NC STATE UNIVERSITY

Complex Networked Control Systems



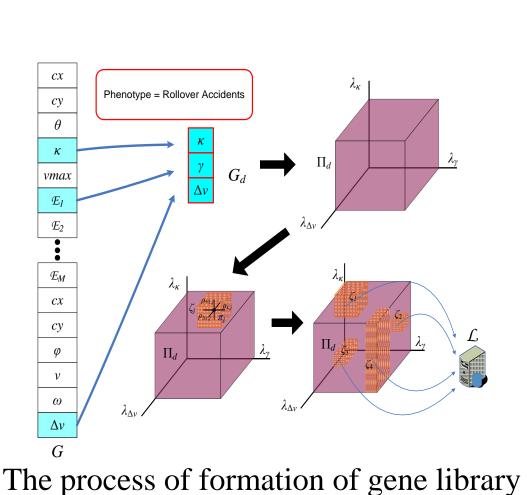
Real-time Optimal Bandwidth Allocation

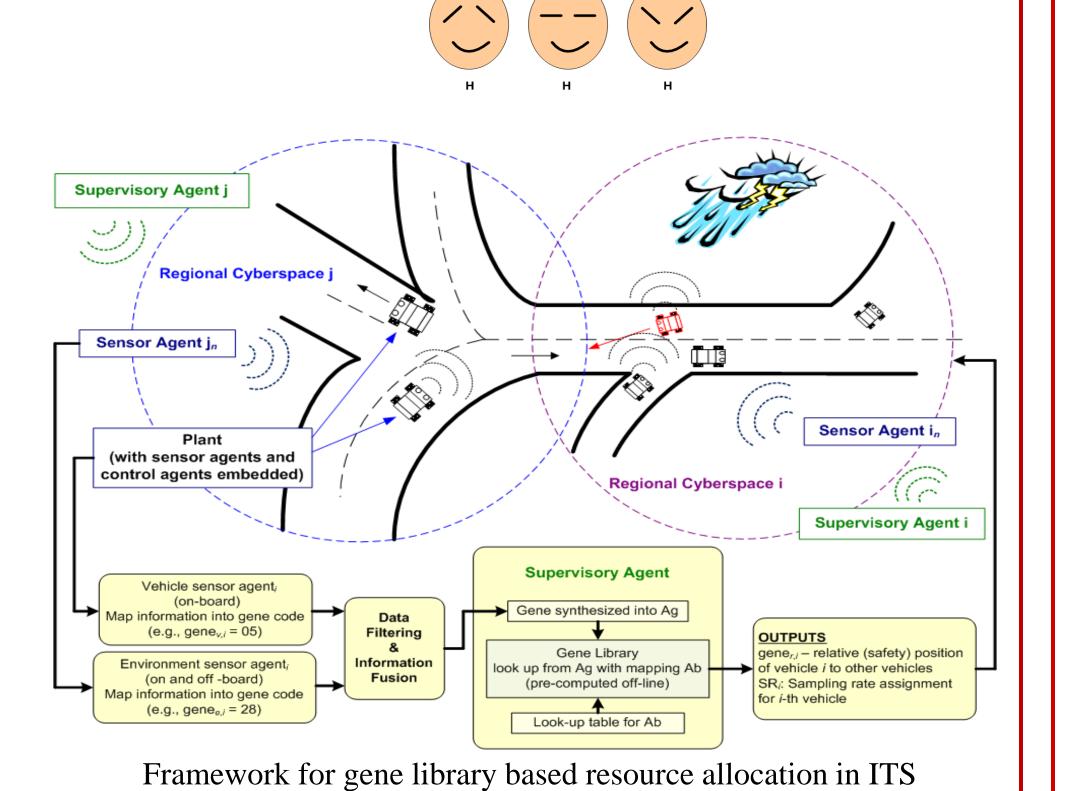
Gene Library based Approach

Gene libraries are biologically inspired database that contain DNA-type building blocks for complex feature expressions

