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# Piper Jeffries: CS5001 - Homework 2

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## Problem 1 (Single-qubit rotations)

Consider the single-qubit gates given by the following unitaries:

$$V_1 = \frac{1}{2} \begin{pmatrix} 1+i & 1-i \\ 1-i & 1+i \end{pmatrix}, \quad V_2 = \begin{pmatrix} e^{i\pi/4} & 0 \\ 0 & e^{-i\pi/4} \end{pmatrix}$$

- A. Determine the axis of rotation on the Bloch sphere for each unitary.
- B. Calculate the rotation angle (in radians) for each gate.
- C. Briefly explain the reasoning behind your deductions based on the provided matrices.

(A)

For  $V_1$ :

Break  $V_1$  down to pauli matrices.

$$V_1 = \frac{1+i}{2}I + \frac{1-i}{2}X$$

Only X appears therefore, rotation is around X-axis.

For  $V_2$ :

Break  $V_2$  down to pauli matrices.

 $V_2$  is already in standard form for single qubit rotation. Therefore, we can determine axis and angle of rotation from original form.  $V_2$  only has entries in the diagonal, which corresponds to rotation around the Z-axis (B)

For  $V_1$ :

Because it is rotating around the x-axis it can be expressed as:

$$R_X(\theta) = \cos(\frac{\theta}{2})I - i\sin(\frac{\theta}{2})X$$

Therefore, angle of rotation is  $\frac{\theta}{2} = 90^{\circ}$ 

For  $V_2$ :

 $V_2$  represents a rotation of  $\frac{\pi}{2} = 90^{\circ}$  around the Z-axis.

(C)

For  $V_1$ :

 $V_1$  is a rotation of 90° around the X-axis that is because only the X matrix shows up when  $V_1$  is broken down into pauli matrix form. This works because:

$$X = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad I = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$V_1 = \frac{1+i}{2}I + \frac{1-i}{2}X \Rightarrow \frac{1}{2} \begin{pmatrix} 1+i & 0 \\ 0 & 1+i \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 0 & 1-i \\ 1-i & 0 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1+i & 1-i \\ 1-i & 1+i \end{pmatrix}$$
For  $V_2$ :
$$Z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

Rotation around Z-axis is written as:

$$R_z(\theta) = \cos\left(\frac{\theta}{2}\right) I - i\sin\left(\frac{\theta}{2}\right) Z = \begin{pmatrix} \cos(\theta/2) - i\sin(\theta/2) & 0\\ 0 & \cos(\theta/2) + i\sin(\theta/2) \end{pmatrix}$$
$$= \begin{pmatrix} e^{-i\theta/2} & 0\\ 0 & e^{i\theta/2} \end{pmatrix}$$
$$V_2 = \begin{pmatrix} e^{i\pi/4} & 0\\ 0 & e^{-i\pi/4} \end{pmatrix}$$

Comparing with standard form, note there is a sign change, therefore rotation around Z-axis.

To reconcile phase change to standard form need to factor out  $e^{i\pi/2}$ 

This is because we need to adjust the exponents by  $\frac{-\pi}{2}$ , therefore we will get matrix with elements  $e^{\frac{-\pi}{4}}$  and  $e^{\frac{\pi}{4}}$  after factoring out  $e^{\frac{\pi}{2}}$ 

Then comparing with standard form we get,  $\frac{\pi}{2} = \frac{\pi}{4}$ , meaning  $\theta = \frac{\pi}{2} = 90^{\circ}$ Therefore angle of rotation is  $\frac{\pi}{2} = 90^{\circ}$ 

#### Problem 2

Determine the axis and angle of rotation for the two single-qubit unitaries, A and B, such that

$$ABA^{\dagger}B^{\dagger} = \sigma_X$$

 $\sigma_X \Rightarrow$  Pauli-X matrix:  $\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$  Therefore, we know A and B gives us X matrix.

We can rewrite A and B to:

$$ABA^{\dagger}B^{\dagger} = AB(AB)^{\dagger}$$

This shows us AB and  $\sigma_X$  only differ by a unitary transformation Choose A and B as rotations around orthogonal axes.

Let:

A = rotation around Z-axis

B = rotation around Y-axis

We can write these as:

$$A = e^{-i\frac{\theta_A}{2}\sigma_Z}$$
$$B = e^{-i\frac{\theta_B}{2}\sigma_Y}$$

Express A and B as matrices:

For Z-rotation by angle  $\theta_A$ :

$$A = \begin{pmatrix} e^{-i\frac{\theta_A}{2}\sigma_Z} & 0\\ 0 & e^{i\frac{\theta_A}{2}\sigma_Z} \end{pmatrix}$$

For Y-rotation by angle  $\theta_B$ :

$$B = \begin{pmatrix} \cos(\frac{\theta_B}{2}) & -\sin(\frac{\theta_B}{2}) \\ \sin(\frac{\theta_B}{2}) & \cos(\frac{\theta_B}{2}) \end{pmatrix}$$

