<<requir
Autonom

text="The autonom
able to navigate in i
it's starting point."
id="01"

<<requirement>>
Line Detection

text="The vehicle should be able to
detect and follow the drawn path without
moving out of the desired track."
id="02"

<<requir
Obstacle/Colo

text="The vehicle s
detect obstacles ba
on the track and eit
around them."
id="03"

<<requirement>>
nous Car

ous car should be
it's enviroment from

<<requirement>>
our Detection

hould be able to
sed on their colour
her remove or drive

<<requirement>>
Speed Optimization

text="The autonomous car should be
able to drive at a designated speed"

id="04"