# Section 2.8 – Row and Column Spaces

### **Definition**

For an  $m \times n$  matrix

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \dots & a_{2n} \\ a_{31} & a_{32} & a_{33} & \dots & a_{3n} \\ \vdots & \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & a_{m3} & \dots & a_{mn} \end{bmatrix}$$

The vectors

$$\vec{v}_{1} = (a_{11}, a_{12}, ..., a_{1n})$$

$$\vec{v}_{2} = (a_{21}, a_{22}, ..., a_{2n})$$

$$\vdots \vdots$$

$$\vec{v}_{m} = (a_{m1}, a_{m2}, ..., a_{mn})$$

In  $\mathbb{R}^n$  that are formed from the rows of *A* are called the *row vectors* of *A*,

The vectors

$$\vec{v}_{1} = \begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{m1} \end{bmatrix} \quad \vec{v}_{2} = \begin{bmatrix} a_{12} \\ a_{22} \\ \vdots \\ a_{m2} \end{bmatrix}, \quad \cdots \quad \vec{v}_{3} = \begin{bmatrix} a_{1n} \\ a_{2n} \\ \vdots \\ a_{mn} \end{bmatrix}$$

In  $\mathbb{R}^m$  that are formed from the columns of A are called the **column vectors** of A.

# **Definition**

If A is  $m \times n$  matrix, then the subspace of  $\mathbb{R}^n$  spanned by the row vectors of A is called the **row space** of A and is denoted by RS(A) or R(A), and the subspace  $\mathbb{R}^m$  spanned by the row vectors of A is called the **column space** of A and is denoted by CS(A) or C(A). The solution space of the homogeneous system of equations Ax = 0, which is a subspace of  $\mathbb{R}^n$ , is called the null space of A.

### The Column Space of A

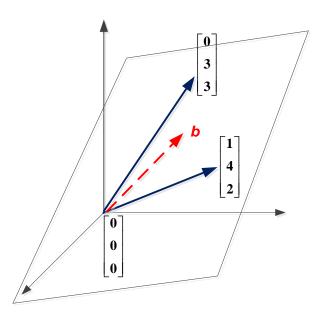
The most important subspaces are tied directly to a matrix A, to solve  $A\vec{x} = b$ .

## **Definition**

The column space consists of all linear combinations of the columns. The combination are all possible vectors Ax. They fill the column space C(A).

$$A = \begin{bmatrix} 1 & 0 \\ 4 & 3 \\ 2 & 3 \end{bmatrix}$$

$$b = x_1 \begin{bmatrix} 1 \\ 4 \\ 2 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 3 \\ 3 \end{bmatrix}$$



To solve  $A\vec{x} = \vec{b}$  is to express b as a combination of the columns.

The column space CS(A) is a plane that containing the two columns.  $A\vec{x} = b$  is solvable when b in on that plane.

#### **Theorem**

The system  $A\vec{x} = b$  is solvable if and only if b is in the column space of A.

# **Example**

Let  $A\vec{x} = b$  be the linear system

$$\begin{bmatrix} -1 & 3 & 2 \\ 1 & 2 & -3 \\ 2 & 1 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ -9 \\ -3 \end{bmatrix}$$

Show that b is in the column space of A by expressing it as a linear combination of the column vectors of A.

#### Solution

$$\begin{bmatrix} -1 & 3 & 2 & 1 \\ 1 & 2 & -3 & -9 \\ 2 & 1 & -2 & -3 \end{bmatrix} \quad \begin{array}{c} R_2 + R_1 \\ R_3 + 2R_1 \end{array}$$

$$\begin{bmatrix} -1 & 3 & 2 & 1 \\ 0 & 5 & -1 & -8 \\ 0 & 7 & 2 & -1 \end{bmatrix} \quad \begin{array}{c} 5R_1 - 3R_2 \\ 5R_3 - 7R_2 \end{array}$$

$$\begin{bmatrix} -5 & 0 & 13 & 29 \\ 0 & 5 & -1 & -8 \\ 0 & 0 & 17 & 51 \end{bmatrix} \quad \begin{array}{c} 17R_1 - 13R_3 \\ 17R_2 + R_3 \end{array}$$

