

## *Multivariable*

$$A = (x_1, y_1, z_1) \quad B = (x_2, y_2, z_2)$$

**Distance:**  $d = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$

**Midpoint:**  $M = \left( \frac{x_1 + x_2}{2}, \frac{y_1 + y_2}{2}, \frac{z_1 + z_2}{2} \right)$

**Sphere Equation:**  $(x - a)^2 + (y - b)^2 + (z - c)^2 = r^2$

**Equation of a line in space:** 
$$\begin{cases} x = x_1 + (x_2 - x_1)t \\ y = y_1 + (y_2 - y_1)t \\ z = z_1 + (z_2 - z_1)t \end{cases}$$

$$u = (u_1, u_2, u_3) \quad v = (v_1, v_2, v_3)$$

**Length (or Norm or Magnitude):**  $\|v\| = |v| = \sqrt{v_1^2 + v_2^2 + v_3^2}$

**Dot (Inner) Product:**  $u \bullet v = |u| |v| \cos \theta$

$$u \bullet v = u_1 v_1 + u_2 v_2 + u_3 v_3$$

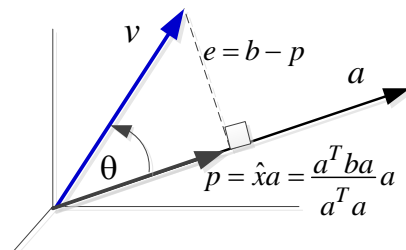
**Angle between 2 vectors:**  $\theta = \cos^{-1} \left( \frac{u \bullet v}{|u| |v|} \right)$

$$\theta = \cos^{-1} \frac{u_1 v_1 + u_2 v_2 + u_3 v_3}{\left( \sqrt{u_1^2 + u_2^2 + u_3^2} \right) \left( \sqrt{v_1^2 + v_2^2 + v_3^2} \right)}$$

**Projection matrix**  $p = \hat{x}a = \frac{a^T v}{a^T a} a$

**Length**  $\|p\| = \|v\| \cos \theta$

**Error**  $e = v - p$



- Two vectors are **parallel** iff they are scalar multiples of each other.
- Two vectors  $A$  and  $B$  are **orthogonal** (perpendicular) iff  $A \cdot B = 0$
- A set of vectors  $v_1, v_2, \dots, v_n$  are **linearly dependent** iff there are scalars  $c_1, c_2, \dots, c_n$  not all zero such that  $c_1 v_1 + c_2 v_2 + \dots + c_n v_n = 0$

They are **linearly independent** if no such collection of scalars exist.

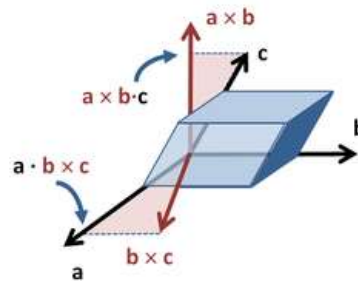
### Properties of Vector Product

- ✓  $A \times B$  is a vector perpendicular to both  $A$  and  $B$ .
- ✓  $A \times B = -(B \times A)$
- ✓  $A \times A = 0$
- ✓  $A \times (B + C) = A \times B + A \times C$
- ✓  $(cA) \times B = A \times cB = c(A \times B)$  for any scalar  $c$ .
- ✓ The length of  $A \times B$  is the **area of the parallelogram** spanned by  $A$  and  $B$ . This area is  $\|A\|\|B\|\sin \theta$
- ✓ If  $A$  or  $B$  is 0 or  $A$  is parallel to  $B$ , then  $A \times B$  is the vector 0.

