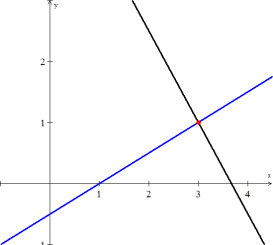
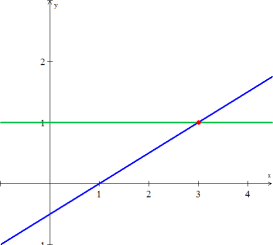
***Section* 1.2 – Gaussian Elimination**

Elimination produces an ***upper triangular system***.



The equation 

This process is called ***back substitution***.

***Before elimination After elimination***

***Definitions***

***Pivot***: first nonzero in the row that does the elimination

***Multiplier***: (entry to eliminate) divide by pivot



The first pivot is 4 (the coefficient of *x*) and the multiplier is 

The pivots are on the diagonal of the triangle after elimination.

***Definition***

The operations are the elementary reduction operations, or row operations, or Gaussian operations. They are swapping, multiplying by a scalar or rescaling, and pivoting.

***Reduced Row Echelon Form***

***Example***

Use the Gaussian elimination method to solve the system



***Solution***

 0 1 2 13

 0 0 1 5

 ⇒ 

(2) ⇒ *y* = 13 − 2*z* = 13 − 2(5) = 3

(3) ⇒ *x* = 19 − *y* − 2*z* = 19 − 3 − 10 = 6

**⇒ (6, 3, 5)**

***Example***

Use Gauss-Jordan elimination to solve the homogeneous linear system



***Solution***











The general solution of the system: 

***Example***

Use Gauss-Jordan elimination to solve the homogeneous linear system



***Solution***





 *Interchange* 





***Solution***: 

***Theorem*: Free Variable Theorem for Homogeneous Systems**

If a *homogeneous linear* system has ***n*** unknowns, and if the reduced row echelon form of its augmented matrix has ***r*** nonzero rows, then the system has *n* − *r* free variables.

***Theorem***

A *homogeneous linear* system with more unknowns than equations has ***infinitely******many*** *unknowns*.

***Breakdown Elimination***

***Permanent failure with no solution***



The last equation ; therefore, there is *no* solution.

This system has no second pivot, since no zero allowed as a pivot.

***Permanent failure with infinitely many solutions***



Every *y* satisfies . There is only one equation .

There are ***unique infinitely*** many solutions.

**Three Equations in Three Unknowns**

To understand Gaussian elimination, you have to go beyond 2 by 2 systems.

Consider the system equations: 







The solution is 

***Definition***

A square matrix is nonsingular if it is the matrix of coefficient of a homogeneous system, with a unique solution. It is singular otherwise, that is, if it is the matrix of coefficients of a homogeneous system, with infinitely many solutions.

***Exercises Section* 1.2 – Gaussian Elimination**

1. When elimination is applied to the matrix 
2. What are the first and second pivots?
3. What is the multiplier in the first step ( times row 1 is subtracted from row 2)?
4. What entry in the 2, 2 position (instead of 9) would force an exchange of rows 2 and 3?
5. What is the multiplier , subtracting 0 times row 1 from row 3?
6. Use elimination to reach upper triangular matrices *U*. Solve by back substitution or explain why this impossible. What are the pivots (never zero)? Exchange equations when necessary. The only difference is the  in equation (3).

1. For which numbers *a* does the elimination break down (1) permanently (2) temporarily



Solve for *x* and *y* after fixing the second breakdown by a row change.

1. Find the pivots and the solution for these four equations:



1. Look for a matrix that has row sums 4 and 8, and column sums 2 and *s*.



The four equations are solvable only if *s* = \_\_\_\_. Then find two different matrices that have the correct row and column sums.

1. Three planes can fail to have an intersection point, even if no planes are parallel. The system is singular if row 3 of *A* is a \_\_\_\_\_\_\_ of the first two rows. Find a third equation that can’t be solved together with  and 

(**7 − 14**) Use the Gauss-Jordan method to solve the system

|  |  |  |
| --- | --- | --- |
|  |  |  |

(**15 − 49**) Use augmented elimination to solve linear system

|  |  |  |
| --- | --- | --- |
|  |  |  |

|  |  |
| --- | --- |
|  |  |

1. Add 3 times the second row to the first of 
2. For what value(s) of *k*, if any, does the system  have
3. A unique solution?
4. Infinitely many solutions?
5. No solution?
6. Choose a coefficient *b* that makes the system singular.



Then choose a right-hand side *g* that makes it solvable.

Find 2 solutions in that singular case.

1. This system us not linear, in some sense,



Does the system have a solution?