

# A Forward Backward Approach to Stochastic Quantisation

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- Osterwalder-Schrader reconstruction theorem ('75):

$$\text{Quantum Field Theory} \quad \begin{array}{c} \xleftrightarrow{\text{Wick}} \\ \xleftrightarrow{\text{rotation}} \end{array} \quad \text{Euclidean Quantum Field Theory}$$

- EQFT: Certain **Probability measures** on the space of **distributions**  $\mathcal{S}'(\mathbb{R}^d)$ .

$$“ \mathbb{E}_\nu[\mathcal{O}(\Phi)] = \int_{\mathcal{S}'(\mathbb{R}^d)} \mathcal{O}(\varphi) \nu(d\varphi) = \frac{1}{\text{norm.}} \int_{\mathcal{S}'(\mathbb{R}^d)} \mathcal{O}(\varphi) e^{-S(\varphi)} d\varphi ”$$

for

$$S(\varphi) = Q(\varphi, \varphi) + V(\varphi),$$

$$Q(\varphi, \varphi) = \int_{\mathbb{R}^d} (m^2 |\varphi(x)|^2 + |\nabla \varphi(x)|^2) dx$$

positive quadratic form

$$V(\varphi) = \lambda \int_{\mathbb{R}^d} U(\varphi(x)) dx$$

$U: \mathbb{R}^d \rightarrow \mathbb{R}$  bounded from below

## Simplest case: Gaussian Free Field

For  $V(\varphi) = 0$ ,

$$\mu(d\varphi) = e^{-S_{\text{free}}(\varphi)} d\varphi, \quad S_{\text{free}}(\varphi) = Q(\varphi, \varphi) = \int_{\mathbb{R}^d} (m^2 |\varphi(x)|^2 + |\nabla \varphi(x)|^2) dx,$$

formally corresponds to a Gaussian measure on  $\mathcal{S}'(\mathbb{R}^d)$  with

$$\text{Cov}(\mu) = (m^2 - \Delta)^{-1},$$

and  $\text{supp}(\mu) \subset H^{\alpha-}(\mathbb{R}^d)$  for  $\alpha = (2-d)/2$

→ only for  $d=1$  supported on functions.

→ Starting point for more interesting EQFTs

$$\nu(d\varphi) = \frac{1}{\text{norm.}} e^{-V(\varphi)} \mu(d\varphi) \quad \text{where} \quad V(\varphi) = \int_{\mathbb{R}^d} U(\varphi(x)) dx$$

- Some possible starting points to obtain non-Gaussian models:
  - in  $d = 2$ :

$$U(x) = \lambda x^{2p} + \sum_{\ell}^{2p-1} a_{\ell} x^{\ell} \quad \text{for any } p > 0,$$

$$U(x) = \lambda \exp(\beta x),$$

$$U(x) = \lambda \cos(\beta x),$$

- in  $d = 2, 3$ :

$$U(x) = \lambda x^4 - b x^2.$$

**Goal:** Make sense of

$$\begin{aligned} \text{`` } \nu(\mathcal{O}) &= \frac{1}{\text{norm.}} \int_{\mathcal{S}'(\mathbb{R}^d)} \mathcal{O}(\varphi) e^{-S(\varphi)} d\varphi \\ &= \frac{1}{\text{norm.}} \int_{\mathcal{S}'(\mathbb{R}^d)} \mathcal{O}(\varphi) e^{-\int_{\mathbb{R}^d} U(\varphi(x)) dx} \mu(d\varphi) \text{''}, \end{aligned}$$

with  $\mu$  the Gaussian free field and,

$$S(\varphi) = \int_{\mathbb{R}^d} \frac{1}{2} (|\nabla \varphi(x)|^2 + m^2 |\varphi(x)|^2) + U(\varphi(x)) dx.$$