**Volume** of the Parallelepiped is

$$V = (\text{area of base}) \cdot (\text{height}) = |u \cdot (v \times w)|$$

$$V = \left| \det \begin{bmatrix} u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{bmatrix} \right|$$



**Schwarz Inequality:**  $\|A \cdot B\| \leq \|A\| \cdot \|B\|$

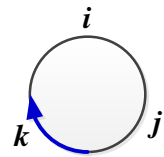
**Determinant:**  $\begin{bmatrix} a & b \\ c & d \end{bmatrix} \Rightarrow ad - bc$

$$\begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} = a_1 \begin{vmatrix} b_2 & b_3 \\ c_2 & c_3 \end{vmatrix} - a_2 \begin{vmatrix} b_1 & b_3 \\ c_1 & c_3 \end{vmatrix} + a_3 \begin{vmatrix} b_1 & b_2 \\ c_1 & c_2 \end{vmatrix}$$

**Cross Product:**  $A \times B = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ x_1 & y_1 & z_1 \\ x_2 & y_2 & z_2 \end{vmatrix} = \begin{vmatrix} y_1 & z_1 \\ y_2 & z_2 \end{vmatrix} \mathbf{i} - \begin{vmatrix} x_1 & z_1 \\ x_2 & z_2 \end{vmatrix} \mathbf{j} + \begin{vmatrix} x_1 & y_1 \\ x_2 & y_2 \end{vmatrix} \mathbf{k}$

$$= \begin{vmatrix} y_1 & z_1 \\ y_2 & z_2 \end{vmatrix} \mathbf{i} - \begin{vmatrix} x_1 & z_1 \\ x_2 & z_2 \end{vmatrix} \mathbf{j} + \begin{vmatrix} x_1 & y_1 \\ x_2 & y_2 \end{vmatrix} \mathbf{k}$$

$$= (y_1 z_2 - y_2 z_1, x_1 y_2 - x_2 y_1, x_1 z_2 - x_2 z_1)$$



### Cross Product Properties

1.  $\mathbf{u} \times \mathbf{v}$  reverses rows 2 and 3 in the determinant so it is equals  $-(\mathbf{u} \times \mathbf{v})$
2. The cross product  $\mathbf{u} \times \mathbf{v}$  is perpendicular to  $\mathbf{u}$ , then  $\mathbf{u} \cdot (\mathbf{u} \times \mathbf{v}) = 0$
3. The cross product  $\mathbf{u} \times \mathbf{v}$  is perpendicular to  $\mathbf{v}$ , then  $(\mathbf{u} \times \mathbf{v}) \cdot \mathbf{v} = 0$
4. The cross product of any vector with itself (two equal rows) is  $\mathbf{u} \times \mathbf{u} = 0$ .
5.  $\mathbf{i} \times \mathbf{j} = \mathbf{k}$ ,  $\mathbf{j} \times \mathbf{k} = \mathbf{i}$ ,  $\mathbf{k} \times \mathbf{i} = \mathbf{j}$
6. Lagrange's identity:  $\|\mathbf{u} \times \mathbf{v}\|^2 = \|\mathbf{u}\|^2 \|\mathbf{v}\|^2 - (\mathbf{u} \cdot \mathbf{v})^2$   
 $= \|\mathbf{u}\| \|\mathbf{v}\| |\sin \theta|$   
 $|\mathbf{u} \cdot \mathbf{v}| = \|\mathbf{u}\| \|\mathbf{v}\| |\cos \theta|$

**Work:**  $W = \int_a^b f(x) dx$

**Volume:**  $V = \int_a^b 2\pi x (y_2 - y_1) dx$

### Planes and Surfaces in Space

The plane through  $P_0(x_0, y_0, z_0)$  normal to  $\mathbf{n} = a\mathbf{i} + b\mathbf{j} + c\mathbf{k}$ :

Vector Equation:  $\mathbf{n} \cdot \overrightarrow{P_0 P} = 0$

Component equation:  $a(x - x_0) + b(y - y_0) + c(z - z_0) = 0$   
 $ax + by + cz = d$ , where  $d = ax_0 + by_0 + cz_0$

## Vector-valued Functions and Motion in Space

Let  $\mathbf{r}(t) = f(t)\mathbf{i} + g(t)\mathbf{j} + h(t)\mathbf{k}$  be a vector function.

Then  $\mathbf{v}(t) = \frac{d\mathbf{r}}{dt}$  is the velocity vector and  $|\mathbf{v}(t)|$  is the speed.

The acceleration vector is  $\mathbf{a}(t) = \frac{d\mathbf{v}}{dt} = \frac{d^2\mathbf{r}}{dt^2}$ .

