at the Montreal Neurological Institute on a 1.5-T Siemens whole body MRI system. Structural T1 volumes were acquired for each participant using a three-dimensional (3D) gradient echo pulse sequence with sagittal volume excitation (repetition time=22ms, echo time=9.2ms, flip angle=30°, 180 1mm contiguous sagittal slices). The rectangular field-of-view for the images was 256mm (SI)204mm (AP). Subject demographics are shown in table 2.

The hippocampus were traced following a validated protocol developed by Dr Jens Pruessner (Pruessner et al., 2000). A recent update to this protocol by Dr J Pruessner in 2006 allows to accurately and consistently subdivide the hippocampus into three different subregions: head, body, and tail.

2.2.3 Winterburn Atlases

The Winterburn atlases (?) are digital hippocampal segmentations of five in-vivo 300u isotropic T1-weighted MR images. The segmentations include subfield segmentations for the cornus ammonis (CA) 1, CA4, dentate gyrus, subiculum, and CA 2 and 3 combined. Subjects in the Winterburn atlases range in age from 29-57 years (mean age of 37), and include two males and three females.

In addition to the high-resolution scans distributed as part of the Winterburn atlases, we also obtained additional T1 BRAVO scans of four of the five subjects.

demographics
explain scan
in more detail

Table 2: Schizophrenia First Episode Patient Demographics

	N	FEP		
		$N = 81$		
Age	80	21	23	26
Gender : M	81	63%	(51)	
Handedness : ambi	81	6%	(5)	
left		5%	(4)	
right		89%	(72)	
Education	81	11	13	15
SES : lower	81	31%	(25)	
middle		54%	(44)	
upper		15%	(12)	
FSIQ	79	88	102	109

a b c represent the lower quartile a , the median b , and the upper quartile c for continuous variables. N is the number of non-missing values. Numbers after percents are frequencies.

Table 3: ANIMAL registration parameters

Parameters	Stage 1	Stage 2	Stage 3
Model Blur (FWHM)	8	8	4
Input Blur (FWHM)	8	8	4
Iterations	30	30	10
Step	8x8x8	4x4x4	2x2x2
Sub-Lattice	6	6	6
Lattice Diameter	24x24x24	12x12x12	6x6x6

2.3 Registration Methods

Before registration, all images underwent preprocessing with the N3 algorithm (Sled et al., 1998) to minimize intensity nonuniformity. In our experiments we use one of two non-linear image registration methods.

2.3.1 Automatic Normalization and Image Matching and Anatomical Labeling (ANIMAL)

The ANIMAL algorithm carries out image registration in two phases. In the first, a 12-parameter linear transformation (3 translations, rotations, scales, shears) is estimated between images using an algorithm that maximizes the correlation between blurred MR intensities and gradient magnitude over the whole brain (Collins et al.). In the second phase, nonlinear registration is completed using the ANIMAL algorithm (Collins et al., 1995): an iterative procedure that estimates a 3D deformation field between two MR images. At first, large deformations are estimated using blurred version of the input data. These larger deformations are then input to subsequent steps where the fit is refined by estimating smaller deformations on data blurred with a Gaussian kernel with a smaller FWHM. The final transformation is a set of local translations defined on a bed of equally spaced nodes that were estimated through the optimization of the correlation coefficient. For the purposes of this work we used the regularization parameters optimized in Robbins et al. (Robbins et al., 2004), displayed in table 2.3.1.

2.3.2 Automatic Normalization Tools (ANTS)

ANTS is a diffeomorphic registration algorithm which provides great flexibility over the choice of transformation model, objective function, and the consistency of the final transformation. The transformation is estimated in a hierarchical fashion where the MRI data is subsampled, allowing large deformations

to be estimated and successively refined at later hierarchical stages (where the data is subsampled to a finer grid). The deformation field and the objective function are regularized with a Gaussian kernel at each level of the hierarchy. The ANTS algorithm is freely available <http://www.picsl.upenn.edu/ANTS/>. We used an implementation of the ANTS algorithm compatible with the MINC data format, mincANTS <https://github.com/vfonov/mincANTS>.

We used the following command line when running ANTS :

```
mincANTS 3 -m PR[target_file.mnc,source_file.mnc,1,4]
--number-of-affine-iterations 10000x10000x10000x10000x10000
--affine-gradient-descent-option 0.5x0.95x1.e-4x1.e-4
--use-Histogram-Matching --MI-option 32x16000
-r Gauss[3,0] -t SyN[0.5] -i 100x100x100x20
-o transformation.xfm
```

These settings were adapted from the "reasonable starting point" given in the ANTS manual ².

2.4 Label Fusion

Label fusion is a term given to the process of combining the information from several candidate labellings for an intensity image into a single labelling. In this paper we explore three fusion methods.

2.4.1 Voxel-wise Majority Vote

Labels are propagated from all template library images to a target. Each output voxel is given the most frequent label at that voxel location amongst all candidate labellings. Ties are broken arbitrarily.

2.4.2 Cross-correlation Weighted Majority Vote

An optimal combination of targets from the template library has previously been shown to improve segmentation accuracy (Aljabar et al., 2009; Collins and Pruessner, 2010). In this method, each template library image is ranked in similarity to each unlabelled image by the normalized cross-correlation (CC) of image intensities after linear registration, over a region of interest (ROI) generously encompassing the hippocampus. Only the top ranked template library image labels are used in a voxel-wise majority vote. The ROI is heuristically defined as the extent of all atlas labels after linear registration to the template, dilated by three voxels (?). The number of top ranked template library image labels is a configurable parameter.

The `xcorr_vol` utility from the ANIMAL toolkit is used to calculate the cross-correlation similarity measure.

2.4.3 Normalised Mutual Information Weighted Majority Vote

This method is similar to cross-correlation weighted voting except that image similarity is calculated by the normalised mutual information score over the region of interest (Studholme et al., 2001). The `itk.similarity` utility from the EZMinc toolkit³ is used to calculate the normalised mutual information measure between to images.