Next find complex conjugate transpose of A and B ( $A^{\dagger}$  and  $B^{\dagger}$ ):

$$A^{\dagger} = \begin{pmatrix} e^{i\frac{\theta_A}{2}\sigma_Z} & 0\\ 0 & e^{-i\frac{\theta_A}{2}\sigma_Z} \end{pmatrix}$$

$$B^{\dagger} = \begin{pmatrix} \cos(\frac{\theta_B}{2}) & \sin(\frac{\theta_B}{2}) \\ -\sin(\frac{\theta_B}{2}) & \cos(\frac{\theta_B}{2}) \end{pmatrix}$$

Calculate  $ABA^{\dagger}B^{dagger}$ : First, let's calculate AB:

$$AB = \begin{pmatrix} e^{-i\theta_A/2}\cos(\theta_B/2) & -e^{-i\theta_A/2}\sin(\theta_B/2) \\ e^{i\theta_A/2}\sin(\theta_B/2) & e^{i\theta_A/2}\cos(\theta_B/2) \end{pmatrix}$$

Next, calculate  $A^{\dagger}B^{dagger}$ :

$$A^{\dagger}B^{\dagger} = \begin{pmatrix} e^{i\theta_A/2}\cos(\theta_B/2) & e^{i\theta_A/2}\sin(\theta_B/2) \\ -e^{-i\theta_A/2}\sin(\theta_B/2) & e^{-i\theta_A/2}\cos(\theta_B/2) \end{pmatrix}$$

Finally, multiply  $(AB)(A^{\dagger}B^{dagger})$ . Which will give us a complex expression that needs to equal  $\sigma_X$ :

$$ABA^{\dagger}B^{\dagger} = \begin{pmatrix} \cos(\theta_A)\cos(\theta_B) - i\sin(\theta_A)\sin(\theta_B) & \sin(\theta_A)\cos(\theta_B) + i\cos(\theta_A)\sin(\theta_B) \\ \sin(\theta_A)\cos(\theta_B) - i\cos(\theta_A)\sin(\theta_B) & \cos(\theta_A)\cos(\theta_B) + i\sin(\theta_A)\sin(\theta_B) \end{pmatrix}$$

For this result to equal  $\sigma_X = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ 

Diagonal elements must equal 0. Therefore,

$$\cos(\theta_A)\cos(\theta_B) - i\sin(\theta_A)\sin(\theta_B) = 0$$

and

$$\cos(\theta_A)\cos(\theta_B) + i\sin(\theta_A)\sin(\theta_B) = 0$$

The only way for these two equations to be true is if:

$$\cos(\theta A)\cos(\theta B) = 0$$

$$\sin(\theta A)\sin(\theta B) = 0$$

We know that:

$$cos(\theta) = 0$$
when  $\theta = \frac{\pi}{2} + n\pi$ (because of unit circle)

$$\sin(\theta) = 0$$
 when  $\theta = n\pi$ 

(Where n is an integer)

Off diagonal elements must equal 1. Therefore,

$$\sin(\theta_A)\cos(\theta_B) - i\cos(\theta_A)\sin(\theta_B) = 1$$

and

$$\sin(\theta_A)\cos(\theta_B) + i\cos(\theta_A)\sin(\theta_B) = 1$$

If we set  $\theta A = \theta B = \frac{\pi}{2}$  these contraints are satisfied because:

$$\cos(\frac{\pi}{2}) = 0$$

$$\sin(\frac{\pi}{2}) = 1$$

Therefore,

A is a rotation along the Z-axis with a angle of rotation of 90°

B is a rotation along the Y-axis with a angle of rotation of 90°

### Problem 3 (A variation of CHSH game)

If the CHSH game were modified so that Alice and Bob to satisfy  $a \lor b = x \oplus y$  instead, what classical and quantum strategies could they employ, and what would be their maximum winning probabilities?

In the standard CHSH game, Alice and Bob need to satisfy  $a \otimes b = x \cdot y$ In this modified version, they need to satisfy:  $a \vee b = x \oplus y$ 

Where,  $a \lor b$  is the logical OR of their outputs and  $x \oplus y$  is the XOR of their inputs The truth table for  $a \lor b$  is:

$\boldsymbol{x}$	y	$a \lor b$
0	0	0
0	1	1
1	0	1
1	1	1

Table 1: Truth table for  $a \vee b$ 

But in order to satisfy  $a \lor b = x \oplus y$ ,  $a \lor b$  needs to be:

Classical Strategy for Modified CHSH Game Alice's Strategy: (always output 0 no matter input)

- If x = 0, output a = 0
- If x = 1, output a = 0

Bob's Strategy:

$\overline{x}$	y	$x \oplus y$	Required $a \vee b$
0	0	0	0
0	1	1	1
1	0	1	1
1	1	0	0

Table 2: Truth table for the modified CHSH game where  $a \lor b = x \oplus y$ 

- If y = 0, output b = 0
- If y = 1, output b = y (also output 1)

With this strategy:

- When (x, y) = (0,0):  $a \lor b = 0 \lor 0 = 0$ , matches  $x \oplus y = 0$
- When (x, y) = (0,1):  $a \lor b = 0 \lor 1 = 1$ , matches  $x \oplus y = 1 \checkmark$
- When (x, y) = (1,0):  $a \lor b = 0 \lor 0 = 0$ , matches  $x \oplus y = 0 \times 0$
- When (x, y) = (1,1):  $a \lor b = 0 \lor 1 = 1$ , matches  $x \oplus y = 1 \times 1$

This strategy succeeds in 2 out of 4 cases, giving a success probability of 2/4 = 50%

Which is the maximum success rate for a classical approach

#### Quantum Strategy for Modified CHSH Game

In the quantum setting, Alice and Bob can share an entangled quantum state to achieve a higher success probability compared to the classical approach. Setup:

Alice and Bob share the Bell state:

$$|\psi\rangle = (|01\rangle - |10\rangle)/\sqrt{2}$$

Quantum Measurement Strategy:

Alice's Measurements:

- If x = 0; Measure in basis rotated by angle 0 (Z-basis)
- X = 1; Measure in basis rotated by angle  $\frac{\pi}{4}$

Bob's Measurements:

- If y = 0; Measure in basis rotated by angle  $\frac{-\pi}{8}$
- If y = 1; Measure in basis rotated by angle  $\frac{3\pi}{8}$

Alice and Bob both use the mapping:

- Measurement outcome  $+1 \rightarrow$  output 0
- Measurement outcome -1  $\rightarrow$  output 1

Calculate success for each input pair. Where probability of getting the same outcome is  $\cos^2((\theta_a - \theta_\beta)/2)$ :

- 1. (x,y) = (0,0):
  - Measurement angles:  $\theta_a = 0$ ,  $\theta_\beta = \frac{-\pi}{8}$
  - Want:  $a \lor b = 1$  (Meaning at least one output must be 1)
  - Probability of at least +1:  $\cos^2((0-(\frac{-\pi}{8}))/2) = \cos^2(\frac{\pi}{16}) \approx 0.9616$
- 2. (x,y) = (0,1):
  - Measurement angles:  $\theta_a = 0$ ,  $\theta_\beta = \frac{3\pi}{8}$
  - Want:  $a \lor b = 1$  (Meaning at least one output must be 1)
  - Probability of at least -1:  $1 \cos^2((0 (\frac{3\pi}{8}))/2) = 1 \cos^2(\frac{3\pi}{16}) \approx 0.8536$
- 3. (x,y) = (1,0):
  - Measurement angles:  $\theta_a = \frac{\pi}{4}$ ,  $\theta_\beta = \frac{-\pi}{8}$
  - Want:  $a \lor b = 1$  (Meaning at least one output must be 1)
  - Probability of at least -1:  $1 \cos^2((\frac{\pi}{4} (\frac{-\pi}{8}))/2) = 1 \cos^2(\frac{3\pi}{16}) \approx 0.8536$
- 4. (x,y) = (0,0):
  - Measurement angles:  $\theta_a = \frac{\pi}{4}$ ,  $\theta_\beta = \frac{-\pi}{8}$
  - Want:  $a \lor b = 1$  (Meaning at least one output must be 1)
  - Probability of at least +1:  $\cos^2((\frac{\pi}{4} (\frac{-\pi}{8}))/2) = \cos^2(\frac{-\pi}{16}) = \cos^2(\frac{\pi}{16}) \approx 0.9616$

Therefore, average success probability is:

$$\frac{0.9619 + 0.8536 + 0.8536 + 0.9619}{4} \approx 0.9078 \approx 90.87\%$$

The quantum strategy achieves approximately 90.78% success, while the classical approach yields a 50%, demonstrating a quantum advantage for this modified CHSH game.

### Problem 4 (Geometric interpretation of controlled rotations)

Consider the controlled X rotation gate  $C(R_X(\gamma))$  defined as:

$$C(R_X(\gamma)) = |0\rangle\langle 0| \otimes I + |1\rangle\langle 1| \otimes R_X(\gamma),$$

Where  $\gamma \neq \pi$ . Provide a clear geometric interpretation of the effect of this gate on a two-qubit system. Specifically, descrive how the second qubit is rotated on the Bloch sphere depending on the state of the first (control) qubit.

 $R_X(\gamma)$  corresponds to a rotation around the X-axis of the Bloch sphere by angle  $\gamma$ . Which is represented as:

$$R_X(\gamma) = \begin{pmatrix} \cos(\frac{\gamma}{2}) & -i\sin(\frac{\gamma}{2}) \\ -i\sin(\frac{\gamma}{2}) & \cos(\frac{\gamma}{2}) \end{pmatrix}$$

For the controlled version  $C(R_X(\gamma))$ , the geometric interpretation is:

- When the control qubit is  $|0\rangle$ :
  - 1. The operator applies  $|0\rangle\langle 0|\otimes I$
  - 2. This means the second qubit (target) remains unchanged

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3. Qubit remains stationary on Bloch sphere	