

$$10/ \quad S = \{ (x, y) \mid x^2 + y^2 = 0 ; x, y \in \mathbb{R} \}$$

$$x^2 + y^2 = 0 \Rightarrow x = y = 0 \quad (x, y \in \mathbb{R})$$

$$\begin{aligned} \text{a) let } \vec{u} = (x_1, y_1) \quad \ni \quad x_1^2 + y_1^2 = 0 & \quad \text{or } x_1 = y_1 = 0 \\ \vec{v} = (x_2, y_2) \quad \ni \quad x_2^2 + y_2^2 = 0 & \quad x_2 = y_2 = 0 \end{aligned}$$

$$\begin{aligned} \vec{u} + \vec{v} &= (x_1, y_1) + (x_2, y_2) \\ &= (x_1 + x_2, y_1 + y_2) \end{aligned}$$

$$\begin{aligned} \hookrightarrow (x_1 + x_2)^2 + (y_1 + y_2)^2 &= x_1^2 + x_2^2 + 2x_1x_2 \\ &\quad + y_1^2 + y_2^2 + 2y_1y_2 \\ &= (x_1^2 + y_1^2) + (x_2^2 + y_2^2) + 2(x_1x_2 + y_1y_2) \\ &= 0 + 0 + 0 \\ &= 0 \quad \checkmark \end{aligned}$$

S is closed under addition

$$\text{b) let } k \in \mathbb{R}$$

$$\begin{aligned} k\vec{u} &= k(x_1, y_1) \\ &= (kx_1, ky_1) \\ &= (kx_1 + ky_1)^2 \\ &= k^2(x_1^2 + y_1^2 + 2x_1y_1) \quad x_1 = y_1 = 0 \\ &= k^2(0 + 0 + 0) \\ &= 0 \quad \checkmark \end{aligned}$$

S is closed under scalar multiplication.

c) Since S is closed under addition & scalar multiplication, then S is a subspace of \mathbb{R}^2

2.6 Linear Independence (LI)

- Independent vectors (not too many)

Columns of A are L.I. when the only soln to $A\vec{x} = \vec{0}$ is $\vec{x} = \vec{0}$, no other combination

Defns

* A set of 2 or more vectors is linearly dependent if 1 vector in the set is a linear combination of others.

$$\vec{0} = 0\vec{v}_1 + 0\vec{v}_2 + \dots + 0\vec{v}_n$$

* $\vec{v}_1, \vec{v}_2, \vec{v}_3$ L.I. $x_1\vec{v}_1 + x_2\vec{v}_2 + x_3\vec{v}_3 = \vec{0}$
non zero vectors $\boxed{x_1, x_2, x_3 \neq 0}$

* A set of vectors is L.I. if it is not linearly dependent

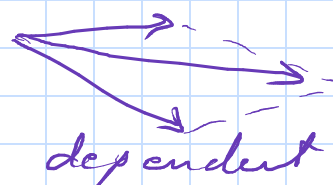
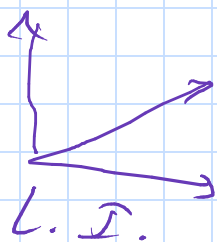
* $\vec{w}_1, \vec{w}_2, \vec{w}_3$ are in the same plane \Rightarrow dependent

* The empty set is L.I. for L. dependent sets must be non empty

$$a\vec{v} = \vec{0} \quad (a \neq 0)$$

$$a^{-1} \cdot a = 1$$

$$\begin{aligned}\vec{v} &= a^{-1} a \vec{v} \\ &= a^{-1} (a\vec{v}) \\ &= a^{-1} \vec{0} \\ &= \vec{0}\end{aligned}$$



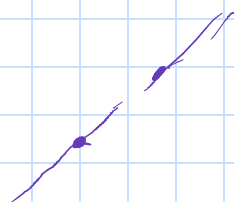
$(1,0), (0,1)$ L.I.