2.5 Assessing Segmentation Agreement

The Dice similarity coefficient (DSC) assesses the agreement between two segmentations. It is one of the most widely used measures of segmentation performance, and we use it as the basis of comparison throughout this paper. Additionally, we report the Jaccard index, another commonly used similarity measure:

$$\text{Dice's coefficient (DSC)} = \frac{2|A \cap B|}{|A| + |B|}$$

²<https://sourceforge.net/projects/advants/files/Documentation/>

³<https://github.com/vfonov/EZminc>

Table 4: ADNI-1 cross-validation subset demographics

	CN <i>N</i> = 23			LMCI <i>N</i> = 23			AD <i>N</i> = 23			Combined <i>N</i> = 69		
Age at baseline Years	72.2	75.5	78.5	71.0	77.1	81.4	71.7	77.8	81.8	71.5	76.6	81.3
Sex : Female	43% (10)			43% (10)			43% (10)			43% (30)		
Education	16.0	16.0	18.0	15.0	16.0	18.0	12.0	16.0	16.5	14.0	16.0	18.0
Ethnicity : Unknown	0% (0)			0% (0)			0% (0)			0% (0)		
Not Hisp/Latino	100% (23)			100% (23)			100% (23)			100% (69)		
Hisp/Latino	0% (0)			0% (0)			0% (0)			0% (0)		
CDR-SB	0.00	0.00	0.00	0.75	1.50	1.50	4.00	4.50	5.00	0.00	1.50	4.00
ADAS 13	4.67	5.67	12.34	14.34	16.00	20.50	23.83	29.00	31.66	10.00	16.00	25.33
MMSE	28.5	29.0	30.0	25.0	27.0	28.0	21.0	23.0	24.0	24.0	27.0	29.0

a b c represent the lower quartile *a*, the median *b*, and the upper quartile *c* for continuous variables. Numbers after percents are frequencies.

$$\text{Jaccard (J)} = \frac{|A \cap B|}{|A \cup B|} = \frac{DSC}{(2 - DSC)}$$

where *A* and *B* are the regions being compared, and the cardinality is the volume measured in voxels.

2.6 Experiments

The following experiments were performed to assess the performance of MAgE-T-Brain with various parameter settings as well as on diverse datasets. In each experiment we contrast the performance of MAgE-T-Brain with that standard single- and multi-atlas segmentations derived from the same atlas library.

2.6.1 ADNI1 cross-validation

To test the effect of parameter settings on the MAgE-T-Brain algorithm, Monte Carlo Cross-Validation (MCCV) (?) was performed using a subset of the ADNI1 dataset for validation. This form of cross-validation (described in detail below) allows us to validate MAgE-T-Brain with various atlas and template library sizes, registration and label fusion methods.

Dataset evaluated. 69 1.5T images were arbitrarily selected from the *ADNI1:Complete 1Yr 1.5T* standardized dataset. 23 subjects were chosen from each disease category (cognitively normal (CN), MCI and AD). Demographics for this subset are shown in Table 4.

Atlas and template library. The atlas and template libraries are selected from the dataset evaluated. Atlases consist of images taken from the dataset, with corresponding manual labels provided by SNT. Template library images were selected at random from remaining images not used as atlases. The atlas library size ranged from 1 to 9 images. Template library size ranged from 1 to 20 images.

Registration method. Both the ANTS and ANIMAL registration methods were used.

Label fusion. Majority vote, cross-correlation weighted majority vote, and Normalized Mutual Information weighted majority vote were used. With the weighted majority vote fusion methods, the number of top labels used in the fusion was varied from 1 to 20 images.

Evaluation. Monte Carlo Cross-Validation (MCCV), also known as repeated random sub-sampling cross-validation, consists of repeated rounds of validation in which items from the dataset are randomly sampled (without replacement) and assigned to a training set or validation set ?.

In this experiment, each validation round consists of the following steps. First, an atlas library is selected (the training set) and, from the remaining images, a template library and subject to be segmented is chosen (the validation set). Second, MAgE-T-Brain and basic multi-atlas segmentation are performed on the subject using the selected atlas and template libraries. Third, the accuracy of the resulting segmentations are measured against the SNT labels.

A total of ten validation rounds are performed on each subject in the dataset, for each combination of parameter settings. Reported subject segmentation accuracy is the averaged over the ten validation rounds. The parameter settings we explore are: atlas library size (1-9), template library size (1-20), registration method (ANTS vs. ANIMAL), and label fusion method (MV, XC-WV, NMI-WV). A total of 10 * 69 *

Table 5: ADNI1 Complete 1Yr Template Library demographics

	CN N = 7			LMCI N = 7			AD N = 7			Combined N = 21		
Age at baseline Years	81.1	84.6	86.7	67.2	71.1	77.9	74.2	79.5	81.2	71.1	79.5	84.6
Sex : Female	71%	(5)		43%	(3)		86%	(6)		67%	(14)	
Education : 10	0%	(0)		0%	(0)		14%	(1)		5%	(1)	
12	0%	(0)		0%	(0)		29%	(2)		10%	(2)	
13	0%	(0)		0%	(0)		29%	(2)		10%	(2)	
14	0%	(0)		14%	(1)		0%	(0)		5%	(1)	
16	57%	(4)		29%	(2)		29%	(2)		38%	(8)	
17	0%	(0)		14%	(1)		0%	(0)		5%	(1)	
18	29%	(2)		29%	(2)		0%	(0)		19%	(4)	
20	14%	(1)		14%	(1)		0%	(0)		10%	(2)	
Ethnicity : Unknown	0%	(0)		0%	(0)		0%	(0)		0%	(0)	
Not Hisp/Latino	100%	(7)		100%	(7)		100%	(7)		100%	(21)	
Hisp/Latino	0%	(0)		0%	(0)		0%	(0)		0%	(0)	
CDR-SB	0.00	0.00	0.00	0.75	1.50	1.75	4.50	5.00	7.25	0.00	1.50	4.00
ADAS 13	4.67	5.33	7.00	16.34	18.00	22.50	26.33	30.33	33.00	7.33	17.00	28.33
MMSE : 21	0%	(0)		0%	(0)		29%	(2)		10%	(2)	
22	0%	(0)		0%	(0)		14%	(1)		5%	(1)	
23	0%	(0)		0%	(0)		14%	(1)		5%	(1)	
25	0%	(0)		14%	(1)		29%	(2)		14%	(3)	
26	0%	(0)		14%	(1)		14%	(1)		10%	(2)	
27	0%	(0)		14%	(1)		0%	(0)		5%	(1)	
28	14%	(1)		14%	(1)		0%	(0)		10%	(2)	
29	29%	(2)		43%	(3)		0%	(0)		24%	(5)	
30	57%	(4)		0%	(0)		0%	(0)		19%	(4)	

a b c represent the lower quartile a , the median b , and the upper quartile c for continuous variables. Numbers after percents are frequencies.