**Problems:**

**Large Scales:** No decay in space:  $S(\varphi) = \infty$  at best (non-sense at worst)

**Small Scales:**  $\nu$  not supported on **function** spaces but only on **distributions**

$\rightarrow U(\varphi(x))$  ill-defined

With  $V(\varphi) = \int_{\mathbb{R}^d} U(\varphi(x)) dx$ , define approximations

$$e^{-V(\varphi)} \mu(d\varphi) \approx e^{-V_T^\xi(\varphi)} \mu^T(d\varphi),$$

## Large scale Problem

$$\int_{\mathbb{R}^d} U(\varphi(x)) dx = \infty?$$

cut-off in space  $\xi \in C_c^\infty(\mathbb{R}^d)$ :

$$V^\xi(\varphi) = \int_{\mathbb{R}^d} \xi(x) U(\varphi(x)) dx$$

## Small Scale Problem

$$\text{supp}(\mu) \subset H^{(2-d)/2-}(\mathbb{R}^d)$$

Regularise the measure:

$$\mu^T \rightarrow \mu,$$

$\mu^T$  supported on **functions**

Additionally:

Choose  $V_T$  depending on  $T$

**Question:** Can we recover a EQFT?

$$\begin{aligned} \nu^{T,\xi}(\mathcal{O}) &= \frac{1}{\text{norm.}} \int_{\mathcal{S}'(\mathbb{R}^d)} \mathcal{O}(\varphi) e^{-V_{\textcolor{red}{T}}^{\xi}(\varphi)} \mu^{\textcolor{red}{T}}(d\varphi) \\ &\quad \xrightarrow{\text{???}} \\ \text{`` } \nu(\mathcal{O}) &= \frac{1}{\text{norm.}} \int_{\mathcal{S}'(\mathbb{R}^d)} \mathcal{O}(\varphi) e^{-V(\varphi)} \mu(d\varphi) \text{''}. \end{aligned}$$

**Problem:** In general,  $\nu$  not absolutely continuous w.r.t. the Gaussian free field  $\mu$

→ Move to different characterisations for  $\nu^{T,\xi}$  that do not rely on absolute continuity

## Starting point:

Given a regularisation  $\mu \mapsto \mu^T$  and a cut-off  $\xi$  we can construct  $\nu^{T,\xi}$  (as the Gibbsian perturbation of the Free Field)

Think of a map

$$``\Phi^\xi: \mu^T \mapsto \nu^{T,\xi} ``$$

**Idea:** Study the maps  $\Phi^\xi$  to learn about the measures  $\nu^{T,\xi}$  and (ideally) remove both regularisations  $T, \xi$ .

By now many, different approaches building on this perspective (e.g. via parabolic, elliptic SPDEs as introduced by Parisi/Wu-'81)



## In this talk:

For a suitable potential  $V$ , and cut-offs  $T < \infty, \xi \in C_c^\infty(\mathbb{R}^d)$ :

If  $X$  solves the SDE

$$X_{t,T}^\xi = W_t - \int_0^t \dot{G}_s \mathbb{E}_s[\nabla V_T^\xi(X_{T,T})] ds, \quad 0 \leq t \leq T.$$

and  $W_s$  is a Brownian motion with covariance  $G_s$  and  $\text{Law}(W_\infty) = \mu$ .

Then, we can show,

$$\Phi^\xi(\mu^T) := \text{Law}(X_{T,T}^\xi) = \nu^{\xi,T}.$$

**So far:** Found the description  $\nu^{\xi,T} = \text{Law}(X_{T,T}^{\xi})$ , where

$$X_{t,T}^{\xi} = W_t - \int_0^t \dot{G}_s \mathbb{E}_s[\nabla V_T^{\xi}(X_{T,T}^{\xi})] ds.$$

**Goal:** Remove the regularisations  $\xi$  and  $T$  to recover  $\nu = \text{Law}(X_{\infty,\infty}^1)$

- $\xi \rightarrow 1$ : Here: now mainly a technical problem<sup>1</sup>
- $T \rightarrow \infty$ : More delicate and more interesting (for this talk):

In dim.  $d \geq 2$ , covariance  $G_T(0) := \int_0^T Q_s^2(0) ds$  diverges as  $T \rightarrow \infty$ , and so

$$\|\nabla V_T\|_{\infty} \rightarrow \infty, \quad \text{as } T \rightarrow \infty.$$

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1. so we drop it from now on.

$$X_{t,T} = W_t - \int_0^t \dot{G}_s \mathbb{E}_s[\nabla V_T(X_{T,T})] ds \quad \text{where} \quad \lim_{T \rightarrow \infty} \|\nabla V_T\|_\infty \rightarrow \infty.$$

**Starting point:** If  $X$  is a Markov process (as we would expect), for some  $\wp$ ,

$$\mathbb{E}_s[\nabla V_T(X_{T,T})] = \wp_s^T(X_{s,T}).$$

**Ansatz:** Find a function  $F$

$$\mathbb{E}_s[\nabla V_T(X_{T,T})] = F_{s,T}(X_{s,T}) + R_{s,T}, \quad R_{T,T} = 0,$$

to bring down the scales.

