

How ice sheets flow, and how to model it on a computer

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19 October 2012

Outline

how do ice sheets flow?

ice sheet models do what?

progress and challenges

questions?

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ice in glaciers is a *viscous fluid*



- ▶ mostly

ice in glaciers is a *viscous fluid*

- ▶ (ice sheets are just big glaciers)
- ▶ we describe fluids primarily by a *velocity field* $\mathbf{u}(t, x, y, z)$
- ▶ if the ice fluid were
 - faster-moving, and
 - linearly-viscous

then ice flow would be a “typical” fluid like liquid water

- ▶ we would use the Navier-Stokes equations as our flow model:

$$\nabla \cdot \mathbf{u} = 0 \qquad \textit{incompressibility}$$

$$\rho(\mathbf{u}_t + \mathbf{u} \cdot \nabla \mathbf{u}) = -\nabla p + \nu \nabla^2 \mathbf{u} + \rho \mathbf{g} \quad \textit{force balance: } m\mathbf{a} = \mathbf{F}$$

- ▶ so, to numerically model our glacier fluid, do we grab a textbook on computational fluid dynamics (CFD) and go?

is numerical ice flow modeling a part of CFD?

- ▶ yes
- ▶ large scale like atmosphere/ocean
- ▶ ... but it is a weird one
- ▶ consider what makes atmosphere/ocean modeling exciting:
 - turbulence
 - convection
 - coriolis force
 - density variation
- ▶ none of the above is relevant to ice flow
- ▶ so what could be interesting about the flow of slow, cold, stiff, laminar, old ice?
- ▶ it's "*ice dynamics!*"

ice is a slow, shear-thinning fluid

- ▶ our glacier fluid is

slow: $\rho(\mathbf{u}_t + \mathbf{u} \cdot \nabla \mathbf{u}) \approx 0$

non-Newtonian: viscosity ν is not constant

- ▶ “slow”:

$$\rho(\mathbf{u}_t + \mathbf{u} \cdot \nabla \mathbf{u}) \approx 0 \quad \iff \quad \begin{pmatrix} \text{forces of inertia} \\ \text{are negligible} \end{pmatrix}$$

- ▶ “non-Newtonian”: flow is “shear-thinning”, so larger strain rate means smaller viscosity
- ▶ thus the standard ice flow model is Glen-law ($n = 3$) Stokes:

$$\nabla \cdot \mathbf{u} = 0 \qquad \qquad \qquad \textit{incompressibility}$$

$$0 = -\nabla p + \nabla \cdot \boldsymbol{\tau}_{ij} + \rho \mathbf{g} \qquad \qquad \qquad \textit{slow force balance}$$

$$\mathbf{D} u_{ij} = A \tau^2 \boldsymbol{\tau}_{ij} \qquad \qquad \qquad \textit{Glen flow law}$$

equations above are true at every instant

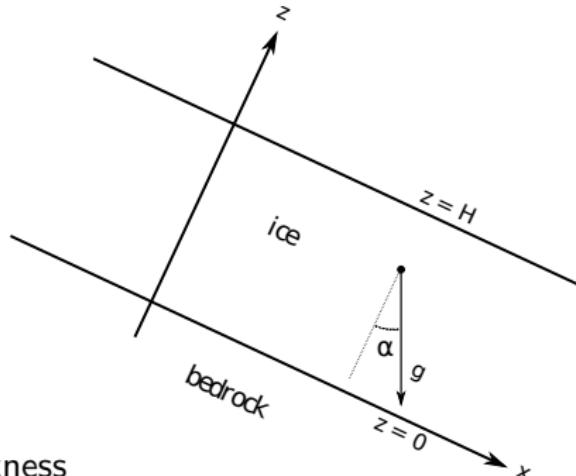
because ice is a slow fluid ...

- ▶ because ice is a slow fluid:
geometry, boundary stress, and ice viscosity determine velocity field instantaneously
- ▶ a time-stepping ice sheet code recomputes the velocity field at every time step, without requiring velocity from the previous step¹
- ▶ thus no memory of previous momentum/velocity
- ▶ velocity is a “diagnostic” output of an ice flow model

¹to be a weatherman you've got to know which way the wind blows ... but don't expect that much from a glaciologist

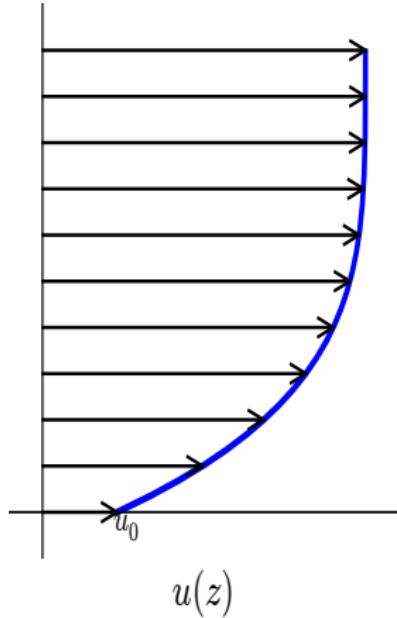
slab-on-a-slope

- ▶ an easiest case!
- ▶ solve the “standard ice flow model” in a tilted slab, below

