

Section 2.8 – Row and Column Spaces

Definition

For an $m \times n$ matrix

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2n} \\ a_{31} & a_{32} & a_{33} & \cdots & a_{3n} \\ \vdots & \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & a_{m3} & \cdots & a_{mn} \end{bmatrix}$$

The vectors

$$\begin{aligned} \vec{v}_1 &= \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \end{bmatrix} \\ \vec{v}_2 &= \begin{bmatrix} a_{21} & a_{22} & \cdots & a_{2n} \end{bmatrix} \\ &\vdots \\ \vec{v}_m &= \begin{bmatrix} a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} \end{aligned}$$

In \mathbf{R}^n that are formed from the rows of A are called the **row vectors** of A , and the vectors

$$\vec{v}_1 = \begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{m1} \end{bmatrix}, \quad \vec{v}_2 = \begin{bmatrix} a_{12} \\ a_{22} \\ \vdots \\ a_{m2} \end{bmatrix}, \quad \cdots \quad \vec{v}_n = \begin{bmatrix} a_{1n} \\ a_{2n} \\ \vdots \\ a_{mn} \end{bmatrix}$$

In \mathbf{R}^m that are formed from the rows of A are called the **column vectors** of A .

Definition

If A is $m \times n$ matrix, then the subspace of \mathbf{R}^n spanned by the row vectors of A is called the **row space** of A and is denoted by $RS(A)$ *or* $R(A)$, and the subspace \mathbf{R}^m spanned by the row vectors of A is called the **column space** of A and is denoted by $CS(A)$ *or* $C(A)$. The solution space of the homogeneous system of equations $Ax = 0$, which is a subspace of \mathbf{R}^n , is called the null space of A .

The *Column Space* of A

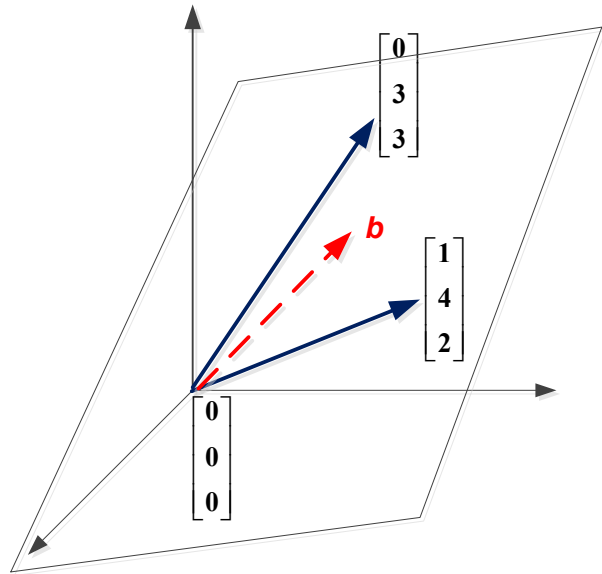
The most important subspaces are tied directly to a matrix A , to solve $A\vec{x} = \vec{b}$.

Definition

The column space consists of all linear combinations of the columns. The combination are all possible vectors $A\vec{x}$. They fill the column space $C(A)$.

$$A = \begin{bmatrix} 1 & 0 \\ 4 & 3 \\ 2 & 3 \end{bmatrix}$$

$$\vec{b} = x_1 \begin{bmatrix} 1 \\ 4 \\ 2 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 3 \\ 3 \end{bmatrix}$$



To solve $A\vec{x} = \vec{b}$ is to express \vec{b} as a combination of the columns.

The column space $CS(A)$ is a plane that containing the two columns. $A\vec{x} = \vec{b}$ is solvable when \vec{b} is in that plane.

Theorem

The system $A\vec{x} = \vec{b}$ is solvable if and only if \vec{b} is in the column space of A .

Example

Let $A\vec{x} = \vec{b}$ be the linear system

$$\begin{bmatrix} -1 & 3 & 2 \\ 1 & 2 & -3 \\ 2 & 1 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ -9 \\ -3 \end{bmatrix}$$

Show that \vec{b} is in the column space of A by expressing it as a linear combination of the column vectors of A .

