## Lecture Two

# **Second Order Differential Equations**

## Section 2.1 – Second-Order Linear Differential Equations

A second order linear differential equation is an equation which can be written in the form

$$y'' + p(x)y' + q(x)y = f(x)$$

Where p, q, and f are continuous functions on some interval I.

The function f(x) is called the *forcing function* or the *nonhomogeneous* term.

The equation is said to be *homogeneous* when:

$$y'' + p(t)y' + q(t)y = 0$$

## Second-Order Equations and Planar Systems

$$y'' = f(t, y, y')$$

Let's re-write in first-order system:

$$y' = v$$
$$v' = F(t, y, v)$$

$$y'' + p(t)y' + q(t)y = F(t)$$

$$y'' = F(t) - p(t)y' - q(t)y$$

$$v' = F(t) - p(t)v - q(t)y$$

$$y' = v$$

$$v' = F(t) - p(t)v - q(t)y$$

### Example

Consider a damped unforced spring: y'' + 0.4y' + 3y = 0; which satisfies the initial conditions y(0) = 2 and v(0) = y'(0) = -1

#### **Solution**

$$\begin{cases} y' = v \\ v' = -0.4v - 3y \end{cases}$$
$$v' + 0.4v = -3y$$

$$ve^{\int 0.4dy} = \int -3ye^{\int 0.4dy} + C$$

$$ve^{0.4y} = -3\int ye^{0.4y} + C$$

$$= -3\frac{e^{0.4y}}{0.4^2}(0.4y - 1) + C$$

$$= -18.75e^{0.4y}(0.4y - 1) + C$$

$$v = -7.5y + 18.75 + Ce^{-0.4y}$$

$$v(0) = -7.5(0) + 18.75 + Ce^{-0.4(0)}$$

$$-1 = 18.75 + C$$

$$C = -19.75$$

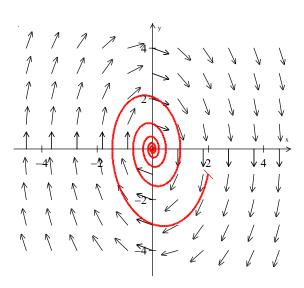
$$v(y) = -7.5y + 18.75 - 19.75e^{-0.4y}$$

$$y' = v = -7.5y + 18.75 - 19.75e^{-0.4y}$$

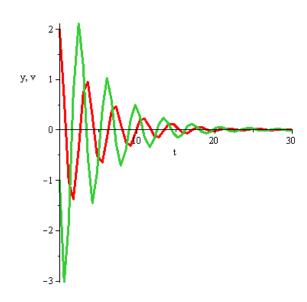
$$\frac{dy}{dt} = -7.5y + 18.75 - 19.75e^{-0.4y}$$

$$y(t) = -\frac{3\sqrt{74}}{74}e^{-t/5}\sin\left(\frac{\sqrt{74}}{5}t\right) + 2e^{-t/5}\cos\left(\frac{\sqrt{74}}{5}t\right)$$

The *yv*-plane is called the *phase plane*.



Phase Plane Plot



 $\int xe^{ax}dx = \frac{e^{ax}}{a^2}(ax-1)$ 

Displacement y and the velocity v

#### **Proposition**

$$y'' + p(t)y' + q(t)y = 0$$

Solutions:  $y = C_1 y_1 + C_2 y_2$ 

 $C_1$ ,  $C_2$  are any constant.

 $y_1(t) & y_2(t)$  are linearly independent solutions forming a *fundamental set of solutions*.

#### Linear

Set 
$$L[y] = y'' + p(t)y' + q(t)y$$

Then, for any two twice differentiable functions  $y_1(t) & y_2(t)$ ,

**Proof** 

$$\begin{split} L\Big[y_{1}(t)\Big] + L\Big[y_{2}(t)\Big] &= y_{1}'' + py_{1}' + qy_{1} + y_{2}'' + py_{2}' + qy_{2} \\ &= y_{1}'' + y_{2}'' + p\Big(y_{1}' + y_{2}'\Big) + q\Big(y_{1} + y_{2}\Big) \\ &= \Big(y_{1} + y_{2}\Big)'' + p\Big(y_{1} + y_{2}\Big)' + q\Big(y_{1} + y_{2}\Big) \\ &= L\Big[y_{1}(t) + y_{2}(t)\Big] \end{split}$$

$$ightharpoonup L[cy(t)] = cL[y(t)]$$

**Proof** 

$$L[cy(t)] = (cy)'' + p(t)(cy)' + q(t)(cy)$$

$$= cy'' + cp(t)y' + cq(t)y$$

$$= c(y'' + p(t)y' + q(t)y)$$

$$= cL[y(t)]$$

That is, L is a linear differential operator.