$9 * 20 * 2 * 3 = 7452000$ validation rounds were conducted, resulting in a total of 1'490'400 segmentations analysed.

2.6.2 ADNI-1 Complete 1Yr Validation

To test the accuracy of MAGeT-Brain on a real-world task we segment the entire ADNI-1 dataset using an atlas set that is not representative of the target set.

Dataset evaluated. All images from the *ADNI1:Complete 1Yr 1.5T* standardized dataset.

Atlas and template library. The Winterburn atlases were used as the atlas library. The template library consisted of 21 randomly selected images from the ADNI1 data dataset (7 healthy, MCI and AD subjects). Clinical and demographic data for the template library subjects are shown in Table 5.

Registration method. The ANTS non-linear registration algorithm was used, as it performed best in the ADNI1 cross-validation experiment (see Results).

Label fusion. Majority vote was used performed equally well in the ADNI1 cross-validation experiment and is the easiest label fusion method to operate.

Evaluation. Since the hippocampal segmentation protocols differ between the ADNI labels and Winterburn atlases, this poses a problem for direct evaluation between labels produced by MAGeT-Brain and the ADNI labels in terms of overlap; we would not expect different segmentation protocols to have a high degree of overlap. Instead, to evaluate the performance of MAGeT-Brain we compare the correlation of MAGeT-Brain segmentation volumes with manual segmentation (SNT) volumes. Additionally, we correlate the hippocampal volumes of established automated segmentation methods to MAGeT-Brain segmentations.

2.6.3 SZ First Episode Patient Validation

Dataset evaluated. To validate that MAGeT-Brain performance generalises to across disease categories, we measure the performance of MAGeT-Brain on the Schizophrenic First Episode Patient (SFEP) dataset.

Atlas and template library. - two different atlas sets: a manual hippocampal segmentation of patients, and Winterburn atlas set.

Registration method. ANTS .

Label fusion. Majority vote.

complete

complete

complete

Evaluation. We validate the FEP-atlas segmentations using Dice’s Kappa, and the Winterburn-atlas segmentations by correlating volumes.

complete

2.6.4 Winterburn Atlases Validation

Dataset evaluated. - T1 BRAVO scans of the same subjects included in the Winterburn atlas set. These scans are taken within weeks of the scans for the Winterburn atlases.

complete

Atlas and template library. - Atlas library is Winterburn T1 atlases. Template library consists of all five T1 BRAVOs, plus 15 T1 healthy control images.

complete

Registration method. ANTS

complete

Label fusion. Majority vote.

complete

Evaluation. - Leave one out cross-validation (LOOCV) in which all five subjects are segmented in separate runs of MAgE-T-Brain . In each run, the subject to be segmented is excluded from the Atlas library (so only four atlases are used).

Segmentation accuracy is judged by difference in hippocampal volume.

complete

3 Results

3.1 ADNI1 Cross-Validation

In this experiment we conducted 10 rounds of MAgE-T-Brain and multi-atlas segmentation of each of 69 subjects at a range of atlas and template library sizes, registration algorithm (ANTS or ANIMAL), and three label fusion techniques. Hippocampal MAgE-T-Brain -based segmentations using both ANIMAL and ANTS registration algorithm demonstrate good overlap with manually derived gold-standards (Figure ??). Qualitatively, both ANIMAL and ANTS -based segmentations demonstrate trend overlap accuracy that increases with the size of atlas library and template library. Improvement in accuracy diminishes noticeably with template libraries larger than ten images.

No marked difference in segmentation accuracy is seen when either ANIMAL or ANTS registration is used with different label fusion techniques, at any atlas or template library sizes. In every parameter configuration, the use of MAgE-T-Brain with ANTS registration shows a pronounced increase in segmentation accuracy over MAgE-T-Brain with ANIMAL registration. In the remainder of this section, only results using the ANTS registration algorithm will be shown.

It is interesting to note that with an even number of templates, MAgE-T-Brain shows a small decrease in performance relative to when one fewer template image is used. See section () for a discussion of this behaviour. In the remainder of this section, only results from odd-sized template libraries will be shown.

ref

With an increasing number of templates, MAgE-T-Brain -based segmenting using ANTS registration and majority vote label fusion shows improvement in overlap accuracy over multi-atlas-based segmentation, using the same number of atlases and voting method (Figure . The magnitude of improvement over multi-atlas-based segmentation decreases with an increasing number of atlases, with accuracy converging with 7 atlases. Peak improvement in MAgE-T-Brain accuracy (0.02 DSC) is found when one atlas is used with a template library of 20 images.

fig:ADNI1-xv

stats?

In addition to an improvement in accuracy over multi-atlas-based segmentation, MAgE-T-Brain also shows a decrease in the variability of segmentation accuracy (Figure). The size of template library necessary to reach a significant ($p < 0.5$) decrease in variance and standard deviation grows with the size of atlas library used. A template library of 19 images is sufficient to show significant decrease in variance and standard deviation for 3-7 atlases.

mention failu

ADNI1-xval-v

Finally, MAgE-T-Brain segmentation volumes show differential agreement with manual (SNT) volumes throughout the range of hippocampal volumes (Figure 4). MAgE-T-Brain shows a fixed bias towards producing smaller segmentations, and shows a negligible proportional bias towards smaller segmentations inversely proportional to volume size. Nevertheless, when using 3 or more atlases, MAgE-T-Brain volumes are within the 95% limits of agreement with manual labels.