$(1,1), (1, \dots, 0, 0, 1)$ ~~L.I.~~

$(1,1), (2,2)$ Linearly dependent

$$2(1,1) = (2,2)$$

$(1,1), (0,0)$ Linearly dependent



Ex $\vec{N}_1 = (1, -2, 3)$ $\vec{N}_2 = (5, 6, -1)$ $\vec{N}_3 = (3, 2, 1)$

L.I or dependent

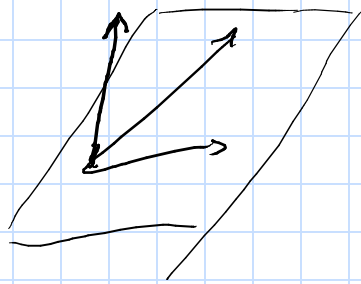
$$\left\{ \begin{array}{l} x_1 \vec{N}_1 + x_2 \vec{N}_2 + x_3 \vec{N}_3 = \vec{0} \quad x_1, x_2, x_3 \neq 0 \\ x_1 \begin{pmatrix} 1 \\ -2 \\ 3 \end{pmatrix} + x_2 \begin{pmatrix} 5 \\ 6 \\ -1 \end{pmatrix} + x_3 \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \\ \begin{array}{l} x_1 + 5x_2 + 3x_3 = 0 \\ -2x_1 + 6x_2 + 2x_3 = 0 \\ 3x_1 - x_2 + x_3 = 0 \end{array} \end{array} \right. \quad \left. \begin{array}{l} \text{indep.} \end{array} \right\}$$

$$A = [\vec{N}_1 \quad \vec{N}_2 \quad \vec{N}_3]$$

$$\det(A) \neq 0 \quad \text{L.I.}$$

$$\begin{vmatrix} 1 & 5 & 3 \\ -2 & 6 & 2 \\ 3 & -1 & 1 \end{vmatrix} = 0$$

$\therefore \vec{N}_1, \vec{N}_2 \text{ \& } \vec{N}_3$ are linearly dependent



Wronskian

$$W = \begin{vmatrix} f_1 & f_2 & \dots & f_n(x) \\ f_1' & f_2' & \dots & f_n' \\ \vdots & \vdots & \ddots & \vdots \\ f_1^{(n-1)} & f_2^{(n-1)} & \dots & f_n^{(n-1)} \end{vmatrix}$$

$$\begin{cases} |W| = 0 & \text{linearly dependent} \\ |W| \neq 0 & \text{L.I.} \end{cases}$$

Ex $f_1 \equiv x$ $f_2 = \sin x$

$$W = \begin{vmatrix} x & \sin x \\ 1 & \cos x \end{vmatrix}$$

$$= x \cos x - \sin x \neq 0$$

(L.I.)

$$f_1 = 1 \quad f_2 = e^x \quad f_3 = e^{2x}$$

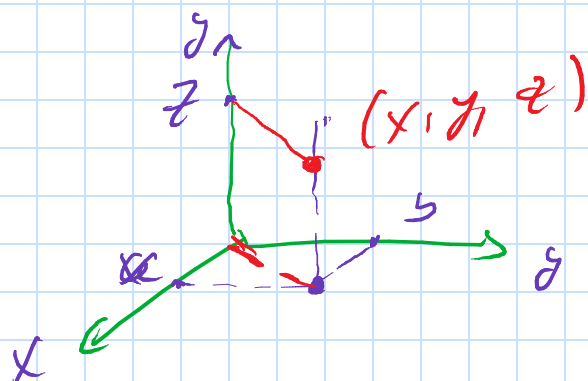
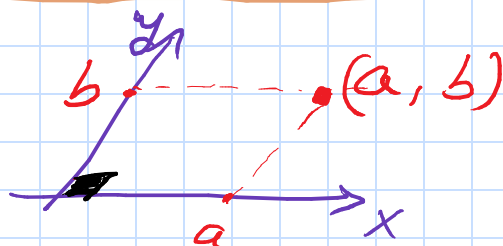
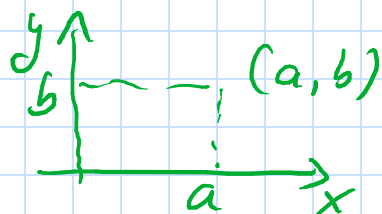
$$W = \begin{vmatrix} 1 & e^x & e^{2x} \\ 0 & e^x & 2e^{2x} \\ 0 & e^x & 4e^{2x} \end{vmatrix}$$

$$= 4e^{3x} - 2e^{3x} = 2e^{3x} \neq 0$$

(L.I.)

Theorem S has a L.I. subset of a vector space V . let \vec{v} be a vector in V that is not in S . Then $S \cup \{\vec{v}\}$ is linearly dependent iff $\vec{v} \in \text{span}(S)$

2.2



Basis if V is any vector space and $S = \{\vec{v}_1, \dots, \vec{v}_n\}$ is a finite set of vectors in V . S is called Basis

$\left\{ \begin{array}{l} S \text{ is L.I.} \\ S \text{ spans } V. \end{array} \right.$

ex

$$\begin{pmatrix} 1 & 2 \\ 2 & 5 \end{pmatrix}$$

Basis

$$A = \begin{pmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \end{pmatrix}$$

