

# Greenland mass changes from 1960 to 2100

## Hindcasting and forecasting with PISM and RACMO2/GR

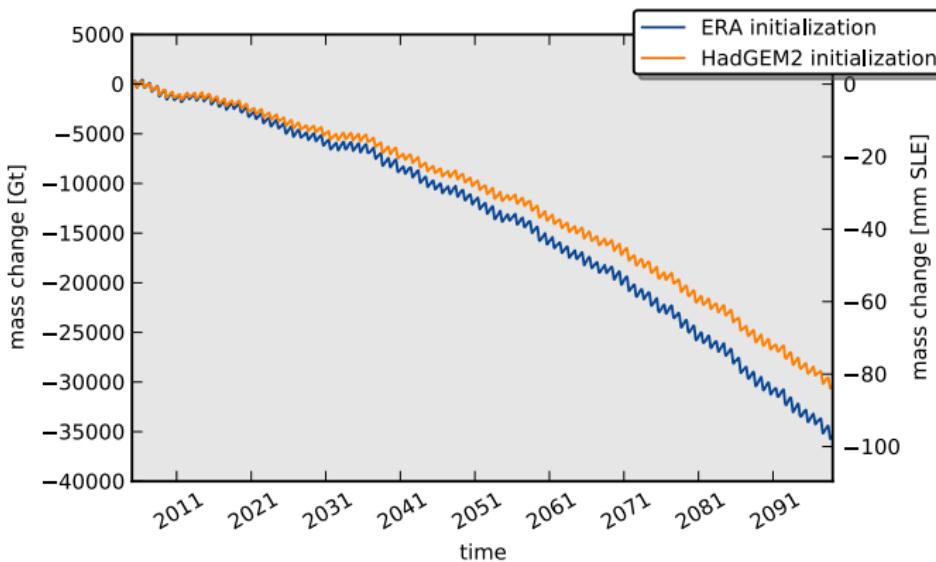
Andy Aschwanden<sup>1</sup> & Jan van Angelen<sup>2</sup>

<sup>1</sup> University of Alaska Fairbanks, USA

<sup>2</sup> Utrecht University, The Netherlands

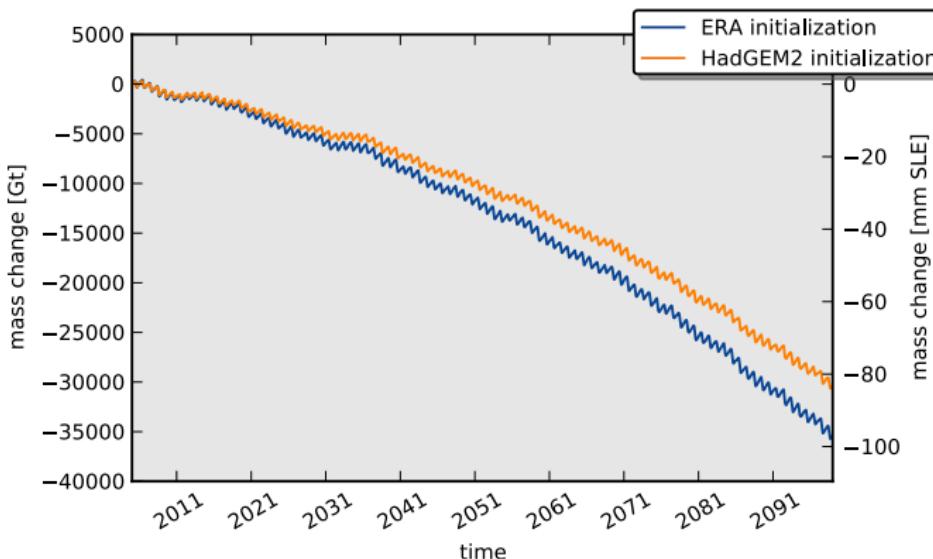
AGU 2012

# Greenland's future contribution to the global sea-level



- ▶ produced with the Parallel Ice Sheet Model PISM
- ▶ climate forcing from RACMO2/GR using RCP4.5 emission scenario
- ▶ what is the difference between the two simulations?