- Features
- Adaptive
- Scales linearly with the size of the problem
- Resources can be dynamically allocated based on the gene library (Translation)
- Application in large-scale time-sensitive systems integrated over communication $\begin{bmatrix} cx \\ cy \\ \theta \end{bmatrix}$ Phenotype = Rollover Accidents

network
e.g. Intelligent
Transportation
System (ITS)





Performance-Security Optimization

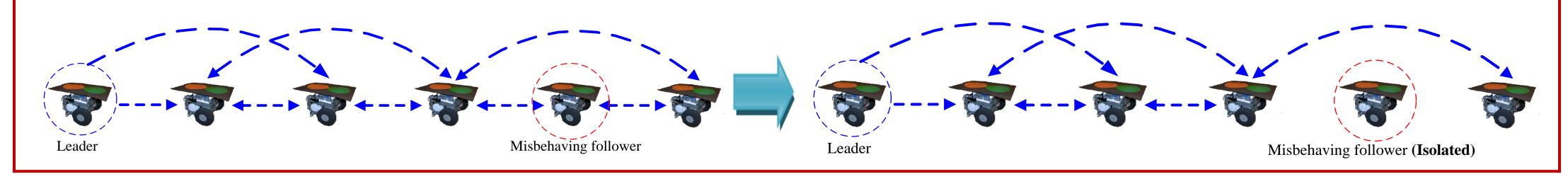
Coevolutionary Paradigm

- Cooperative and competitive Coevolutionary Genetic Algorithms (CGA)
- Fast convergence & good diversity
- Robust to the local minima and non-linearity
- Multi-objective optimization and machine learning
- Application in performance-security trade-off optimization on NCS

Networked Controller Security Mechanism Networked Control System Model System Model Species 1: Performance Level Encryption Algorithms Security Level Encryption Algorithms AES Performance - Security Trade-off CGA Optimization Framework

Secured Distributed Control Algorithms

- Distributed control algorithms (consensus, gossip etc) are vulnerable to malicious cyber attacks
- Analyze the vulnerabilities of distributed algorithms and their impacts
- Design novel secured distributed control algorithms that can detect the misbehaving nodes and recover from the malicious attacks



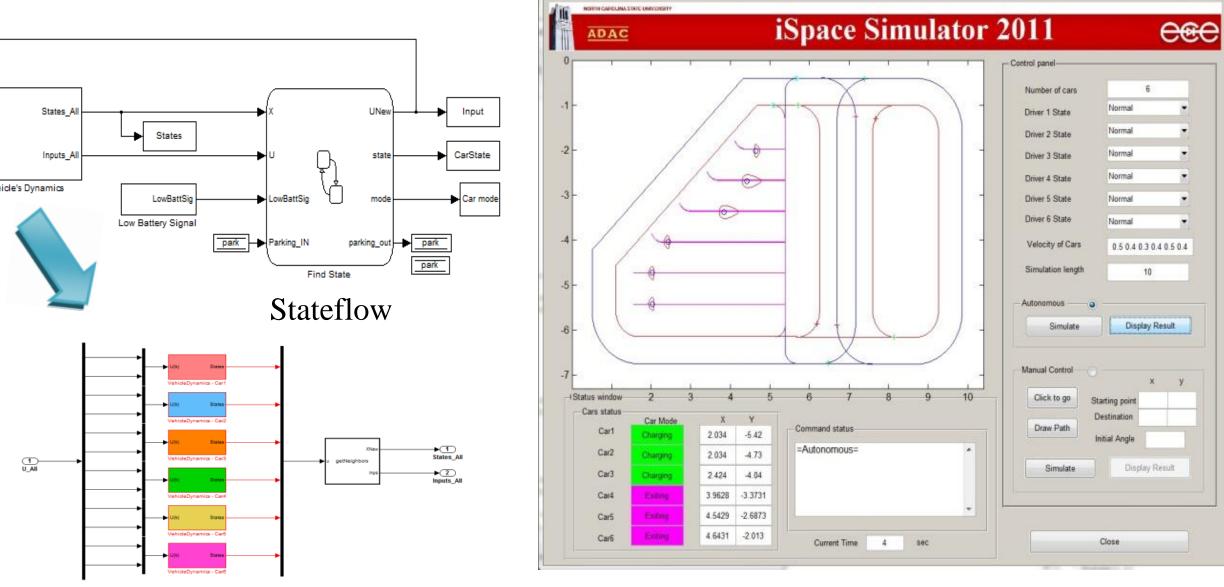
Test Platform: iSpace

iSpace Simulator

- Matlab/Simulink-based software
- Simulates behavior of unmanned ground vehicles in various traffic scenarios

