Problem Set #2

$$|V| = \overrightarrow{W_{R+1}} = \overrightarrow{W_{K}} + \overrightarrow{y_{K}} \times \overrightarrow{x_{K}}$$

since two classes are linearly seperable, who could make no mistakes to predict. Then $y_R \times_R^T w_{opt} > 0$ And $Y(w_{opt}) > \frac{1}{11} w_{opt} \times_1^1$

> WKHT WOPE > WK WOPE + Y (1 WOPE 1)

12 NWKI N2 = WKI WKI

= (WR+YKXR) T(WR+ YKXR)

= IIWkII't 2 YkwkTXk + 86211 Xk1)2

Since ykwetxx <0 and 11xx112=1. Yk = 1-1,17

then $\| \overline{W}_{ET} \|^2 = \| \overline{W}_{ET} \|^2 + 2y_R \overline{W}_R T \overline{X}_R T y_R^2 \| \overline{X}_R \|^2$ $\leq \| \overline{W}_R \|^2 + y_R^2 \| \overline{X}_R \|^2 \leq \| \overline{W}_R \|^2 + 1$

Therefore, ILWKIN2 < 1/WK 112+)

WK+1 WOPE = WM WOPE + Y 11 WOPE 11 1-3 > WM- Wape + 24 11 Wape 11 > Wo Wapo + MY 11 WOPEH sma Wo = 0 WK+1 WOPU > MY11 WOPE 11 then Dut to carry-Schwartz inequality MY 11 Wopen & WK+1 Wopt & 11 WK+1 111 WOPD 1 50 M Y ≤ 1/W KH 1. similarly 1/Wkt 112 = 1/WM112+1 < 11 WM-1112+ 2 < 11 Wo 112+ M, Wo = 0 50 11WK+1112 = M => 11WK+111 = JM Since (M-k) iteration make no mistakes and it closes to matter therefore, My 5/1 WETI 11 5 VM NY ym ≤ √m ⇒ M ≤ y-2

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2-1 LCvo, b) = - 2 (4n In [5 (w) xn + b)] + C+yn) In [+ 5 (w) xn + b)] }
        \nabla_{W}L = -\frac{1}{n} \left\{ y_{\eta} \frac{b(z)(1-b(z))}{b(w)} \right\} = w \nabla_{\eta} t b \cdot \nabla_{\eta} t + \frac{1}{n} \left\{ y_{\eta} \frac{b(z)(1-b(z))}{b(w)} \right\} = w \nabla_{\eta} t b \cdot \nabla_{\eta} t + \frac{1}{n} \left\{ y_{\eta} \frac{b(z)(1-b(z))}{b(w)} \right\} = w \nabla_{\eta} t b \cdot \nabla_{\eta} t b
                                  \frac{(1-y_n)\cdot - 6(3)(1-6(3))/3=\overline{w_1}\overline{x_n^2+b}}{1-6(\overline{w_1}\overline{x_n^2+b})}\cdot \overline{x_n^2}
              = -\sum_{n} \left\{ y_n \left( 1 - \delta(z) \right) \overrightarrow{X_n} + (y_n - 1) \delta(z) \cdot \overrightarrow{X_n} \right\} 
\geq = \overline{w_n} \overrightarrow{X_n} + b
            = - = { ynxn - 5(wxn+b)xn}
            = -\frac{1}{n}\left[y_n-6(\vec{w}^T\vec{x_n}+b)\right]\cdot \frac{1}{x_n}
 50, W \leftarrow W + \lambda \stackrel{N}{\nearrow} [y_n - b c \overrightarrow{w} + \overrightarrow{x} \overrightarrow{n} + b)] \cdot \overrightarrow{x} \overrightarrow{n}
22
                    3 [yn - 6 cmxn)] · xn
                      (0-6(0)).1+(1-6(0)).1+
                       ( 1- 5(0)) 1 + (1- 5(0)) 1
                                                                                           \left( 500 = \frac{1}{1+e^0} = 0.5 \right)
           W ≥ 0.00 ( ← Wot 2 = [8n - 5(wx)]. Xn
                                             2 0+0.00 | x 1
                                                 predice
  input
                        b(wx)
                                                                      label
                                                                                         thathing accuracy
                 F(0.001)=0.50025
                                                                                              こるこのひ
                 5(000))
                 51000D)
                 50000)
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2.3 from 2.2, w = 0.001we could get