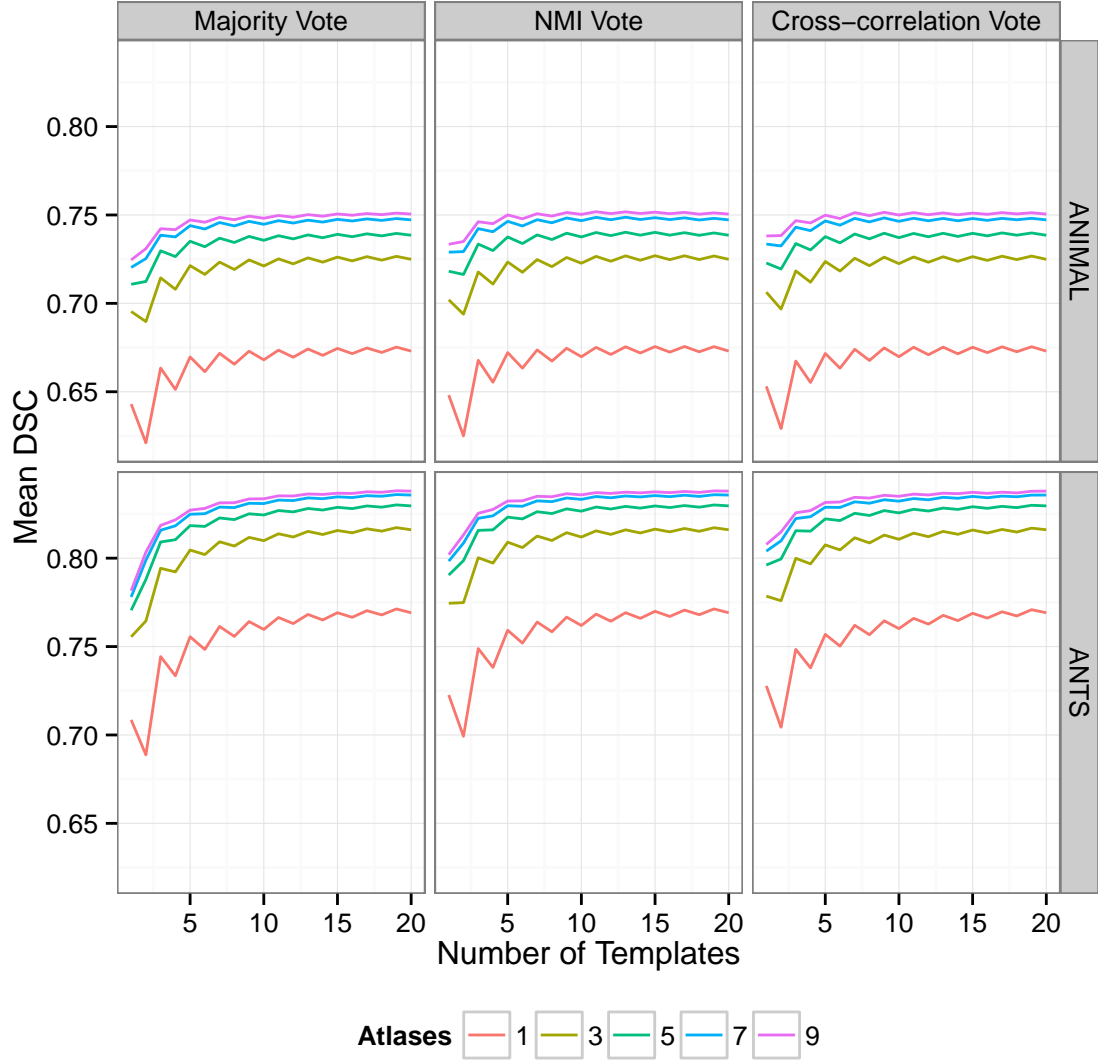


Figure 1: **Mean DSC by atlas and template library size, registration algorithm, and label fusion method.** The mean DSC score is calculated over all subjects from the ADNI1 Cross-Validation dataset for each parameter setting.

