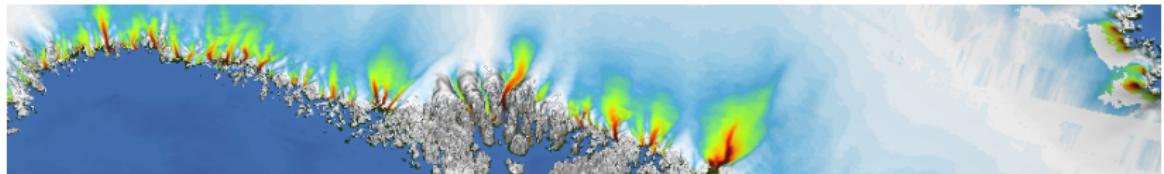


Implicit time-stepping for ice sheets

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Outline

problem, goals, and models

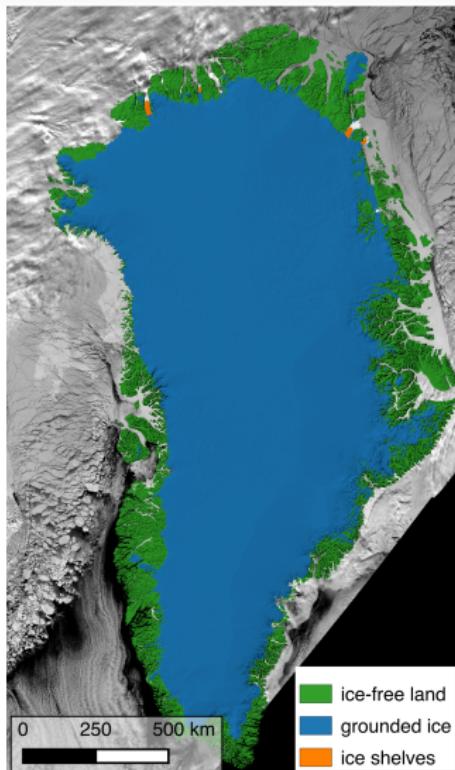
semi-discretizations

solving the equations for one time step

some early results

ice sheet flows and their boundaries

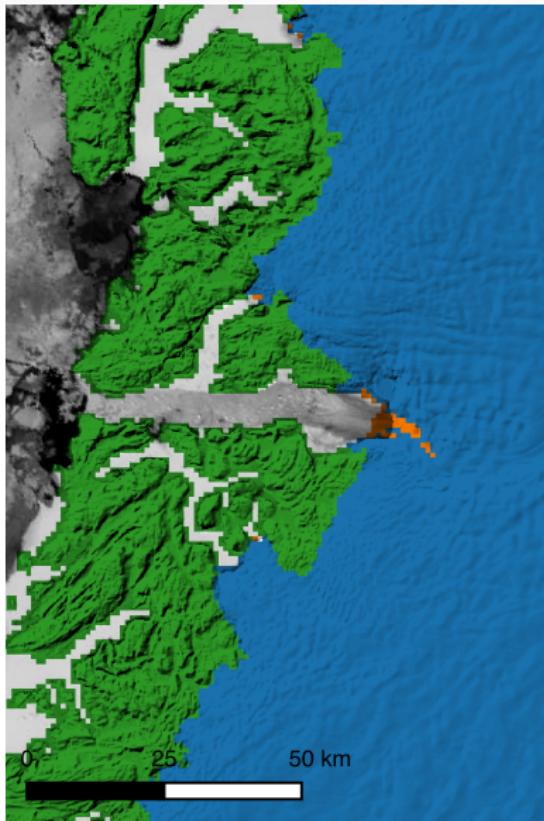
- nearly-fractal free boundaries
 - location determined by flow, topography, and atmosphere/ocean inputs
- large fraction of the boundary: grounded margins
- surface slope is discontinuous at grounded margins



PISM mask, by A. Aschwanden

ice sheet flows and their boundaries

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Taku Glacier, Alaska, by M. Truffer

computational goal: long-time, high-res runs

- my goal:

routinely simulate ice sheets on their natural time scales (ice age cycles $\gtrsim 10^5$ years) at resolutions where bedrock bumps, outlet glaciers, ice streams, and grounding lines are resolved ($\lesssim 500$ m)