Basis

$$2 \times \begin{pmatrix} 1 & 2 \\ 2 & 4 \end{pmatrix}$$

not

All standard unit vectors are Basis

$$\begin{pmatrix} 1 & 2 \\ 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$L.I \Rightarrow n \times n \Rightarrow \det \neq 0$$

n vectors
 n - components

pivot columns of A are Basis for column space

Ex

$$R = \begin{matrix} & \begin{matrix} x_1 & x_2 & x_3 & x_4 \end{matrix} \\ \begin{bmatrix} 1 & 2 & 0 & 3 \\ 0 & 0 & 1 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix} \\ \begin{matrix} \uparrow & & \uparrow & \end{matrix} \end{matrix}$$

Col_n: 1, 3 are pivot columns
Basis for col_n space

col: 2 & 4 are basis \rightarrow

Coordinates Relative to Basis (Uniqueness)

If $S = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$ is a basis for a vector V
every \vec{v}_i in V can be expressed.

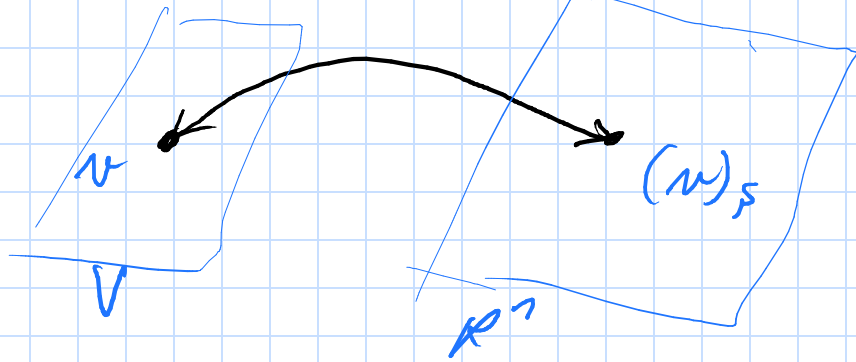
$$\vec{v} = c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_n \vec{v}_n$$

$$\begin{aligned} \vec{v} &= c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_n \vec{v}_n \\ \vec{v} &= k_1 \vec{v}_1 + k_2 \vec{v}_2 + \dots + k_n \vec{v}_n \end{aligned}$$

$$\vec{0} = (c_1 - k_1) \vec{v}_1 + (c_2 - k_2) \vec{v}_2 + \dots + (c_n - k_n) \vec{v}_n$$

$$c_1 - k_1 = 0 \quad c_2 - k_2 = 0 \quad \dots \quad c_n - k_n = 0$$

$$c_1 = k_1 \quad c_2 = k_2 \quad \dots \quad c_n = k_n$$



Ex $\vec{v}_1 = (1, 2, 1)$ $\vec{v}_2 = (2, 9, 0)$ $\vec{v}_3 = (3, 3, 4)$ \mathbb{R}^3

Find coordinate vector $\vec{v} = (5, -1, 9)$ relative to

$$S = \{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$$

$$\vec{v} = c_1 \vec{v}_1 + c_2 \vec{v}_2 + c_3 \vec{v}_3$$

$$(5, -1, 9) = c_1 (1, 2, 1) + c_2 (2, 9, 0) + c_3 (3, 3, 4)$$

$$\begin{cases} c_1 + 2c_2 + 3c_3 = 5 \\ 2c_1 + 9c_2 + 3c_3 = -1 \\ c_1 + 4c_3 = 9 \end{cases} \quad (c_1, c_2, c_3)$$

$$c_1 = 1, c_2 = -1, c_3 = 2$$

$$\therefore (\vec{v})_S = (1, -1, 2)$$

b) $\vec{v} \quad (\vec{v})_S = (-1, 3, 2)$

$$\begin{aligned} \vec{v} &= (-1)\vec{v}_1 + 3\vec{v}_2 + 2\vec{v}_3 \\ &= -(1, 2, 1) + 3(2, 9, 0) + 2(3, 3, 4) \\ &= (11, 31, 7) \end{aligned}$$

Dimension

Dim of a finite-dimensional V is $\dim(V)$ is number of vectors in a basis of V , zero vector space $\Rightarrow \dim = 0$

* $\dim(V) = \# \text{ elts}$ V is finite

$$V = \{ \vec{0} \} \quad \dim(V) = 0$$

$$\dim(V) = \infty$$

$$\dim(\mathbb{R}^n) = n$$

$$\dim(P_n) = n + 1$$

$$\dim(M_{mn}) = mn$$

$$P_3 = \underbrace{a_3 x^3}_{1} + \underbrace{a_2 x^2}_{1} + \underbrace{a_1 x}_{1} + \underbrace{a_0}_{1}$$