## **Definition**

A linear combination of the two functions u & v is any function of the form

$$w = Au + Bv$$

### **Definition**

Two functions u & v are said to be linearly independent on the interval  $(\alpha, \beta)$ , if neither is a constant multiple of the order on that interval. If one is a constant multiple of the other on  $(\alpha, \beta)$ , they said to be linearly dependent there.

#### **Existence and Uniqueness for Linear Equations**

#### **Theorem**

Suppose that the functions p, q, and f are continuous on the open interval I containing the point a. Then, given any two numbers  $b_1$  and  $b_2$ , the equation

$$y'' + p(x)y' + q(x)y = f(x)$$

Has a unique solution on the entire interval I that satisfies the initial conditions

$$y(a) = b_1, \quad y'(a) = b_2$$

#### **Example**

Verify that the functions  $y_1(x) = e^x$  and  $y_2(x) = xe^x$  are solutions of the differential equation y'' - 2y' + y = 0 and then find a solution satisfying the initial conditions y(0) = 3, y'(0) = 1

#### **Solution**

$$y(x) = C_1 e^x + C_2 x e^x$$

$$y'(x) = C_1 e^x + C_2 e^x + C_2 x e^x = (C_1 + C_2) e^x + C_2 x e^x$$

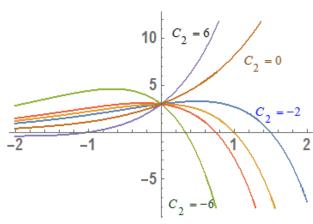
$$y(0) = \underline{C_1 = 3}$$

$$y'(0) = C_1 + C_2 = 1 \implies \underline{C_2 = -2}$$

Hence the solution of the original initial value problem is

$$y(x) = 3e^x - 2xe^x$$

The plot shows several addition solutions of y'' - 2y' + y = 0, all having the same initial value y(0) = 3



### **Linearly Independent (LI) Solutions**

#### **Definition**

Two functions defined on an open interval *I* are said to be *linearly independent* on *I* provided that neither is a constant multiple of the other.

#### **Example**

The following pair functions are linearly independent on the entire real line.

$$f(x) = \sin x$$
 and  $g(x) = \cos x$ 

$$f(x) = e^x$$
 and  $g(x) = e^{-2x}$ 

$$f(x) = x+1$$
 and  $g(x) = x^2$ 

Two functions are said to be *linearly dependent* on an open interval provided that they are not linearly independent there; that is, one of them is a constant multiplication of the other.

#### **Example**

Let 
$$f(x) = \sin 2x$$
 and  $g(x) = \sin x \cos x$ 

Are linearly dependent on any interval because f(x) = 2g(x).

#### Wronskian

The Wronskian is a function named after the Polish mathematician Józef Hoene-Wroński and it is used to determine whether a set of differentiable functions (solutions) is *linearly independent* on a given interval.

$$W(x) = \begin{vmatrix} f_1(x) & f_2(x) & f_n(x) \\ f_1'(x) & f_2'(x) & f_n'(x) \\ f_1^{(n-1)}(x) & f_2^{(n-1)}(x) & f_n^{(n-1)}(x) \end{vmatrix}$$

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$$W = \begin{vmatrix} u & v \\ u' & v' \end{vmatrix} = uv' - vu'$$

If  $W = 0 \implies u \& v$  are linearly dependent.

If  $W \neq 0 \implies u \& v$  are linearly independent.

#### **Theorem**

Suppose that  $y_1$  and  $y_2$  are two solutions of the homogeneous second-order linear equation

$$y'' + p(x)y' + q(x)y = 0$$

On an open interval I on which p and q are continuous

- 1. If  $y_1$  and  $y_2$  are linearly dependent, then  $W(y_1, y_2) \equiv 0$  on I.
- **2.** If  $y_1$  and  $y_2$  are linearly independent, then  $W(y_1, y_2) \neq 0$  at each point of I.

#### **Example**

Use the Wronskian to show that  $\mathbf{f}_1 = x$ ,  $\mathbf{f}_2 = \sin x$  are linearly independence

#### **Solution**

The Wronskian is

$$W(x) = \begin{vmatrix} x & \sin x \\ 1 & \cos x \end{vmatrix} = x \cos x - \sin x \neq 0$$

This function is not identically zero. Thus, the functions are linearly independent.

