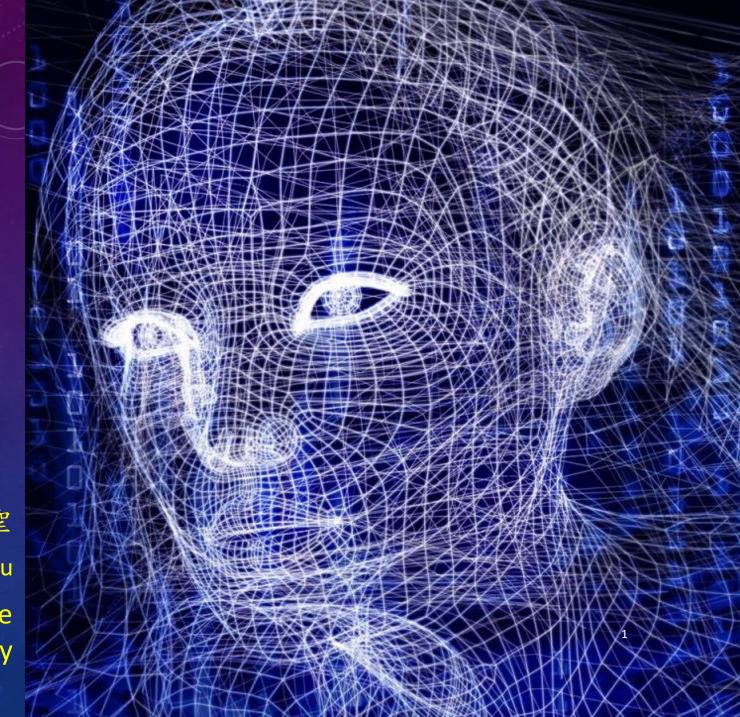


# CH 4 EXERCISE

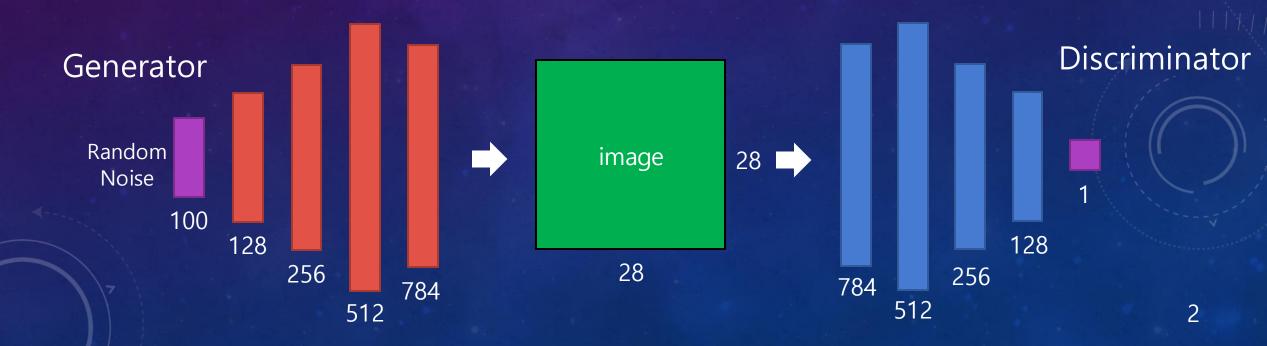
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National Taiwan University of Science and Technology



- Please download the "exercise4.1\_ GAN.ipynb" on Moodle.
- Upload the "exercise4.1\_ GAN.ipynb" to the Google Colab.
- Follow the sample code to understand the data flow of the generative adversarial network.
  - > The generator aims to generate a novel image from a noise input.
  - > The discriminator aims to distinguish the generated image from the real one.