The unit tangent vector is  $\mathbf{T} = \frac{\mathbf{v}}{|\mathbf{v}|}$  and the length of  $\mathbf{r}(t)$  from  $t = a$  to  $t = b$  is  $L = \int_a^b |\mathbf{v}| dt$

## Lines in Space

A vector equation of the line through  $P_0(x_0, y_0, z_0)$  parallel to  $\mathbf{v} = (v_1, v_2, v_3)$  is  $\mathbf{r}(t) = \mathbf{r}_0 + t\mathbf{v}$

$$\langle x, y, z \rangle = \langle x_0, y_0, z_0 \rangle + t \langle v_1, v_2, v_3 \rangle, \text{ for } -\infty < t < \infty$$

Parametric equations for this line are:

$$x = x_0 + tv_1, \quad y = y_0 + tv_2, \quad z = z_0 + tv_3, \text{ for } -\infty < t < \infty$$

Principal Unit Normal:  $\mathbf{N} = \frac{d\mathbf{T}/dt}{|d\mathbf{T}/dt|}$

**Curvature:**  $\kappa = \left| \frac{d\mathbf{T}}{ds} \right| = \frac{1}{|\mathbf{v}|} \left| \frac{d\mathbf{T}}{dt} \right| = \frac{|\mathbf{a} \times \mathbf{v}|}{|\mathbf{v}|^3}$

Radius of **Curvature:**  $\rho = \frac{1}{\kappa}$

Tangential and normal scalar components of acceleration:

$$\mathbf{a} = a_T \mathbf{T} + a_N \mathbf{N} \quad \left\{ \begin{array}{l} a_T = \frac{d^2s}{dt^2} = \frac{\mathbf{a} \cdot \mathbf{v}}{|\mathbf{v}|} \\ a_N = \kappa \left( \frac{ds}{dt} \right)^2 = \kappa |\mathbf{v}|^2 = \frac{|\mathbf{a} \times \mathbf{v}|}{|\mathbf{v}|} \end{array} \right.$$

## ***Quadratic Surfaces***

***Ellipsoid:***  $\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$

***Elliptic Paraboloid:***  $z = \frac{x^2}{a^2} + \frac{y^2}{b^2}$

***Elliptic Cone:***  $\frac{x^2}{a^2} + \frac{y^2}{b^2} = \frac{z^2}{c^2}$

***Hyperboloid of one sheet:***  $\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = 1$

***Hyperboloid of two sheets:***  $-\frac{x^2}{a^2} - \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$

***Hyperbolic Paraboloid:***  $z = \frac{x^2}{a^2} - \frac{y^2}{b^2}$

## Integration in Vector Fields

### Line Integrals

To integrate a continuous function  $f(x, y, z)$  over a curve  $C$ :

$$\triangleright \mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j} + z(t)\mathbf{k} \quad a \leq t \leq b$$

$$\triangleright \int_C f(x, y, z) ds = \int_a^b f(x(t), y(t), z(t)) \cdot |v(t)| dt$$

$$\text{Where } v(t) = \frac{d\mathbf{r}}{dt} \quad \text{and} \quad ds = |v(t)| dt$$

$\mathbf{F}$  conservative on  $D \Leftrightarrow \mathbf{F} = \nabla \varphi$  for some potential function  $\varphi$

$$\Leftrightarrow \oint_C \mathbf{F} \cdot d\mathbf{x} = 0 \text{ over closed paths } C \text{ in } D$$

$$\Leftrightarrow \int_C \mathbf{F} \cdot d\mathbf{x} \text{ is independent of path for } C \text{ in } D.$$

$$\Leftrightarrow \nabla \times \mathbf{F} = 0 \text{ on } D.$$

$$\textbf{Work:} \quad W = \int_C \mathbf{F} \cdot \mathbf{T} ds = \int_a^b \mathbf{F} \cdot \mathbf{r}'(t) dt = \int_a^b \mathbf{F} \cdot d\mathbf{x} = \int_C (f dx + g dy + h dz)$$

$$\textbf{Circulation of } \mathbf{F} \text{ on } C: \oint_C \mathbf{F} \cdot \mathbf{T} ds$$

$$\textbf{Flux of } \mathbf{F} \text{ across } C = \oint_C \mathbf{F} \cdot \mathbf{n} ds = \oint_C (f dy - g dx)$$

Where  $\mathbf{F} = \langle f, g \rangle$  and  $\mathbf{n}$  is outward pointing normal along  $C$ .