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# Initialization, hindcast, forecast

“Traditional”



This study



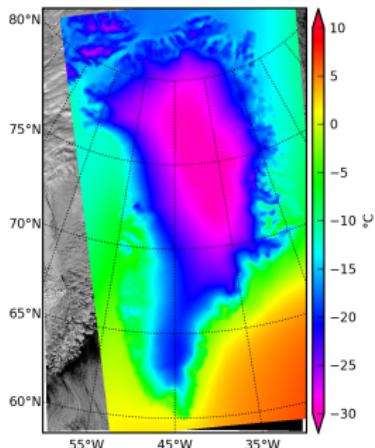
A hindcast is a way of testing a mathematical model. Known or closely estimated inputs for past events are entered into the model to see how well the output matches the known results.

# Initialization

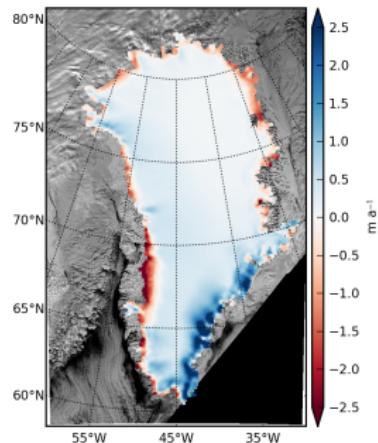


- ▶ RACMO2/GR driven by
  - ▶ ERA-reanalysis from 1961-2004
  - ▶ HadGEM2 from 1971-2004
- ▶ PISM driven by **mean values** of:

2 m air temperature



climatic mass balance

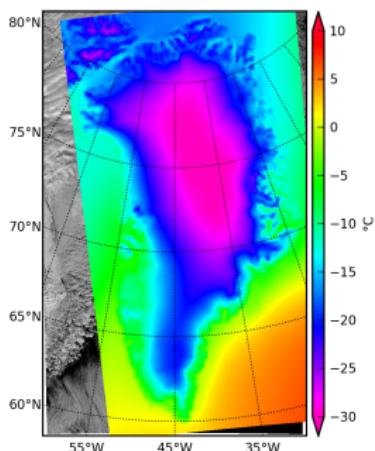


# Hindcast

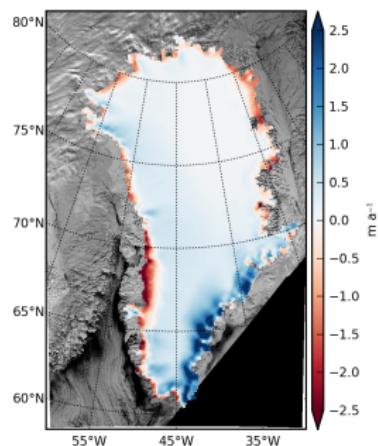


- ▶ RACMO2/GR driven by
  - ▶ ERA-reanalysis from 1961-2004
  - ▶ HadGEM2 from 1971-2004
- ▶ PISM driven by **monthly time-series** of:

2 m air temperature



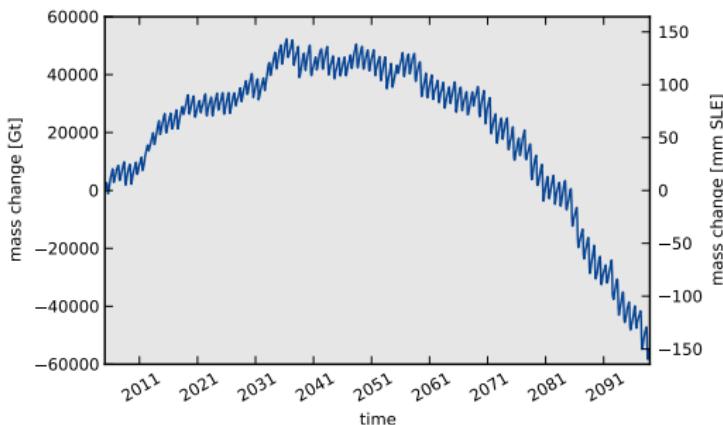
climatic mass balance



# Forecast

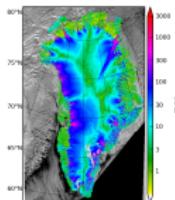


- ▶ RACMO2/GR driven by HadGEM2 RCP 4.5 forcing
- ▶ PISM driven by RACMO climate:
  - ▶ RACMO - HadGEM2 directly
  - ▶ RACMO - ERA/HadGEM2 anomalies