#### **Example**

Use the Wronskian to show that  $\mathbf{f}_1 = 1$ ,  $\mathbf{f}_2 = e^x$ ,  $\mathbf{f}_3 = e^{2x}$  are linearly independence **Solution** 

The Wronskian is

$$W(x) = \begin{vmatrix} 1 & e^x & e^{2x} \\ 0 & e^x & 2e^{2x} \\ 0 & e^x & 4e^{2x} \end{vmatrix} = e^x 4e^{2x} - 2e^{2x}e^x = 2e^{3x} \neq 0$$

Thus, the functions are linearly independent.

## **Exercises** Section 2.1 – Second-Order Linear Differential Equations

Use the substitution v = y' to write each second-order equation as a system of two first-order differential equation.

1. 
$$y'' + 2y' - 3y = 0$$

2. 
$$y'' + 3y' + 4y = 2\cos 2t$$

3. 
$$y'' + 2y' + 2y = 2\sin 2\pi t$$

**4.** 
$$y'' + \mu(t^2 - 1)y' + y = 0$$

$$5. \quad 4y'' + 4y' + y = 0$$

- 1. Show that the functions  $y_1(x) = e^{-3x}$ ,  $y_2(x) = \cos 2x$ ,  $y_3(x) = \sin 2x$  are linearly independent.
- 2. Determine whether  $\{e^x, xe^x, (x+1)e^x\}$  is a set of linearly independent.

Use the Wronskian to show that are linearly independence

3. 
$$y_1(x) = e^{-3x}, y_2(x) = e^{3x}$$

**4.** 
$$\mathbf{f}_1 = 1$$
,  $\mathbf{f}_2 = e^x$ ,  $\mathbf{f}_3 = e^{2x}$ 

$$5. \quad \left\{ e^x, xe^x, (x+1)e^x \right\}$$

**6.** 
$$y_1(x) = e^{-3x}$$
,  $y_2(x) = \cos 2x$ ,  $y_3(x) = \sin 2x$ 

7. 
$$y_1(x) = e^x$$
,  $y_2(x) = e^{2x}$ ,  $y_3(x) = e^{3x}$ 

8. 
$$y_1(x) = \cos^2 x$$
,  $y_2(x) = \sin^2 x$ ,  $y_3(x) = \sec^2 x$ ,  $y_4(x) = \tan^2 x$ 

Determine whether the functions  $y_1(t)$  and  $y_2(t)$  are linearly dependent on the interval (0, 1)

**9.** 
$$y_1(t) = \cos t \sin t, \quad y_2(t) = \sin 2t$$

12. 
$$y_1(t) = t^2 \cos(\ln t), \quad y_2(t) = t^2 \sin(\ln t)$$

**10.** 
$$y_1(t) = e^{3t}$$
,  $y_2(t) = e^{-4t}$ 

13. 
$$y_1(t) = \tan^2 t - \sec^2 t$$
,  $y_2(t) = 3$ 

**11.** 
$$y_1(t) = te^{2t}$$
,  $y_2(t) = e^{2t}$ 

**14.** 
$$y_1(t) \equiv 0, \quad y_2(t) = e^t$$

Find a particular solution satisfying the given initial conditions

**15.** 
$$y'' - 4y = 0$$
;  $y_1(t) = e^{2t}$ ,  $y_2(t) = 2e^{-2t}$ ;  $y(0) = 1$ ,  $y'(0) = -2$ 

**16.** 
$$y'' - y = 0$$
;  $y_1(t) = 2e^t$ ,  $y_2(t) = e^{-t+3}$ ;  $y(-1) = 1$ ,  $y'(-1) = 0$ 

17. 
$$y'' + y = 0$$
;  $y_1(t) = 0$ ,  $y_2(t) = \sin t$ ;  $y(\frac{\pi}{2}) = 1$ ,  $y'(\frac{\pi}{2}) = 1$ 

**18.** 
$$y'' + y = 0$$
;  $y_1(t) = \cos t$ ,  $y_2(t) = \sin t$ ;  $y(\frac{\pi}{2}) = 1$ ,  $y'(\frac{\pi}{2}) = 1$ 

**19.** 
$$y'' - 4y' + 4y = 0$$
;  $y_1(t) = e^{2t}$ ,  $y_2(t) = te^{2t}$ ;  $y(0) = 2$ ,  $y'(0) = 0$ 

**20.** 
$$2y'' - y' = 0$$
;  $y_1(t) = 1$ ,  $y_2(t) = e^{t/2}$ ;  $y(2) = 0$ ,  $y'(2) = 2$ 

**21.** 
$$y'' - 3y' + 2y = 0$$
;  $y_1(t) = 2e^t$ ,  $y_2(t) = e^{2t}$ ;  $y(-1) = 1$ ,  $y'(-1) = 0$ 

**22.** 
$$ty'' + y' = 0$$
;  $y_1(t) = \ln t$ ,  $y_2(t) = \ln 3t$ ;  $y(3) = 0$ ,  $y'(3) = 3$ 

**23.** 
$$t^2y'' - ty' - 3y = 0$$
;  $y_1(t) = t^3$ ,  $y_2(t) = -\frac{1}{t}$ ;  $y(-1) = 0$ ,  $y'(-1) = -2$   $(t < 0)$ 

