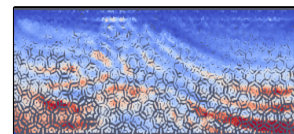
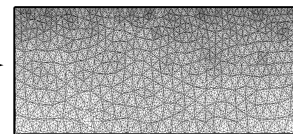


Getting the size map



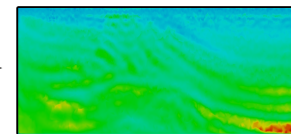
Output model
(point cloud)

triangulation



Intermediate mesh
to adapt

compute
size map



Size Map

Output from FWI
iteration i