inpur	Б(юх)	predice	abel
4	6 (-0.00 D=0.49975	0	0
1	5(0,001) = 0.50025 6(0,001)	1	1
•		1	0
te	est accuracy $\geq \frac{2}{3}z$	0-6]	

$$\frac{\partial L}{\partial y_{jk}} = \frac{\partial L}{\partial y_{j}} \cdot \frac{\partial \hat{y}_{j}}{\partial y_{j}} \cdot \frac{\partial Q_{j}}{\partial y_{jk}} \cdot \frac{\partial Q_{j}}{\partial y_{jk}}$$

$$\frac{\partial L}{\partial \hat{y}_{j}} \geq -\frac{y_{j}}{\hat{y}_{j}}$$

$$\frac{\partial V}{\partial y_{j}} = \begin{cases}
-\frac{y_{j}}{\hat{y}_{j}} \cdot \frac{\partial Q_{j}}{\partial y_{j}} \cdot \frac{\partial Q_{j}}{\partial y_{j}} \\
-\frac{Q_{j}}{2} \cdot \frac{\partial Q_{j}}{\partial y_{j}} \cdot \frac{\partial Q_{j}}{\partial y_{j}}
\end{cases}$$

$$\frac{\partial L}{\partial Q_{j}} = \frac{\partial L}{\partial y_{j}} \cdot \frac{\partial Q_{j}}{\partial y_{j}} \cdot \frac{\partial Q_{j}}{\partial y_{j}} \cdot \frac{\partial Q_{j}}{\partial y_{j}}$$

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$$\frac{\partial Q_{j}}{\partial y_{j}} = \frac{\partial Q_{j}}{\partial y_{j}}$$

$$\frac{\partial L}{\partial W_{Ri}} = \frac{\partial L}{\partial Z_{R}} \cdot \frac{\partial Z_{R}}{\partial W_{Ri}}$$

$$\frac{\partial L}{\partial W_{Ri}} = \frac{3}{3} \frac{\partial L}{\partial \hat{y}_{i}} \cdot \frac{\partial \hat{y}_{i}}{\partial \hat{y}_{i}} \cdot \frac{\partial \hat{y}_{i}}{\partial \hat{y}_{i}} \cdot \frac{\partial \hat{y}_{i}}{\partial Z_{R}}$$

$$= \frac{3}{3} \left(-\hat{y}_{i} + \hat{y}_{i} + \hat{y}_{i} + \hat{y}_{i} + \hat{y}_{i} + \hat{y}_{i} \right) V_{jR}$$

$$\frac{\partial L}{\partial W_{Ri}} = \frac{3}{3} \frac{\partial L}{\partial Z_{R}} \cdot \frac{\partial Z_{R}}{\partial W_{Ri}}$$

$$= \frac{3}{3} \frac{\partial L}{\partial W_{Ri}} \cdot \frac{\partial Z_{R}}{\partial W_{Ri}}$$

$$= \frac{3}{3} \frac{\partial L}{\partial W_{Ri}} \cdot \frac{\partial Z_{R}}{\partial W_{Ri}} \cdot \frac{\partial \hat{y}_{i}}{\partial Z_{R}} \cdot \frac{\partial \hat{y}_{i}}{\partial Z_{R}} \cdot \frac{\partial \hat{y}_{i}}{\partial Z_{R}}$$

$$= \frac{3}{3} \frac{\partial L}{\partial W_{Ri}} \cdot \frac{\partial Z_{R}}{\partial W_{Ri}} \cdot \frac{\partial \hat{y}_{i}}{\partial Z_{R}} \cdot \frac{\partial \hat{y}_{i}}{\partial$$

So.
$$\frac{JL}{3Wki} = \frac{3}{5!} (-y_i + y_i \leq y_m) \cdot V_{jk} \cdot (1-Z_k^2) \cdot x_i$$