Define the hyper-parameter and load the training data

```
train_epoch = 50
batch_size = 64
noise_size = 100
lr = 2e-4

img_transform = transforms.Compose([
transforms.ToTensor(), transforms.Normalize([0.5], [0.5])])

Download the FashionMNIST dataset to the folder dataset = torchvision.datasets. FashionMNIST(root='./data', train=True, download=True, transform=img_transform)
dataloader = torch.utils.data.DataLoader(dataset, batch_size=batch_size, shuffle=False)
```

Define the generator and discriminator

```
class generator(nn.Module):
   def __init__(self, input_size=100, n_class = 28*28):
      super(generator, self).__init__()
      self.fc1 = nn.Linear(input_size, 256)
      self.fc2 = nn.Linear(self.fc1.out features, 512)
      self.fc3 = nn.Linear(self.fc2.out_features, 1024)
      self.fc4 = nn.Linear(self.fc3.out features, n class)
      self.tanh = nn.Tanh()
   def forward(self, input):
                                             Network
      x = F.leaky_relu(self.fc1(input), 0.2)
                                             Structure of
      x = F.leaky relu(self.fc2(x), 0.2)
                                             the Generator
      x = F.leaky relu(self.fc3(x), 0.2)
      x = self.tanh(self.fc4(x))
      return x
```

```
class discriminator(nn.Module):
  def __init__(self, input_size=28*28, n_class=1):
      super(discriminator, self).__init__()
      self.fc1 = nn.Linear(input_size, 1024)
      self.fc2 = nn.Linear(self.fc1.out_features, 512)
      self.fc3 = nn.Linear(self.fc2.out features, 256)
      self.fc4 = nn.Linear(self.fc3.out_features, n_class)
      self.sigmoid = nn.Sigmoid()
  def forward(self, input):
      x = F.leaky_relu(self.fc1(input), 0.2)
      x = F.dropout(x, 0.3)
                                        Network structure
      x = F.leaky_relu(self.fc2(x), 0.2)
                                        of the discriminator
      x = F.dropout(x, 0.3)
      x = F.leaky_relu(self.fc3(x), 0.2)
      x = F.dropout(x, 0.3)
      x = self.sigmoid(self.fc4(x))
      return x
```

#### Define the loss function

```
G = generator(input size=noise size, n class=28*28)
D = discriminator(input_size=28*28, n_class=1)
                                                        Build a model
if torch.cuda.is_available():
   G.cuda()
   D.cuda()
print(G)
print(D)
BCE_loss = nn.BCELoss()
                                  Use "binary cross-entropy" as loss function
D_optimizer = torch.optim.Adam(D.parameters(), lr=lr, betas=(0.5, 0.999))
G_optimizer = torch.optim.Adam(G.parameters(), lr=lr, betas=(0.5, 0.999))
```

Train the discriminator to determine whether a sample is from the real/fake distribution.

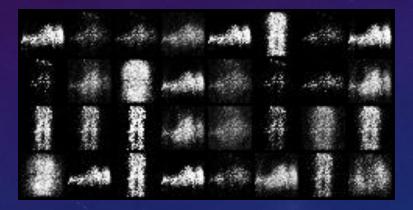
```
# train discriminator D
                                                                   z_{-} = Variable(z_{-})
                                                                   if torch.cuda.is_available():
      D.zero grad()
      x_{-} = x_{-}.view(-1, 28 * 28) \leftarrow Flatten the input images
                                                                       z_{-} = z_{-}.cuda()
                                                                                          Generate the image from the
                                                                   G_{result} = G(z_{result})
      mini batch = x \cdot size()[0]
                                                                                          random noise
      y_real_ = torch.ones(mini_batch)
      y_fake_ = torch.zeros(mini_batch)
                                                                   D result = D(G result)
      x_, y_real_, y_fake_ = Variable(x_),
                                                                   D_fake_loss = BCE_loss(D_result, y_fake_)
     Variable(y_real_), Variable(y_fake_)
                                                                   D fake score = D result
      if torch.cuda.is available():
                                                                   D_train_loss = D_real_loss + D_fake_loss
          x_{-} = x_{-}.cuda()
          y real = y real .cuda()
          y_fake_ = y_fake_.cuda()
                                                                   D train loss.backward()
      D result = D(x)
                                                                   D optimizer.step()
       D_real_loss = BCE_loss(D_result, y_real_)
                                                                            Note that, during training discriminator,
                                                                                 Real input with Label 1
       D_real_score = D_result
                                                                                      Generated input with Label 0
```