Then, the remainder  $R$  satisfies a BSDE

$$R_{t,T} = \mathbb{E}_t[F_{T,T}(X_{T,T}) - F_{t,T}(X_{t,T})].$$

Derived the system

$$\begin{cases} X_{t,T} = W_t - \int_0^t \dot{G}_s(F_s(X_{s,T}) + R_{s,T}) ds, \\ R_{t,T} = \mathbb{E}_t[F_T(X_{T,T}) - F_t(X_{t,T})], \end{cases}$$

and from Itô's formula obtain an equation for  $R$ ,

$$R_{t,T} = \mathbb{E}_t \int_t^T [H_s^F(X_{s,T}) - DF_s(X_{s,T}) \dot{G}_s R_{s,T}] ds,$$

where

$$H_s^F(\varphi) = \left( \partial_s F_{s,T} + \frac{1}{2} \text{Tr}(\dot{G}_s D^2 F_{s,T}) - \mathbf{D} F_{s,T} \dot{G}_s F_{s,T} \right)(\varphi).$$

## A new problem: Approximate solutions to the flow equation

**Goal:** Find a “good enough” approximation  $F$  to the flow equation

$$H_s^F := \partial_s F_{s,T} + \frac{1}{2} \text{Tr}(\dot{G}_s D^2 F_{s,T}) - \textcolor{red}{D} F_{s,T} \dot{G}_s F_{s,T} \approx 0,$$

and solve

$$\left\{ \begin{array}{l} X_{t,T} = W_t - \int_0^t \dot{G}_{\textcolor{blue}{s}}^2(F_{\textcolor{blue}{s}}(X_{T,T}) + R_{\textcolor{blue}{s},T}) ds, \\ R_{t,T} = \mathbb{E}_t[F_T(X_{T,T}) - F_t(X_{t,T})] \\ \quad = \mathbb{E}_t \int_t^T ds H_s^F(X_{s,T}) - \mathbb{E}_t \int_t^T ds D F_s \dot{G}_s R_s. \end{array} \right.$$

with uniform bounds in  $T$ .

A concrete example: First order approximation for  $V_t(x) = \lambda_t \int_{\mathbb{R}^2} dx \cos(\beta \varphi(x))$

$$\begin{cases} X_{t,T} = W_t - \int_0^t \dot{G}_s(F_{s,T}(X_{s,T}) + R_{s,T}) ds \\ R_{t,T} = \mathbb{E}_t \int_t^T [H_s^F(X_{s,T}) - DF_s(X_{s,T}) \dot{G}_s R_{s,T}] ds \end{cases} \quad \text{where} \quad H_s^F = \partial_s F_{s,T} + \frac{1}{2} \text{Tr}(\dot{G}_s D^2 F_{s,T}) - DF_{s,T} \dot{G}_s F_{s,T}$$

Start by solving **only the linear equation**,

$$\partial_s F_s + \frac{1}{2} \text{Tr}(\dot{G}_s D^2 F_s) = 0, \quad F_T = \nabla V_T.$$

so that  $H_s^F = DF_s \dot{G}_s F_s$ , and  $F_t = \nabla V_t = -\lambda_t \beta \sin(\beta \varphi)$ ,

$$(\star) \begin{cases} X_{t,T} = W_t - \int_0^t \dot{G}_s(F_s(X_{s,T}) + R_{s,T}) ds, \\ R_{t,T} = \mathbb{E}_t \int_t^T [DF_{s,T} \dot{G}_s F_s - DF_s(X_{s,T}) \dot{G}_s R_{s,T}] ds. \end{cases}$$

## Theorem

*For any  $T \in [0, \infty]$  and  $\beta^2 < 4\pi$ , there is a solution  $(X_{\cdot,T}, R_{\cdot,T})$  to the FBSDE  $(\star)$  (unique for weak interactions) with  $\sup_{t,T} \|R_{t,T}\|_{L^\infty} \lesssim 1$ . Moreover, writing*

$$X_{t,\infty} = \mathcal{Z}_t + W_t \quad \text{where} \quad \mathcal{Z}_t = \int_0^t \dot{G}_s(F_{s,\infty}(X_{s,\infty}) + R_{s,\infty}) ds.$$