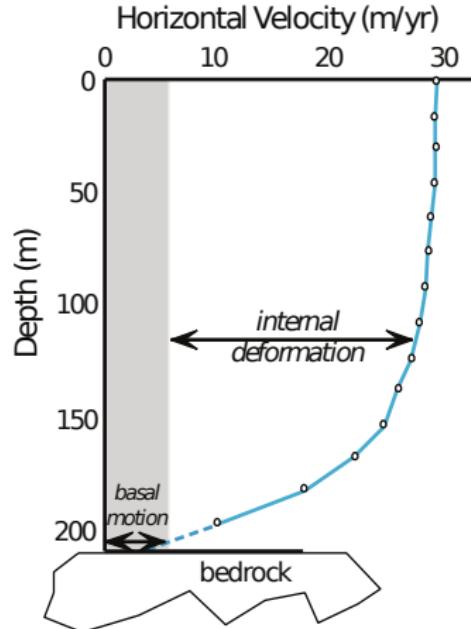


- ▶ assume
 - constant thickness
 - no variation in flow with x
- ▶ compute velocity $\mathbf{u}(z)$... formulas suppressed

slab-on-a-slope



velocity from slab-on-a-slope formula



velocity profile of the Athabasca Glacier
from inclinometry
(Savage and Paterson, 1963)

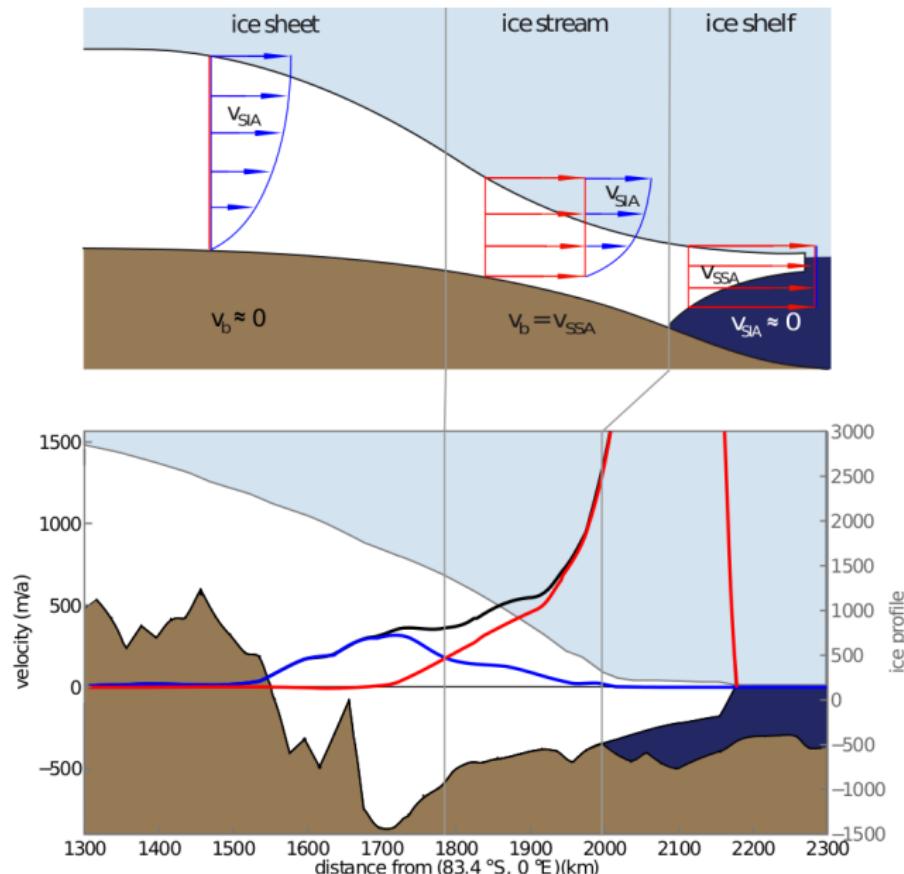
deformation versus basal motion

- ▶ top:

cartoon of
non-sliding (SIA)
and sliding/floating
(SSA) modes

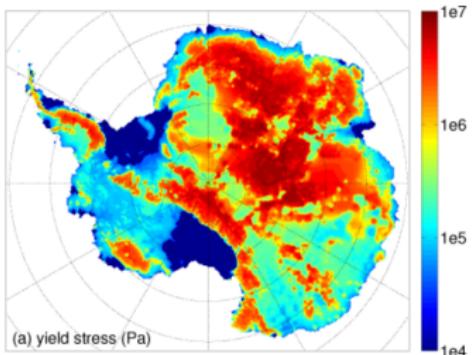
- ▶ bottom:

sheet-stream-shelf
transition,
Lambert Glacier &
Amery Ice Shelf,
Antarctica

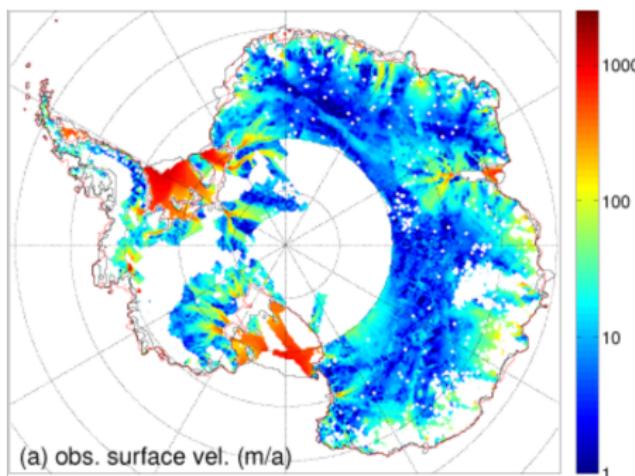


Antarctica is a *marine ice sheet*

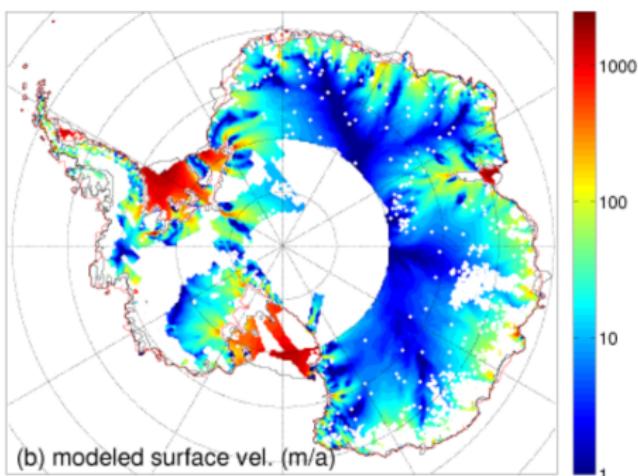
- ▶ in fact we should not forgetting floating parts of ice sheets
- ▶ i.e. *ice shelves*
- ▶ and they often have fast upstream grounded ice: *ice streams*



(a) yield stress (Pa)



(a) obs. surface vel. (m/a)



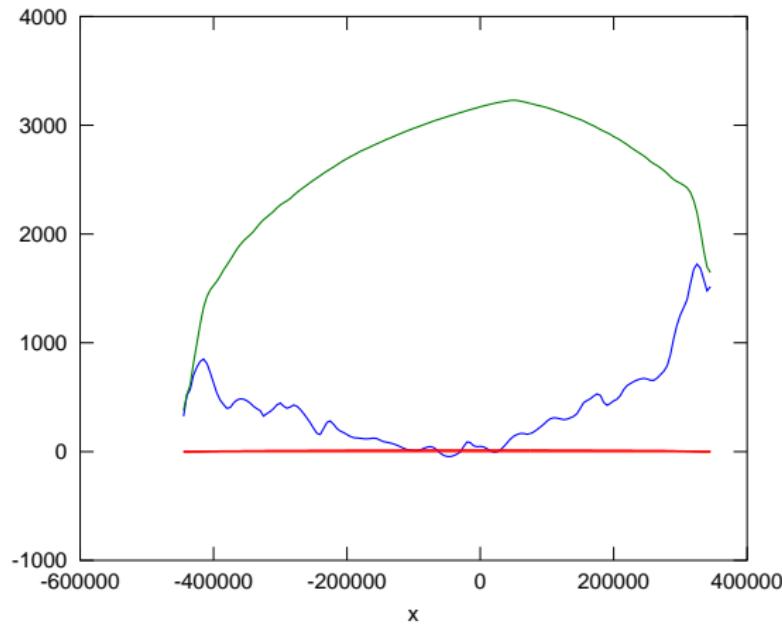
(b) modeled surface vel. (m/a)

slow, non-Newtonian, some basal slip, and shallow

- ▶ ice sheets have four outstanding properties *as fluids*:
 1. slow
 2. non-Newtonian
 3. shallow
 4. contact slip (sometimes)

regarding “shallow”

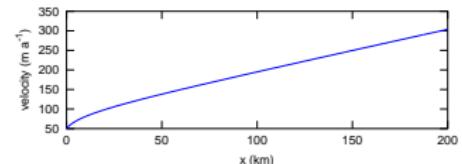
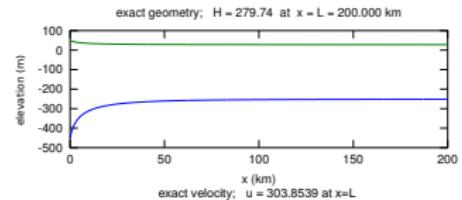
- ▶ consider cross section of Greenland ice sheet at 71° N
- ▶ below in red is a no-vertical-exaggeration view
 - green and blue: standard vertically-exaggerated cross section



shallow models of ice sheets and shelves

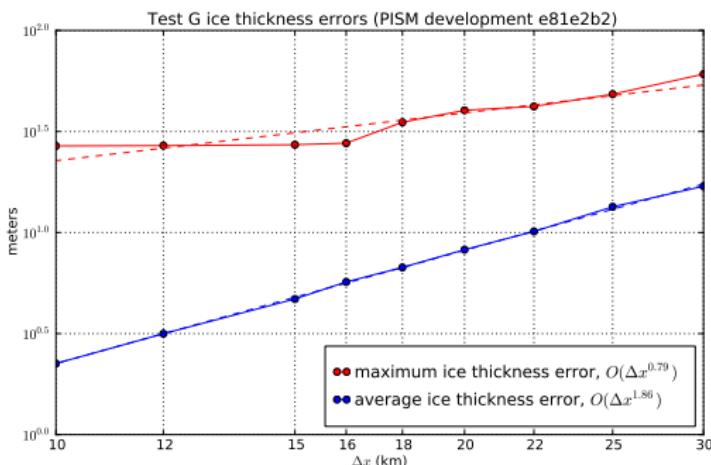
- ▶ we don't actually use the "standard ice flow model" (i.e. the Stokes equations) very often
- ▶ shown are two most-common shallow approximations
 - **top**: time-dependent exact solution to the "SIA" = shallow ice approximation
 - **bottom**: steady exact solution to the "SSA" = shallow shelf approximation
- ▶ ... but I'll suppress the partial differential equations for the SIA and SSA models in this talk