Solution

$$\left[\begin{array}{ccc|c} -1 & 3 & 2 & 1 \\ 1 & 2 & -3 & -9 \\ 2 & 1 & -2 & -3 \end{array} \right] \quad \begin{array}{l} R_2 + R_1 \\ R_3 + 2R_1 \end{array}$$

$$\left[\begin{array}{ccc|c} -1 & 3 & 2 & 1 \\ 0 & 5 & -1 & -8 \\ 0 & 7 & 2 & -1 \end{array} \right] \quad \begin{array}{l} 5R_1 - 3R_2 \\ 5R_3 - 7R_2 \end{array}$$

$$\left[\begin{array}{ccc|c} -5 & 0 & 13 & 29 \\ 0 & 5 & -1 & -8 \\ 0 & 0 & 17 & 51 \end{array} \right] \quad \begin{array}{l} 17R_1 - 13R_3 \\ 17R_2 + R_3 \end{array}$$

$$\left[\begin{array}{ccc|c} -85 & 0 & 0 & -170 \\ 0 & 85 & 0 & -85 \\ 0 & 0 & 17 & 51 \end{array} \right] \quad \begin{array}{l} -\frac{1}{85}R_1 \\ \frac{1}{85}R_2 \\ \frac{1}{17}R_3 \end{array}$$

$$\left[\begin{array}{ccc|c} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 3 \end{array} \right]$$

That implies to $x_1 = 2$, $x_2 = -1$, $x_3 = 3$

It follows that

$$2 \begin{bmatrix} -1 \\ 1 \\ 2 \end{bmatrix} - \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix} + 3 \begin{bmatrix} 2 \\ -3 \\ -2 \end{bmatrix} = \begin{bmatrix} 1 \\ -9 \\ -3 \end{bmatrix},$$

Example

Describe the column spaces (they are subspaces of \mathbb{R}^2) for

$$I = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \quad A = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \quad B = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 4 & 4 \end{bmatrix}$$

Solution

The column space of I is the whole space \mathbb{R}^2 . Every vector is a combination of the columns of I . In the space language $CS(I)$ is \mathbb{R}^2 .

The column space of A is only a line, the second column $(2, 4)$ is a multiple of the first column $(1, 2)$ and $(2, 4)$ and all other vectors $(c, 2c)$ along that line. The equation $A\vec{x} = \vec{b}$ is only solvable when \vec{b} is on the line.

The column space $C(B)$ is all of \mathbb{R}^2 . Every b is attainable. The vector $\vec{b} = (3, 4)$ is summation of column 1 and 2.

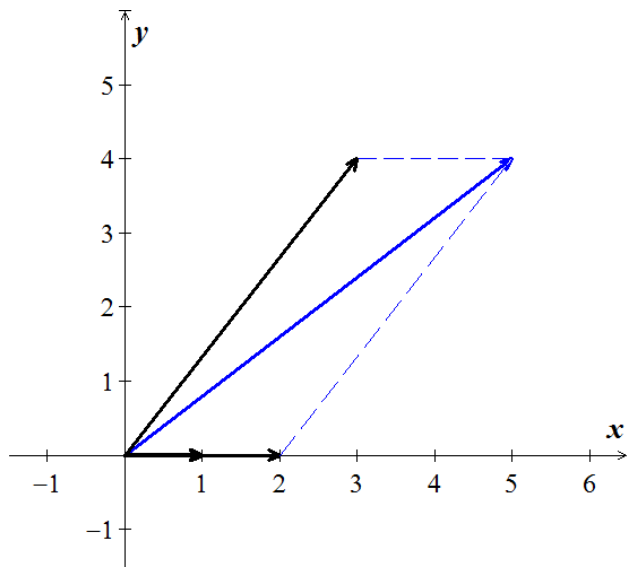
$$\begin{pmatrix} 1 & 2 & 3 \\ 0 & 0 & 4 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 5 \\ 4 \end{pmatrix}$$

$$\begin{cases} x_1 + 2x_2 + 3x_3 = 5 \\ 4x_3 = 4 \end{cases}$$

$$\Rightarrow \begin{cases} x_1 + 2x_2 = 2 \\ x_3 = 1 \end{cases}$$

$$\Rightarrow \begin{cases} x_1 = 0 \\ x_2 = 1 \end{cases} \quad \text{or} \quad \Rightarrow \begin{cases} x_1 = 2 \\ x_2 = 0 \end{cases}$$

$$x = (0, 1, 1) \quad \text{also} \quad x = (2, 0, 1)$$



This matrix has the same column as I and any \vec{b} is allowed. \vec{x} has an extra component (more solutions).