*we have convergence  $\mathcal{Z}_t \rightarrow \mathcal{Z}_\infty$  in  $L^\infty(dP; W^{1,\infty}(\mathbb{R}^d))$  so that we obtain the sine-Gordon EQFT as a random shift of the GFF*

$$\nu_{\text{SG}} = \text{Law}(X_{\infty,\infty}) = \text{Law}(\mathcal{Z}_\infty + W_\infty).$$

## Why this approach?

- Pathwise, scale-by-scale coupling of the GFF and the EQFT
- Amenable to stochastic analysis: e.g. coupling methods  $\rightarrow$  decay of correlations
- Approximate solutions to the infinite dimensional, non-linear PDE (“renormalisation flow equation”)

$$\partial_s F_s + \frac{1}{2} \text{Tr}(\dot{G}_s D^2 F_s) - \mathbf{D} F_s \dot{G}_s F_s = 0, \quad F_T = \nabla V_T,$$

are sufficient (if you can control the resulting FBSDE).

- closely linked to an optimisation problem  $\rightarrow$  large deviations
- Can verify OS axioms from studying the FBSDE (so we constructed a EQFT)
- Limit is non-Gaussian (i.e. the EQFT is non-trivial)



## What's next?

For this specific model: Cover a wider parameter range for  $\beta^2$ ?:

- For  $\beta^2 \in (0, 8\pi)$ : model is known to be renormalisable but with **infinitely many thresholds** requiring additional renormalisations (full control on the full space not yet achieved). [G. Benfatto, G. Gallavotti, F. Nicoló, et al. · On the massive sine-Gordon equation in {the first few/ higher/ all} regions of collapse · Comm. math. phys. {1982/ 1983/ 1986}]
- Beyond  $4\pi$ : The linear approximation for the renormalisation flow is not enough  $\rightarrow$  requires better understanding of **approximations**

$$\partial_s F_s + \frac{1}{2} \text{Tr} \dot{G}_s D^2 F_s - D F_s \dot{G}_s F_s \approx 0; \quad F_T = \lambda_T \sin(\beta \varphi).$$

- As critically is approached, this requires more and more ‘non-linear’ approximations  $F$  making the analysis of the forward equation more difficult.

## What's next?

Better approximations of the renormalisation flow. Start from

$$F_s^{[0]}(\varphi) = 0,$$

and schematically expect better approximations by iterating for  $\ell > 0$ ,

$$\partial_s F_s^{[\ell]} + \text{Tr} \dot{G}_s D^2 F_s^{[\ell]} = - \sum_{\ell_1 + \ell_2 = \ell} D F_s^{[\ell_1]} \dot{G}_s F_s^{[\ell_2]}, \quad F_T^{[\ell]} = \begin{cases} \nabla V_T & , \ell = 1 \\ 0 & , \text{else} \end{cases}$$

(so even bounded initial conditions appear polynomial as  $\ell$  increases!)

Then with  $F_s = \sum_{q \leq \ell} F_s^{[q]}$ , we need more and more terms as we approach criticality

→ FBSEs appear nonlinear and the analysis becomes more involved.

Thanks!

Decompose the Gaussian free field as

$$\text{Cov}(\mu) = (m^2 - \Delta)^{-1} = \int_0^\infty Q_s^2 ds$$

for “nice”<sup>2</sup> operators  $Q_s$ , and a cylindrical Brownian motion  $B$ ,

$$W_t := \int_0^t Q_s dB_s \text{ is a Brownian motion with } \text{Cov}(W_t) = \int_0^t Q_s^2 ds =: G_t,$$

$$\text{e.g. } Q_t^2 = \frac{1}{t^2} e^{-(m^2 - \Delta)/t^2}.$$

Then,  $W_t$  is a **function** for any  $t \in (0, \infty)$  with  $W_\infty \sim \mu$  and we define

$$\mu^T := \text{Law}(W_T)$$

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2. self-adjoint, positive and Hilbert-Schmidt