- PISM (Parallel Ice Sheet Model) not there yet . . . either long-time *OR* high-res
- some concerns:
 1. stress-balance solves expensive
 - if time steps are short then stress balance is a lot of work
 - . . . energy conservation (temperature and basal melt) too!
 2. evolution of ice thickness $H(t, x, y)$ is diffusive . . . thus stiff
 - because ice flows downhill
 3. ice margins are low-regularity
 - 2 reasons: (i) constraint $H \geq 0$ and (ii) degeneracy
 4. bedrock is steep

a performance model

- grid spacing $h = \Delta x = \Delta y$ in 2D
 - (degrees of freedom) = $O(h^{-2})$
- time step limited by stability or accuracy:

$$\Delta t \leq O(h^q)$$

- $q = 2$ for conditionally-stable explicit schemes on diffusions
- accuracy alone suggests $0 < q < 1$? ... a scientific question?
- solution at one time step:
 - $N(h)$ Newton iterations
 - $K(h)$ (preconditioned) Krylov steps per Newton
- cost of computation on $\Omega \times [0, T]$:

$$\begin{aligned} C(h) &= (\text{number of steps}) \cdot (\text{iterations per step}) \cdot (\text{cost of 1 residual}) \\ &= O(h^{-q}) \cdot N(h) \cdot K(h) \cdot O(h^{-2}) \end{aligned}$$

- explicit: $C(h) = O(h^{-2}) \cdot 1 \cdot 1 \cdot O(h^{-2}) = O(h^{-4}) \leftarrow \text{beat this!}$

ice sheet models

- fixed computational domain $\Omega \subset \mathbb{R}^2$ where inputs $b =$ (bed elevation) and $m =$ (mass balance) are given
 - Ω is only partly-covered by ice
- shallow, possibly-hybrid, thickness-based $H, \mathbf{u} = (u, v)$

$$H_t + \nabla \cdot (-D\nabla H + \bar{\mathbf{u}}H) = m(x, t) \quad \text{mass conservation}$$

$$\mathcal{L}(\mathbf{u}, H) = 0 \quad \text{shallow stress balance}$$

- also: Stokes, surface-elevation-based $s, \mathbf{u} = (u, v, w)$

$$s_t + \mathbf{u}|_s \cdot (s_x, s_y, -1) = m(x, t) \quad \text{surface kinematical}$$

$$\nabla \cdot \mathbf{u} = 0 \quad \text{incompressibility}$$

$$\mathcal{L}(\mathbf{u}, s) = 0 \quad \text{Stokes stress balance}$$

- notation & assumptions:

- H thickness, s surface elevation, \mathbf{u} velocity
- $D = D(H, |\nabla s|)$ is SIA diffusivity (nonlinear & degenerate)
- conservation of energy ignored for simplicity
- Eulerian, fixed grid (structured or not)

semi-discretize in space

- method of lines (MOL)
 - *can you hand the thing to an ODE solver?*
- well-known: MOL for slow fluids is a DAE problem

$$\dot{H} = f(H, \mathbf{u}, t) \quad \text{mass conservation}$$

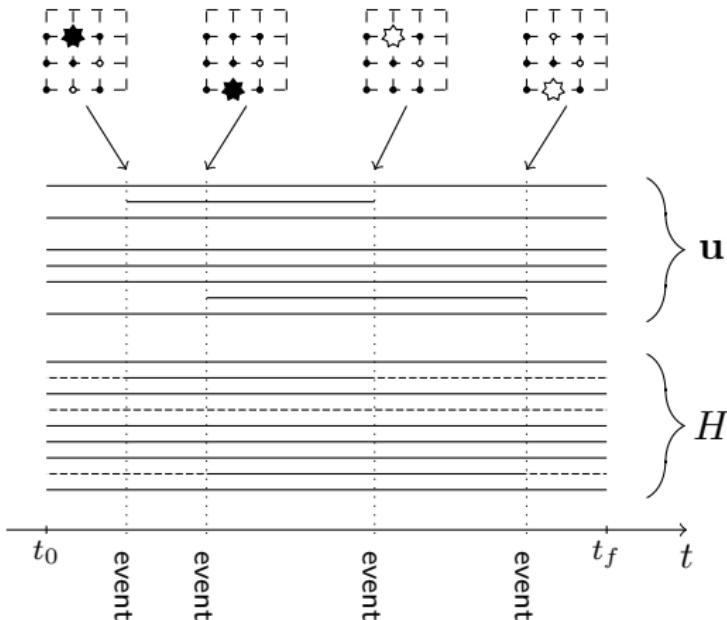
$$0 = g(H, \mathbf{u}) \quad \text{momentum conservation}$$