**24.** 
$$y'' + \pi^2 y = 0$$
;  $y_1(t) = \sin \pi t + \cos \pi t$ ,  $y_2(t) = \sin \pi t - \cos \pi t$ ;  $y(\frac{1}{2}) = 1$ ,  $y'(\frac{1}{2}) = 0$ 

25. 
$$x^3 y^{(3)} - x^2 y'' + 2xy' - 2y = 0$$
  
 $y(1) = 3, \quad y'(1) = 2, \quad y''(1) = 1$   $y_1(x) = x, \quad y_2(x) = x \ln x, \quad y_3(x) = x^2$ 

**26.** 
$$y^{(3)} + 2y'' - y' - 2y = 0$$
  
 $y(0) = 1, \quad y'(0) = 2, \quad y''(0) = 0$   $y_1(x) = e^x, \quad y_2(x) = e^{-x}, \quad y_3(x) = e^{-2x}$ 

27. 
$$y^{(3)} - 6y'' + 11y' - 6y = 0$$
  
 $y(0) = 0, \quad y'(0) = 0, \quad y''(0) = 3$   $y_1(x) = e^x, \quad y_2(x) = e^{2x}, \quad y_3(x) = e^{3x}$ 

28. 
$$y^{(3)} - 3y'' + 3y' - y = 0$$
  
 $y(0) = 2$ ,  $y'(0) = 0$ ,  $y''(0) = 0$   $y_1(x) = e^x$ ,  $y_2(x) = xe^x$ ,  $y_3(x) = x^2e^x$ 

**29.** 
$$y^{(3)} - 5y'' + 8y' - 4y = 0$$
  
 $y(0) = 1$ ,  $y'(0) = 4$ ,  $y''(0) = 0$   $y_1(x) = e^x$ ,  $y_2(x) = e^{2x}$ ,  $y_3(x) = xe^{2x}$ 

30. 
$$y^{(3)} + 9y'' = 0$$
  
 $y(0) = 3$ ,  $y'(0) = -1$ ,  $y''(0) = 2$   $y_1(x) = 1$ ,  $y_2(x) = \cos 3x$ ,  $y_3(x) = \sin 3x$ 

31. 
$$y^{(3)} - 3y'' + 4y' - 2y = 0$$
  
 $y(0) = 1$ ,  $y'(0) = 0$ ,  $y''(0) = 0$   $y_1(x) = e^x$ ,  $y_2(x) = e^x \cos x$ ,  $y_3(x) = e^x \sin x$ 

32. 
$$x^3 y^{(3)} - 3x^2 y'' + 6xy' - 6y = 0$$
  
 $y(1) = 6, \quad y'(1) = 14, \quad y''(1) = 1$   $y_1(x) = x, \quad y_2(x) = x^2, \quad y_3(x) = x^3$ 

33. 
$$x^3 y^{(3)} + 6x^2 y'' + 4xy' - 4y = 0$$
  
 $y(1) = 1, \quad y'(1) = 5, \quad y''(1) = -11$   $y_1(x) = x, \quad y_2(x) = x^{-2}, \quad y_3(x) = x^{-2} \ln x$ 

**34.** When the values of a solution to a differential equation are specified at two different points, these conditions. (In contrast, initial conditions specify the values of a function and its derivative at the same point). The purpose of this is to show that for boundary value problems there is no existence-uniqueness theorem. Given that every solution to

$$y'' + y = 0$$
 is of the form  $y(t) = c_1 \cos t + c_2 \sin t$ 

Where  $\boldsymbol{c}_1$  and  $\boldsymbol{c}_2$  are arbitrary constants, show that

- a) There is a unique solution to the given differential equation that satisfies the boundary conditions y(0) = 2 and  $y(\frac{\pi}{2}) = 0$
- b) There is no solution to given equation that satisfies y(2) = 0 and  $y(\pi) = 0$
- c) There are infinitely many solution to the given DE equation that satisfy y(0) = 2 and  $y(\pi) = -2$