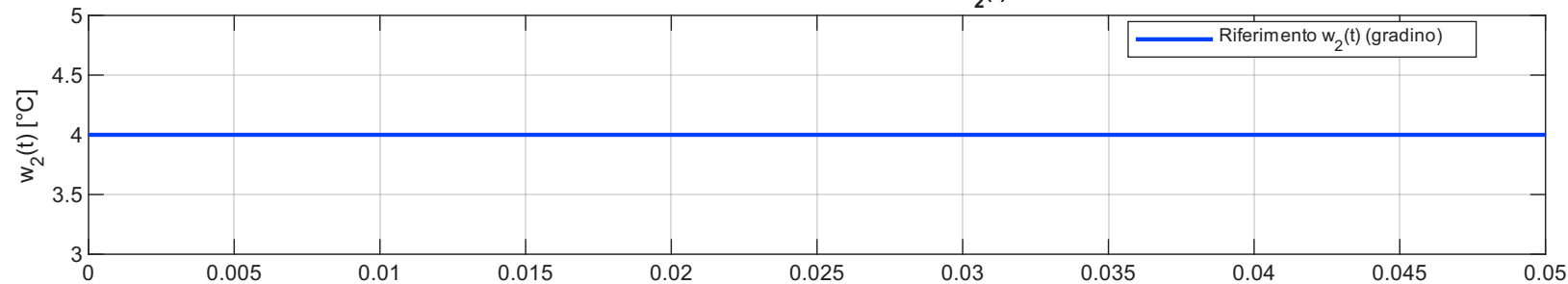
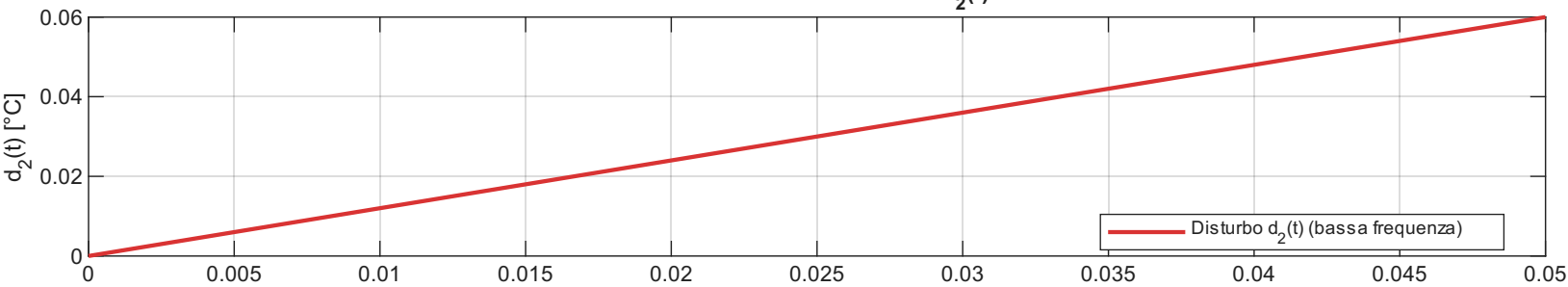


Scenario breve — Riferimento $w_2(t)$



Scenario breve — Disturbo $d_2(t)$



Scenario breve — Rumore $n_2(t)$ (zoom 2 ms)

