



SWINBURNE  
UNIVERSITY OF  
TECHNOLOGY

# **COS10004 Computer Systems**

## **Lecture 10.2 ARM Assembly – The Software Stack**

CRICOS provider 00111D

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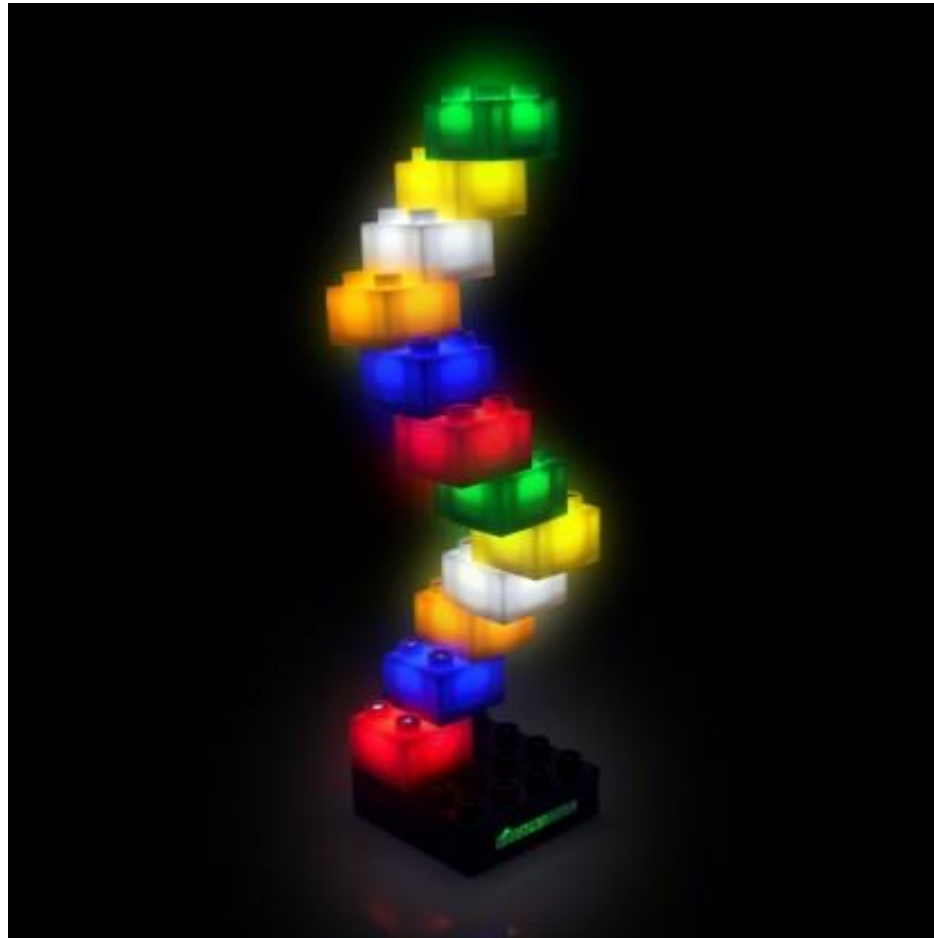
# FUNCTIONS IN ASM

- Not 'native' to assembly
  - We need to do a lot of the management ourselves
- Argument passing:
  - How do we pass arguments from one function to another
- Storing and recalling register values
  - each function we call will want to use the same registers (only 13 general purpose registers !)
  - How do we manage this ?
- Managing the program control
  - Jumping from one function to another, and then returning back !

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- Managing the program control
  - Jumping from one function to another, and then returning back !

# STACKS



# PUSH, POP AND THE STACK

- ARM computers have a software stack\*.
- A separate area of RAM is available for temporary values.
- A value in a register can be pushed onto the stack to preserve it for later.
- It can be popped off later (in LIFO order).
- We can get the memory location (a pointer to it) by *checking the SP* (R13) register.