Pivot Columns

The pivot columns of R have 1's in the pivots and 0's everywhere else.

$$\text{Pivot columns: } A = \begin{bmatrix} 1 & 3 & 0 & 2 & -1 \\ 0 & 0 & 1 & 4 & -3 \\ 1 & 3 & 1 & 6 & -4 \end{bmatrix}$$

$$\text{Yields to: } R = \begin{bmatrix} 1 & 3 & 0 & 2 & -1 \\ 0 & 0 & 1 & 4 & -3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

 **The pivot columns are not combinations of earlier columns. The free columns are combinations of columns which are the special solutions!**

Complete Solution to $AX = B$

To solve $A\vec{x} = \vec{b}$, we need to put into an ***augmented*** form where \vec{b} is not zero.

$$A = \begin{bmatrix} 1 & 3 & 0 & 2 \\ 0 & 0 & 1 & 4 \\ 1 & 3 & 1 & 6 \end{bmatrix}$$

$$B = \vec{b} = \begin{bmatrix} 1 \\ 6 \\ 7 \end{bmatrix}$$

$$A\vec{x} = \vec{b}$$

$$\begin{bmatrix} 1 & 3 & 0 & 2 \\ 0 & 0 & 1 & 4 \\ 1 & 3 & 1 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 1 \\ 6 \\ 7 \end{bmatrix}$$

$$X = \vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

The augmented matrix is just $[A \quad B]$

$$\left[\begin{array}{cccc|c} 1 & 3 & 0 & 2 & 1 \\ 0 & 0 & 1 & 4 & 6 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] = [R \quad \textcolor{green}{d}]$$

Special Solutions

Each special solution to $A\vec{x} = 0$ and $R\vec{x} = 0$ has one free variable equal to 1.

$$R\vec{x} = \begin{bmatrix} 1 & 3 & 0 & 2 & -1 \\ 0 & 0 & 1 & 4 & -3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

F *F* *F*

The **free variables** are x_2, x_4, x_5

$$\rightarrow \begin{cases} x_1 + 3x_2 + 2x_4 - x_5 = 0 \\ x_3 + 4x_4 - 3x_5 = 0 \end{cases}$$

$$1. \text{ Set } x_2 = 1, x_4 = x_5 = 0 \Rightarrow \begin{cases} x_1 = -3 \\ x_3 = 0 \end{cases} \quad (\text{Column 2})$$

The special solution: $s_1 = (-3, 1, 0, 0, 0)$

$$2. \text{ Set } x_4 = 1, x_2 = x_5 = 0 \Rightarrow \begin{cases} x_1 = -2 \\ x_3 = -4 \end{cases} \quad (\text{Column 4})$$

The special solution: $s_2 = (-2, 0, -4, 1, 0)$

$$3. \text{ Set } x_5 = 1, x_2 = x_4 = 0 \Rightarrow \begin{cases} x_1 = 1 \\ x_3 = 3 \end{cases} \quad (\text{Column 5})$$

The special solution: $s_3 = (1, 0, 3, 0, 1)$

The nullspace matrix N contains the 3 special solutions in its columns.

$$N = \begin{bmatrix} -3 & -2 & 1 \\ 1 & 0 & 0 \\ 0 & -4 & 3 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \begin{matrix} \text{not free} \\ \text{free} \\ \text{not free} \\ \text{free} \\ \text{free} \end{matrix}$$

The linear combinations of these three columns give all vectors in the nullspace.

One *Particular* Solution

$$A = \begin{bmatrix} 1 & 3 & 0 & 2 \\ 0 & 0 & 1 & 4 \\ 1 & 3 & 1 & 6 \end{bmatrix} \quad \vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \quad \vec{b} = \begin{bmatrix} 1 \\ 6 \\ 7 \end{bmatrix}$$

$$\left[\begin{array}{cccc|c} 1 & 3 & 0 & 2 & 1 \\ 0 & 0 & 1 & 4 & 6 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] = [R \quad \mathbf{d}]$$

The *free variables* for R to be $x_2 = x_4$.

