$$\vec{r}_{0}\vec{r} = t\vec{v} \qquad \qquad \vec{r}_{0}(x_{0}, z_{0}) \\
\vec{r}_{0}(x_{0}, z_{0}, z_{0}, z_{0}) \\
\vec{r}_{0}(x_{0}, z_{0}, z_{0}, z_{0}) \\
\vec{r}_{0}(x_{0}, z_{0}, z_{0}, z_{0}, z_{0}) \\
\vec{r}_{0}(x_{0}, z_{0}, z_{0}, z_{0}, z_{0}) \\
\vec{r}_{0}(x_{0}, z_{0}, z_{0}, z_{0}, z_{0}, z_{0}, z_{0}) \\
\vec{r}_{0}(x_{0}, z_{0}, z_{$$

Fr line? 7(-3,2,-3) Q (1,-1,4)

soln $\vec{v} = \overrightarrow{PQ}$ $= 4\vec{c} - 3\vec{j} + 7\vec{k}$ x = -3 + 4t y = 3 + 7t

$$\Sigma(t) = ro + t\bar{v}$$

$$= ro + t |\bar{v}| \frac{\bar{v}}{|\bar{v}|}$$
 and vector
$$= ro + t |\bar{v}| \frac{\bar{v}}{|\bar{v}|}$$
 direction

magnitude speed

$$\vec{v} = \vec{v} + \vec{j} + \vec{k}$$

$$\vec{v} = \vec{v} + \vec{j} + \vec{k}$$

$$\vec{v} = \vec{v} + \vec{j} + \vec{k}$$

$$TH = 0 + t(60) \left(\frac{1 + \hat{j} + \hat{k}}{\sqrt{3}}\right)$$

$$= 20t \sqrt{3}' \left(\hat{i} + \hat{j} + \hat{k}\right)$$

$$\hat{i}(0) = 200 \sqrt{3}' \left(\hat{i} + \hat{j} + \hat{k}\right)$$

$$\left(\tilde{i}(0)\right) = 200 \sqrt{3}' \left(\sqrt{3}\right)$$

$$= 600 \text{ ft}$$

Distance S - Line (7/10) d= 185 xx1 d? 5(1,1,5) - line 7 (1,3,0) プニ<1,-1,2> PS=<0,-2,5 $= \begin{pmatrix} \hat{c} & \hat{j} & \hat{k} \\ 0 & -2 & 5 \\ 1 & -1 & 2 \\ 1 \end{pmatrix}$ $= \hat{c} + 5\hat{j} + 2\hat{k}$ 11+25+4

France in Space

$$\vec{n} = A\vec{i} + B\vec{j} + C\vec{k}$$
 $P(x,y,z)$ $P_0(x_0,y_0,z_0)$
 $\vec{n} \perp P_0 = S$
 $\vec{n} \cdot P_0 = S$
 $\vec{n} \cdot P_0 = S$
 $(A\vec{i} + B\vec{j} + C\vec{k}) \cdot [(x-x_0)\vec{i} + (y-y_0)\vec{j} + (z-z_0)\vec{k}] = S$
 $A(x-x_0) + B(y-y_0) + C(z-z_0) = S$
 $A(x-x_0) + B(y-y_0) + C(z-z_0) = S$
 $A(x+By+Cz=Ax_0+By_0+Cz_0)$
 $A(x+By+Cz=D)$
 $A($

$$\frac{tx}{Point?} = \frac{8}{3} + 2t$$

$$y = -2t$$

$$2 = 1+t$$

$$3(\frac{8}{3} + 2t) + 2(-2t) + 6(1+t) = 6$$

$$8 + 6t - 4t + 6 + 6t = 6$$

$$8t = -8$$

$$t = -11$$

$$x = \frac{8}{3} - 2 = \frac{2}{3}, y = +2, z = 1-1=0$$

Distance from a Pt to applane $d = \left| \overrightarrow{PS} \cdot \frac{\overrightarrow{n}}{|\overrightarrow{n}|} \right|$

 $\frac{EX}{Soln} = \frac{17}{7} \quad \text{and} \quad \begin{cases} (1,1,3) \to 3x + 2y + 6z = 6 \\ (0,0,1) \to 3z + 2f + 6k \end{cases}$ $(0,0,1) \quad (0,3,0) \quad ($

| Control | Cont

v, /v/, a (t) I(t) = 2 cost î + 2 sint j +5 cost l t = 71 V(0=-2 sint 2 + 2 cost j - 10 cost sint k =-2 sint (+2 Cost j -5 sin 2 + k a(t) = -2 cost i - 2 sint j - 10 cos 2 t k /v/= /4 sin2+ +4 cos2+ +25 sin22+ = 1 4 (sin2++ cv52+)+ 25 sin22+ = /4 + 25 sin 2+ $\frac{1}{\sqrt{1 + \frac{7u}{u}}} = -\frac{1}{2} \sin \frac{7u}{u} \hat{i} + 2 \cos \frac{7u}{u} \hat{j} - 5 \sin \frac{7u}{u} \hat{k}$ $= \sqrt{3} \hat{i} + \sqrt{3} \hat{j} + 45 \hat{k}$ 12+2+25

- 1

$$\frac{10}{50 \ln 2} = 2 \ln(t+1) \hat{c} + t^2 \hat{j} + \frac{1}{2} t^2 \hat{k} = 1$$

$$\frac{2}{t+1} \hat{c} + 2 \hat{f} + t \hat{k} \Big|_{t=1}$$

$$= \hat{c} + 2 \hat{j} + \hat{k}$$

$$|\hat{k}| = \sqrt{1 + 4 + 1} = \sqrt{6}$$

$$\hat{a}(t) = -\frac{2}{(t+1)^2} \hat{c} + 2 \hat{j} + \hat{k} \Big|_{t=1}$$

$$= -\frac{1}{2} \hat{c} + 2 \hat{j} + \hat{k}$$

$$\underbrace{Ex} \quad \int (Cost) \, \hat{i} + \hat{j} - 2t \, \hat{k} \right) dt$$

$$= (xint + c_j) \hat{i} + (t + c_i) \, \hat{j} + (-t^2 + c_j) \hat{k}$$

$$= sin + \hat{i} + t + \hat{j} - t^2 \hat{k} + c_i \, \hat{c} + c_i \, \hat{j} + c_j \, \hat{k}$$

$$= xin + \hat{i} + t + \hat{j} - t^2 \hat{k} + c_i$$

$$\hat{c} = c_i + c_i + c_j + c_j \hat{k}$$