

Professor: Fred Houry

1. Find the standard matrix for the operator T defined by the formula

$$a) \quad T(x_1, x_2, x_3, x_4) = (7x_1 + 2x_2 - x_3 + x_4, \quad x_2 + x_3, \quad -x_1)$$

$$b) \quad T(x_1, x_2, x_3) = (2x_1 + x_3, \quad x_1 + x_2 - x_3, \quad x_1 - x_2 + x_3)$$

2. Find the characteristic equation, eigenvalues, and eigenvectors of $\begin{pmatrix} 10 & -9 \\ 4 & -2 \end{pmatrix}$

3. Find the characteristic equation, eigenvalues, and eigenvectors of $\begin{pmatrix} 3 & 1 \\ 1 & 3 \end{pmatrix}$

4. Find the eigenvalues, and eigenvectors of $\begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$

5. Find the characteristic equation, eigenvalues, and eigenvectors of $\begin{pmatrix} 3 & 0 & -5 \\ \frac{1}{5} & -1 & 0 \\ 1 & 1 & -2 \end{pmatrix}$

6. Find the characteristic equation, eigenvalues, and eigenvectors of $\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 2 & -5 & 4 \end{pmatrix}$

7. Find a matrix P that diagonalizes $A = \begin{bmatrix} -1 & 4 & -2 \\ -3 & 4 & 0 \\ -3 & 1 & 3 \end{bmatrix}$

8. Let $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$, determine when A is diagonalizable, not diagonalizable. (Hint: discriminant of the characteristic equation)

9. Show that $A = \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix}$ and $B = \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix}$ are not similar matrices

10. Show that the matrix $A = \begin{bmatrix} 2 & 0 \\ 1 & 2 \end{bmatrix}$ is not diagonalizable

11. Show that the function $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ given the formula

$$T(x_1, x_2, x_3) = (2x_1 - x_2 + x_3, \quad x_2 - 4x_3)$$
 is linear transformation

12. Determine whether the function $T: M_{22} \rightarrow \mathbb{R}$ is linear transformation

$$a) \quad T\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}\right) = 3a - 4b + c - d$$

$$b) \quad T\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}\right) = a^2 + b^2$$

- 13.** Consider the basis $S = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ for R^3 , where $\mathbf{v}_1 = (-2, 1)$ $\mathbf{v}_2 = (1, 3)$ and let $T : R^2 \rightarrow R^3$ be the linear transformation for which

$$T(\mathbf{v}_1) = (-1, 2, 0), \quad T(\mathbf{v}_2) = (0, -3, 5)$$

Find a formula for $T(\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3)$, and then use that formula to compute $T(2, 4, -1)$

Solution

$$1. \quad a) \begin{pmatrix} 7 & 2 & -1 & 1 \\ 0 & 1 & 1 & 0 \\ -1 & 0 & 0 & 0 \end{pmatrix} \quad b) \begin{pmatrix} 2 & 0 & 1 \\ 1 & 1 & -1 \\ 1 & -1 & 1 \end{pmatrix}$$

$$1. \quad \lambda^2 - 8\lambda + 16 \quad \text{Eigenvalue: } \lambda = 4 \quad \text{Eigenvector: } \begin{pmatrix} \frac{3}{2} \\ 1 \end{pmatrix}$$

$$2. \quad \lambda^2 - 6\lambda + 8 \quad \text{Eigenvalue: } \lambda = 2, 4 \quad \text{Eigenvector: } \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$3. \quad \lambda^2 - 1 = 0 \quad \text{Eigenvalue: } \lambda = \pm 1 \quad \text{Eigenvector: } \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$4. \quad -\lambda^3 + 2\lambda = 0 \quad \text{Eigenvalue: } \lambda = 0, \pm\sqrt{2} \quad \text{Eigenvector: } \begin{pmatrix} \frac{5}{3} \\ \frac{1}{3} \\ 1 \end{pmatrix}, \begin{pmatrix} -\frac{5}{\sqrt{2}-3} \\ \frac{1}{7} \frac{3+\sqrt{2}}{1+\sqrt{2}} \\ 1 \end{pmatrix}, \begin{pmatrix} \frac{5}{3+\sqrt{2}} \\ \frac{1}{7} \frac{3-\sqrt{2}}{1-\sqrt{2}} \\ 1 \end{pmatrix}$$