- *isn't implicit time-stepping required for DAEs anyway?*
- velocity variables only exist at positive-thickness locations i :

$$\mathbf{u}_i \text{ exists} \iff H_i > 0$$

- thus ODE solver must handle *events* like these?:
 - ice disappears during time step: $H_i(t) > 0 \rightarrow H_i(t + \Delta t) = 0$
 - ice appears during time step: $H_i(t) = 0 \rightarrow H_i(t + \Delta t) > 0$

MOL+events cannot scale



- at each event the ice velocity dimension changes
- ice sheet margins nearly fractal, so a *lot* of events to handle
- re-meshing at every event probably won't scale

semi-discretize in time

- semi-discretize in time *for understanding*
- consider a single backward Euler time-step
 - better time-stepping later
- hybrid equations become (notation: $H = H_{\text{new}}$, $\mathbf{u} = \mathbf{u}_{\text{new}}$):

$$H - H_{\text{old}} + \Delta t \nabla \cdot (-D \nabla H + \mathbf{u} H) = \Delta t m$$

$$\mathcal{L}(\mathbf{u}, H) = 0$$

single time-step problem for mass conservation

- solve for H subject to $H \geq 0$:

$$H - H_{\text{old}} + \Delta t \nabla \cdot \mathbf{q} = \Delta t m$$

- where $\mathbf{q} = -D \nabla H + \mathbf{u} H$
- note: $D = D(H, |\nabla s|) \rightarrow 0$ at margins

- make rigorous two ways:

- variational inequality (VI)

$$\int_{\Omega} (H - H_{\text{old}} - \Delta t m)(\eta - H) - \Delta t \mathbf{q} \cdot \nabla (\eta - H) \geq 0, \quad \forall \eta \geq 0$$

- nonlinear complementarity problem (NCP)

$$F(H) = H - H_{\text{old}} + \Delta t \nabla \cdot \mathbf{q} - \Delta t m \geq 0$$

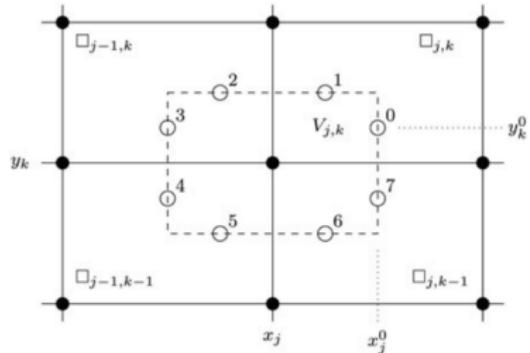
$$H \geq 0$$

$$HF(H) = 0$$

solving the equations

- discretize in space:

- e.g. $M^* = (Q^1 \text{ elements and finite volume weak form } \int_V)$ Bueler 2016

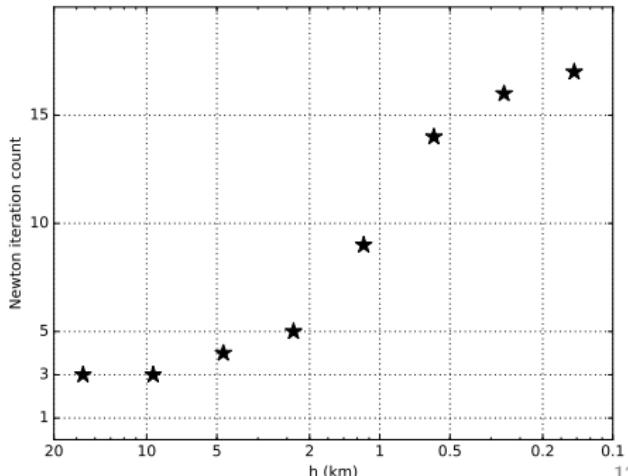
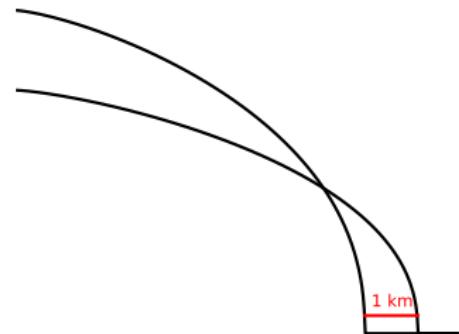