Then the equations give the *pivot variables* $x_1 = 1 \quad x_3 = 6$

The *particular solution* is: $(1, 0, 6, 0)$

The two special (nullspace) solutions to $Rx = 0$:

$$\left[\begin{array}{cccc|c} 1 & 3 & 0 & 2 & 0 \\ 0 & 0 & 1 & 4 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] \Rightarrow \begin{cases} x_1 + 3x_2 + x_4 = 0 \\ x_3 + 4x_4 = 0 \end{cases}$$

$$\Rightarrow \begin{cases} x_1 = -3x_2 - x_4 \\ x_3 = -4x_4 \end{cases}$$

$$x_2 = 1, \quad x_4 = 0$$

$$\Rightarrow x_1 = -3, \quad x_3 = 0 \rightarrow \underline{(-3, 1, 0, 0)}$$

$$x_2 = 0, \quad x_4 = 1$$

$$\Rightarrow x_1 = -2, \quad x_3 = -4 \rightarrow \underline{(-2, 0, -4, 1)}$$

The *complete solution*:

$$x = x_p + x_n$$

$$= \begin{pmatrix} 1 \\ 0 \\ 6 \\ 0 \end{pmatrix} + x_2 \begin{pmatrix} -3 \\ 1 \\ 0 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} -2 \\ 0 \\ -4 \\ 1 \end{pmatrix}$$

Example

Find the condition on (b_1, b_2, b_3) for $A\vec{x} = \vec{b}$ to be solvable, if

$$A = \begin{bmatrix} 1 & 1 \\ 1 & 2 \\ -2 & -3 \end{bmatrix} \quad \vec{b} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

Solution

The augmented form:

$$\left[\begin{array}{ccc|c} 1 & 1 & b_1 & \\ 1 & 2 & b_2 & \\ -2 & -3 & b_3 & \end{array} \right] \quad \begin{array}{l} \\ R_2 - R_1 \\ R_3 + 2R_1 \end{array}$$

$$\left[\begin{array}{ccc|c} 1 & 1 & b_1 & \\ 0 & 1 & b_2 - b_1 & \\ 0 & -1 & b_3 + 2b_1 & \end{array} \right] \quad \begin{array}{l} R_1 - R_2 \\ \\ R_3 + R_2 \end{array}$$

$$\left[\begin{array}{ccc|c} 1 & 0 & 2b_1 - b_2 & \\ 0 & 1 & b_2 - b_1 & \\ 0 & 0 & b_3 + b_1 + b_2 & \end{array} \right] \rightarrow \underline{b_1 + b_2 + b_3 = 0}$$

The last equation is $0 = 0$ provided $b_1 + b_2 + b_3 = 0$.

There are **no** free variables and **no** special solutions.

The nullspace solution: $x_n = 0$

The complete solution:

$$\begin{aligned} x &= x_p + x_n \\ &= \begin{bmatrix} 2b_1 - b_2 \\ b_2 - b_1 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \end{bmatrix} \end{aligned}$$

If $b_1 + b_2 + b_3 \neq 0$, there is no solution to $A\vec{x} = \vec{b}$ and \vec{x}_p doesn't exist.

Example

a) Find a subset of the vectors

$$\vec{v}_1 = (1, -2, 0, 3) \quad \vec{v}_2 = (2, -5, -3, 6), \quad \vec{v}_3 = (0, 1, 3, 0), \quad \vec{v}_4 = (2, -1, 4, -7), \quad \vec{v}_5 = (5, -8, 1, 2)$$

That forms a basis for the space spanned by these vectors

b) Express each vector not in the basis as a linear combination of the basis vectors

Solution

a) Construct the vectors as its column vectors

$$\begin{bmatrix} 1 & 2 & 0 & 2 & 5 \\ -2 & -5 & 1 & -1 & -8 \\ 0 & -3 & 3 & 4 & 1 \\ 3 & 6 & 0 & -7 & 2 \end{bmatrix} \quad \begin{array}{l} R_2 + 2R_1 \\ R_4 - 3R_1 \end{array}$$

$$\begin{bmatrix} 1 & 2 & 0 & 2 & 5 \\ 0 & -1 & 1 & 3 & 2 \\ 0 & -3 & 3 & 4 & 1 \\ 0 & 0 & 0 & -13 & -13 \end{bmatrix} \quad \begin{array}{l} R_1 + 2R_2 \\ R_3 - 3R_2 \end{array}$$

$$\begin{bmatrix} 5 & 0 & 10 & 0 & 5 \\ 0 & -5 & 5 & 0 & -5 \\ 0 & 0 & 0 & -5 & -5 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \quad \begin{array}{l} \frac{1}{5}R_1 \\ -\frac{1}{5}R_2 \\ -\frac{1}{5}R_3 \end{array}$$

$$\begin{bmatrix} 1 & 0 & 2 & 0 & 1 \\ 0 & 1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$\uparrow \quad \uparrow \quad \uparrow \quad \uparrow \quad \uparrow$
 $\vec{w}_1 \quad \vec{w}_2 \quad \vec{w}_3 \quad \vec{w}_4 \quad \vec{w}_5$

The leading 1's occurs in columns 1, 2, and 4.