$$\begin{bmatrix} -85 & 0 & 0 & | & -170 \\ 0 & 85 & 0 & | & -85 \\ 0 & 0 & 17 & | & 51 \end{bmatrix} \qquad \frac{-\frac{1}{85}R_1}{\frac{1}{85}R_2}$$

$$\begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 3 \end{bmatrix}$$

That implies to  $x_1 = 2$ ,  $x_2 = -1$ ,  $x_3 = 3$ 

It follows that

$$2\begin{bmatrix} -1\\1\\2\end{bmatrix} - \begin{bmatrix} 3\\2\\1\end{bmatrix} + 3\begin{bmatrix} 2\\-3\\-2\end{bmatrix} = \begin{bmatrix} 1\\-9\\-3\end{bmatrix}$$

## **Example**

Describe the column spaces (they are subspaces of  $\mathbb{R}^2$ ) for

$$I = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \qquad A = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \qquad B = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 4 & 4 \end{bmatrix}$$

#### **Solution**

The column space of I is the whole space  $\mathbb{R}^2$ . Every vector is a combination of the columns of I. In the space language CS(I) is  $\mathbb{R}^2$ .

The column space of A is only a line, the second column (2, 4) is a multiple of the first column (1, 2) and (2, 4) and all other vectors (c, 2c) along that line. The equation  $A\vec{x} = \vec{b}$  is only solvable when  $\vec{b}$  is on the line.

The column space C(B) is all of  $\mathbb{R}^2$ . Every b is attainable. The vector  $\vec{b} = (3, 4)$  is summation of column 1 and 2.

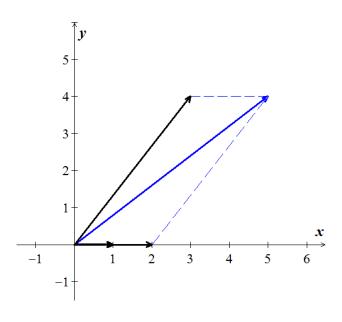
$$\begin{pmatrix}
1 & 2 & 3 \\
0 & 0 & 4
\end{pmatrix} \begin{pmatrix}
x_1 \\
x_2 \\
x_3
\end{pmatrix} = \begin{pmatrix}
5 \\
4
\end{pmatrix}$$

$$\begin{cases}
x_1 + 2x_2 + 3x_3 = 5 \\
4x_3 = 4
\end{cases}$$

$$\Rightarrow \begin{cases}
x_1 + 2x_2 = 2 \\
x_3 = 1
\end{cases}$$

$$\Rightarrow \begin{cases}
x_1 = 0 \\
x_2 = 1
\end{cases}$$
or
$$\Rightarrow \begin{cases}
x_1 = 2 \\
x_2 = 0
\end{cases}$$

$$x = (0, 1, 1) \quad also \quad x = (2, 0, 1)$$



This matrix has the same column as  $\vec{l}$  and any  $\vec{b}$  is allowed.  $\vec{x}$  has an extra component (more solutions).

### **Pivot Columns**

The pivot columns of R have 1's in the pivots and 0's everywhere else.

Pivot columns: 
$$A = \begin{bmatrix} 1 & 3 & 0 & 2 & -1 \\ 0 & 0 & 1 & 4 & -3 \\ 1 & 3 & 1 & 6 & -4 \end{bmatrix}$$
  
Yields to:  $R = \begin{bmatrix} 1 & 3 & 0 & 2 & -1 \\ 0 & 0 & 1 & 4 & -3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$ 

Yields to: 
$$R = \begin{bmatrix} 1 & 3 & 0 & 2 & -1 \\ 0 & 0 & 1 & 4 & -3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

♣ The pivot columns are not combinations of earlier columns. The free columns are combinations of columns which are the special solutions!