$$5. \quad -\lambda^3 + 4\lambda^2 - 5\lambda + 2 \quad \text{Eigenvalue: } \lambda_{1,2} = 1, \lambda_3 = 2 \quad \text{Eigenvector: } \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \\ 4 \end{pmatrix}$$

$$6. \quad P = \begin{pmatrix} 1 & 2 & 1 \\ 1 & 3 & 3 \\ 1 & 3 & 4 \end{pmatrix}$$

$$7. \quad \text{diagonalizable: } (a-d)^2 + 4bc > 0, \quad \text{not diagonalizable: } (a-d)^2 + 4bc < 0$$

$$8. \quad \det(A) = -3 \neq \det(B) = 3$$

$$9. \quad a) -4 \quad b) -16$$

$$10. \quad (2-\lambda)^2 = 0 \rightarrow \lambda_{1,2} = 2 \text{ repeated eigenvalues therefore is not diagonalizable}$$

$$11. \quad \text{Let } \vec{u} = (u_1, u_2, u_3) \text{ and } \vec{v} = (v_1, v_2, v_3)$$

$$\begin{aligned} T(\mathbf{u} + \mathbf{v}) &= T(u_1 + v_1, u_2 + v_2, u_3 + v_3) \\ &= (2u_1 + 2v_1 - u_2 - v_2 + u_3 + v_3, u_2 + v_2 - 4u_3 - 4v_3) \\ &= (2u_1 - u_2 + u_3, u_2 - 4u_3) + (2v_1 - v_2 + v_3, v_2 - 4v_3) \\ &= T(\mathbf{u}) + T(\mathbf{v}) \end{aligned}$$

$$\begin{aligned}
T(\mathbf{ru}) &= T(ru_1, ru_2, ru_3) \\
&= (2ru_1 - ru_2 + ru_3, ru_2 - 4ru_3) \\
&= r(2u_1 - u_2 + u_3, u_2 - 4u_3) \\
&= rT(\mathbf{u})
\end{aligned}$$

Since $T(\mathbf{u} + \mathbf{v}) = T(\mathbf{u}) + T(\mathbf{v})$ and $T(\mathbf{ru}) = rT(\mathbf{u})$, then function T is a linear transformation.

12.

$$\begin{aligned}
a) \quad T(A + B) &= T \begin{bmatrix} a_1 + a_2 & b_1 + b_2 \\ c_1 + c_2 & d_1 + d_2 \end{bmatrix} \\
&= 3a_1 + 3a_2 - 4b_1 - 4b_2 + c_1 + c_2 - d_1 - d_2 \\
&= (3a_1 - 4b_1 + c_1 - d_1) + (3a_2 - 4b_2 + c_2 - d_2) \\
&= T(A) + T(B) \quad \checkmark
\end{aligned}$$

$$\begin{aligned}
T(kA) &= T \left(k \begin{bmatrix} a_1 & b_1 \\ c_1 & d_1 \end{bmatrix} \right) \\
&= T \left(\begin{bmatrix} ka_1 & kb_1 \\ kc_1 & kd_1 \end{bmatrix} \right) \\
&= 3ka_1 - 4kb_1 + kc_1 - kd_1 \\
&= k(3a_1 - 4b_1 + c_1 - d_1) \\
&= kT(A) \quad \checkmark
\end{aligned}$$

$$\begin{aligned}
b) \quad T(A + B) &= T \begin{bmatrix} a_1 + a_2 & b_1 + b_2 \\ c_1 + c_2 & d_1 + d_2 \end{bmatrix} \\
&= (a_1 + a_2)^2 + (b_1 - b_2)^2 \\
&= a_1^2 + a_2^2 + 2a_1a_2 + b_1^2 + b_2^2 + 2b_1a_2 \\
&= (a_1^2 + b_1^2) + (a_2^2 + b_2^2) + 2a_1a_2 + 2b_1a_2 \\
&= T(A) + T(B) \quad \#
\end{aligned}$$

It is not a linear transformation

$$\begin{aligned}
13. \quad T(x_1, x_2, x_3) &= (-x_1 + 4x_2 - x_3, 5x_1 - 5x_2 - x_3, x_1 + 3x_3) \\
T(2, 4, -1) &= (15, -9, -1)
\end{aligned}$$