Start to training the "generator" G

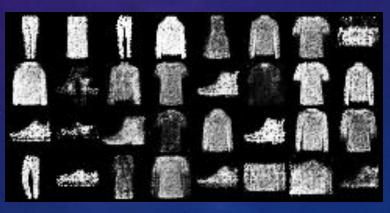
```
# train generator G
       G.zero_grad()
       z_{-} = torch.randn((mini_batch, noise_size)) \leftarrow Generate the noises
       y_ = torch.ones(mini_batch)
       z_{-}, y_{-} = Variable(z_{-}), Variable(y_{-})
       if torch.cuda.is available():
           z_{-} = z_{-}.cuda()
           y_{-} = y_{-}.cuda()
       G_{\text{result}} = G(z_{\text{loc}}) \leftarrow G_{\text{enerate}} the images by the noises
       D result = D(G result)
       G_{train\_loss} = BCE\_loss(D\_result, y_) Note that, during training generator,
                                                                     **Generated input with Label 1
       G_train_loss.backward()
       G optimizer.step()
```

• Result:

Epoch 1:



Epoch 30:



Epoch 50:

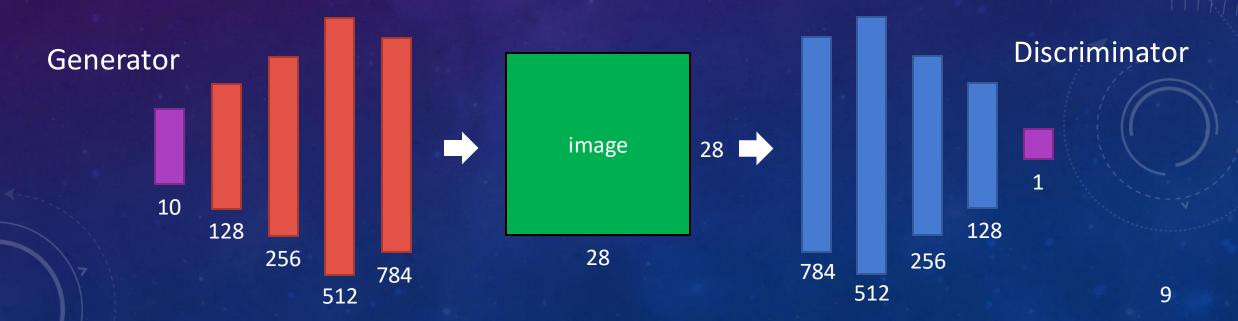


~30 mins

#### **Exercise 4-1: Generative Adversarial Network**

- Please download the "exercise4.1\_ GAN.ipynb" on Moodle.
  - 1. Train the GAN and compare the images reconstructed from different numbers of epochs.
  - 2. Change the learning rate from 0.0002 to 0.002 and compare the images.
  - Change the generator and the discriminator structures to the below architecture and compare the differences of the results.

Please copy your results and code and paste to a MS Word, then upload to Moodle.