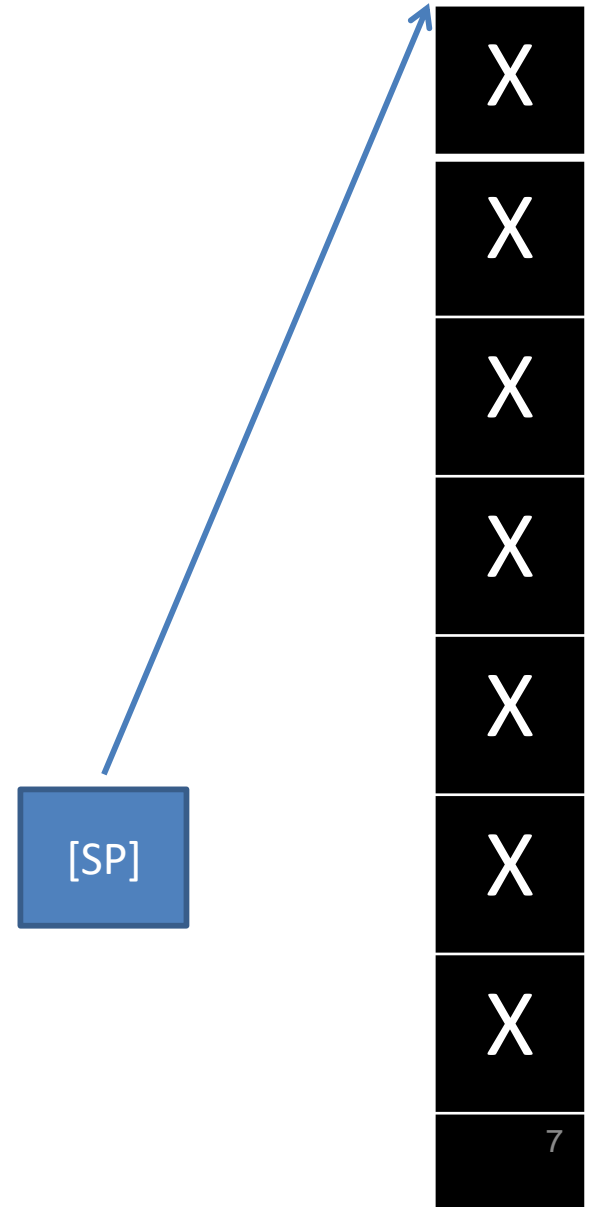
# \* SOFTWARE STACK?

- A section of RAM managed by the SP (stack pointer) register.
- A sort of 32-bit (64-bit in ARM8) wide array which starts (element 0) high in RAM and grows down as values are added to it.
- The stack pointer stores the memory location of the last value added (pushed) to the stack.
- Each push decrements SP by 4 (4 bytes per word).
- A pop operation removes the last value in the stack and increments the SP by 4 (4 bytes per word)