With

$$\mu^T = \text{Law}(W_T) = \int_0^T Q_s dB_s$$

we can write

$$\nu_{\text{SG}}^{\xi, T}(\mathcal{O}) = \frac{1}{\text{norm.}} \int_{\mathcal{S}'(\mathbb{R}^2)} \mathcal{O}(\varphi) e^{-V_T^\xi(\varphi)} \mu^T(d\varphi) = \frac{\mathbb{E}[\mathcal{O}(W_T) e^{-V_T^\xi(W_T)}]}{\mathbb{E}[e^{-V_T^\xi(W_T)}]},$$

e.g. for the family of observables

$$\mathcal{O}(\varphi) = e^{-g(\varphi)}.$$

→ study exponential functionals of Brownian motion

**Theorem. (Boué-Dupuis ('98))** *For a bounded functional  $F$  and a  $Q$ -Brownian motion  $W$ , the variational description*

$$-\log \mathbb{E}[e^{-F(W)}] = \inf_{u \in \mathbb{H}^0} \mathbb{E} \left[ F(X_\bullet(u)) + \frac{1}{2} \int_0^\infty \|u_s\|_{L^2(\mathbb{R}^d)}^2 ds \right],$$

*holds. Here,  $\mathbb{H}^0$  is the space of adapted processes and*

$$X_t(u) := W_t + \int_0^t Q_s u_s ds.$$

[M. Boué, P. Dupuis · A variational representation for certain functionals of Brownian motion · Ann. Prob. 1998]

[N. Barashkov, M. Gubinelli · A variational method for  $\varphi_3^4$  · Duke math. J. 2020]

[N. Barashkov, M. Gubinelli · On the variational method for EQFT in 2D · arXiv preprint · 2021]

Apply the BD-formula to the BM  $W$  and the functional,

$$V_T^\xi(\varphi) := \lambda_T \int_{\mathbb{R}^2} \xi(x) \cos(\varphi(x)) dx,$$

$$-\log \int e^{-V_T^\xi(\varphi)} \mu^T(d\varphi) = -\log \mathbb{E}[e^{-V_T^\xi(W_T)}] = \inf_{u \in \mathbb{H}^0} \mathbb{E} \left[ V_T^\xi(X_T(u)) + \int_0^\infty \|u_s\|_{L^2}^2 ds \right],$$

where

$$X_T(u) = W_T + \int_0^T Q_s u_s ds.$$

Now: Look for optimal control  $u$ , derive Euler-Lagrange equation.

## Theorem

*The infimum is a minimum and the optimal control satisfies*

$$u_s^{\xi,T} = -Q_s \mathbb{E}_s[\nabla V_T^{\xi}(X_T(u^{T,\xi}))],$$

*and the optimal dynamics are*

$$(*) \quad X_{t,T}^{\xi} = W_t - \int_0^t Q_s^2 \mathbb{E}_s[\nabla V_T^{\xi}(X_{T,T}^{\xi})] ds.$$

*Moreover, the solution to (\*) satisfies*

$$\Phi^{\xi,T}(\mu) := \text{Law}(X_{T,T}^{\xi}) = \nu_{SG}^{\xi,T}.$$



For a centered Gaussian random variable  $W$  with covariance  $G$  define the Wick ordered exponentials

$$\llbracket \exp(i\beta W) \rrbracket := e^{\frac{\beta^2}{2}G} e^{i\beta W}.$$

Use this to define the Wick ordered cosine in the usual way (from  $\cos(x) = \operatorname{Re}(e^{ix})$ ).

### Theorem

*For any  $\delta > 0$ ,  $p \geq 1$  and  $\beta^2 < 4\pi$ , the Wick ordered cosine satisfies*

$$\sup_{t \geq 0} \mathbb{E} \left[ \left\| \llbracket \cos(\beta W_t) \rrbracket \right\|_{B_{p,p}^{-\beta^2/4\pi - \delta}(\langle x \rangle^{-\ell})}^p \right] < \infty,$$

*and converges in  $L^p(dP; B_{p,p}^{-\beta^2/4\pi - \delta}(\langle x \rangle^{-\ell}))$  and almost surely to a limit (denoted by  $\llbracket \cos(\beta W_\infty) \rrbracket$ )*

*(i) Euclidean invariance (ii) Reflection positivity (iii) Exponential moment bounds*