- wrote small PETSc code for mass conservation problem:
 - MOL using M^*
 - tells TS object which part is stiff: $F(H_t, H) = G(t, H)$
 - $F = H_t + \nabla \cdot \mathbf{q}$ and $G = m$
 - allows any implicit or IMEX time-stepping
- equations at each time step are solved with
 - NCP-adapted (“reduced-space” or “semi-smooth”) Newton
 - * `-snes_type vinewton{rs|ss}ls`
 - + Krylov solver + preconditioning

Benson & Munson 2006

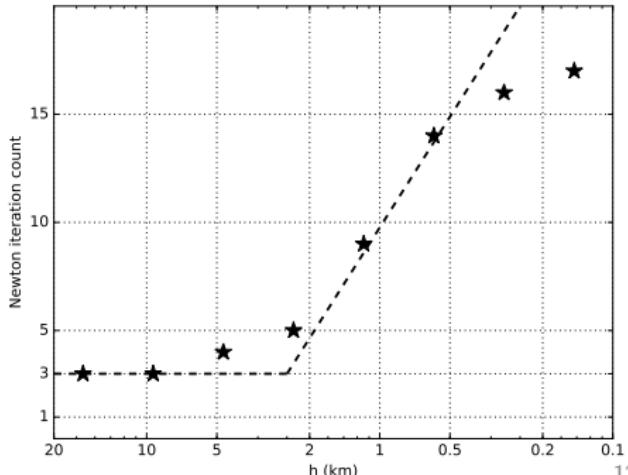
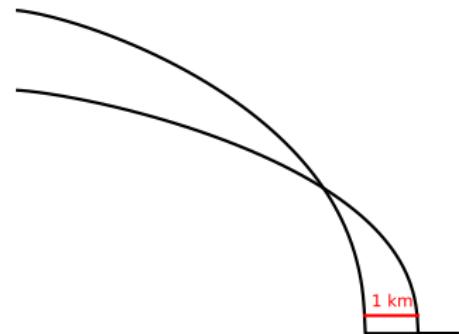
margin advance experiment: Newton iterations

- consider a single 10-year
beuler time step
- of a Greenland-sized
radial ice sheet
 - flat bed, $m = 0$
 - margin advance 975 m
- reduced-space Newton
solver sees Jacobian in
inactive variables only
 - states are admissible
 - dimension changes at
each Newton step
- on fine grids ($\lesssim 1 \text{ km}$)
the number of Newton
iterations is proportional
to margin motion divided
by Δx



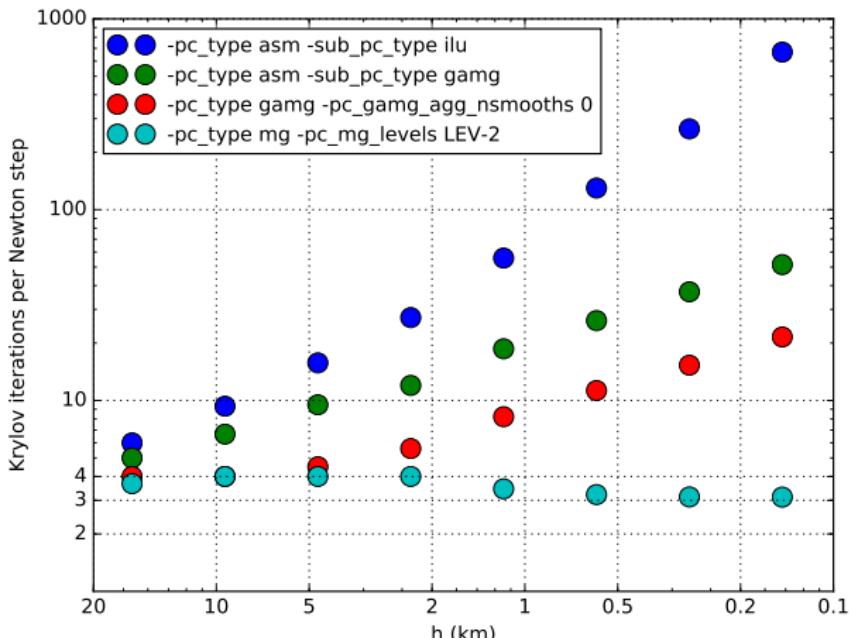
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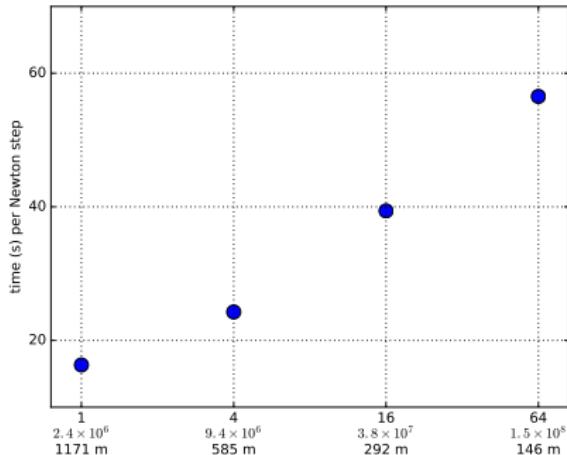
margin advance experiment: preconditioners