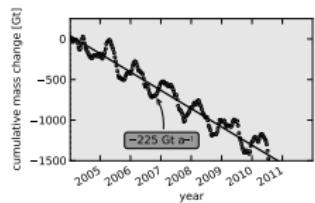


# Let's look at the recent history: model validation

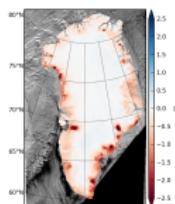
The hindcasts covers an era where we have a variety of in-situ and remotely-sensed observations such as:



- ▶ mean flow speed from 2000, 2006–2008 (SAR) from *Joughin et al.* (2010)



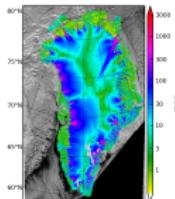
- ▶ cumulative mass change from 2003–2011 (GRACE) from *Luthcke et al.* (under review)



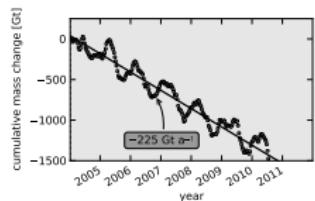
- ▶ elevation change from 2003–2009 (ICESat) from *Sørensen et al.* (2011)

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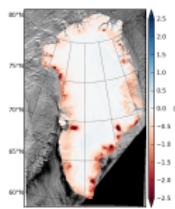
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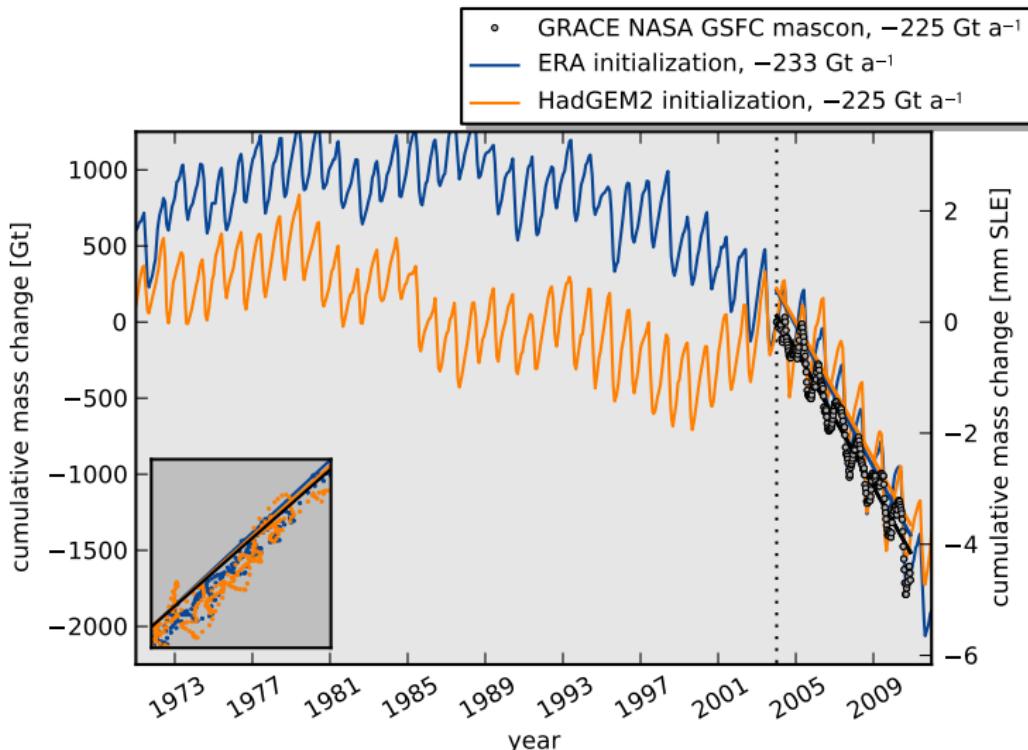