$\{\vec{w}_1, \vec{w}_2, \vec{w}_4\}$ is a basis for the column space, and consequently $\{\vec{v}_1, \vec{v}_2, \vec{v}_4\}$

b) $\vec{w}_1 = (1, 0, 0, 0) \quad \vec{w}_2 = (0, 1, 0, 0), \quad \vec{w}_3 = (2, -1, 0, 0)$

$\vec{w}_4 = (0, 0, 1, 0), \quad \vec{w}_5 = (1, 1, 1, 0)$

$$\vec{w}_3 = 2\vec{w}_1 - \vec{w}_2$$

$$\vec{w}_5 = \vec{w}_1 + \vec{w}_2 + \vec{w}_4$$

We call these *dependency equations*

The corresponding relationships are:

$$\vec{v}_3 = 2\vec{v}_1 - \vec{v}_2$$

$$\vec{v}_3 = \vec{v}_1 + \vec{v}_2 + \vec{v}_4$$

Solving $Ax = 0$ by *elimination*

Matrix A is rectangular and we still use the elimination.

1. Forward elimination from A to a triangular U .
2. Back substitution in $Ax = 0$ to find x .

Consider the matrix $A = \begin{bmatrix} 1 & 1 & 2 & 3 \\ 2 & 2 & 8 & 10 \\ 3 & 3 & 10 & 13 \end{bmatrix}$

$$\begin{bmatrix} 1 & 1 & 2 & 3 \\ 2 & 2 & 8 & 10 \\ 3 & 3 & 10 & 13 \end{bmatrix} \begin{array}{l} \\ R_2 - 2R_1 \\ R_3 - 3R_1 \end{array}$$

$$\begin{bmatrix} 1 & 1 & 2 & 3 \\ 0 & 0 & 4 & 4 \\ 0 & 0 & 4 & 4 \end{bmatrix} \begin{array}{l} \\ \\ R_3 - 4R_2 \end{array}$$

Triangular U : $\begin{bmatrix} 1 & 1 & 2 & 3 \\ 0 & 0 & 4 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix}$

P: The *pivot* variables are x_1 and x_3 , since columns 1 and 3 contains pivots.

F: The *free* variables are x_2 and x_4 , since columns 2 and 4 have no pivots.

Special solutions to:

$$\begin{cases} x_1 + x_2 + 2x_3 + 3x_4 = 0 \\ 4x_3 + 4x_4 = 0 \end{cases} \rightarrow \begin{cases} x_1 = -x_2 - x_4 \\ x_3 = -x_4 \end{cases}$$

Complete solution: $x = x_2 \underbrace{\begin{pmatrix} -1 \\ 1 \\ 0 \\ 0 \end{pmatrix}}_{\text{Special}} + x_4 \underbrace{\begin{pmatrix} -1 \\ 0 \\ -1 \\ 1 \end{pmatrix}}_{\text{Special}} = \underbrace{\begin{pmatrix} -x_2 - x_4 \\ x_2 \\ -x_4 \\ x_4 \end{pmatrix}}_{\text{Complete}}$

The special solution are in the nullspace $NS(A)$, and their combinations fill out the whole Nullspace.

Exercises

Section 2.8 – Row and Column Spaces

1. List the row vectors and column vectors of the matrix

$$\begin{bmatrix} 2 & -1 & 0 & 1 \\ 3 & 5 & 7 & -1 \\ 1 & 4 & 2 & 7 \end{bmatrix}$$

- (2 – 4) Express the product $A\vec{x}$ as a linear combination of the column vectors of A .