## *Conservative Vector Field*

$\mathbf{F}$  is conservative if  $\mathbf{F} = \nabla \varphi$  for some function  $\varphi(x, y, z)$ . If  $\mathbf{F}$  is conservative, then  $\int_A^B \mathbf{F} \cdot d\mathbf{r}$

is independent of path and  $\int_A^B \mathbf{F} \cdot d\mathbf{r} = \varphi(B) - \varphi(A)$

$$\oint_C \mathbf{F} \cdot d\mathbf{r} = 0$$

$$\frac{\partial f}{\partial y} = \frac{\partial g}{\partial x}, \quad \frac{\partial f}{\partial z} = \frac{\partial h}{\partial x}, \quad \text{and} \quad \frac{\partial g}{\partial z} = \frac{\partial h}{\partial y}$$

## *Fundamental Theorem of Calculus*

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$$\int_a^b f'(x) dx = f(b) - f(a)$$

*Fundamental Theorem of Line Integrals*

$$\int_C \nabla f \cdot d\mathbf{r} = f(B) - f(A)$$

## Green's Theorem

$$\oint_C \mathbf{F} \cdot \mathbf{n} \, ds = \oint_C (f dy - g dx) = \iint_R \left( \frac{\partial f}{\partial x} + \frac{\partial g}{\partial y} \right) dA$$

*outward flux* *Divergence integral*

$$\oint_C \mathbf{F} \cdot \mathbf{T} \, ds = \oint_C (f dy + g dx) = \iint_R \left( \frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) dA$$

*ccw circulation* *Curl integral*

$$\text{Area of } R = \oint_C x dy = - \oint_C y dx = \frac{1}{2} \oint_C (x dy - y dx)$$

$$\text{Circulation: } \oint_C \mathbf{F} \cdot d\mathbf{r} = \iint_R \nabla \times \mathbf{F} \cdot \mathbf{k} \, dA$$

$$\text{Flux: } \oint_C \mathbf{F} \cdot \mathbf{n} \, ds = \iint_R \nabla \cdot \mathbf{F} \, dA$$

$$\text{Divergence: } \oint_S \mathbf{F} \cdot \mathbf{n} \, dS = \iiint_D \nabla \cdot \mathbf{F} \, dV$$

## Stokes' Theorem

$$\oint_C \mathbf{F} \cdot d\mathbf{r} = \iint_S (\nabla \times \mathbf{F}) \cdot \mathbf{n} \, dS$$

*ccw* *Curl integral*  
*circulation*



## Surface Integrals

$$\mathbf{r}(u, v) = \langle x(u, v), y(u, v), z(u, v) \rangle, \quad a \leq u \leq b, \quad c \leq v \leq d$$

$$\text{Unit normal to the surface: } \frac{\mathbf{t}_u \times \mathbf{t}_v}{|\mathbf{t}_u \times \mathbf{t}_v|} = \mathbf{n}$$

$$\text{Area:} \quad \text{Area of surface } S = \int_c^d \int_a^b |\mathbf{t}_u \times \mathbf{t}_v| du dv$$

$$\iint_S f(x, y, z) dS = \int_c^d \int_a^b f(x(u, v), y(u, v), z(u, v)) |\mathbf{t}_u \times \mathbf{t}_v| du dv$$

## Formulas from Vector Calculus

Assume  $F(x, y, z) = f(x, y, z)\mathbf{i} + g(x, y, z)\mathbf{j} + h(x, y, z)\mathbf{k}$ , where  $f$ ,  $g$ , and  $h$  are differentiable on a region  $D$  of  $\mathbf{R}^3$ .