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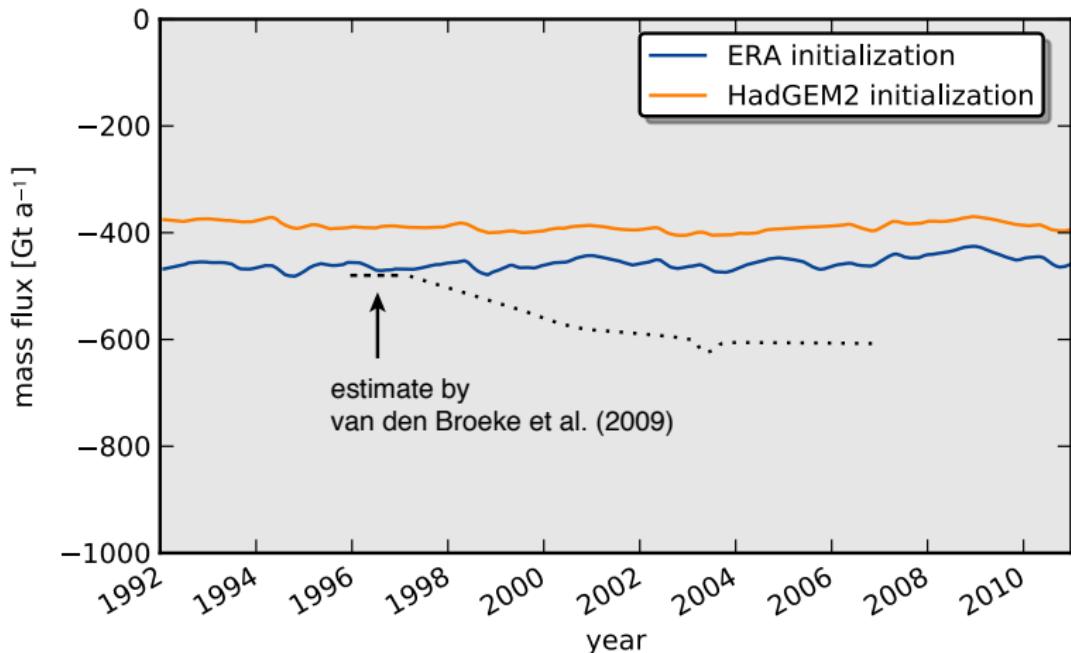
- ▶ elevation change from 2003–2009 (ICESat) from *Sørensen et al.* (2011)

## Validation: mass changes



- ▶ an almost perfect fit (?)

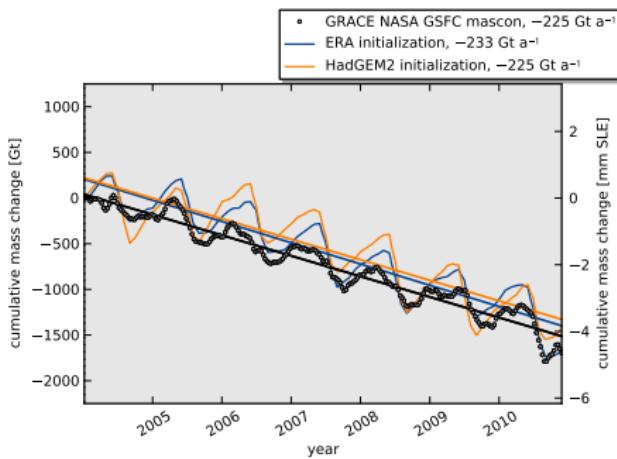
## Validation: ice discharge at ice/ocean interface



- ▶ observed increase not simulated
- ▶ simulated ice discharge remains nearly constant