- Looking for Gaussian measures satisfying (i) and (ii) leaves us with only combinations of the GFF
- Given a RP measure  $\mu$  (like the GFF) the perturbation

$$e^{-\int_{\Lambda} U(\varphi(x)) dx} \mu(d\varphi)$$

is again reflection positive for any  $\Lambda \subset \mathbb{R}^d$

- Euclidean invariance means that we need  $\Lambda = \mathbb{R}^d$

i.e. the cut-off  $\xi$  destroys (i), and the mollification  $T$  destroys (ii)

**But:** both properties can be recovered in the limit

## Optimality for the BD variational problem

On the finite volume: We can show that the solution  $X_\infty^\xi$  to the FBSDE  $(\star)$  is optimal for

$$\mathcal{V}^\xi = \inf_u \mathbb{E} \left[ \underbrace{\lambda_0 \int_{\mathbb{R}^2} \xi(x) \mathbb{I}(\cos(\beta X_t(u))) (x) dx + \frac{1}{2} \int_0^\infty \|u_s\|_{L^2}^2 ds}_{=: \mathcal{J}^{0,\xi}(u)} \right], \quad X_t = W_t + \int_0^t Q_s u_s ds.$$

Makes no sense for  $\xi = 1$ .

**However:** The solution is Lipschitz in small perturbations of the interaction term  $V$ , so we can hope that the variational problem for the Laplace transform

$$\mathcal{W}^{\xi,T}(g) := \nu^{\xi,T}(e^{-g}) = \inf_u (\mathcal{J}_T^{g,\xi}(u) - \mathcal{J}_T^{0,\xi}(u))$$

converges as the cut-off  $\xi$  is removed.

## Theorem

*For  $n$  sufficiently large,  $\lambda > 0$  small enough, the limit of the Laplace transforms exists and satisfies the variational problem*

$$\mathcal{W}(g) = \lim_{\substack{\xi \rightarrow 1 \\ T \rightarrow \infty}} \mathcal{W}^{\xi, T}(g) = \inf_{v \in \mathcal{A}(g)} \mathbb{E} \left[ g(X_\infty(\bar{u} + v)) + \int_{\mathbb{R}^2} (U_\infty(X_\infty(\bar{u} + v)) - U_\infty(X_\infty(\bar{u}))) + \mathcal{E}(\bar{u}, v) \right].$$

*Here  $X_\infty(u) = I_\infty(u) + W_\infty$  is the shifted GFF and*

- $\bar{u}$  is an adapted process which does not depend on  $g$  and  $v$
- $I_\infty$  is a linear functional increasing regularity by 1
- $\mathcal{E}$  is a quadratic form
- $\mathcal{A}(g)$  is the set of adapted controls  $v$  s.t.  $\mathbb{E} \int_0^\infty \|v_s\|_{L^2(\langle x \rangle^n)}^2 ds \leq C_{\nabla g, n}$ .

## Non-Gaussianity of the limit

For a Gaussian measure supported on  $H^{-1}(\langle x \rangle^{-\ell})$  with Cameron-Martin space  $H_{\text{CM}}(\nu) \subset H^{-1}(\langle x \rangle^{-\ell})$ ,

$$\log \int \exp(-\langle \varphi, \psi \rangle) \nu(d\varphi) = \frac{1}{2} \|\psi\|_{H_{\text{CM}}(\nu)}^2 + \langle m, \psi \rangle_{H^{-1}(\langle x \rangle^{-\ell})}$$

So it is sufficient to show that the lhs is not quadratic for  $\nu_{\text{SG}}$ .

Applying the BD formula with  $V^\psi = V + \langle \cdot, \psi \rangle$  we can write the lhs as the limit of the approximate measures  $\nu_{\text{SG}}^{\xi, T}$  and (after a Cameron Martin shift) obtain

$$= \lim_{\substack{T \rightarrow \infty \\ \xi \rightarrow 1}} \langle G_T \psi, G_T \psi \rangle_{(m^2 - \Delta)^{-1}} + \mathcal{V}_T^\xi((m^2 - \Delta)^{-1} \psi) - \mathcal{V}_T^\xi(0)$$

but  $\nabla \mathcal{V}_T^\xi = \nabla V_0^\xi(X_{0,T}^\xi) + R_{t,T}^\xi \sim T^{c(\beta)} \sin(\beta \cdot) + O(1)$  is not linear.