2. $\begin{bmatrix} 2 & 3 \\ -1 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$

4. $\begin{bmatrix} -3 & 6 & 2 \\ 5 & -4 & 0 \\ 2 & 3 & -1 \\ 1 & 8 & 3 \end{bmatrix} \begin{bmatrix} -1 \\ 2 \\ 5 \end{bmatrix}$

3. $\begin{bmatrix} 4 & 0 & -1 \\ 3 & 6 & 2 \\ 0 & -1 & 4 \end{bmatrix} \begin{bmatrix} -2 \\ 3 \\ 5 \end{bmatrix}$

- (5 – 8) Determine whether \vec{b} is in the column space of A , and if so, express \vec{b} as a linear combination of the column vectors of A .

5. $A = \begin{bmatrix} 1 & 3 \\ 4 & -6 \end{bmatrix}, \vec{b} = \begin{bmatrix} -2 \\ 10 \end{bmatrix}$

7. $A = \begin{bmatrix} 1 & 1 & 2 \\ 1 & 0 & 1 \\ 2 & 1 & 3 \end{bmatrix}, \vec{b} = \begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix}$

6. $A = \begin{bmatrix} 1 & -1 & 1 \\ 9 & 3 & 1 \\ 1 & 1 & 1 \end{bmatrix}, \vec{b} = \begin{bmatrix} 5 \\ 1 \\ -1 \end{bmatrix}$

8. $A = \begin{bmatrix} 1 & 2 & 0 & 1 \\ 0 & 1 & 2 & 1 \\ 1 & 2 & 1 & 3 \\ 0 & 1 & 2 & 2 \end{bmatrix}, \vec{b} = \begin{bmatrix} 4 \\ 3 \\ 5 \\ 7 \end{bmatrix}$

9. Suppose that $x_1 = -1, x_2 = 2, x_3 = 4, x_4 = -3$ is a solution of a nonhomogeneous linear system $A\vec{x} = \vec{b}$ and that the solution set of the homogeneous system $A\vec{x} = \vec{0}$ is given by the formulas $x_1 = -3r + 4s, x_2 = r - s, x_3 = r, x_4 = s$

a) Find a vector form of the general solution of $A\vec{x} = \vec{0}$

b) Find a vector form of the general solution of $A\vec{x} = \vec{b}$

- (10 – 13) Find the vector form of the general solution of the given linear system $A\vec{x} = \vec{b}$; then use that result to find the vector form of the general solution of $A\vec{x} = \vec{0}$.

10. $\begin{cases} x_1 - 3x_2 = 1 \\ 2x_1 - 6x_2 = 2 \end{cases}$

$$11. \begin{cases} x_1 + x_2 + 2x_3 = 5 \\ x_1 + x_3 = -2 \\ 2x_1 + x_2 + 3x_3 = 3 \end{cases}$$

$$12. \begin{cases} x_1 + 2x_2 - 3x_3 + x_4 = 4 \\ -2x_1 + x_2 + 2x_3 + x_4 = -1 \\ -x_1 + 3x_2 - x_3 + 2x_4 = 3 \\ 4x_1 - 7x_2 - 5x_4 = -5 \end{cases}$$

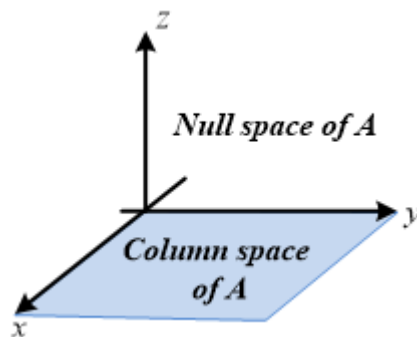
$$13. \begin{cases} x_1 - 2x_2 + x_3 + 2x_4 = -1 \\ 2x_1 - 4x_2 + 2x_3 + 4x_4 = -2 \\ -x_1 + 2x_2 - x_3 - 2x_4 = 1 \\ 3x_1 - 6x_2 + 3x_3 + 6x_4 = -3 \end{cases}$$

14. Given the vectors $\vec{v}_1 = (1, 2, 0)$ and $\vec{v}_2 = (2, 3, 0)$

- Are they linearly independent?
- Are they a basis for any space?
- What space \mathbf{V} do they span?
- What is the dimension of that space?
- What matrices \mathbf{A} have \mathbf{V} as their column space?
- Which matrices have \mathbf{V} as their nullspace?
- Describe all vectors \vec{v}_3 that complete a basis $\vec{v}_1, \vec{v}_2, \vec{v}_3$ for \mathbb{R}^3 .

$$15. a) \text{ Let } A = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Show that relative to an xyz -coordinate system in 3-space the null space of A consists of all points on the z -axis and that the column space consists of all points in the xy -plane.



b) Find a 3×3 matrix whose null space is the x -axis and whose column space is the yz -plane.

