



Github:  
[@rahulknns](#)

# RAHULKANNAN S

+91 9344882661  
[srahulkannan63@gmail.com](mailto:srahulkannan63@gmail.com)

## EXPERIENCE

Software Developer	AUV Society, IIITDM	2021-22
<ul style="list-style-type: none"><li>Worked majorly with developing and documenting control software, drivers for autonomous underwater vehicles in C++ and Python.</li><li>Developed highly optimized sensor fusion algorithms implemented in C++ and ARM inline assembly.</li></ul>		

## EDUCATION

Chennai, India	IIITDM Kancheepuram	2020 - 2024
<ul style="list-style-type: none"><li>B. Tech in Electronics and Communication Engineering. CGPA of 8.19</li></ul>		

## RELEVANT COURSES

- Data Structures
- Introduction to React ( In progress)
- Algorithms ( Coursera Audit)
- Computer architecture (Coursera Audit)
- Introduction to IoT and Cloud Computing (In Progress)

## Tools and Technologies

- MongoDB, Nodejs, postman
- Docker
- git, github
- tensorflow, opencv, pybind11, CMake

## Programming languages

- Javascript,TypeScript
- C++
- Java
- Python,
- GoLang

## Projects:

### Electron app for sensor calibration of AUV:

- Developed an web app using tensorflow.js and electron for sensor calibration.

### Localisation Algorithm for Hydrophones:

- Developed and implemented a highly efficient Hydrophone sound localisation algorithm in C++ and inline ARM assembly.

### Motion Control Library for underwater vehicle:

- Conceptualized and developed an generic, modular and easily reconfigurable motion control library for any AUV in C++ from scratch and exposed API via Pybind11.

### Object localisation using Yolo V5 for underwater vehicle:

- Trained and deployed yolo V5 model for underwater object detection.

### Cloud IOT based smart grid:

- Implemented a smart grid system using Docker, FIWARE, MongoDB,OpenADR and Mosquitto Broker in AWS.