# Software stack (depth only limited by RAM)

**Example:**

**x = don't care. [SP] points to start of stack.**

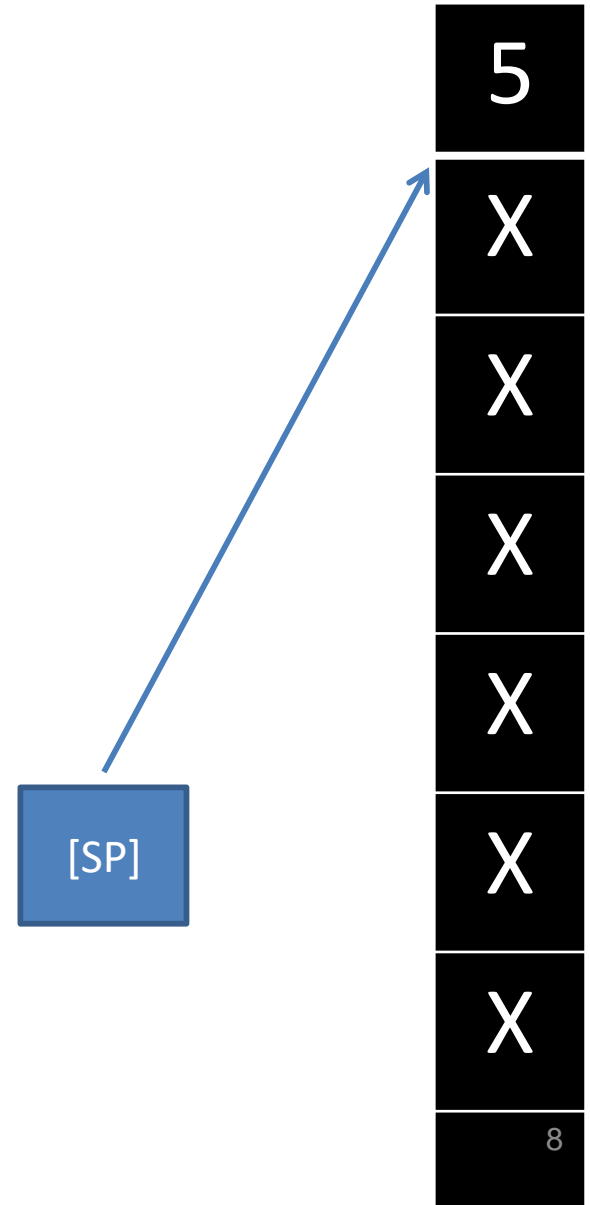


# Software stack (depth only limited by RAM)

**Example:**

**x = don't care.**

**push 5 – SP decremented by 4. [SP] points to 5**





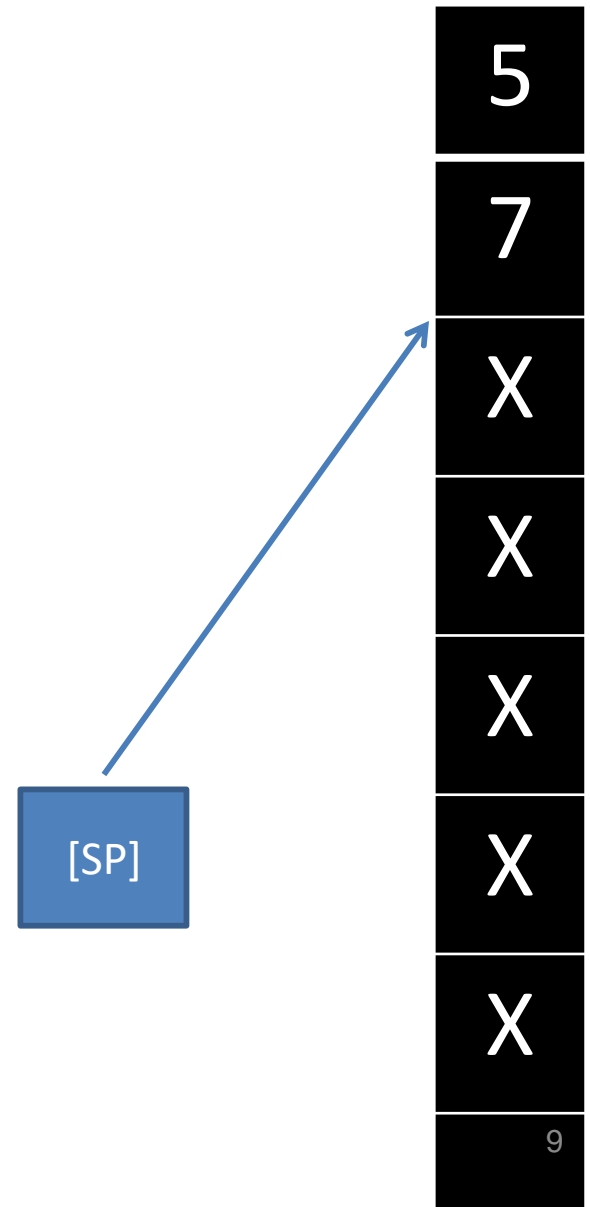
# Software stack (32-bit) (depth only limited by RAM)