# Complete Solution to AX = B

To solve  $A\vec{x} = \vec{b}$ , we need to put into an *augmented* form where  $\vec{b}$  is not zero.

$$A = \begin{bmatrix} 1 & 3 & 0 & 2 \\ 0 & 0 & 1 & 4 \\ 1 & 3 & 1 & 6 \end{bmatrix}$$

$$B = \vec{b} = \begin{bmatrix} 1 \\ 6 \\ 7 \end{bmatrix}$$

$$A\vec{x} = \vec{b}$$

$$\begin{bmatrix} 1 & 3 & 0 & 2 \\ 0 & 0 & 1 & 4 \\ 1 & 3 & 1 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 1 \\ 6 \\ 7 \end{bmatrix}$$

$$X = \vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

The augmented matrix is just  $\begin{bmatrix} A & B \end{bmatrix}$ 

$$\begin{bmatrix} 1 & 3 & 0 & 2 & 1 \\ 0 & 0 & 1 & 4 & 6 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} R & d \end{bmatrix}$$

## **Special Solutions**

Each special solution to  $A\vec{x} = 0$  and  $R\vec{x} = 0$  has one free variable equal to 1.

$$R\vec{x} = \begin{bmatrix} 1 & 3 & 0 & 2 & -1 \\ 0 & 0 & 1 & 4 & -3 \\ 0 & 0 & 0 & 0 & 0 \\ F & F & F \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The *free variables* are  $x_2$ ,  $x_4$ ,  $x_5$ 

$$\rightarrow \begin{cases} x_1 + 3x_2 + 2x_4 - x_5 = 0 \\ x_3 + 4x_4 - 3x_5 = 0 \end{cases}$$

**1.** Set 
$$x_2 = 1$$
,  $x_4 = x_5 = 0 \Rightarrow \begin{cases} x_1 = -3 \\ x_3 = 0 \end{cases}$  (Column 2)

The special solution:  $s_1 = (-3, 1, 0, 0, 0)$ 

**2.** Set 
$$x_4 = 1$$
,  $x_2 = x_5 = 0 \Rightarrow \begin{cases} x_1 = -2 \\ x_3 = -4 \end{cases}$  (Column 4)

The special solution:  $s_2 = (-2, 0, -4, 1, 0)$ 

3. Set 
$$x_5 = 1$$
,  $x_2 = x_4 = 0 \Rightarrow \begin{cases} x_1 = 1 \\ x_3 = 3 \end{cases}$  (Column 5)

The special solution:  $s_3 = (1, 0, 3, 0, 1)$ 

The nullspace matrix N contains the 3 special solutions in its columns.

$$N = \begin{bmatrix} -3 & -2 & 1 \\ 1 & 0 & 0 \\ 0 & -4 & 3 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$
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The linear combinations of these three columns give all vectors in the nullspace.

### One Particular Solution

$$A = \begin{bmatrix} 1 & 3 & 0 & 2 \\ 0 & 0 & 1 & 4 \\ 1 & 3 & 1 & 6 \end{bmatrix} \qquad \vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \quad \vec{b} = \begin{bmatrix} 1 \\ 6 \\ 7 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 3 & 0 & 2 & 1 \\ 0 & 0 & 1 & 4 & 6 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} R & d \end{bmatrix}$$

The *free variables* for *R* to be  $x_2 = x_4$ .

Then the equations give the *pivot variables*  $x_1 = 1$   $x_3 = 6$ 

The *particular solution* is: (1, 0, 6, 0)

The two special (nullspace) solutions to Rx = 0:

$$\begin{bmatrix} 1 & 3 & 0 & 2 & 0 \\ 0 & 0 & 1 & 4 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \Rightarrow \begin{cases} x_1 + 3x_2 + x_4 = 0 \\ \Rightarrow x_3 + 4x_4 = 0 \end{cases}$$

$$\Rightarrow \begin{cases} x_1 = -3x_2 - x_4 \\ x_3 = -4x_4 \end{cases}$$

$$x_2 = 1, x_4 = 0$$
  
 $\Rightarrow x_1 = -3, x_3 = 0 \rightarrow (-3, 1, 0, 0)$ 

$$x_2 = 0, \ x_4 = 1$$
  
 $\Rightarrow x_1 = -2, \ x_3 = -4 \rightarrow (-2, 0, -4, 1)$ 

The *complete solution*:

$$x = x_{p} + x_{n}$$

$$= \begin{pmatrix} 1 \\ 0 \\ 6 \\ 0 \end{pmatrix} + x_{2} \begin{pmatrix} -3 \\ 1 \\ 0 \\ 0 \end{pmatrix} + x_{4} \begin{pmatrix} -2 \\ 0 \\ -4 \\ 1 \end{pmatrix}$$