- Please download the "exercise4.2\_ StyleGAN.ipynb" on Moodle.
- Upload the "exercise4.2\_ StyleGAN.ipynb" to the Google Colab.
- Follow the sample code to understand the data flow of the StyleGAN.
  - Generator will generate the faces from random noises.
  - Use two random noises to generate the mixing-style image.



```
!wget https://nnabla.org/pretrained-models/nnabla-examples/GANs/stylegan2/styleGAN2_G_params.h5

from generate import *
from IPython.display import Image, display
ctx = get_extension_context("cudnn")
nn.set_default_context(ctx)

Get the stylegan pretrained
num_layers = 18
output_dir = 'results'

nn.load_parameters("styleGAN2_G_params.h5")
```

```
#@markdown Choose the seed for noise input **z**. (This drastically changes the result) latent_seed = 217  #@param {type: "slider", min: 0, max: 1000, step:1}

#@markdown Choose the value for truncation trick.
truncation_psi = 0.5  #@param {type: "slider", min: 0.0, max: 1.0, step: 0.01}

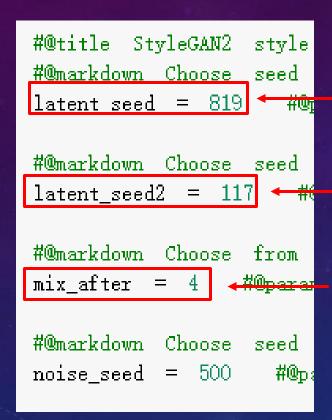
#@markdown Choose the seed for stochasticity input. (This slightly changes the result) noise_seed = 500  #@param {type: "slider", min: 0, max: 1000, step:1}

#@markdown Number of images to generate batch_size = 1  #@param {type: "slider", min: 0, max: 20, step:1}
```

Choose the seed for noises, make the noise fixed each time.

```
rnd = np.random.RandomState(latent_seed)
                                               Generate the noises as the style.
z = rnd.randn(batch_size, 512)
nn.set_auto_forward(True)
                                                Generate the facial image by
                                                given noise
style_noise = nn.NdArray.from_numpy_array(z)
style_noises = [style_noise for _ in range(2)]
rgb_output = generate(batch_size, style_noises, noise_seed, mix_after=7, truncation_psi=truncation_psi
images = convert_images_to_uint8(rgb_output, drange=[-1, 1])
# Display all the images
for i in range(batch_size):
   filename = f'seed{latent_seed}_{i}.png'
   imsave(filename, images[i], channel_first=True)
                                                                                     Output
   display(Image(filename, width=512, height=512))
```

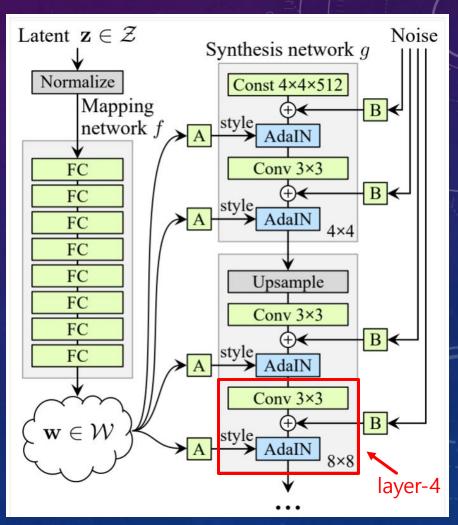
Make mixing-style image



The noise seed for Style-A

The noise seed for Style-B

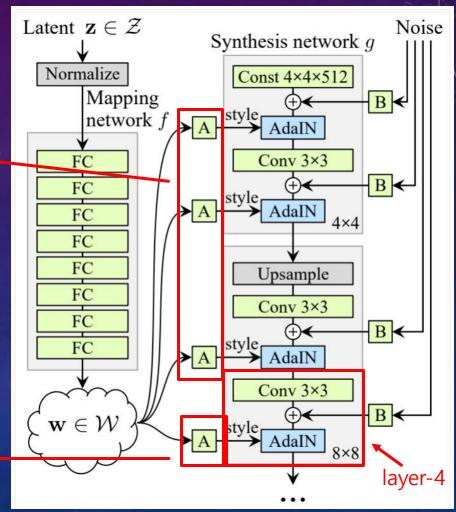
The layer of mixing, Style-A before layer-4, Style-B after layer-4



Make mixing-style image

```
#@title
         StyleGAN2
                    style
#@markdown Choose
                   seed
latent_seed = 819
                     #@1
#@markdown Choose
latent_seed2
#@markdown
           Choose
                    from
mix_after
                   #@parar
#@markdown
          Choose
                    seed
noise_seed
               500
                      #@p:
```

Style-A Style-B



Make mixing-style image

```
#WMSORK COWN
            unoose
                     seed
noise_seed
                       #@#
               500
#@markdown Choose
truncation_psi
#@markdown
            Number
                     ο£
batch_size_A
                       #04
#@markdown Number of
batch_size_B
                       #@1
```

The number of style-A images, it will generate the two noises from style-A random seed, 819.

