

Observation  
(Data)

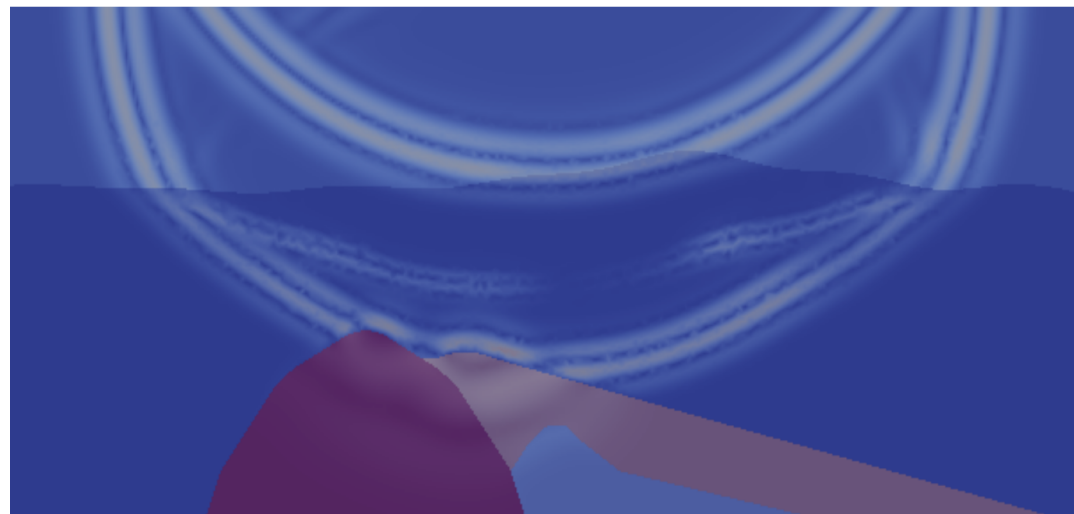
Initial model (m)



Cost function  
( $\mathcal{J}$ )



Direct Problem (m)



Update  
model (m)