## Example

Find the condition on  $(b_1, b_2, b_3)$  for  $A\vec{x} = \vec{b}$  to be solvable, if

$$A = \begin{bmatrix} 1 & 1 \\ 1 & 2 \\ -2 & -3 \end{bmatrix} \quad \vec{b} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

#### **Solution**

The augmented form:

$$\begin{bmatrix} 1 & 1 & b_1 \\ 1 & 2 & b_2 \\ -2 & -3 & b_3 \end{bmatrix} \xrightarrow{R_2 - R_1} R_3 + 2R_1$$

$$\begin{bmatrix} 1 & 1 & b_1 \\ 0 & 1 & b_2 - b_1 \\ 0 & -1 & b_3 + 2b_1 \end{bmatrix} \xrightarrow{R_1 - R_2} R_3 + R_2$$

$$\begin{bmatrix} 1 & 0 & 2b_1 - b_2 \\ 0 & 1 & b_2 - b_1 \\ 0 & 0 & b_3 + b_1 + b_2 \end{bmatrix} \xrightarrow{b_1 + b_2 + b_3 = 0}$$

The last equation is 0 = 0 provided  $b_1 + b_2 + b_3 = 0$ .

There are *no* free variables and *no* special solutions.

The nullspace solution:  $x_n = 0$ 

The complete solution:

$$x = x_p + x_n$$

$$= \begin{bmatrix} 2b_1 - b_2 \\ b_2 - b_1 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

If  $b_1 + b_2 + b_3 \neq 0$ , there is no solution to  $A\vec{x} = \vec{b}$  and  $\vec{x}_p$  doesn't exist.

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## **Example**

a) Find a subset of the vectors

$$\vec{v}_1 = (1, -2, 0, 3)$$
  $\vec{v}_2 = (2, -5, -3, 6),$   $\vec{v}_3 = (0, 1, 3, 0),$   $\vec{v}_4 = (2, -1, 4, -7),$   $\vec{v}_5 = (5, -8, 1, 2)$ 

That forms a basis for the space spanned by these vectors

b) Express each vector not in the basis as a linear combination of the basis vectors

#### **Solution**

a) Construct the vectors as its column vectors

$$\begin{bmatrix} 1 & 2 & 0 & 2 & 5 \\ -2 & -5 & 1 & -1 & -8 \\ 0 & -3 & 3 & 4 & 1 \\ 3 & 6 & 0 & -7 & 2 \end{bmatrix} \qquad \begin{matrix} R_2 + 2R_1 \\ R_4 - 3R_1 \end{matrix}$$

$$\begin{bmatrix} 1 & 2 & 0 & 2 & 5 \\ 0 & -1 & 1 & 3 & 2 \\ 0 & -3 & 3 & 4 & 1 \\ 0 & 0 & 0 & -13 & -13 \end{bmatrix} \qquad \begin{matrix} R_1 + 2R_2 \\ R_3 - 3R_2 \end{matrix}$$

$$\begin{bmatrix} 5 & 0 & 10 & 0 & 5 \\ 0 & -5 & 5 & 0 & -5 \\ 0 & 0 & 0 & -5 & -5 \\ 0 & 0 & 0 & 0 & 0 \end{matrix} \qquad \begin{matrix} \frac{1}{5}R_1 \\ -\frac{1}{5}R_2 \\ -\frac{1}{5}R_3 \end{matrix}$$

$$\begin{bmatrix} 1 & 0 & 2 & 0 & 1 \\ 0 & 1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\uparrow \quad \uparrow \quad \uparrow \quad \uparrow \quad \uparrow$$

$$\vec{w}_1 \ \vec{w}_2 \ \vec{w}_3 \ \vec{w}_4 \ \vec{w}_5$$

The leading 1's occurs in columns 1, 2, and 4.