frames from $t = 4$ months to $t = 10^6$ years,
equal spaced in *exponential* time



importance of verification

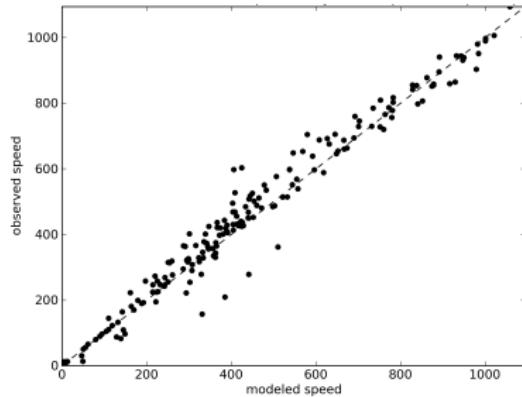
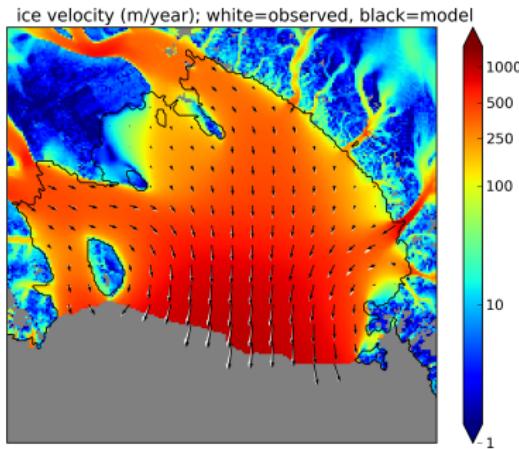
- ▶ suppose we are now **ice sheet modellers**, the chosen few ...
- ▶ we take the SIA, SSA, etc. equations and turn them into computer programs
- ▶ ... and get pretty pictures
- ▶ but last slide showed **exact** solutions
- ▶ instead of “eyeballing” we can **measure** errors from the numerical code, as at right



from now on in this talk, I'll assume we have a verified ice sheet model in hand

next step: validation?

- ▶ sometimes observational data is
 - of high quality
 - measures exactly what the model is simulating
- ▶ for example, below:
 - observed surface velocities versus
 - velocity computed by SSA model in PISM



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ice sheet “weather” forecasting 101

Because ice sheets change more slowly than the atmosphere, predicting their behavior over the coming century has more in common with short-term weather prediction: small errors in the initial state could systematically affect a forecast throughout the 21st century.

(Arthern & Gudmundsson, 2010, *J. Glaciol*)

ice sheet “weather” forecasting 101

- ▶ *weather model testing*: Enter measured forcing variables into a weather forecast model. If the model accurately shows weather events that are known to have occurred then it can be considered successful.

From wikipedia

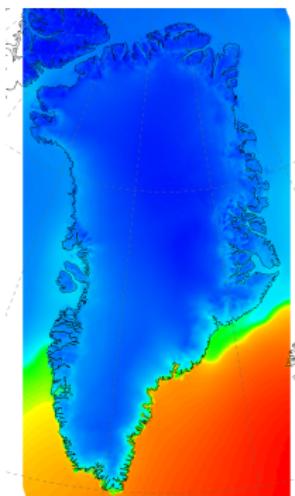
A [hindcast](#) is a way of testing a mathematical [prediction] model. Known or closely estimated inputs for past events are entered into the model to see how well the output matches the known results.

- ▶ hindcast *before* forecast
- ▶ verification *before* (hindcast + validation) *before* forecast

climate “forcings” for a model of an ice sheet

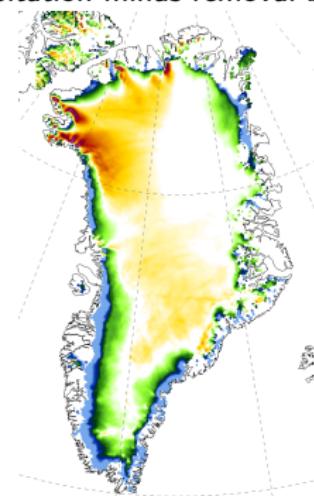
- ▶ reanalysis from a regional climate model (HIRHAM5) as climate forcing
- ▶ timeseries from 1989–2011 with monthly values of:

2m air temperature



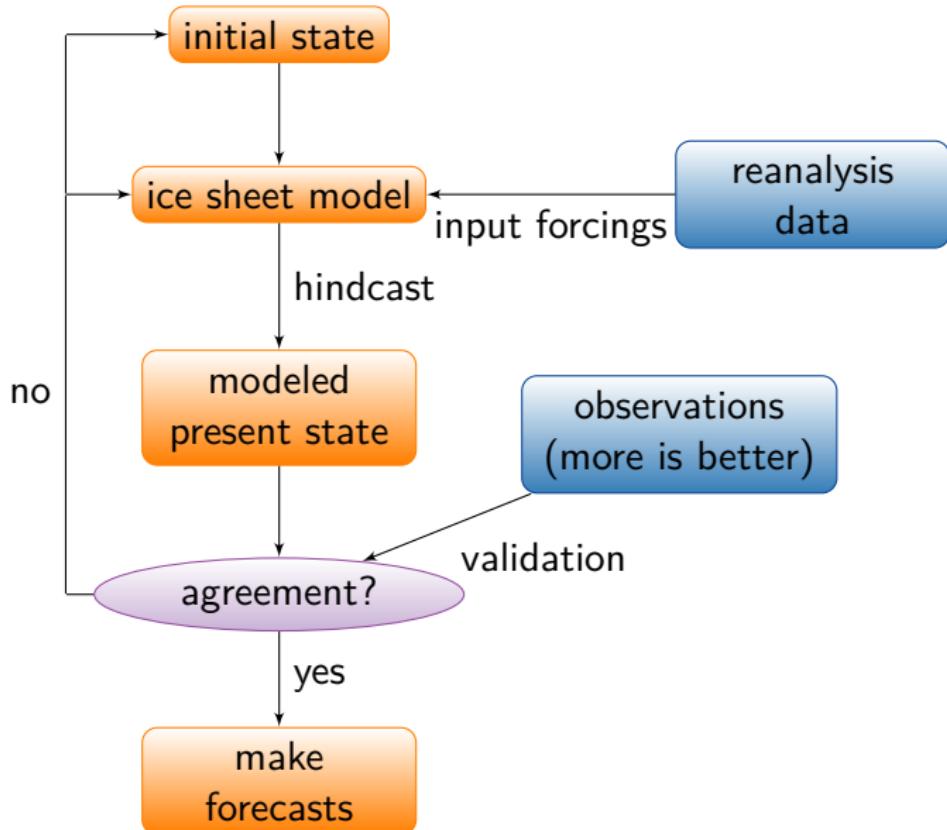
climatic mass balance

(= precipitation minus removal by melting)



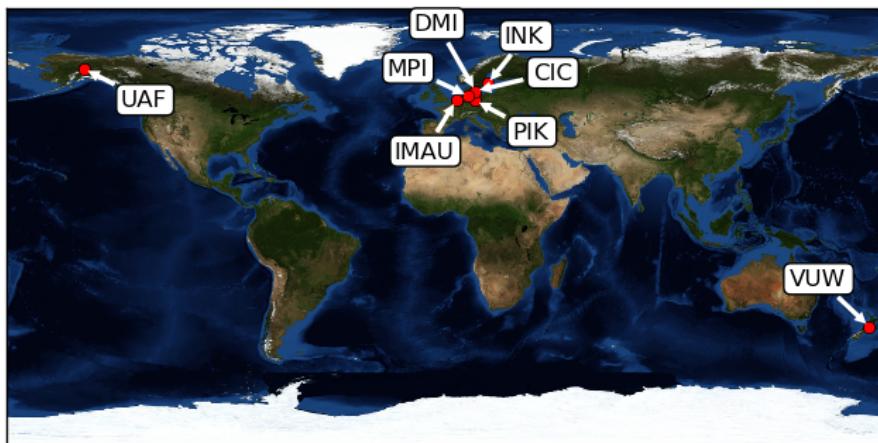
- ▶ also: ocean temperatures, geothermal heat, bedrock topography, ...

testing ice sheet initial states



PISM = Parallel Ice Sheet Model

- ▶ arguably the most widely-used ice sheet model in the world:



- ▶ developed here at UAF
- ▶ supported by NASA MAP and ARSC
- ▶ see www.pism-docs.org
- ▶ ... but just an example for this talk

generating initial states using PISM

some initialization schemes:

- ▶ constant-climate steady-state using present-day climate
 - ▶ paleo-climate uses (imperfect) data from a full Ice Age cycle
 - ▶ flux-corrected paleo-climate combines paleo-climate with information about present-day ice thickness
-
- ▶ next four slides: Andy's Greenland runs using PISM on 2 km grid

validation metric: ice volume and ice thickness

- ▶ the most common validation metric is ice volume
- ▶ ice volume measurement based on ice thickness observation
- ▶ PISM Greenland runs comparison:

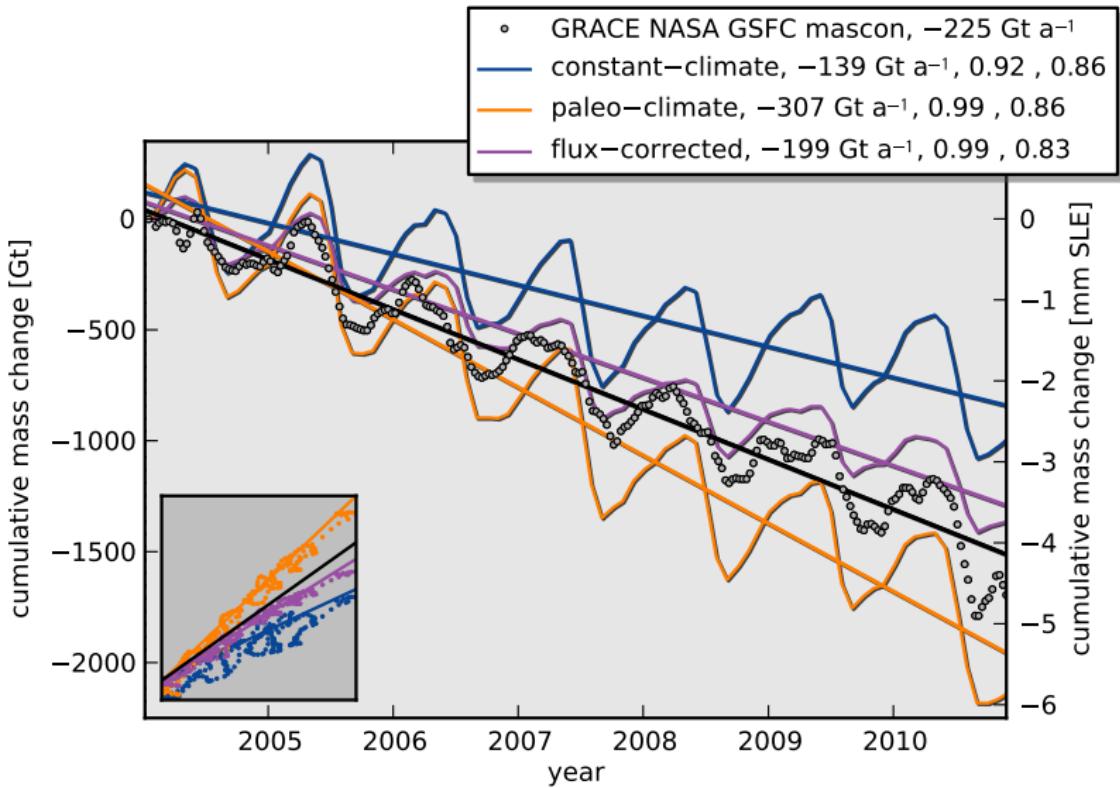
	observed	constant-climate	paleo-climate	flux-corrected
<i>ice volume</i>				
initial volume [10^6 km^3]	2.93	3.18	3.37	X
<i>ice thickness</i>				
avg abs. difference [m]		99	121	X
rms difference [m]		199	244	X

observed ice thickness is from Griggs & Bamber (unpublished)

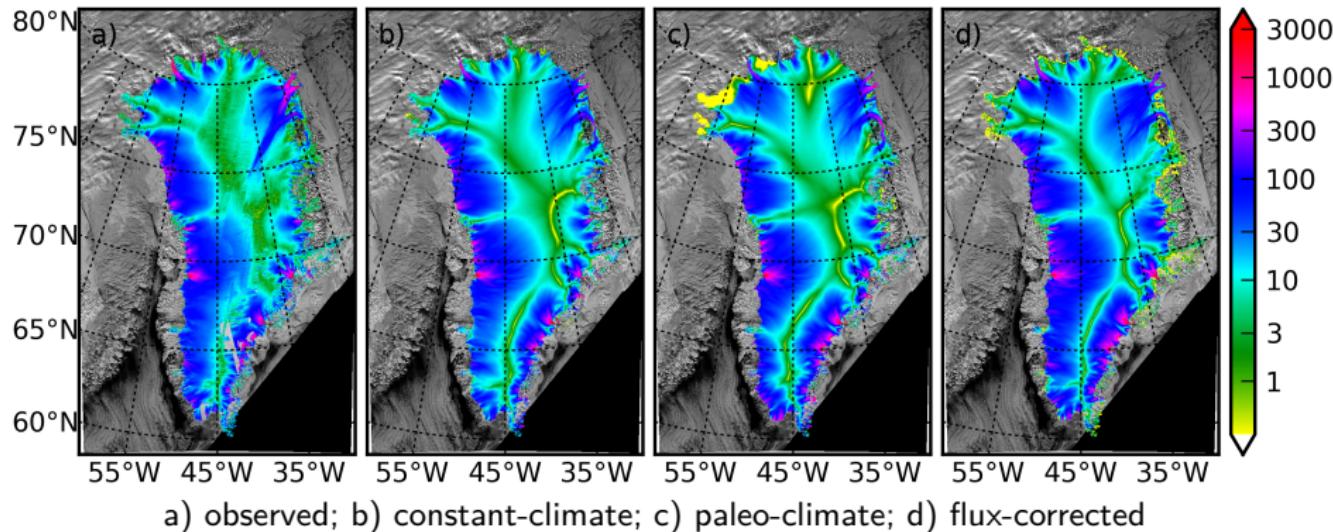
X = ice thickness used in "flux-correcting" is not available for validation

- ▶ thus: volume is a weak metric because it averages out positive and negative thickness errors
- ▶ how well do we know ice thickness?