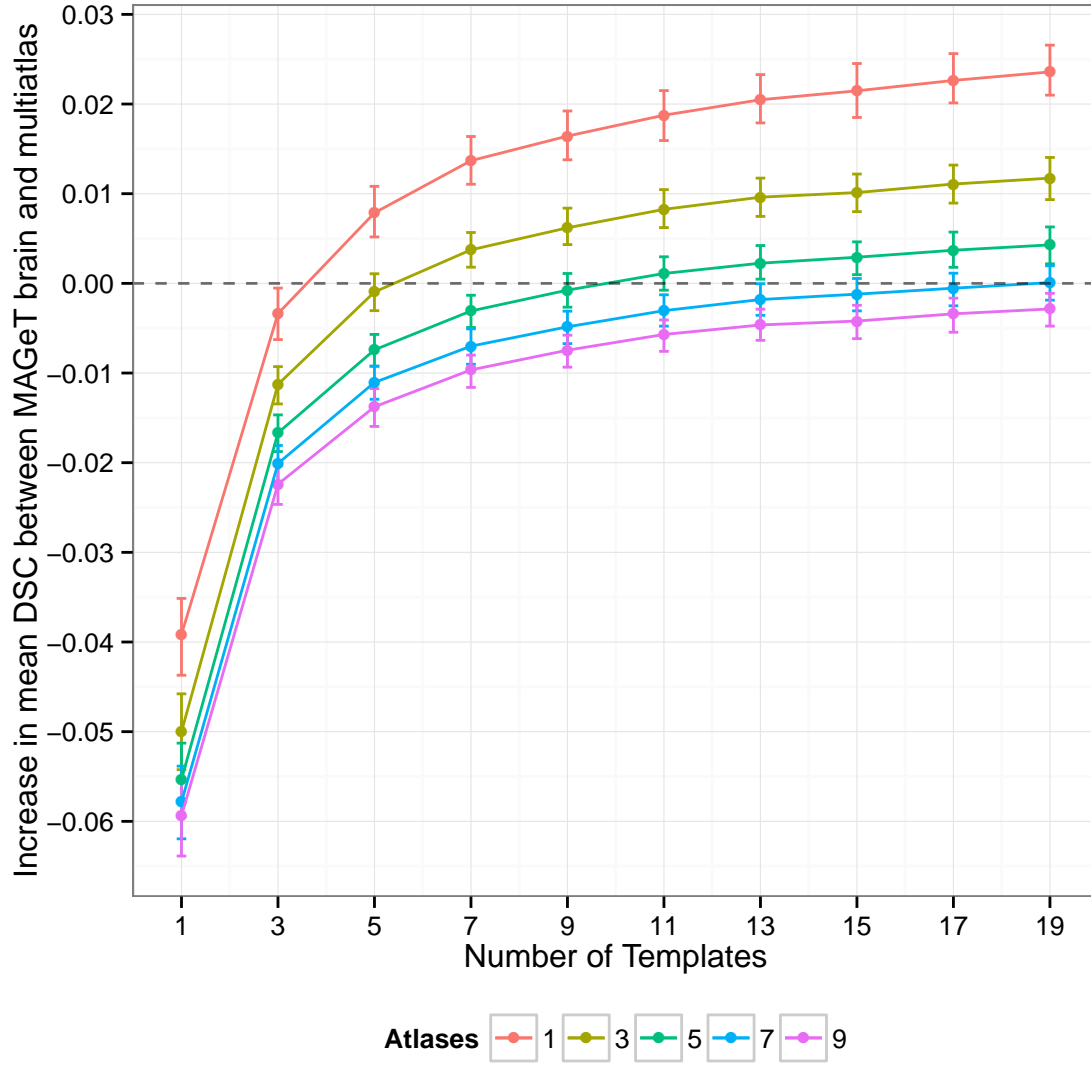


Figure 2: The difference in mean DSC between MAGEt-Brain and multi-atlas segmentations for a range of parameter settings.

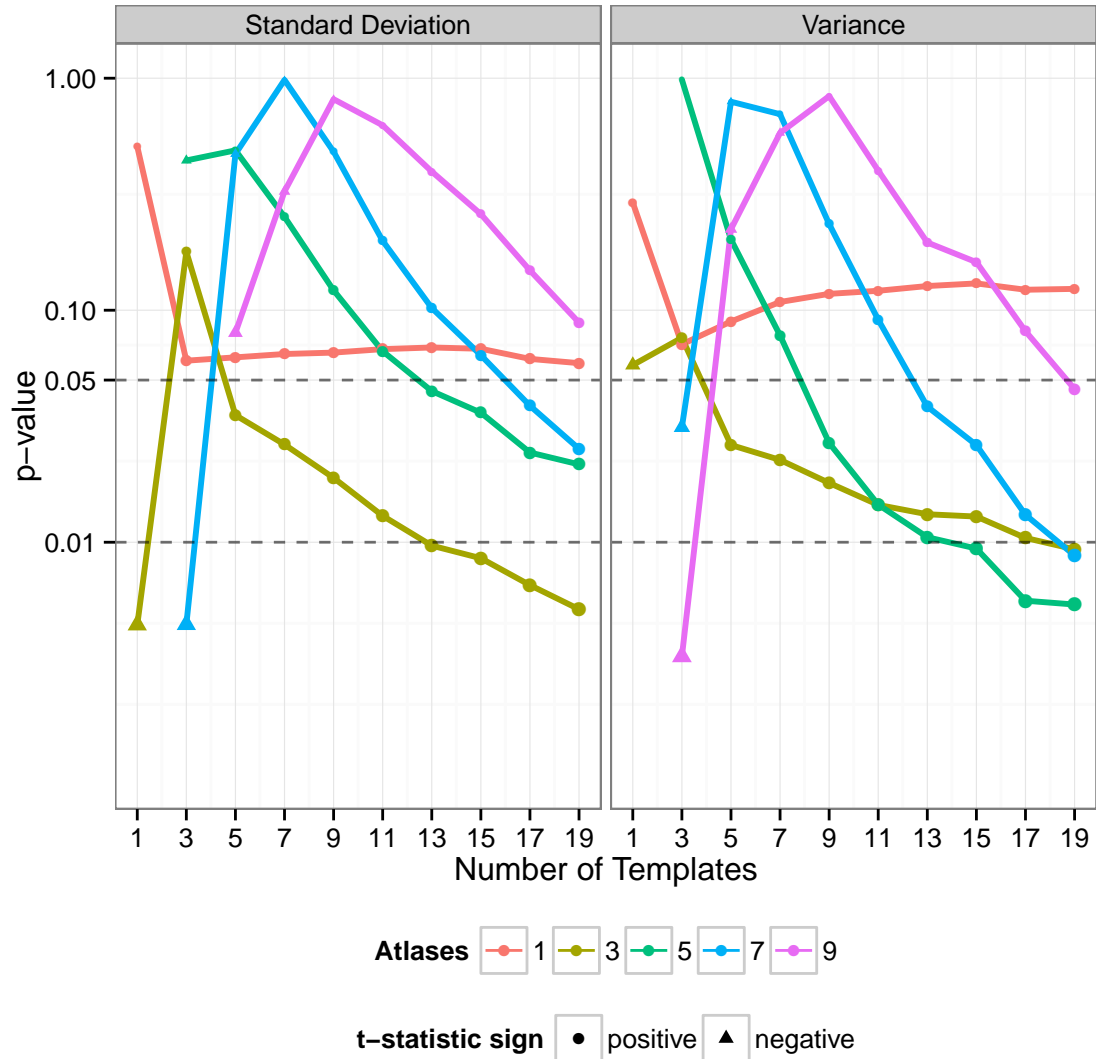


Figure 3: **Difference in variability of MAGeT-Brain vs. multi-atlas segmentation accuracy.** In these plots we consider the segmentation accuracy within each subject across the 10 rounds of validation per parameter setting. Standard deviation and variance is computed per subject for MAGeT-Brain and multi-atlas, and the distribution of these test statistics is compared with a t-test. The p-value of this test, is shown on the y-axis (scaled logarithmically).

