

Research notes on metrics for GNNs applied to biological problems

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1 Fundamental concepts

1.1 Graph Laplacian

Given Adjacency matrix A of dimension $n \times n$ and degree matrix D of a given graph G , the graph Laplacian L of G is given by: $L = D - A$. $p_w(L) = w_0 I_n + w_1 L + w_2 L + \dots + w_d L^d = \sum_{i=0}^d w_i L^i$. $p_w(L)$ is $n \times n$.

1.2 ChebNet

$p_w(L) = w_0 I_n + w_1 L + w_2 L + \dots + w_d L^d = \sum_{i=0}^d w_i T_i L^i$ where T_i is the degree- i Chebyshev polynomial of the first kind and \tilde{L} is the normalized Laplacian derived using the largest eigenvalue of L .

L is p.s.d., all eigenvalues of L are > 0 . If $\lambda_{\max}(L) > 1$, then L 's entries increase. \tilde{L} normalizes the eigenvalues of L and bounds them in $[-1, 1]$. \tilde{L} is defined as

$$\tilde{L} = \frac{2L}{\lambda_{\max}(L) - I_n}$$

Embedding computation

1. $h^0 = x$
2. For $k = 1, 2, \dots, K$:
 - (a) $p^{(k)} = p_{w^{(k)}}(L)$
 - (b) $g^{(k)} = p^{(k)} \times h^{k-1}$
 - (c) $h^{(k)} = \sigma(g^{(k)})$

where σ is some non-linearity.

1.3 Modern GNNs

When going back to $p_w(L) = L$, focussing on one verted, we have:

$$\begin{aligned}(Lx)_v &= L_v x \\ &= \sum_{u \in G} L_{vu} x_u \\ &= \sum_{u \in G} (D_{vu} - A_{vu}) x_u \\ &= D_v x_v - \sum_{u \in \mathcal{N}(v)} x_u\end{aligned}$$

This is a 1-hop localized convolution. This does two steps:

- Aggregating over immediate neighbour features x_u .
- Combining with the node's own feature x_v

Ensuring that the agg. is node order equivariant, the overall convolution becomes node-order equivariant. This can be considered as message passing between adjacent nodes. After each step, some nodes receive information from their neighbour.

By iteratively repeating the 1-hop localized convolutions K times (i.e. repeatedly passing messages), the receptive field of the conv. effectively includes all nodes up to K hops away.

Some modern aggregation and combination functions:

- graph convolutional networks (GCN)
- graph attention networks (GAT)
- graph sample and aggregate (GraphSAGE)
- graph isomorphism network (GIN)

1.4 Global convolutions

1.4.1 Spectral convolutions

Smoother graphs have a quantity $R(x) = \sum_{(i,j) \in E} (x_i - x_j)^2$ that reflects that feature vectors x that assign similar values to adjacent nodes in G would have smaller values of $R_L(x)$. L is a real, symmetric matrix which has eigenvalues $\lambda_1 \leq \dots \leq \lambda_n$. Eigenvectors can be taken to be orthonormal.

The set of eigenvalues of L are successively less smooth. They are called the spectrum of L .

The spectral decomp. of L as $L = U\Lambda U^T$ where Λ is the diagonal matrix of sorted eigenvalues, and U denotes the matrix of the eigenvectors. sorted by increasing eigenvalues. Orthonormality between eigenvectors gives us $U^T U = I$. Since each $u \in \mathbb{R}^n$, any x can be represented as a linear combination of these eigenvectors, i.e.:

$$x = \sum_{i=1}^n \tilde{x}_i u_i = U\tilde{x}.$$

where \tilde{x} are the coefficients. Again, the orthonormality of the eigenvalues allows us to state $x = U\tilde{x} \iff U^T x = \tilde{x}$. We can then compute global convolutions, defining:

$$h^{(k)} = \begin{bmatrix} h_1^{(k)} \\ \vdots \\ h_n^{(k)} \end{bmatrix}$$

We start with the original features $h^{(0)} = x$, then

1. $\hat{h}^{(k-1)} = U_m^T h^{(k-1)}$
2. $\hat{g}^{(k)} = \hat{w}^{(k)} \odot \hat{h}^{(k-1)}$
3. $h^{(k)} = \sigma(g^{(k)})$

2 Graph Neural Networks

2.1 Reviews

2.1.1 Graph neural networks:

A review of methods and applications Zhou et al mention several GNN approaches in use today Generative models popular today:

Sequential graph generation process

- GraphRNN - generates the adjacency matrix of a graph by generating the adjacency vector of each node step by step, with graph outputs with different number of nodes.
- Li 2018 - also generates nodes and edges sequentially uses the hidden state to decide what to do at the next step
- GraphAF - also a sequential process, Conducts a validity check of each molecule generated at each step to see if it's valid.

Non-sequential graph generation process

- MolGAN - to generate small molecules. Uses a permutation-invariant to solve the node adjacency matrix at once. Also implements an RL-based optimization toward desired chemical properties
- Ma et al 2018 - constrained VAE for semantic validity of generated graph
- GCPN similar to MolGAN, uses RL based methods to ensure validity of domain-specific rules Example work showing EMD kernel:
- Graph Normalizing Flows

This one has a fairly comprehensive website: <https://sites.google.com/view/graph-normalizing-f>
Full architecture