**Example:**

**x = don't care.**

**push 5 – SP decremented by 4**

**push 7 - SP decremented by 4, [SP] points to 7.**



# Software stack (depth only limited by RAM)

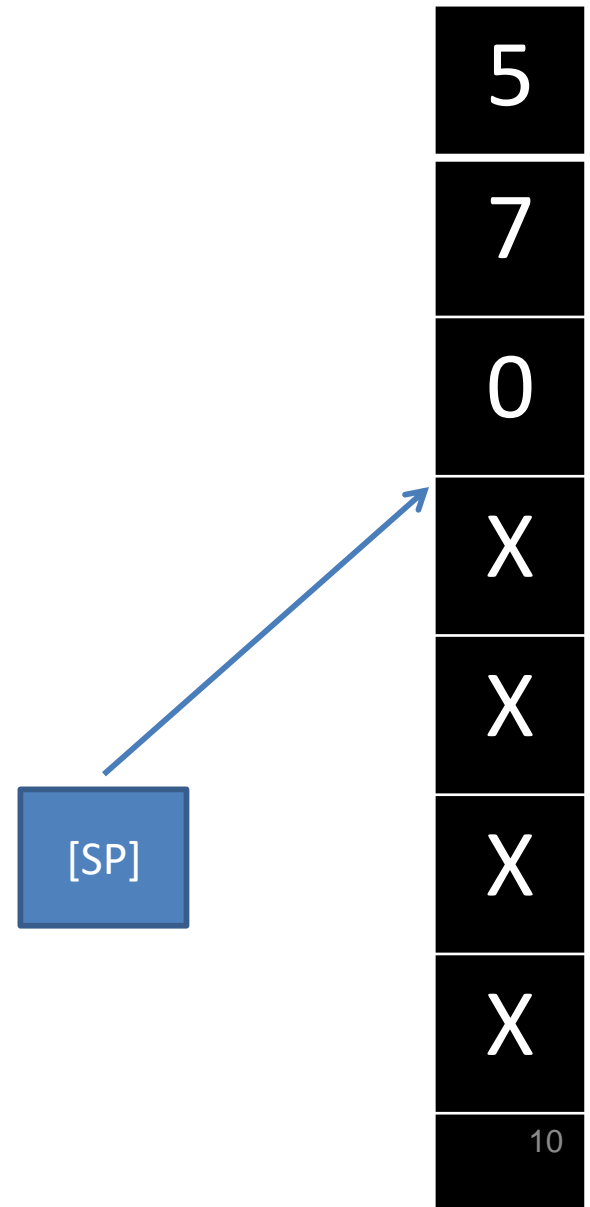
**Example:**

**x = don't care.**

**push 5 – SP decremented by 4**

**push 7 - SP decremented by 4**

**push 0 – SP decremented by 4. [SP] points to 0**



# Software stack (depth only limited by RAM)

**Example:**

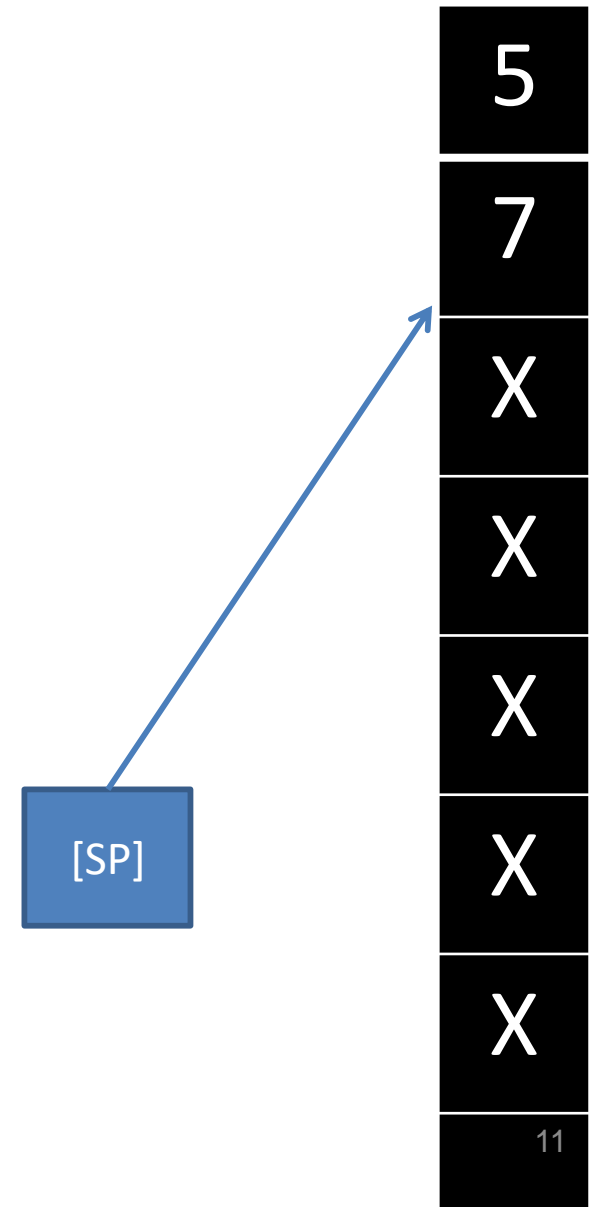
**x = don't care.**

**push 5 – SP decremented by 4**

**push 7 - SP decremented by 4**

**push 0 – SP decremented by 4**

**pop 0 – SP incremented by 4. [SP] points to 7**



# Software stack (depth only limited by RAM)

**Example:**

**x = don't care.**

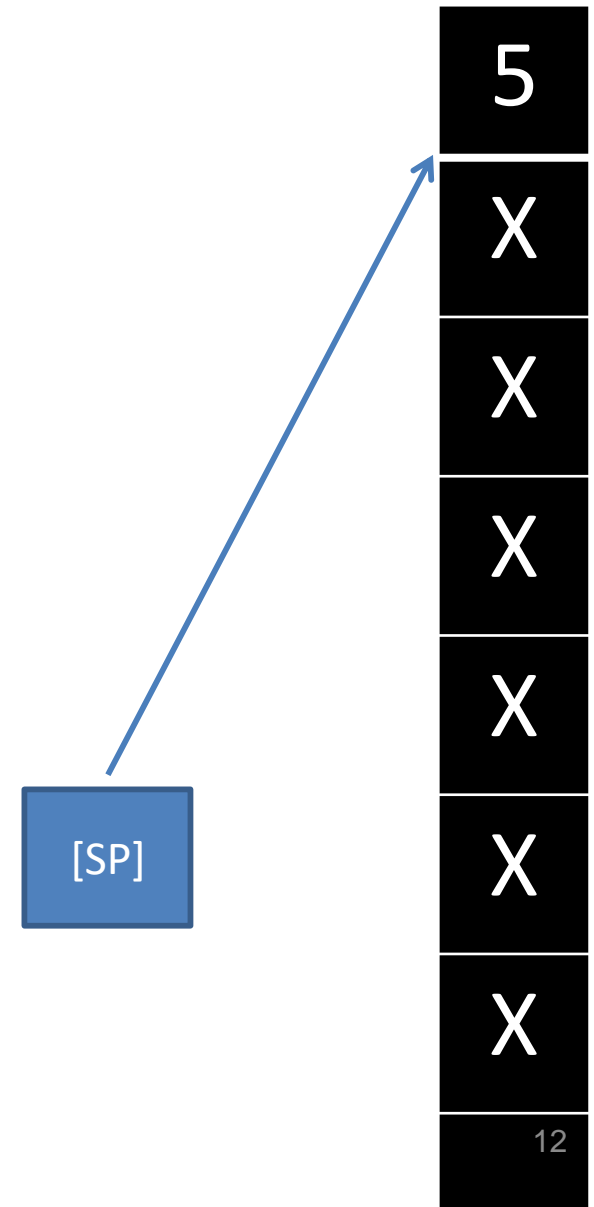
**push 5 – SP decremented by 4**

**push 7 - SP decremented by 4**

**push 0 – SP decremented by 4**

**pop 0 – SP incremented by 4**

**pop 7 – SP incremented by 4. [SP] points to 5.