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## MATRICES

Transpose  $\rightarrow [1 \ 2]^T = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$  row  $\rightarrow$  col  
col  $\rightarrow$  row

$$(AB)^T = B^T A^T$$

Symmetric if  $A^T = A$ ,  $A + A^T$  is also symm.

Anti-symmetric if  $A^T = -A$ , Any mat  $B = B^T$  is AS,  $A - A^T$  is AS

if  $A$  is AS,  $BA B^T$  is also AS

Length of vector  $|\vec{u}| = \sqrt{\vec{u} \cdot \vec{u}} = \sqrt{\vec{u}^T \vec{u}}$

Orthogonal matrix: if it satisfies  $B^T B = I \rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$  Note:  $IA = A = AI$

Rotational matrix:  $\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$ , AC through  $\theta$

\*  $R(\theta)$  is  $\begin{bmatrix} \cos(150^\circ) & -\sin(150^\circ) \\ \sin(150^\circ) & \cos(150^\circ) \end{bmatrix} = \begin{bmatrix} -\frac{\sqrt{3}}{2} & -\frac{1}{2} \\ \frac{1}{2} & -\frac{\sqrt{3}}{2} \end{bmatrix}$  convert to rotational 45° & compute

Involuntary matrix:  $AA = I$ ,  $A^9 = A^8 A = IA = A$ ,  $A^{100} = I$

Shear matrix:  $\begin{bmatrix} 1 & \tan \theta \\ 0 & 1 \end{bmatrix}$ , maps  $\hat{i} + \hat{j}$  to  $(\tan \theta + \hat{j})$

Rotate, shear, rotate  
3rd 2nd 1st

$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$   $\begin{vmatrix} + & - & + \\ - & + & - \\ + & - & + \end{vmatrix}$   
 $\det A = a_{11} \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} - a_{12} \begin{vmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{vmatrix} + a_{13} \begin{vmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{vmatrix}$

Steps for inverse: ① work out cofactor for each slot with correct sign.

② Take det & slot back

③ Transpose

④ Divide by determinant of  $A$  (initial mat.)

\* if  $\det = 0$ , no inv.  
\* if  $A =$  upper/lower  $\Delta$ ,  
 $\det A =$  prod of diagonal entries

Inverse of  $2 \times 2$  mat:  $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ ,  $A^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$

$\det(ST) = \det(S) \det(T)$ ,  $\det(M^T) = \det(M)$ ,  $\det(cM) = c^n \det M$   
 $n = \text{size of } M$

Leontief model: form any matrices.

E-val:  $\det(T - \lambda I) = 0$ , E.vec:  $(T - \lambda I)u = 0$

Diagonalisation:  $A = PDP^{-1}$  ( $A$  must be  $n \times n$  with non-0 vec.)

Eg:  $P_1 = \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}$ ,  $P_2 = \begin{bmatrix} 1 & -1 \\ 1 & -2 \end{bmatrix}$ ,  $\Rightarrow D = \begin{bmatrix} 2 & 0 \\ 0 & -3 \end{bmatrix}$ ,  $P = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$ ,  $P^{-1} = \text{inv.}$   
 $\lambda = 2$   $\lambda = -3$

$M^n = P D^n P^{-1} = P \begin{bmatrix} \lambda_1^n & 0 \\ 0 & \lambda_2^n \end{bmatrix} P^{-1}$   $\text{Tr}(A) = \sum \text{e-val}$

Trace: sum of diagonal values,  $\text{Tr}(NM) = \text{Tr}(MN) = \text{Tr}(PDP^{-1}) = \text{Tr}(D)$

\* Note:  $\det(PDP^{-1}) = \det(P) \det(D) \det(P^{-1}) = \det(D)$  for  $\text{Tr}(M) = \text{Tr}(D) = \sum \text{e-val}$

Linear T: eg:  $T = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$   
Area of parallelogram  $= |\vec{u}| |\vec{v}| \sin \theta = |\vec{u} \times \vec{v}| = \det A = |\det A|$