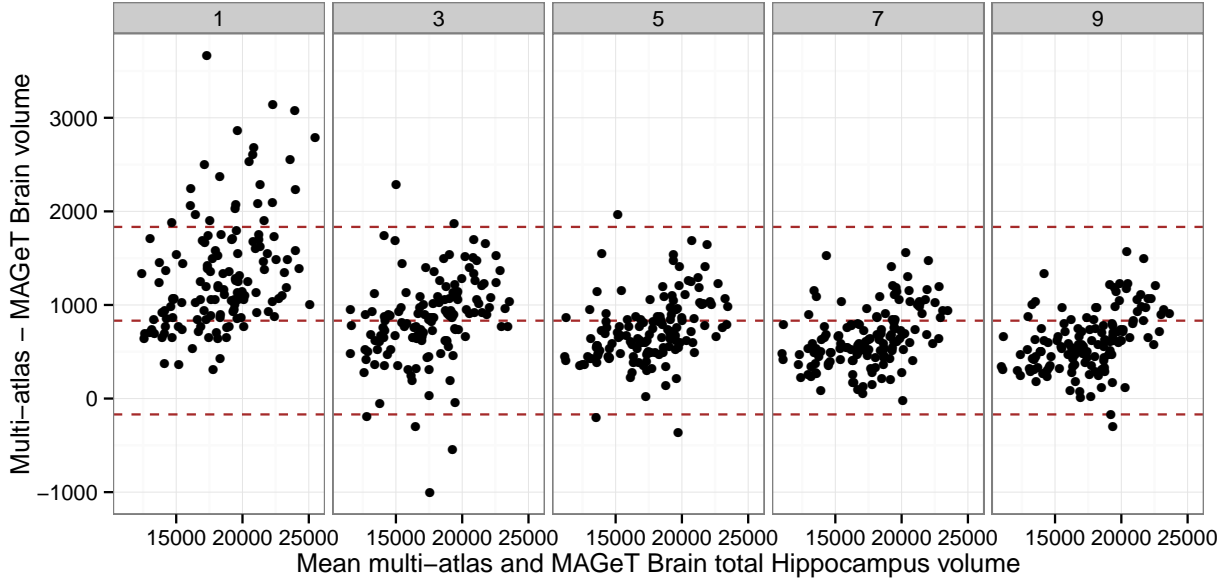


Figure 4: Bland-Altman plot comparing multi-atlas and MAGEt-Brain hippocampal volumes when using 9 atlases, and a 20 image template library.

Table 6: Pass/fail quality control indicators were supplied with the FreeSurfer volumes downloaded from the ADNI website (we used the temporal lobe quality control indicator, TEMPQC). One of the authors (MP) performed visual quality inspection for MAGEt and FSL segmentations.

	Total	SNT	MAGEt	MAPER	FSL	FS
Images	2294	1446	2294	636	2257	1909
Failures	N/A	–	42	–	39	355

3.2 ADNI1 Complete 1Yr Validation

Based on the results from the ADNI1 Cross-Validation experiment, in this experiment MAGEt-Brain was configured with a template library of 21 randomly chosen subject images (7 from each disease class) and used majority vote label fusion. The entire ADNI1 Complete 1Yr 1.5T dataset was segmented by MAGEt-Brain and we now compare the resulting volumes with those obtained by manual segmentation (SNT), and other automated segmentation techniques (MAPER, FreeSurfer, and FSL). Table ?? shows the total count of segmentations available, including a count of those which have failed a quality control inspection. Only those images which had segmentations from every method are included in the following analysis (a total of 345 images).

Comparing total hippocampal volume across segmentation methods, we find close agreement between manual volumes and MAPER and MAGEt volumes across disease categories (Figure 5). FSL and FreeSurfer both produce volumes which are demonstratively larger than manually segmented volumes.

3.3 First Episode Schizophrenic Patients

High volume correlation between Winterburn segmentation volumes and ground truth. (High-ish?) Kappa when using manual segmentations as Atlases.

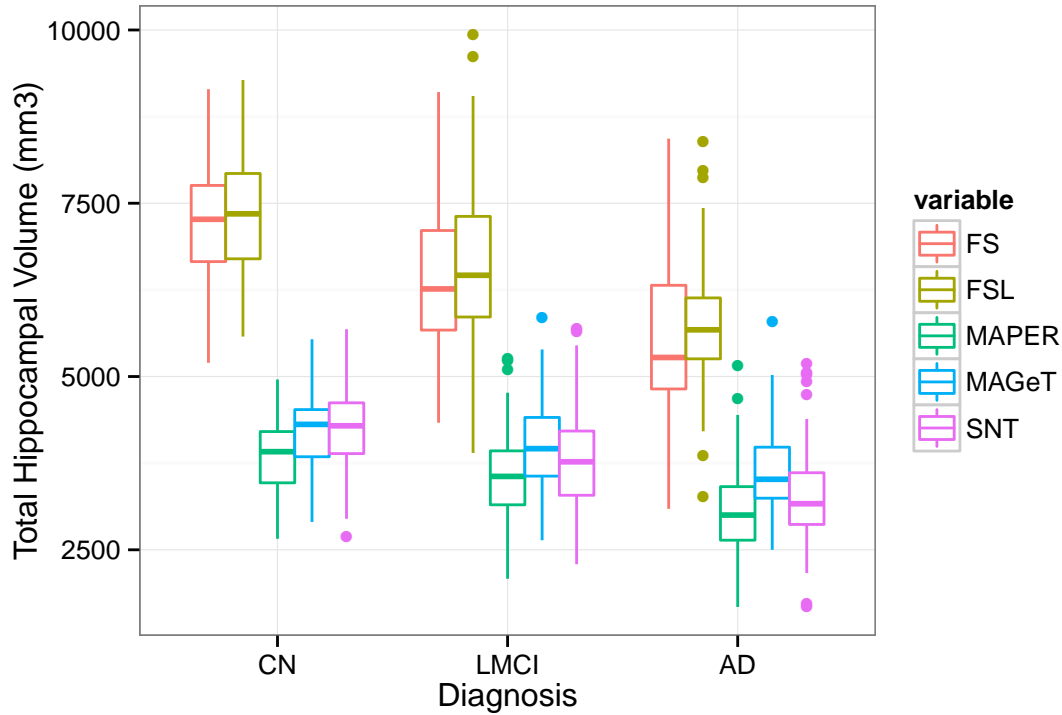


Figure 5: Comparison of hippocampus volumes obtained by FreeSurfer (FS), FSL, MAPER, MAGeT-Brain (MAGeT) and manual (SNT).

