

# Assignment 1

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Download all python codes from

<https://github.com/piyushSTK/EE3025/tree/main/Assignment1/codes>

and latex-tikz codes from

<https://github.com/piyushSTK/EE3025/tree/main/Assignment1>

Now to obtain DFT from Z transform, we evaluate (2.0.4) at  $z = e^{j\omega}$  where  $\omega = 2\pi k/N$   
Hence  $H(k)$  :

$$H(k) = H(z = e^{j2\pi k/N}). \quad (2.0.5)$$

$X(k)$  is calculated from our input signal  $x(n)$  using **np.fft.fft**.  
Therefore  $Y(k)$ :

$$Y(k) = H(k) X(k) \quad (2.0.6)$$

Since this is in frequency domain,  $y(n)$  is found from  $Y(K)$  using **np.fft.ifft** command.

Below is the python code for this question. This code plots the output signals and returns the corresponding soundfiles.

codes/ee18btech11036.py

## 1 PROBLEM

(7.1) The command

`output_signal = signal.lfilter(b, a, input_signal)`

in Problem (2.3) is executed through the following difference equation

$$\sum_{m=0}^M a(m) y(n-m) = \sum_{k=0}^N b(k) x(n-k) \quad (1.0.1)$$

where the input signal is  $x(n)$  and the output signal is  $y(n)$  with initial values all 0. Replace **signal.filtfilt** with your own routine and verify.

## 2 SOLUTION

This problem can be solved by using Z transform on the difference equation and then applying the properties of Z transform. Let take  $X(z)$  and  $Y(z)$  as the z-transforms of  $x(n)$  and  $y(n)$ .

Using the time shifting property,

$$\mathcal{Z}\{x(n-k)\} = z^{-k} X(z) \quad (2.0.1)$$

$$\mathcal{Z}\{y(n-m)\} = z^{-m} Y(z) \quad (2.0.2)$$

We get:

$$Y(z) \sum_{m=0}^M a(m) z^{-m} = X(z) \sum_{k=0}^N b(k) z^{-k} \quad (2.0.3)$$

$$H(z) = \frac{Y(z)}{X(z)} = \frac{\sum_{k=0}^N b(k) z^{-k}}{\sum_{m=0}^M a(m) z^{-m}} \quad (2.0.4)$$

## 3 VERIFICATION

Plotting the time domain output signal  $y(n)$  obtained using `signal.filtfilt` as well as constructed filter.

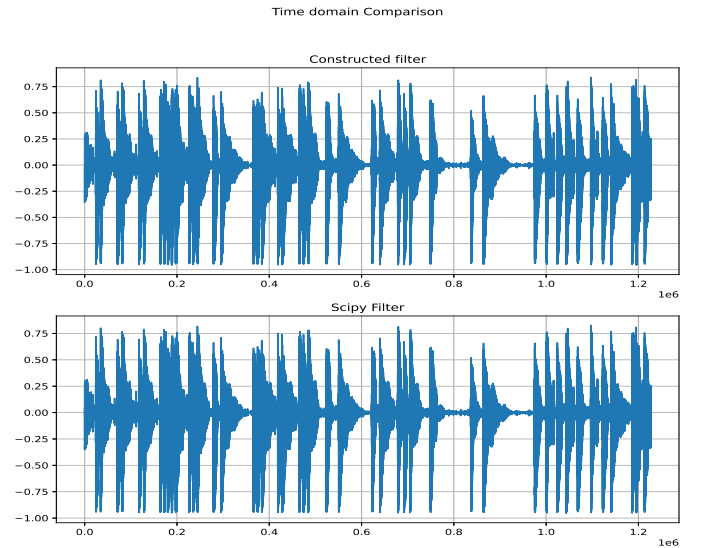


Fig. 0: Time domain response

Frequency Response of both, constructed filter, and  
signal.filtfilt for further verification

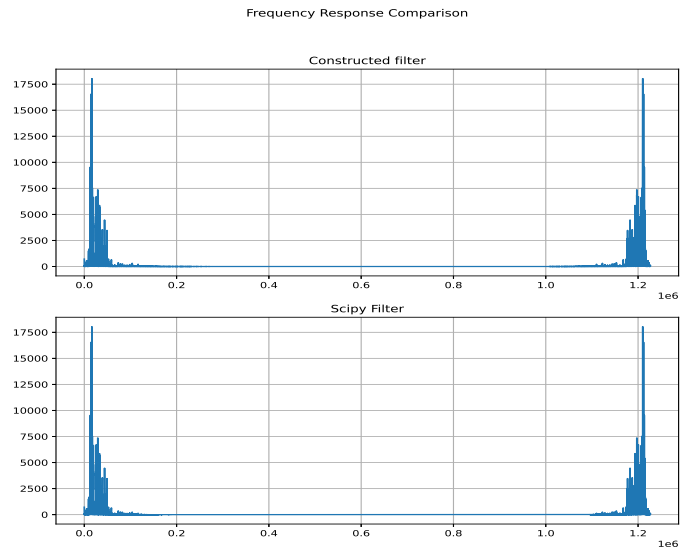


Fig. 0: Frequency domain response