- fixed MPI rank = 64
- compare preconditioners:
-snes_type vinewtonrsls -ksp_type gmres -pc_type X
- Krylov iterations per Newton step:



margin advance experiment: weak scaling?

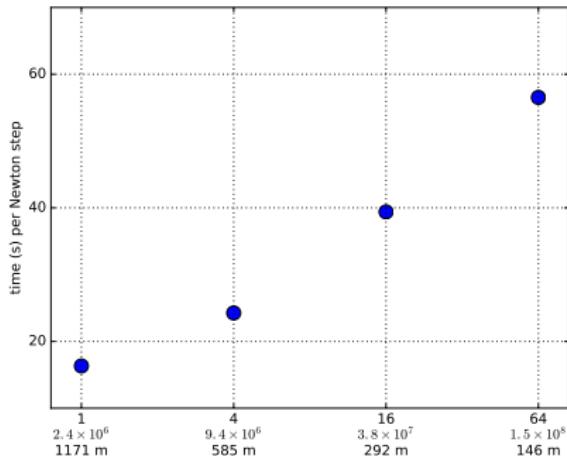
- very preliminary weak-scaling evidence
 - ranks 1, 4, 16, 64
 - fixed d.o.f. per process: 2.4×10^6
 - `-pc_type mg`
- time per Newton step: *... should be flat!*



- the good news: $\Delta t / \Delta t_{FE} = 9 \times 10^4$ on finest grid

margin advance experiment: weak scaling?

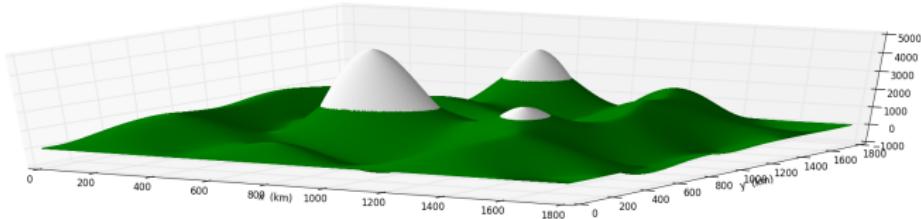
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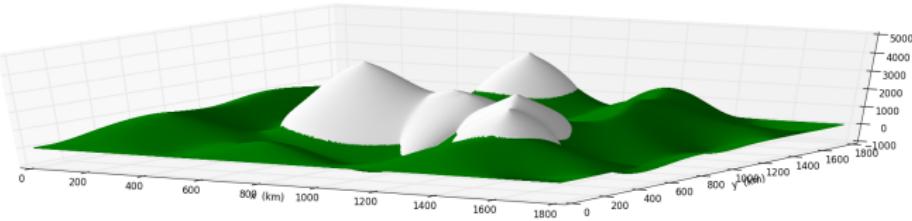
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example: 50ka run with topography and sliding

