

Scribe: Cryptography and Network Security

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1 Introduction

Second preimage resistance is the property of a hash function that it is computationally infeasible to find any second distinct input that has the same output as a given input.

in other words, second-preimage resistance is computationally infeasible to find any second input which has the same output as that of a specified input; i.e., given x , it is difficult to find a second preimage $x' \neq x$ such that $h(x) = h(x')$

2 Algorithm to Find Second Preimage

Algorithm

FIND-SECOND-PREIMAGE(h, x, Q)

- $y \leftarrow h(x)$
- Choose $X_o \subseteq X \setminus \{x\}$, $|X_o| = Q - 1$
- for each $x_o \in X_o$, do
 - if $h(x_o) = y$, then return (x_o)
- return (failure)

The analysis of FIND-SECOND-PREIMAGE algorithm is similar to the FIND-PREIMAGE algorithm. The only difference is that we require an *extra* application of h to compute $y = h(x)$ for the input value x .

Theorem : For any $X_o \subseteq X \setminus \{x\}$ with $|X_o| = Q - 1$, the success probability of FIND-SECOND-PREIMAGE algorithm is $\epsilon = 1 - (1 - \frac{1}{M})^{Q-1}$

3 Algorithm FindCollision

Algorithm

FIND-Collision(h,Q)

- Choose $X_o \subseteq X$, $|X_o| = Q$
- **for each** $x \in X_o$
 - **do** $y_x < -h(x)$
- **if** $y_x = y_{x'}$ for some $x' \neq x$
 - **then return** (x, x')
- **else return** (failure)

Theorem : For any $X_o \subseteq X$ with $|X_o| = Q$, the success probability of FIND-COLLISION algorithm is :

$$\epsilon = 1 - \left(\frac{M-1}{M}\right)\left(\frac{M-2}{M}\right)\left(\frac{M-3}{M}\right)\dots\dots\dots\left(\frac{M-Q+1}{M}\right)$$

Relating Q and ϵ

$$Q \approx \sqrt{2 * M * \ln \frac{1}{1-\epsilon}}$$

If we take $\epsilon=0.5$ then $Q \approx 1.17 \sqrt{M}$

- So, if we hash around \sqrt{M} values, we have a 50% chance of collision.
- Thus, algorithm is $(\frac{1}{2}, O(\sqrt{M}))$ algo.
- Collision solving is better than solving preimage or second preimage, as it is easier than this.
- $Collision_{Hardness} \ll Preimage_{Hardness}$
- Resistance against Collision \Rightarrow Preimage Resistance

4 First Reduction

Algorithm

COLLISION-TO-SECOND-PREIMAGE(h)

- **external** ORACLE-2ND-PREIMAGE
- choose $x \in X$ uniformly at random

- **if** ORACLE-2ND-PREIMAGE(h, x)= x'
 - **then return** (x, x')
- **else return**(failure)

ORACLE-2ND-PREIMAGE is an (ϵ, q) algorithm. If it gives answer then it will be correct as it is a Las-Vegas algorithm. So, $x \neq x'$ and $h(x) = h(x')$.

Thus, the collision is also found.

COLLISION-TO-SECOND-PREIMAGE is also an (ϵ, q) Las-Vegas algo.

5 Second Reduction

Algorithm

COLLISION-TO-PREIMAGE(h)

- **external** ORACLE-PREIMAGE
- choose $x \in X$ uniformly at random
- $y < -h(x)$
- **if** (ORACLE-PREIMAGE(h, x)= x') and ($x' \neq x$)
 - **then return** (x, x')
- **else return**(failure)

ORACLE-PREIMAGE is a $(1, Q)$ las Vegas Algo.

Theorem: Suppose $h: X \rightarrow Y$ is a hash function where $|X|$ and $|Y|$ are finite and $|X| \geq 2|Y|$. Suppose ORACLE-PREIMAGE is $(1, Q)$ -algo for Preimage, for the fixed hash function h . Then COLLISION-TO-PREIMAGE is a $(\frac{1}{2}, Q+1)$ -algo for collision, for the fixed hash function.

Proof: The Probability of success of the algorithm COLLISION-TO-PREIMAGE is computed by averaging over all possible choice for x :

$$\begin{aligned}
 \Pr[\text{success}] &= \Pr[x \neq x'] = \frac{1}{|X|} \sum_{x \in X} \frac{|x|-1}{|x|} \\
 &= \frac{1}{|X|} \sum_{C \in Y} \sum_{x \in C} \frac{|C|-1}{|C|} \\
 &= \frac{1}{|X|} \sum_{C \in Y} (|C| - 1) \\
 &= \frac{1}{|X|} (\sum_{C \in Y} |C| - \sum_{C \in Y} 1) \\
 &= \frac{|X| - |Y|}{|X|} \\
 &\geq \frac{|X| - \frac{|X|}{2}}{|X|} \\
 &\geq \frac{1}{2}
 \end{aligned}$$

6 Conclusion

We have a COLLISION-TO-PREIMAGE algo of Las-Vegas type , which has a average case success probability of atleast $\frac{1}{2}$