$T = n \times n$  mat  $A$ , if  $\det A = 0$ ,  $T$  is not 1-1 (singular)

Vol of parallelepiped = base  $A \times h$  =  $|\vec{u} \times \vec{v}| |\vec{w}| \cos \theta = |\vec{u} \cdot \vec{v} \times \vec{w}| = |\det A|$

Rank: ①  $\det T \neq 0$  ②  $\det T = 0$   
3d onto 3d  $\Rightarrow$  3d onto plane  $\Rightarrow$  2d onto line  $\Rightarrow$  1d onto point  $\Rightarrow$  0d

FIRST/SECOND ORDER ODE:

Methods: sep. var., sub., Bernoulli ( $z = y^{1-n}$ ), I.R.  $f(x) = e^{\int p(x) dx}$ ,  $xy = \frac{1}{2} r^2 f(x)$

2nd order: Homog  $\rightarrow y'' + p_1 y' + p_2 y = 0 \Rightarrow \lambda^2 + p_1 \lambda + p_2 = 0$

③ Non-homog: ① char. eqn. solve  $f(x)$ ,  $y_1, y_2 \Rightarrow \det y_1, y_2$

②  $\lambda_1 = \lambda_2 \Rightarrow \det y_1, y_2 = 0$

③  $\lambda_1 \neq \lambda_2 \Rightarrow \det y_1, y_2 \neq 0$

④ Variation of Parameters: ① find homog soln ②  $y_p = u_1 y_1 + u_2 y_2$  ③ find  $u_1, u_2$  ④  $u = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} \Rightarrow y_1 y_2' - y_1' y_2$

⑤  $u = \int \frac{y_2 f(x)}{W} dx$ ,  $v = \int \frac{y_1 f(x)}{W} dx$ , solve with IVP, Note:  $e^{i\theta} = \cos \theta + i \sin \theta$

Newton's cooling:  $\frac{dT}{dt} = -k(T - T_{\infty})$ , Heating:  $\frac{dT}{dt} = k(T_{\infty} - T)$

Extra: Taylor series:  $f(x) = f(a) + f'(a)(x-a) + \frac{f''(a)}{2!} (x-a)^2 + \dots + \frac{f^{(n)}(a)}{n!} (x-a)^n + \dots$

Partial fraction:  $\frac{1}{(x-1)^2} = \frac{A}{x-1} + \frac{B}{(x-1)^2}$ ,  $\frac{1}{x^2+3} = \frac{A}{x+i\sqrt{3}} + \frac{B}{x-i\sqrt{3}}$ ,  $\frac{1}{x(x+1)} = \frac{A}{x} + \frac{B}{x+1}$

## Systems of First Order ODE.

$\frac{dx}{dt} = -2x + y$ ,  $\frac{dy}{dt} = 2x - 3y \Rightarrow B = \begin{bmatrix} -2 & 1 \\ 2 & -3 \end{bmatrix}$

① E-val:  $\lambda = \frac{1}{2} (\text{Tr } B \pm \sqrt{\text{Tr } B^2 - 4 \det B})$

② distinct:  $c_1 u_1 e^{\lambda_1 t} + c_2 u_2 e^{\lambda_2 t}$  where  $u_1, u_2$  are e-vectors

③ complex:  $c_1 e^{\alpha t} [u \cos \beta t - v \sin \beta t] + c_2 e^{\alpha t} [u \sin \beta t + v \cos \beta t]$

$w = u + iv$  (only consider one complex pair) e.vec.  $\Rightarrow$  eg:  $\begin{pmatrix} 1 \\ -i \end{pmatrix}$   
 $w = \begin{pmatrix} 1 \\ 0 \end{pmatrix} + i \begin{pmatrix} 0 \\ -1 \end{pmatrix}$

④ Laplace method  $\vec{y} = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$ ,  $\frac{d\vec{y}}{dt} = B \vec{y}$ ,  $\vec{y}(0) = \begin{bmatrix} x_0 \\ y_0 \end{bmatrix}$