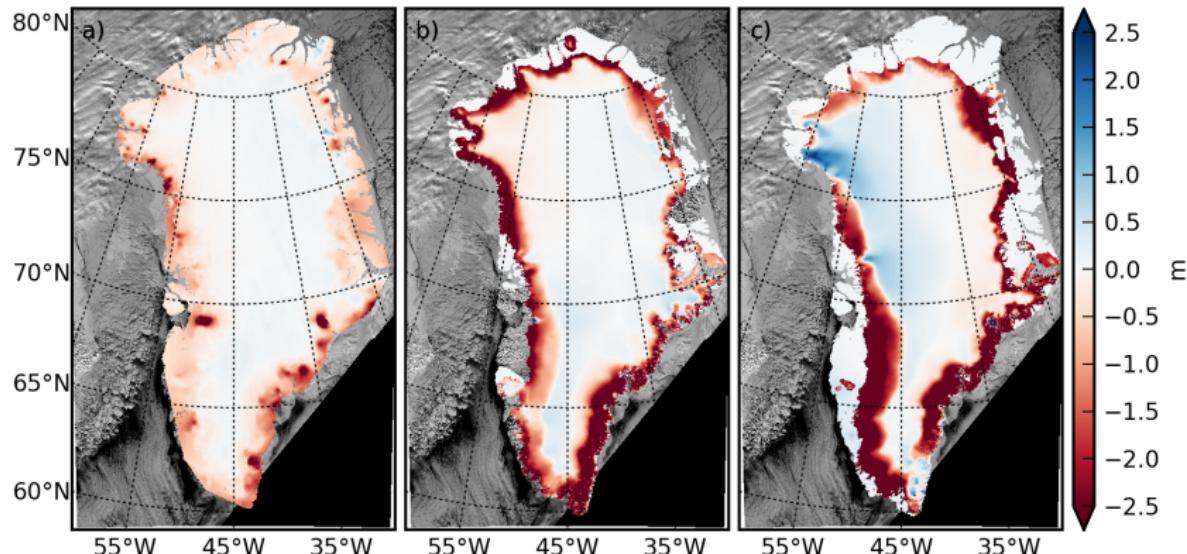
## Wait a minute...

- ▶ 2000–2008 mass changes equally split between changes in surface mass balance and ice discharge (van den Broeke et al, 2009)
- ▶ but simulated ice discharge is nearly constant
- ▶ why do we get such a good agreement with observed mass loss?



bottom line: careful validation is crucial!

# Validation: surface elevation changes 2003–2009



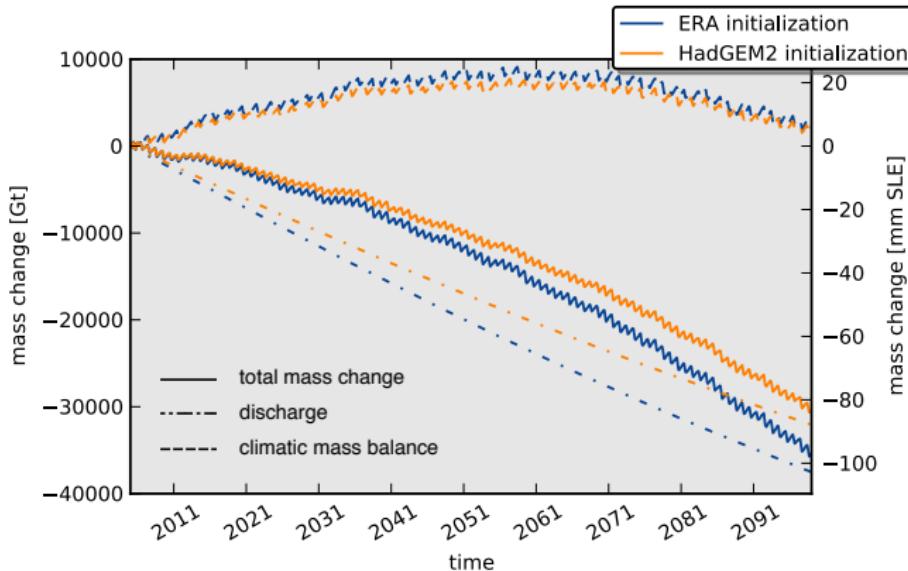
(a) ICESat  
(Sørensen et al, 2011)

(b) ERA init.

(c) HadGEM2 init.

too much mass loss around the perimeter

# Conclusions I



- ▶ despite ERA and HadGEM2 initializations showing very similar mass loss trends between 2004 and 2010, they differ by 2 cm SLE by 2100
- ▶ as a result of having different initial states

## Conclusions II

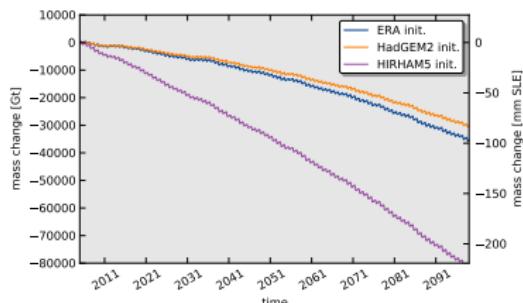
Switching from



to



facilitates careful and thorough validation of initial states



and allows measuring the sensitivity to initial states