validation metric: gravimetric total mass changes

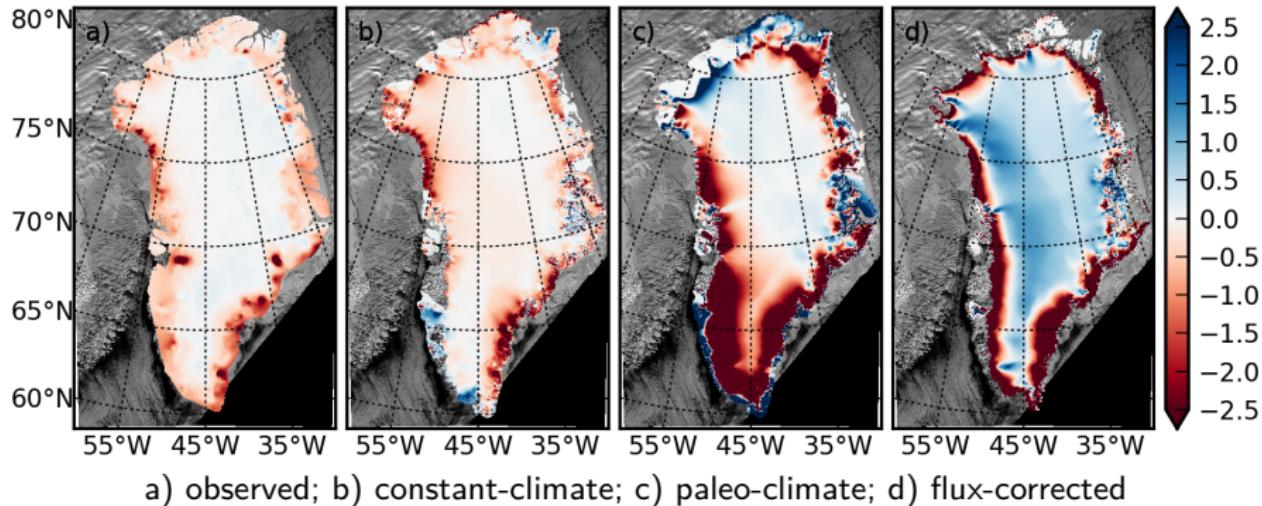


validation metric: surface speeds



- ▶ values in m/a
- ▶ observed = interferometric SAR + feature-tracking (Joughin et al., 2010)
- ▶ some “data assimilation techniques” (= inverse modelling of the observed velocities) give much better match to observed velocities
... but it’s not clear if time-evolution is better

validation metric: surface elevation change



- ▶ values in m
- ▶ change over period 2003–2009
- ▶ observed = ICESat laser altimetry (Sørensen, 2011)

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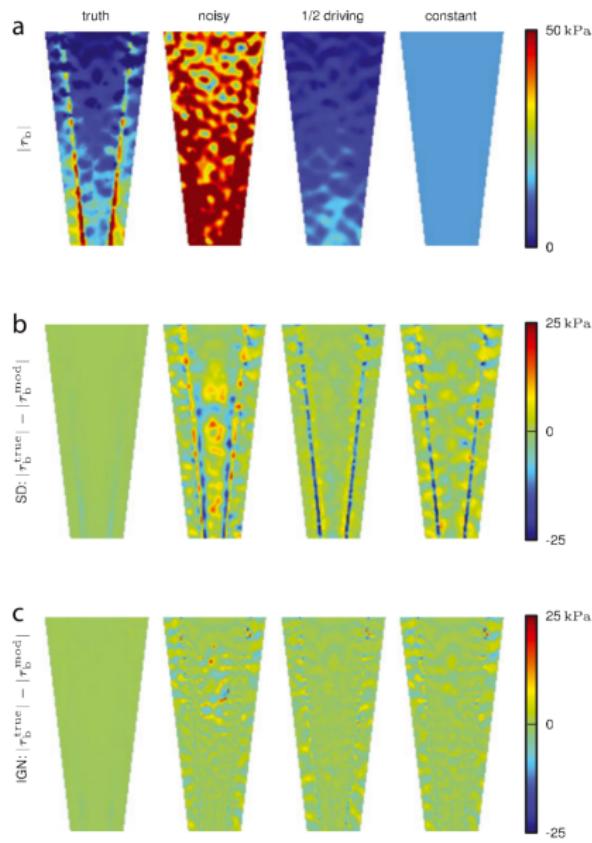
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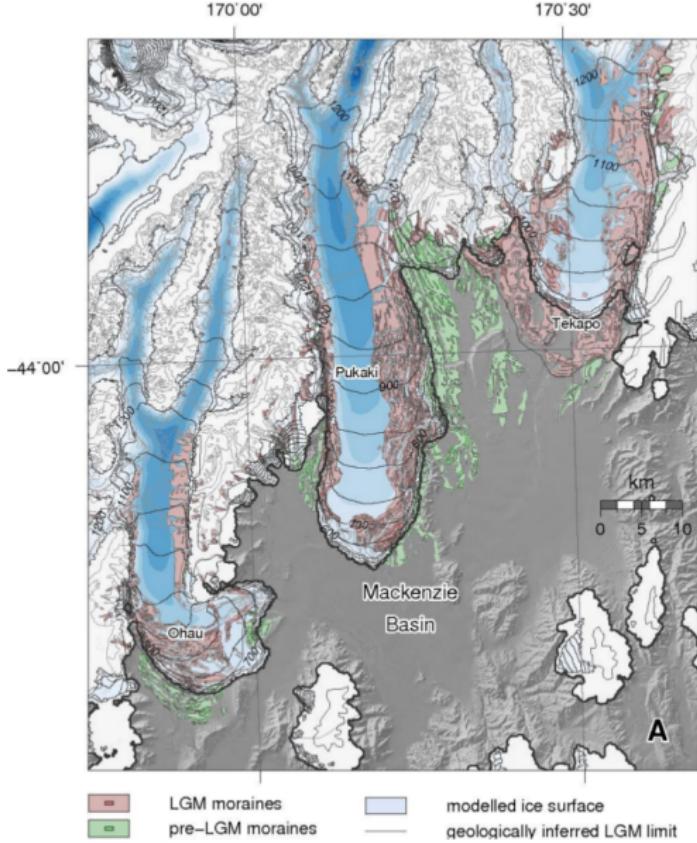
do we know the basal resistance under an ice sheet?