UGV dynamics

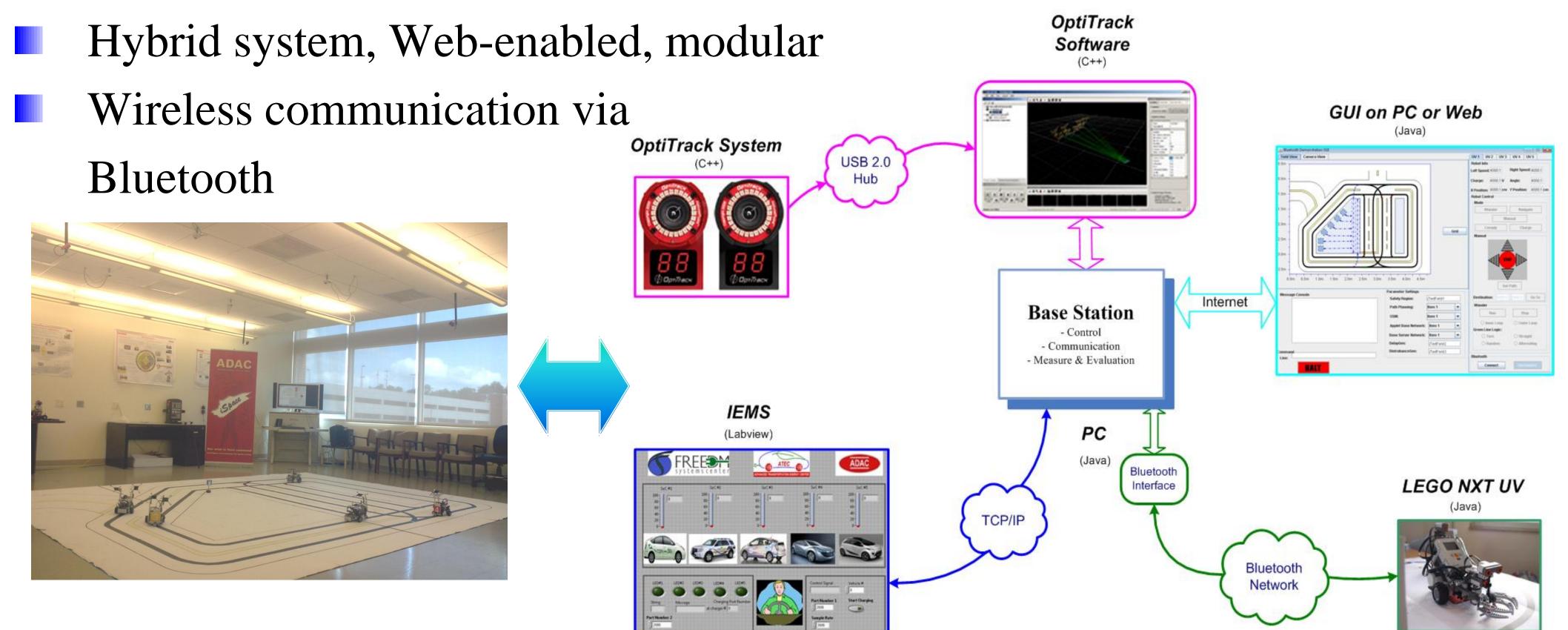
- Implements quadratic curve path tracking algorithm, fast marching based path generation, feedback
 - path generation, feedbace preprocessor, predictive control gain scheduler, dynamic bandwidth allocation etc
- Simulates different kinds of driving behavior (normal, conservative, impaired etc).



Graphical User Interface

iSpace at ADAC

- Physical realization of iSpace simulator using JAVA and LeJOS
- Lego-mindstorms based unmanned ground vehicles (UGVs)
- Indoor GPS system using the OptiTrack for localization of UGVs







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