 $\left\{\vec{v}_{1},\ \vec{v}_{2},\ \vec{v}_{4}\right\}$  is a basis for the column space, and consequently  $\left\{\vec{v}_{1},\ \vec{v}_{2},\ \vec{v}_{4}\right\}$ 

**b**) 
$$\vec{w}_1 = (1, 0, 0, 0)$$
  $\vec{w}_2 = (0, 1, 0, 0),$   $\vec{w}_3 = (2, -1, 0, 0)$ 

$$\vec{w}_4 = (0, 0, 1, 0), \quad \vec{w}_5 = (1, 1, 1, 0)$$

$$\vec{w}_3 = 2\vec{w}_1 - \vec{w}_2$$

$$\vec{w}_3 = \vec{w}_1 + \vec{w}_2 + \vec{w}_4$$

# We call these *dependency equations*

The corresponding relationships are:

$$\vec{v}_3 = 2\vec{v}_1 - \vec{v}_2$$

$$\vec{v}_3 = \vec{v}_1 + \vec{v}_2 + \vec{v}_4$$

## **Solving** Ax = 0 by *elimination*

Matrix A is rectangular and we still use the elimination.

- 1. Forward elimnation from A to a triangular U.
- 2. Back substitution in Ax = 0 to find x.

Consider the matrix 
$$A = \begin{bmatrix} 1 & 1 & 2 & 3 \\ 2 & 2 & 8 & 10 \\ 3 & 3 & 10 & 13 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 2 & 3 \\ 2 & 2 & 8 & 10 \\ 3 & 3 & 10 & 13 \end{bmatrix} \quad \begin{array}{c} R_2 - 2R_1 \\ R_3 - 3R_1 \end{array}$$

$$\begin{bmatrix} 1 & 1 & 2 & 3 \\ 0 & 0 & 4 & 4 \\ 0 & 0 & 4 & 4 \end{bmatrix}$$

$$\begin{bmatrix} R_3 - 4R_2 \\ R_3 - 4R_2 \end{bmatrix}$$

*Triangular U*: 
$$\begin{bmatrix} 1 & 1 & 2 & 3 \\ 0 & 0 & 4 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

**P**: The **pivot** variables are  $x_1$  and  $x_3$ , since columns 1 and 3 contains pivots.

**F**: The *free* variables are  $x_2$  and  $x_4$ , since columns 2 and 4 have no pivots.

Special solutions to:

$$\begin{cases} x_1 + x_2 + 2x_3 + 3x_4 = 0 \\ 4x_3 + 4x_4 = 0 \end{cases} \rightarrow \begin{cases} x_1 = -x_2 - x_4 \\ x_3 = -x_4 \end{cases}$$

Complete solution: 
$$x = x_2 \begin{pmatrix} -1 \\ 1 \\ 0 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} -1 \\ 0 \\ -1 \\ 1 \end{pmatrix} = \begin{pmatrix} -x_2 - x_4 \\ x_2 \\ -x_4 \\ x_4 \end{pmatrix}$$

Special Special Complete

The special solution are in the nullspace NS(A), and their combinations fill out the whole Nullspace.

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$$\begin{bmatrix} 2 & -1 & 0 & 1 \\ 3 & 5 & 7 & -1 \\ 1 & 4 & 2 & 7 \end{bmatrix}$$

(2-4) Express the product  $A\vec{x}$  as a linear combination of the column vectors of A.

$$2. \quad \begin{bmatrix} 2 & 3 \\ -1 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

3. 
$$\begin{bmatrix} 4 & 0 & -1 \\ 3 & 6 & 2 \\ 0 & -1 & 4 \end{bmatrix} \begin{bmatrix} -2 \\ 3 \\ 5 \end{bmatrix}$$

4. 
$$\begin{bmatrix} -3 & 6 & 2 \\ 5 & -4 & 0 \\ 2 & 3 & -1 \\ 1 & 8 & 3 \end{bmatrix} \begin{bmatrix} -1 \\ 2 \\ 5 \end{bmatrix}$$

(5 – 8) Determine whether  $\vec{b}$  is in the column space of A, and if so, express  $\vec{b}$  as a linear combination of the column vectors of A.