$$\text{Gradient:} \quad \nabla f(x, y, z) = \frac{\partial f}{\partial x}\mathbf{i} + \frac{\partial f}{\partial y}\mathbf{j} + \frac{\partial f}{\partial z}\mathbf{k}$$

$$\begin{aligned} \text{Curl:} \quad \text{curl } \mathbf{F} &= \left( \frac{\partial h}{\partial y} - \frac{\partial g}{\partial z} \right) \mathbf{i} + \left( \frac{\partial f}{\partial z} - \frac{\partial h}{\partial x} \right) \mathbf{j} + \left( \frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) \mathbf{k} \\ &= \nabla \times \mathbf{F} \end{aligned}$$

$$\nabla \times \mathbf{F}(x, y, z) = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ f & g & h \end{vmatrix}$$

$$\text{Divergence:} \quad \text{div } \mathbf{F} = \nabla \cdot \mathbf{F}(x, y, z) = \frac{\partial f}{\partial x} + \frac{\partial g}{\partial y} + \frac{\partial h}{\partial z}$$

$$\oint_S \mathbf{F} \cdot \mathbf{n} dS = \iiint_D \nabla \cdot \mathbf{F} dV \quad \iint_S \mathbf{F} \cdot \mathbf{n} dS = \oint_D \nabla \cdot \mathbf{F} dV$$

*outward flux    Divergence integral*

$$\nabla \times (\nabla f) = 0$$

$$\nabla \cdot (\nabla \times \mathbf{f}) = 0$$

## Multiple Integrals

### Double Integrals as Volumes

When  $f(x, y)$  is a positive function over a region  $R$  in the  $xy$ -plane, we may interpret the double integral of  $f$  over  $R$  as the volume of the 3-dimensional solid region over the  $xy$ -plane bounded below by  $R$  and above the surface  $z = f(x, y)$ .

This volume can be evaluated by computing an iterated integral

Let  $f(x, y)$  be continuous on a region  $R$ .

1. If  $R$  is defined by  $a \leq x \leq b$ ,  $g_1(x) \leq y \leq g_2(x)$ , with  $g_1$  and  $g_2$  continuous on  $[a, b]$ , then

$$\iint_R f(x, y) dA = \int_a^b \int_{g_1(x)}^{g_2(x)} f(x, y) dy dx$$

2. If  $R$  is defined by  $c \leq y \leq d$ ,  $h_1(y) \leq x \leq h_2(y)$ , with  $h_1$  and  $h_2$  continuous on  $[c, d]$ , then

$$\iint_R f(x, y) dA = \int_c^d \int_{h_1(y)}^{h_2(y)} f(x, y) dx dy$$

**Area:**  $A = \iint_R dA = \iint_R dx dy = \iint_R dy dx$

$$A = \iint_R r dr d\theta \quad (\text{Polar Coordinates})$$

### Triple Integrals

$$\iiint_R f(x, y, z) dV = \int_a^b \int_{g(x)}^{h(x)} \int_{G(x, y)}^{H(x, y)} f(x, y, z) dz dy dx$$

$$a \leq x \leq b, \quad g(x) \leq y \leq h(x), \quad G(x, y) \leq z \leq H(x, y)$$

## Cylindrical Coordinates $(r, \theta, z)$

Equations Relating Rectangular  $(x, y, z)$  and Cylindrical  $(r, \theta, z)$  Coordinates

$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \\ z = z \end{cases} \quad \begin{cases} r^2 = x^2 + y^2 \\ \tan \theta = \frac{y}{x} \end{cases}$$

$$\iiint_D f(r, \theta, z) dV = \iiint_D f(r, \theta, z) dz \, r dr \, d\theta$$

## Spherical Coordinates $(\rho, \varphi, \theta)$

$$x = r \cos \theta = \rho \sin \varphi \cos \theta$$

$$y = r \sin \theta = \rho \sin \varphi \sin \theta$$

$$z = \rho \cos \varphi$$

$$r = \rho \sin \varphi$$

$$\rho = \sqrt{x^2 + y^2 + z^2} = \sqrt{r^2 + z^2}$$

$$\iiint_D f(\rho, \varphi, \theta) dV = \iiint_D f(\rho, \varphi, \theta) \rho^2 \sin \varphi \, d\rho \, d\varphi \, d\theta$$

Change of Variables Formula for Double Integrals

$$\iint_R f(x, y) dy dx = \iint_S f(g(u, v), h(u, v)) |J(u, v)| dA$$

**Jacobian determinant:** 
$$J(u, v) = \frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \frac{\partial x}{\partial u} \frac{\partial y}{\partial v} - \frac{\partial x}{\partial v} \frac{\partial y}{\partial u}$$