**



# Software stack (depth only limited by RAM)

**Example:**

**x = don't care.**

**push 5 – SP decremented by 4**

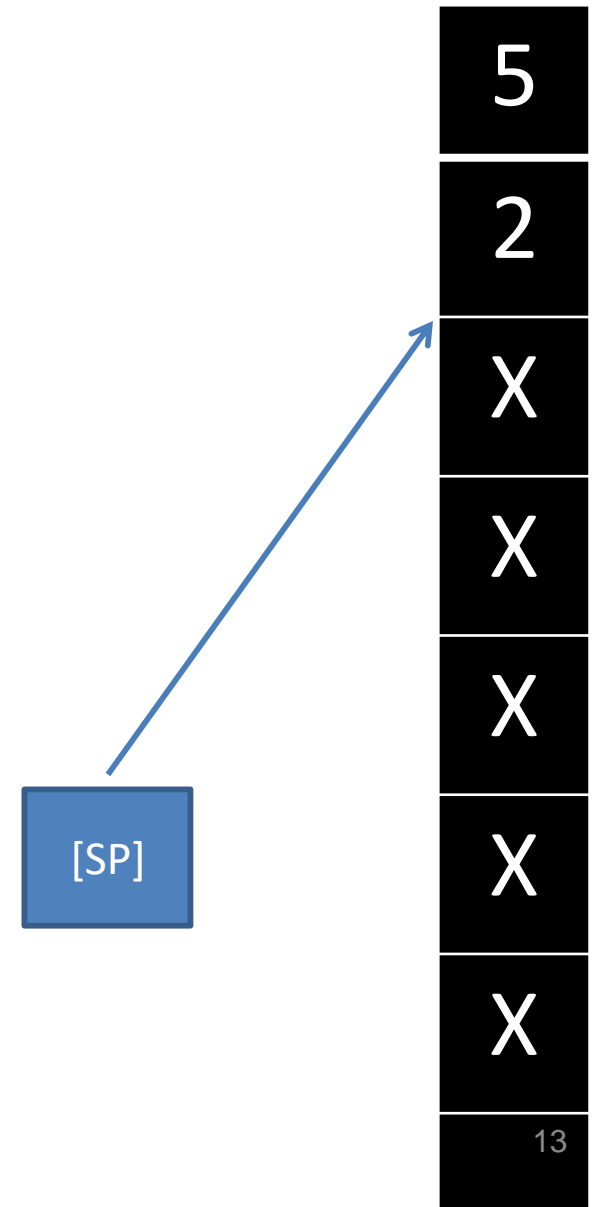
**push 7 - SP decremented by 4**

**push 0 – SP decremented by 4**

**pop 0 – SP incremented by 4**

**pop 7 – SP incremented by 4**

**push 2 – SP decremented by 4. [SP] points to 2.**



# Software stack (depth only limited by RAM)

**Example:**

**x = don't care.**

**push 5 – SP decremented by 4**

**push 7 - SP decremented by 4**

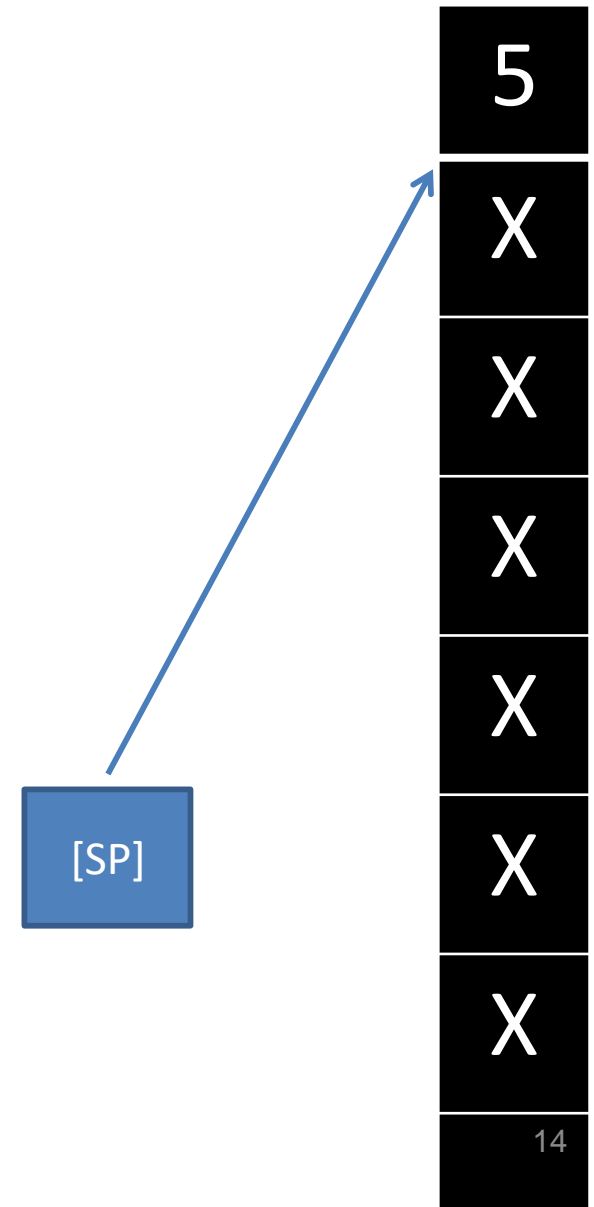
**push 0 – SP decremented by 4**

**pop 0 – SP incremented by 4**

**pop 7 – SP incremented by 4**

**push 2 – SP decremented by 4**

**pop 2 – SP incremented by 4. [SP] points to 5.**



# Software stack (depth only limited by RAM)

**Example:**

**x = don't care.**

**push 5 – SP decremented by 4**

**push 7 - SP decremented by 4**

**push 0 – SP decremented by 4**

**pop 0 – SP incremented by 4**

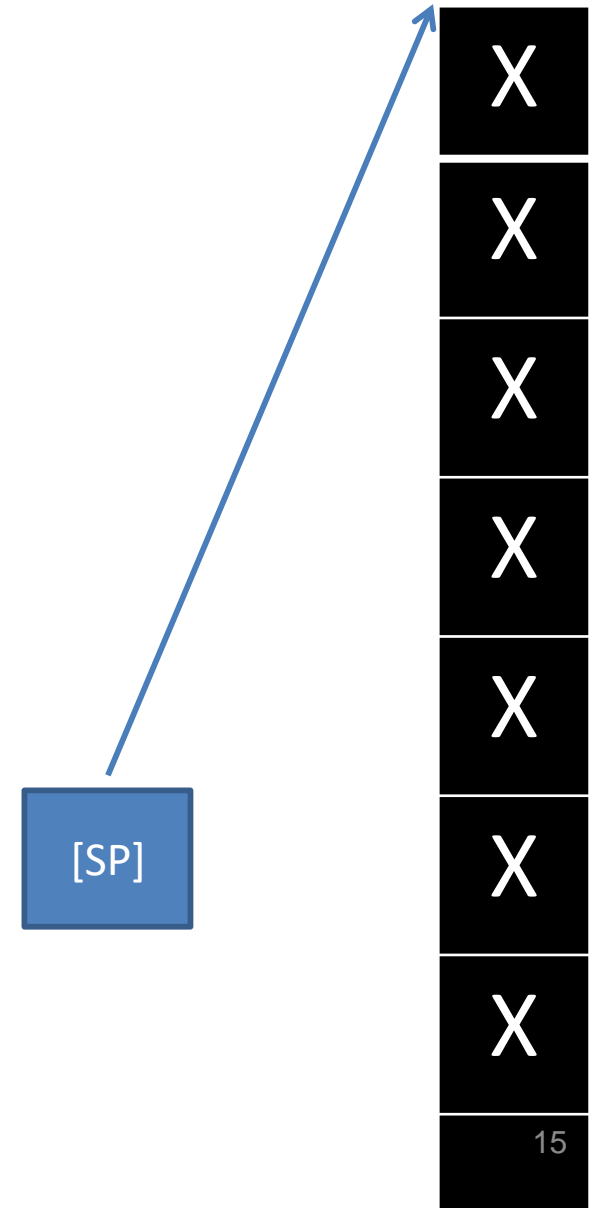