5. 
$$A = \begin{bmatrix} 1 & 3 \\ 4 & -6 \end{bmatrix}$$
,  $\vec{b} = \begin{bmatrix} -2 \\ 10 \end{bmatrix}$ 

**6.** 
$$A = \begin{bmatrix} 1 & -1 & 1 \\ 9 & 3 & 1 \\ 1 & 1 & 1 \end{bmatrix}, \quad \vec{b} = \begin{bmatrix} 5 \\ 1 \\ -1 \end{bmatrix}$$

7. 
$$A = \begin{bmatrix} 1 & 1 & 2 \\ 1 & 0 & 1 \\ 2 & 1 & 3 \end{bmatrix}$$
  $\vec{b} = \begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix}$ 

8. 
$$A = \begin{bmatrix} 1 & 2 & 0 & 1 \\ 0 & 1 & 2 & 1 \\ 1 & 2 & 1 & 3 \\ 0 & 1 & 2 & 2 \end{bmatrix}, \quad \vec{b} = \begin{bmatrix} 4 \\ 3 \\ 5 \\ 7 \end{bmatrix}$$

9. Suppose that  $x_1 = -1$ ,  $x_2 = 2$ ,  $x_3 = 4$ ,  $x_4 = -3$  is a solution of a nonhomogeneous linear system  $A\vec{x} = \vec{b}$  and that the solution set of the homogeneous system  $A\vec{x} = \vec{0}$  is given by the formulas  $x_1 = -3r + 4s$ ,  $x_2 = r - s$ ,  $x_3 = r$ ,  $x_4 = s$ 

a) Find a vector form of the general solution of  $A\vec{x} = \vec{0}$ 

b) Find a vector form of the general solution of  $A\vec{x} = \vec{b}$ 

(10 – 13) Find the vector form of the general solution of the given linear system  $A\vec{x} = \vec{b}$ ; then use that result to find the vector form of the general solution of  $A\vec{x} = \vec{0}$ .

**10.**  $\begin{cases} x_1 - 3x_2 = 1 \\ 2x_1 - 6x_2 = 2 \end{cases}$ 

11. 
$$\begin{cases} x_1 + x_2 + 2x_3 = 5 \\ x_1 + x_3 = -2 \\ 2x_1 + x_2 + 3x_3 = 3 \end{cases}$$

12. 
$$\begin{cases} x_1 + 2x_2 - 3x_3 + x_4 = 4 \\ -2x_1 + x_2 + 2x_3 + x_4 = -1 \\ -x_1 + 3x_2 - x_3 + 2x_4 = 3 \\ 4x_1 - 7x_2 - 5x_4 = -5 \end{cases}$$

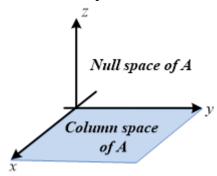
13. 
$$\begin{cases} x_1 - 2x_2 + x_3 + 2x_4 = -1 \\ 2x_1 - 4x_2 + 2x_3 + 4x_4 = -2 \\ -x_1 + 2x_2 - x_3 - 2x_4 = 1 \\ 3x_1 - 6x_2 + 3x_3 + 6x_4 = -3 \end{cases}$$

**14.** Given the vectors 
$$\vec{v}_1 = (1, 2, 0)$$
 and  $\vec{v}_2 = (2, 3, 0)$ 

- a) Are they linearly independent?
- b) Are they a basis for any space?
- c) What space V do they span?
- d) What is the dimension of that space?
- e) What matrices A have V as their column space?
- f) Which matrices have **V** as their nullspace?
- g) Describe all vectors  $\vec{v}_3$  that complete a basis  $\vec{v}_1$ ,  $\vec{v}_2$ ,  $\vec{v}_3$  for  $\mathbb{R}^3$ .

**15.** a) Let 
$$A = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Show that relative to an xyz-coordinate system in 3-space the null space of A consists of all points on the z-axis and that the column space consists of all points in the xy-plane.



b) Find a 3 x 3 matrix whose null space is the x-axis and whose column space is the yz-plane.