$\Rightarrow$  Apply L.T:  $L(\vec{y}') = sL(\vec{y}) - \vec{y}(0)$

$sL(\vec{y}) - \vec{y}(0) = B L(\vec{y}) \Rightarrow (sI - B)L(\vec{y}) = \vec{y}(0)$

$(sI - B)L(\vec{y}) = \vec{y}(0) \Rightarrow L(\vec{y}) = (sI - B)^{-1} \vec{y}(0) \Rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} L(\vec{y}) = \vec{y}(0)$

$L(\vec{y}) = (sI - B)^{-1} \vec{y}(0) \Rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} L(\vec{y}) = \vec{y}(0)$

Stability: ① E-val  $\leq 0$  } real.  $\det B > 0$  } no.  $\text{Tr } B < 0$

②  $\text{Tr } B \leq 0$  } complex.  $\det B > 0$

Phase planes: Type E-val.  $\text{Tr } B$   $\det B$  Stability

N.s.sink Both  $> 0$   $> 0$   $> 0$  unstable

N.sink Both  $< 0$   $< 0$   $< 0$  stable

Saddle opp  $< 0$   $< 0$   $< 0$  unstable

\* Note: e-val  $< 0$ : traj goes to 0  
 $> 0$ : goes to  $\infty$

all traj.  $\rightarrow$  to E-val of bigger val.

③ Centre,  $\text{Tr } B = 0$

\* To find direction, use  $\frac{dy}{dx} = \frac{y}{x}$

eg:  $\frac{dy}{dx} = \frac{2x - 2y}{x + y} \Rightarrow y = 0, y = 2x$

Near  $x = 0, y = 0$

m2:  $\text{Tr } B^2 - 4 \det(B)$

$\text{Tr } B > 0 \Rightarrow$  s.s.sink

$\text{Tr } B < 0 \Rightarrow$  s.s.sink

$\text{Tr } B = 0 \Rightarrow$  centre

Partial Differential Eqns:

SEP VAR: Assume  $u(x, y) = X(x)Y(y)$ , eg:  $\frac{1}{x} \frac{X'(x)}{X(x)} = \frac{Y'(y)}{Y(y)} = \text{constant}$

Sturm-Liouville Egn:  $X''(x) + \lambda X(x) = 0$ ,  $X(0) = 0$ ,  $X'(0) = 0$

uses: ①  $\lambda < 0$  or  $\lambda > 0 \Rightarrow$  only the only sol

②  $\lambda > 0 \Rightarrow$  when  $\lambda \neq (\frac{n\pi}{L})^2 \Rightarrow 0$  is the only sol

③ when  $\lambda = (\frac{n\pi}{L})^2 \Rightarrow$  there exists a non-zero sol

$X(x) = \sin(\frac{n\pi}{L} x)$   $\leftarrow$  eigenfunction.

Wave Egn:  $\frac{\partial^2 u(x, t)}{\partial x^2} = \frac{\partial^2 u(x, t)}{\partial t^2}$ ,  $0 < x < L$ ,  $t > 0$

G.S.:  $y(x, t) = \sum_{n=1}^{\infty} A_n \sin(\frac{n\pi}{L} x) \cos(\frac{n\pi}{L} t)$

$A_n = \frac{2}{L} \int_0^L f(x) \sin(\frac{n\pi}{L} x) dx$

General steps: ① Let  $y(x, t) = u(x) v(t)$

②  $u''(x) + \lambda u(x) = 0$ ,  $v''(t) + \lambda v(t) = 0$

③ For  $u$ , use  $\lambda = (\frac{n\pi}{L})^2$ ,  $u(x) = B_n \sin(\frac{n\pi}{L} x)$

④ For  $v$ , use initial cond,  $v(t) = (n \cos[\frac{n\pi}{L} t]) = n \cos t$

⑤ (pure coeff. of  $f(x)$ ) with  $A_n$

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