- ▶ no
- ▶ to slightly better approximation, at times like the present where we know surface velocities, we can invert the ice flow model for basal shear stress
- ▶ (in forward mode, the ice flow model turns basal resistance into surface velocity)
- ▶ at right: figure from Habermann et al (2012)



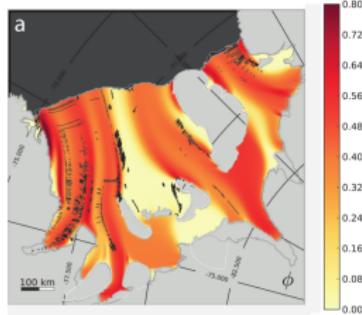
can we effectively use paleo- constraints?

- ▶ some of the best information about underneath ice sheets is from geomorphology
- ▶ for example, at right is comparison of the LGM moraines of the New Zealand (South Island) ice cap versus a 500 m resolution PISM simulation (Golledge et al., 2012)
- ▶ major goal here: recover the climate at the LGM

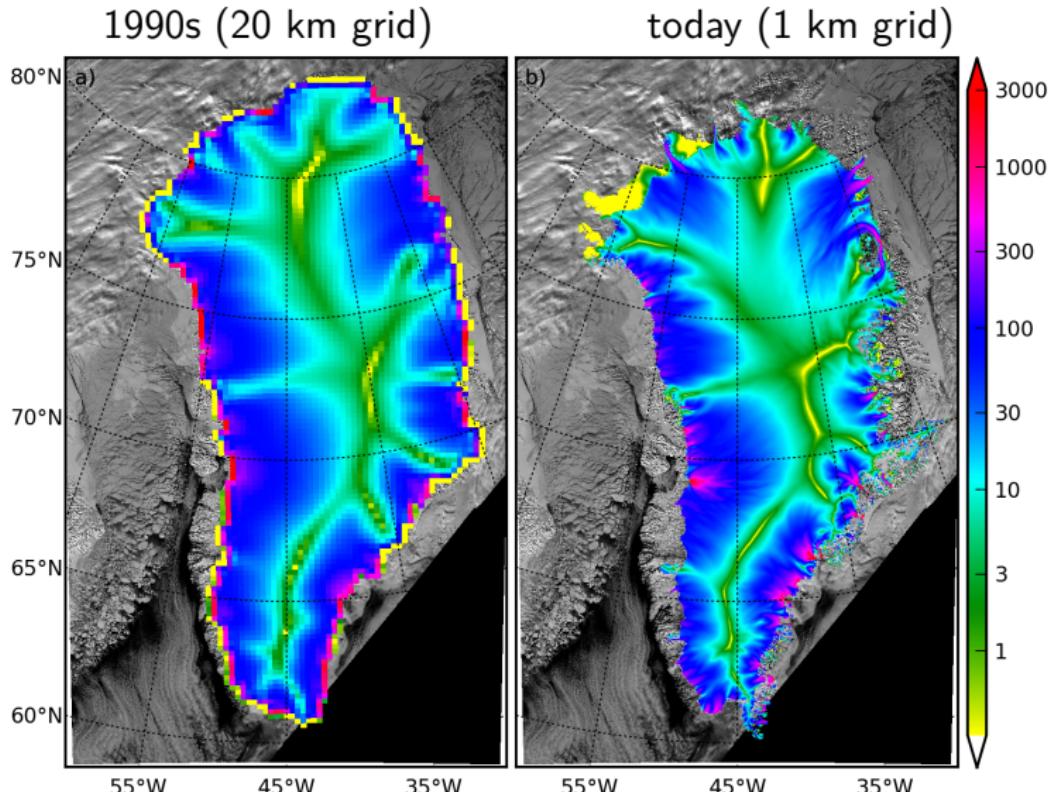


a decent calving law for ice shelves?

- ▶ two issues:
 - physical fracture process which causes weakening
 - stress condition at front which causes calving
- ▶ top: PISM fracture-density model of the Filchner-Ronne ice shelf showing observed surface crevasse fields (black) and modelled density (color)
Albrecht and Levermann (2012)
- ▶ top: PISM “eigen-calving” model; modeled steady states of Larsen A & B ice shelves closely-approximate observed
Levermann et al. (2012)



we've come a long way, baby?



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