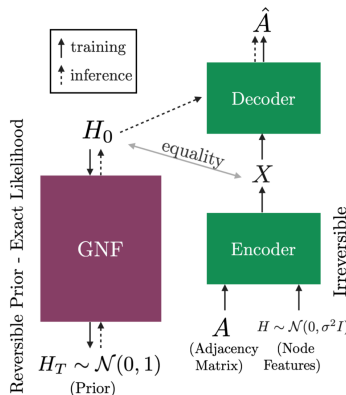


Figure 1: figure name

- Graphite isotropic gaussian for VAE + iterative refinement for decoding

2.2 Three most popular according to O’Bray 2021:

- GraphRNN, GRAN, Graph Score Matching.
- Graph Recurrent Attention Networks

In previous work, You et al. [37] computed degree distributions, clustering coefficient distributions, and the number of occurrence of all orbits with 4 nodes, and then used the maximum mean discrepancy (MMD) over these graph statistics, relying on Gaussian kernels with the first Wasserstein distance, i.e., earth mover’s distance (EMD), in the MMD. In practice, we found computing this MMD with the Gaussian EMD kernel to be very slow for moderately large graphs. Therefore, we use the total variation (TV) distance, which greatly speeds up the evaluation and is still consistent with EMD. In addition to the node

degree, clustering coefficient and orbit counts (used by [36]), we also compare the spectra of the graphs by computing the eigenvalues of the normalized graph Laplacian (quantized to approximate a probability density). This spectral comparison provides a view of the global graph properties, whereas the previous metrics focus on local graph statistics.

- Graph Score Matching On MMD, they say the following:

a common practice of applying Langevin dynamics. We chose the value of the hyper-parameters based on the **MMD** metrics on the validation set, which contains 32 samples from the training set.

$$\tilde{\mathbf{x}}_t \leftarrow \tilde{\mathbf{x}}_{t-1} + \frac{\alpha_i}{2} \mathbf{s}_{\theta}(\tilde{\mathbf{x}}_{t-1}, \sigma_i) + \epsilon_s \sqrt{\alpha_i} \mathbf{z}_t$$

Figure 2: MMD optimization strategy

3 Generative modelling metrics

3.1 Objective:

3.1.1 Generative graph dist close to the input graph dist

3.1.2 (pseudo)-metric to assess dissimilarity between G (generated graphs) and G* (input graphs)

3.2 On images

3.2.1 Frechet Inception Distance

The idea here is to use deeper representational layers of an ANN and used the squared Wasserstein metric to compare two multinomial Gaussians. Introduced 2017

3.2.2 LPIPS Project page

Introduced 2017

3.2.3 Why comparing graphs is hard:

- Metrics need to deal with spatial invariances such as cycles.
- Graph edit distance is NP-hard (Zeng 2009) and therefore does not satisfy efficiency criterion.
- Other publications:

3.3 Desiderata for good metrics:

1. Robust to noise

2. Expressive, if they don't arise from the same dist, then metric should detect this.
3. Computationally efficient.

4 MMD - current accepted method to evaluate generative GNNs

- The MMD formula goes as follows:

$$\text{MMD}(X, Y) := \frac{1}{n^2} \sum_{i,j=1}^n k(x_i, x_j) + \frac{1}{m^2} \sum_{i,j=1}^m k(y_i, y_j) - \frac{2}{nm} \sum_{i=1}^n \sum_{j=1}^m k(y_i, y_j)$$

- use it for hypothesis/two-sample testing.
- In practice, we evaluate $d_{MMD}(\mathcal{G}, \mathcal{G}^*) := MMD(f(\mathcal{G}), f(\mathcal{G}^*))$ for a distribution \mathcal{G} . Given multiple distributions G_1, G_2, \dots , the values of d_{MMD} can be used to rank models, where smaller values are assumed to indicate a larger agreement with the original distribution \mathcal{G}^* .
- Commonly used kernels: first Wasserstein distance, total variation distance, radial basis function.
- Commonly used descriptor functions: degree distribution histogram, clustering coefficient, Laplacian spectrum histogram.
- Recommended kernels: RBF, Laplacian kernel, linear kernel (expressivity & robustness need to be analyzed)

4.1 Potential pitfalls of descriptors

- Degree distributions are ok seemingly
- Clustering does not distinguish fully connected vs disconnected cliques
- Spectral methods are not clearly expressive. Does not seem to be for certain classes of graphs.
- Parameters and descriptors are set a priori in the best case
- Model performance is highly dependent on parameters and descriptor functions.

5 Research objectives

There are multiple objectives here:

1. Find optimal kernel/hyperparameter combination based on controlled experiments on a given dataset to evaluate a good MMD configuration.

- For this we will need <https://www.alphafold.ebi.ac.uk/download>, because it's clean. Also filter single chain proteins to extract graphs in the first place.
 - This can be built as a first step to get the pipeline going.
2. Show which parameters influence evaluation and how?
 - Conduct perturbation experiments on graphs
 3. Find novel domain-agnostic evaluation & domain-specific evaluation metrics
 - (a) Domain-agnostic evaluation measures
 - Correlation with graph-edit distance
 - Correlation with perturbation
 - Topology/persistence based approaches could be useful for modelling features like binding pockets, etc?
 - (b) Domain-specific evaluation measures
 - Alignment
 - Energy?

5.1 From Tim: gather literature sources. Intro structure

5.1.1 Evaluation of generative models (different domains)

5.1.2 Evaluation of generative models for graphs

Check how it was done before, why combo of parameters/kernels were used.

5.1.3 Evaluation of proteins (.../molecules/drugs) (What makes a valid protein?)

5.1.4 Evaluation of generative models for proteins

6 Module-wise breakdown of the plan

- Graph extraction
- Descriptor functions
- kernels, MMD
- Domain agnostic
- Domain specific

- Other metrics
- TDA descriptors
- Labeled edge graph
- NSPDK
- Other metrics
- Extract graph from real datasets

7 References

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