- 16. If we add an extra column  $\vec{b}$  to a matrix A, then the column space gets larger unless \_\_\_\_\_. Give an example where the column space gets larger and an example where it doesn't. Why is  $A\vec{x} = \vec{b}$  solvable exactly when the column space doesn't get larger it is the same for A and A and A and A are A and A and A are A are A and A are A are A are A and A are A and A are A and A are A and A are A ar
- 17. For which right sides (find a condition on  $b_1$ ,  $b_2$ ,  $b_3$ ) are these solvable. (Use the column space C(A) and the equation  $A\vec{x} = \vec{b}$ )

a) 
$$\begin{bmatrix} 1 & 4 & 2 \\ 2 & 8 & 4 \\ -1 & -4 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

$$b) \begin{bmatrix} 1 & 4 \\ 2 & 9 \\ -1 & -4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

- **18.** Show that the matrices A and  $\begin{bmatrix} A & AB \end{bmatrix}$  (with extra columns) have the same column space. But find a square matrix with  $C(A^2)$  smaller than C(A). Important point: An n by n matrix has  $C(A) = \mathbb{R}^n$  exactly when A is an \_\_\_\_\_ matrix.
- 19. The column of AB are combinations of the columns of A. This means: The column space of AB is contained in (possibly equal to) to the column space of A. Give an example where the column spaces A and AB are not equal.
- **20.** Find a square matrix A where  $C(A^2)$  (the column space of  $A^2$  is smaller than C(A).
- **21.** Suppose  $A\vec{x} = \vec{b}$  and  $C\vec{x} = \vec{b}$  have the same (complete) solutions for every  $\vec{b}$ . Is true that A = C?
- **22.** Apply Gauss-Jordan elimination to  $U\vec{x} = 0$  and  $U\vec{x} = c$ . Reach  $R\vec{x} = 0$  and  $R\vec{x} = d$ :

$$\begin{bmatrix} U & 0 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 & 0 \\ 0 & 0 & 4 & 0 \end{bmatrix} \qquad \begin{bmatrix} U & c \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 & 5 \\ 0 & 0 & 4 & 8 \end{bmatrix}$$

Solve  $R\vec{x} = 0$  to find  $x_n$  (its free variable is  $x_2 = 1$ ).

Solve  $R\vec{x} = d$  to find  $x_p$  (its free variable is  $x_2 = 0$ ).

The subspace requirements: x + y and cx (and then all linear combinations cx + dy) must stay in the subspace.

- Which of the following subsets of  $\mathbb{R}^3$  are actually subspaces?
  - a) The plane of vectors  $(b_1, b_2, b_3)$  with  $b_1 = b_2$
  - b) The plane of vectors with  $b_1 = 1$ .
  - c) The vectors with  $b_1b_2b_3 = 0$ .
  - d) All linear combinations of v = (1, 4, 0) and w = (2, 2, 2).
  - e) All vectors that satisfies  $b_1 + b_2 + b_3 = 0$
  - f) All vectors with  $b_1 \le b_2 \le b_3$ .
- We are given three different vectors  $\vec{b}_1$ ,  $\vec{b}_2$ ,  $\vec{b}_3$ . Construct a matrix so that the equations  $A\vec{x} = \vec{b}_1$ and  $A\vec{x} = \vec{b}_2$  are solvable, but  $A\vec{x} = \vec{b}_3$  is not solvable.
  - a) How can you decide if this possible?
  - b) How could you construct A?
- For which vectors  $(b_1, b_2, b_3)$  do these systems have a solution?

a) 
$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$
 c) 
$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

$$c) \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

$$b) \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

- $A = \begin{bmatrix} 1 & -3 & 2 & 2 & 1 \\ 0 & 3 & 6 & 0 & -3 \\ 2 & -3 & -2 & 4 & 4 \\ 3 & -6 & 0 & 6 & 5 \\ 2 & 0 & 2 & 4 & 5 \end{bmatrix}$ Find a basis for the null space of *A*.
- Is it true that is m = n then the row space of A equals the column space.
- If the row space equals the column space the  $A^T = A$ 28.
- If  $A^T = -A$ , then the row space of A equals the column space. 29.
- Does the matrices A and -A share the same 4 subspaces?

- **31.** Is *A* and *B* share the same 4 subspaces then *A* is multiple of *B*.
- **32.** Suppose  $A\vec{x} = \vec{b}$  &  $C\vec{x} = \vec{b}$  have the same (complete) solutions for every  $\vec{b}$ . Is it true that A = C
- **33.** A and  $A^T$  have the same left nullspace?