3.4 Winterburn Atlases Validation

4 Discussion

5 Conclusion

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Total hippocampus volume by disease and measurement method

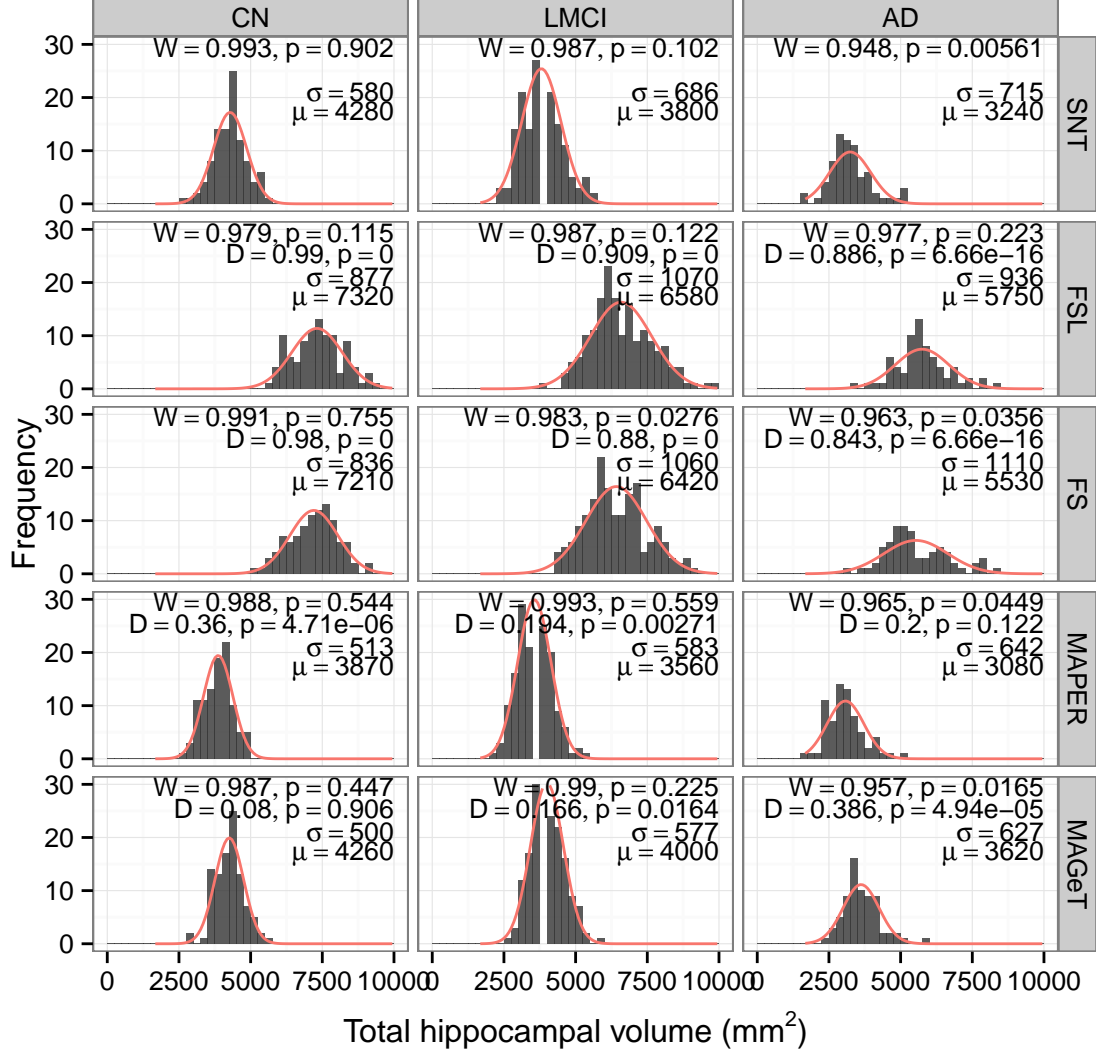


Figure 6: **ADNI Baseline cohort.** Comparison of total hippocampal volumes as measured by SNT, FSL, FreeSurfer (FS), MAPER, and MAGeT-Brain (MAGeT). A fitted normal curve is shown in red. W is the Shapiro-Wilkes test statistic measuring normality of the data (significance indicates non-normality). D is the Kolmogorov-Smirnov test statistic measuring the goodness-of-fit between the distribution of measured volumes and SNT volumes (significance indicates a difference).