$t = 0$ a



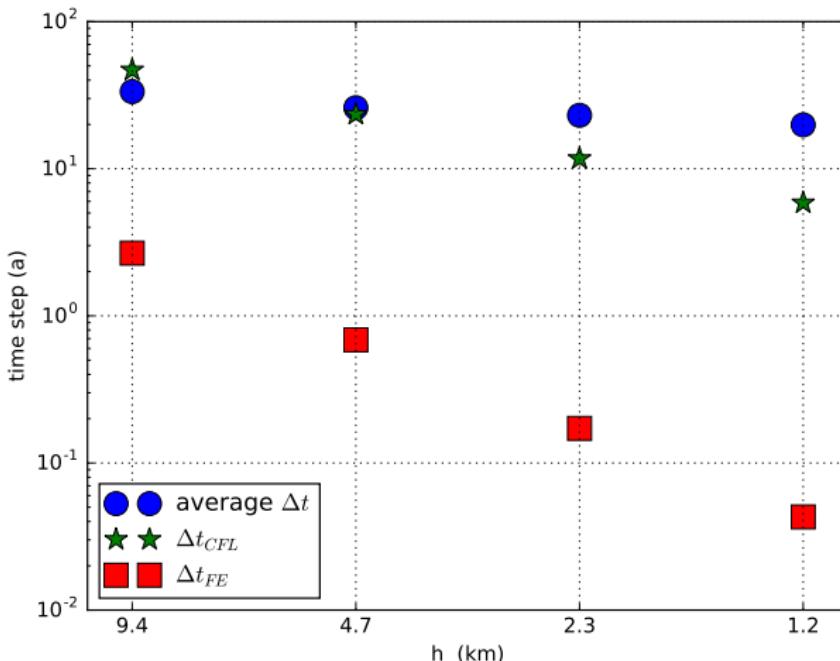
$t = 50$ ka



- solve: $H_t + \nabla \cdot \mathbf{q} = m$ where $\mathbf{q} = -D\nabla H + \mathbf{u}H$
 - imposed “sliding” $\mathbf{u}(x, y)$
 - elevation-dependent accumulation/ablation $m = m(s)$

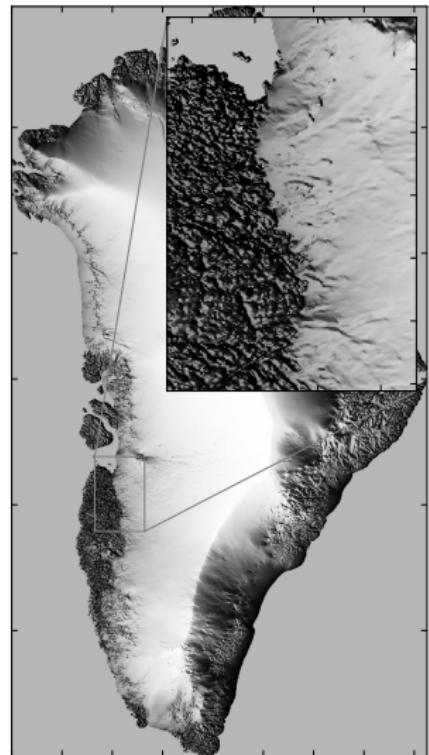
50ka run: time-stepping performance

- ARKIMEX(3): adaptive Runge-Kutta implicit/explicit 3rd-order (3 stage) time-stepping
- at least three nonlinear solves per time step



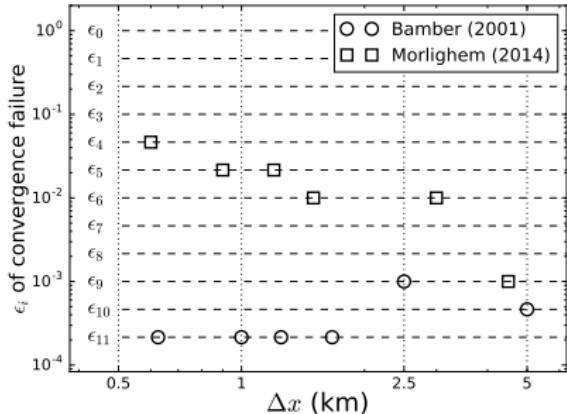
example: Greenland ice sheet $\Delta t = \infty$

- steady geometry $H(x, y)$ of the Greenland ice sheet
 - given $m(x, y)$ and $b(x, y)$
- Bueler 2016, J. Glaciol.
- one $\Delta t = \infty$ step
 - 900 m structured grid
 - 7×10^6 d.o.f.
- *but* Newton convergence suffers from bed roughness



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summary

- recommendations for implicit time-stepping of thickness-based mass conservation:
 - enforce $H \geq 0$ as NCP or VI
 - use reduced-space solver which has admissible states for stress balance solution
 - use geometric multigrid (?)
 - result: $> 10^5 \Delta t_{\text{FE}}$ achievable
- some limitations:
 - extra Newton steps needed to move margins x grid spaces
 - bed roughness eventually limits Newton solver convergence
 - calving and front-melting not addressed in this framework
 - ... yet
- wiser now? ... if I were to start over with PISM:

```
mpiexec -n N newpism -da_refine M \
-ts_type arkimex -snes_type vinewtonrsls -pc_type mg
```