16. If we add an extra column \vec{b} to a matrix A , then the column space gets larger unless _____. Give an example where the column space gets larger and an example where it doesn't. Why is $A\vec{x} = \vec{b}$ solvable exactly when the column space doesn't get larger – it is the same for A and $\begin{bmatrix} A & \vec{b} \end{bmatrix}$?
17. For which right sides (find a condition on b_1, b_2, b_3) are these solvable. (Use the column space $C(A)$ and the equation $A\vec{x} = \vec{b}$)
- a)
$$\begin{bmatrix} 1 & 4 & 2 \\ 2 & 8 & 4 \\ -1 & -4 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$
- b)
$$\begin{bmatrix} 1 & 4 \\ 2 & 9 \\ -1 & -4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$
18. Show that the matrices A and $\begin{bmatrix} A & AB \end{bmatrix}$ (with extra columns) have the same column space. But find a square matrix with $C(A^2)$ smaller than $C(A)$. Important point: An n by n matrix has $C(A) = \mathbb{R}^n$ exactly when A is an _____ matrix.
19. The column of AB are combinations of the columns of A . This means: The column space of AB is contained in (possibly equal to) to the column space of A . Give an example where the column spaces A and AB are not equal.
20. Find a square matrix A where $C(A^2)$ (the column space of A^2 is smaller than $C(A)$.
21. Suppose $A\vec{x} = \vec{b}$ and $C\vec{x} = \vec{b}$ have the same (complete) solutions for every \vec{b} . Is true that $A = C$?
22. Apply Gauss-Jordan elimination to $U\vec{x} = 0$ and $U\vec{x} = c$. Reach $R\vec{x} = 0$ and $R\vec{x} = d$:

$$\begin{bmatrix} U & 0 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 & 0 \\ 0 & 0 & 4 & 0 \end{bmatrix} \qquad \begin{bmatrix} U & c \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 & 5 \\ 0 & 0 & 4 & 8 \end{bmatrix}$$

Solve $R\vec{x} = 0$ to find x_n (its free variable is $x_2 = 1$).

Solve $R\vec{x} = d$ to find x_p (its free variable is $x_2 = 0$).

The subspace requirements: $x + y$ and cx (and then all linear combinations $cx + dy$) must stay in the subspace.

23. Which of the following subsets of \mathbb{R}^3 are actually subspaces?

- a) The plane of vectors (b_1, b_2, b_3) with $b_1 = b_2$
- b) The plane of vectors with $b_1 = 1$.
- c) The vectors with $b_1 b_2 b_3 = 0$.
- d) All linear combinations of $v = (1, 4, 0)$ and $w = (2, 2, 2)$.
- e) All vectors that satisfies $b_1 + b_2 + b_3 = 0$
- f) All vectors with $b_1 \leq b_2 \leq b_3$.

24. We are given three different vectors $\vec{b}_1, \vec{b}_2, \vec{b}_3$. Construct a matrix so that the equations $A\vec{x} = \vec{b}_1$ and $A\vec{x} = \vec{b}_2$ are solvable, but $A\vec{x} = \vec{b}_3$ is not solvable.

- a) How can you decide if this possible?
- b) How could you construct A ?

25. For which vectors (b_1, b_2, b_3) do these systems have a solution?

$$a) \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

$$c) \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

$$b) \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

26. Find a basis for the null space of A . $A = \begin{bmatrix} 1 & -3 & 2 & 2 & 1 \\ 0 & 3 & 6 & 0 & -3 \\ 2 & -3 & -2 & 4 & 4 \\ 3 & -6 & 0 & 6 & 5 \\ -2 & 9 & 2 & -4 & -5 \end{bmatrix}$

27. Is it true that is $m = n$ then the row space of A equals the column space.

28. If the row space equals the column space the $A^T = A$

29. If $A^T = -A$, then the row space of A equals the column space.

30. Does the matrices A and $-A$ share the same 4 subspaces?

31. If A and B share the same 4 subspaces then A is multiple of B .
32. Suppose $A\vec{x} = \vec{b}$ & $C\vec{x} = \vec{b}$ have the same (complete) solutions for every \vec{b} . Is it true that $A = C$?
33. A and A^T have the same left nullspace?