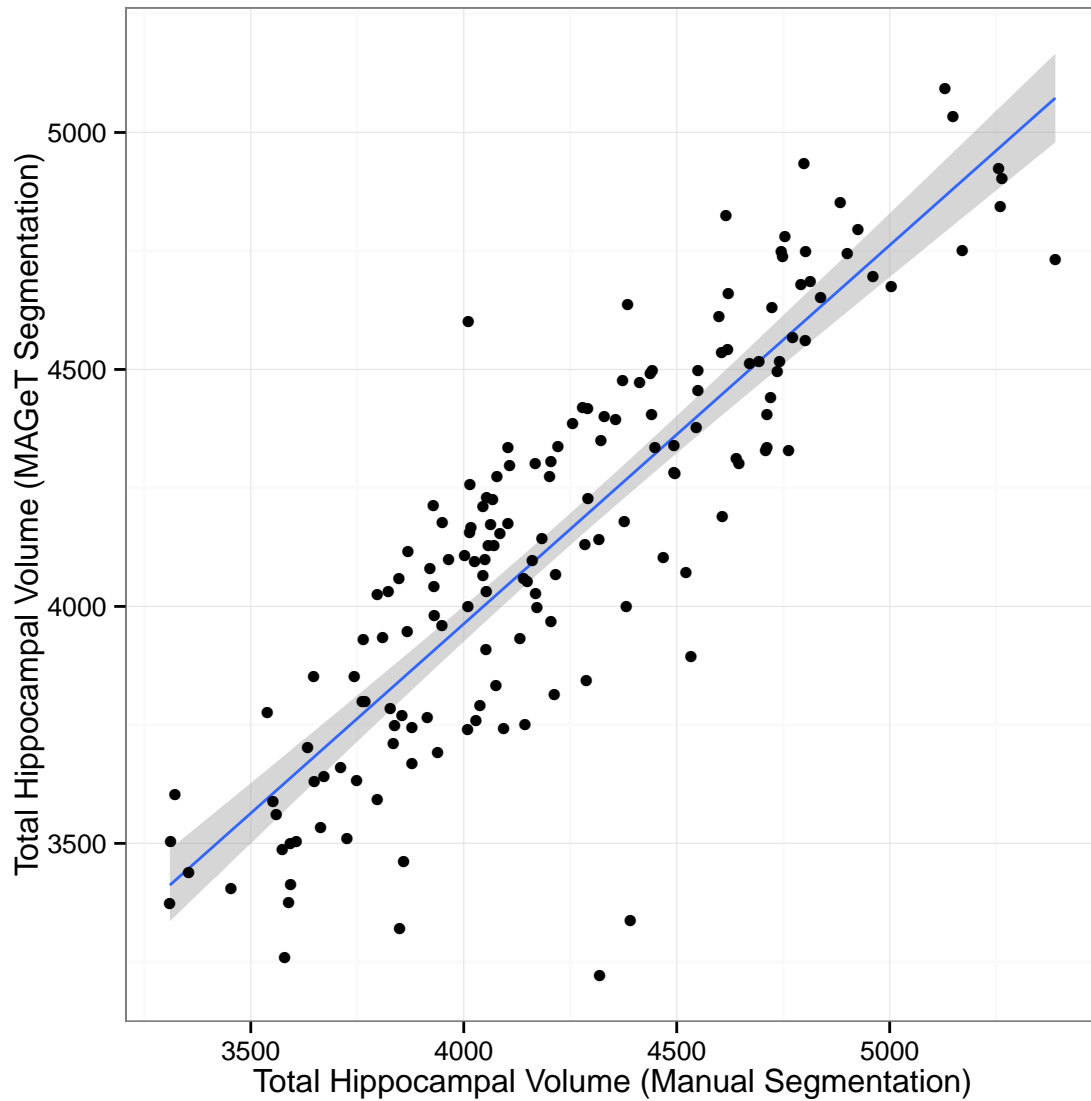


Figure 7: **First Episode Schizophrenic Patients.** Comparison of total HC volumes for MAGeT-Brain against manually rated Hippocampal volumes

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Figure 8: Bland-Altman plot comparing manual and MAGeT-Brain hippocampal volumes when using five Winterburn atlases, and a 21 image template library.

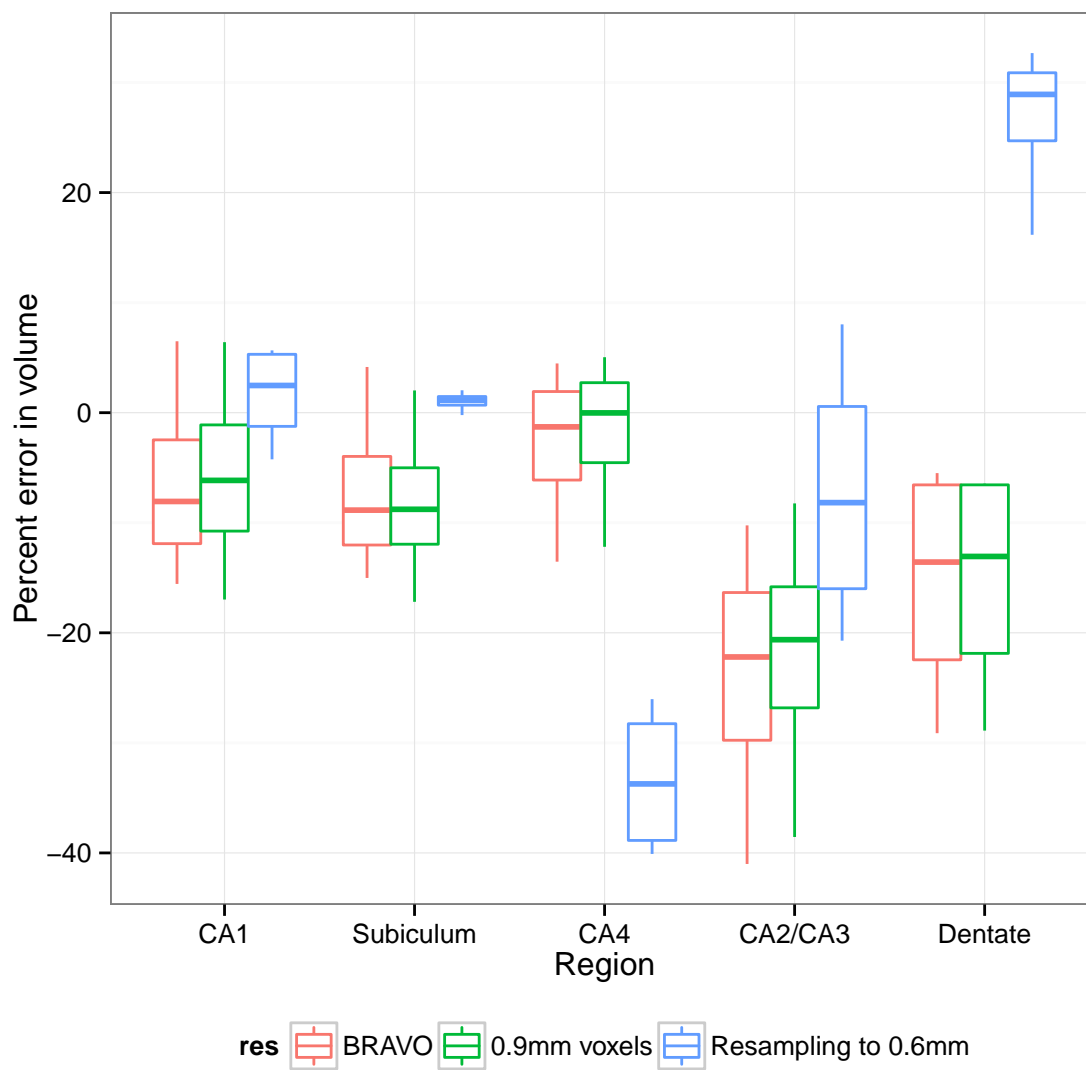


Figure 9: **Percent error in segmentation volume by Hippocampus subregion.**