**pop 7 – SP incremented by 4**

**push 2 – SP decremented by 4**

**pop 2 – SP incremented by 4**

**pop 5 - SP incremented back to it's starting value. The stack is now empty.**

**[SP] points to end of stack.**



## EXAMPLE SYNTAX

- Push and pop accept multiple registers if in a { , , ,... } list

push {r4,r5} ;back them up onto the stack

;use r4 and r5 for something else

pop {r4,r5} ;restore them from the stack

Correct order is preserved for {lists}

- Alternatively, do one at a time (but pop in reverse order)

push {r4}

push {r5}

; do something

pop {r5}

pop {r4}



# RECALL THE ABI

- **Application Binary Interface (ABI)** sets standard way of using ARM registers.
  - r0-r3 used for function arguments and return values
  - r4-r12 promised not to be altered by functions
  - **lr** and **sp** used for stack management
  - **pc** is the next instruction – we can use it to exit a function call

# ABI CONVENTIONS

- ABI compliant functions:
  - Use r0-r3 for passing and returning values to functions
  - Promise not to alter r4-r12
- ... but suppose the function needs to use many registers to do calculations ??
- We can use the stack to store and recall register values !

# PASSING ARGUMENTS TO FUNCTIONS

- To re-use the registers we need to:
  - Back up registers we need to re-use in a function
  - Store arguments for the function in r0-r3
  - Call the function
  - Read the return values from r0-r1 (optional)
  - Restore the registers we backed up.

# SUMMARY

- Software Stack:
  - Dedicated RAM used to store values FILO
    - Special register “sp” used to store address of start of the stack
- Stacks allow us to store and recall register values efficiently
- Stacks integral to functions:
  - We need to store and recall register values so we don’t run out of registers to use!