The number of style-B images, it will generate the four noises from style-B random seed, 117.

Make mixing-style image

```
rnd1 = np.random.RandomState(latent_seed) Use the seed to get the fixed noises

z1 = nn.NdArray.from_numpy_array(rnd1.randn(batch_size_A, 512))

Generate the 512-dimension noises.

rnd2 = np.random.RandomState(latent_seed2) Use the seed to get the fixed noises

z2 = nn.NdArray.from_numpy_array(rnd2.randn(batch_size_B, 512))

nn.set_auto_forward(True)
```

Make mixing-style image

Use for loop to mix the two styles and generate the mixing images

• Make mixing-style image

Generate the style-A image

```
style_noises= [z1, z1] style-A noise
rgb_output = generate(batch_size_A, style_noises, noise_seed, mix_after, truncation_psi)
image_A = convert_images_to_uint8(rgb_output, drange=[-1, 1])
image_A = np.concatenate([image for image in image_A], axis=1)

style_noises = [z2, z2] style-B noise
rgb_output = generate(batch_size_B, style_noises, noise_seed, mix_after, truncation_psi)
image_B = convert_images_to_uint8(rgb_output, drange=[-1, 1])
image_B = np.concatenate([image for image in image_B], axis=2)
```

Generate the style-B image

Make mixing-style image

```
top_image = 255 * np.ones(rgb_output[0].shape).astype(np.uint8)

top_image = np.concatenate((top_image, image_B), axis=2)

grid_image = np.concatenate((image_A, mix_image_stacks), axis=2)

grid_image = np.concatenate((top_image, grid_image), axis=1)

imsave("grid.png", grid_image, channel_first=True)

display(Image("grid.png", width=256*(batch_size_B+1), height=256*(batch_size_A+1)))
```

Make the grid images for visualization

Make mixing-style image

Style-B, seed 117 mixing layer: 4

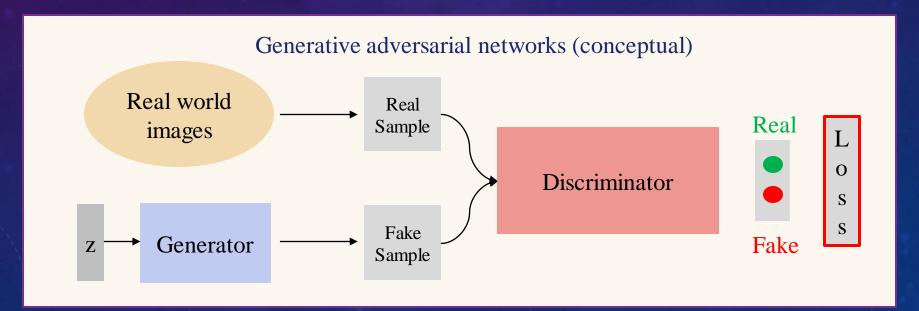


Style-A, seed 819 mixing layer: 4

#### Exercise 4-2: Generate faces from StyleGAN

- Please download the "exercise4.2\_ StyleGAN.ipynb" on Moodle.
- Upload the "exercise4.2\_ StyleGAN.ipynb" to the Google Colab.
- Follow the sample code to understand the data flow of the StyleGAN.
  - Adjust the seed number to generate the different image and record the seed number
  - Use mixing method to generate the images
  - Adjust the mixing layer to generate the synthesized image and observe the change along the layer number.

- Please download the "exercise4.3\_ GAN.ipynb" on Moodle.
- Upload the "exercise4.3\_ GAN.ipynb" to the Google Colab.
- Follow the sample code to understand the data flow of the generative adversarial network.
  - > The generator aims to generate a novel image from a noise input.
  - > The discriminator aims to distinguish the generated image from the real one.
  - Observe the trajectories of the generator loss and discriminator loss



```
train_epoch = 50
batch size = 64
noise size = 100
lr = 2e-4
loss_type = 'non-saturated' #'non-saturated','saturated','wgan','wgan-gp
                                                                             Loss type
img_transform = transforms.Compose([
transforms. ToTensor(), transforms. Normalize([0.5], [0.5])])
|dataset = torchvision.datasets.FashionMNIST(root='./data', train=True, download=True, transform=img_transform)
dataloader = torch.utils.data.DataLoader(dataset, batch_size=batch_size, shuffle=False)
```

We use the structure of previous exercise as the model for training. Refer to Example 4-1

```
class generator (nn. Module):
       # initializers
       def __init__(self, input_size=100, n_class = 28*28):
               super(generator, self).__init ()
               self.fc1 = nn.Linear(input_size, 256)
               self.fc2 = nn.Linear(self.fc1.out features,
                                                            512)
               self.fc3 = nn.Linear(self.fc2.out_features,
                                                            1024)
               self.fc4 = nn.Linear(self.fc3.out_features, n_class)
               self. tanh = nn. Tanh()
       # forward method
       def forward(self, input):
               x = F.leaky_relu(self.fc1(input), 0.2)
               x = F.leaky_relu(self.fc2(x), 0.2)
               x = F.leaky_relu(self.fc3(x), 0.2)
               x = self. tanh(self. fc4(x))
               return x
```

```
class discriminator (nn. Module):
       # initializers
       def __init__(self, input_size=28*28, n_class=1):
               super(discriminator, self).__init__()
               self.fc1 = nn.Linear(input_size, 1024)
               self.fc2 = nn.Linear(self.fc1.out_features,
               self.fc3 = nn.Linear(self.fc2.out_features, 256)
               self.fc4 = nn.Linear(self.fc3.out_features, n_class)
               self.sigmoid = nn.Sigmoid()
       # forward method
       def forward(self, input):
               x = F.leaky_relu(self.fcl(input), 0.2)
               x = F.dropout(x, 0.3)
               x = F.leaky_relu(self.fc2(x), 0.2)
               x = F.dropout(x, 0.3)
               x = F.leaky_relu(self.fc3(x), 0.2)
               x = F.dropout(x, 0.3)
               x = self.sigmoid(self.fc4(x))
               return x
```

#### Loss part:

```
##define the loss function
####saturated loss
def saturated_loss(DG_score):
   G_{loss} = torch.mean(torch.log((1-DG_score) + 1e-8))
   return G loss
###non-saturated
BCE\_loss = nn.BCELoss()
def non saturated loss(D result, y ):
   G loss = BCE loss(D result, y )
   return G loss
####wgan
def wgan (D_real, D_fake):
    loss D = -torch.mean(D real) + torch.mean(D fake)
    loss G = -torch.mean(D fake)
   return loss D, loss G
```

Saturated loss

Non-saturated loss

WGAN loss

Loss part:

```
def wgan gp(D, interpolates, D_real, D_fake, flag):
   if flag = 'D':
       loss = -torch.mean(D_real) + torch.mean(D_fake)
       # wgan = loss.detach()
                                     Wasserstein distance
            = loss
         = D(interpolates)
                                  Find the discriminator's gradients
       # print(x.shape)
       gradients = autograd.grad(outputs=x.sum(), inputs=interpolates,
                                 create_graph=True)[0]
       gradients = gradients.view(gradients.size(0), -1)
       gradient\_penalty = ((gradients.norm(2, dim=1) - 1) ** 2).mean()
                                                 Gradient penalty
       loss += 10*gradient_penalty
       return loss, wgan, (gradients.norm(2, dim=1)).mean()
   if flag = 'G':
           = -D_fake.mean()
       return loss
```

training part, using non-saturated loss:

```
D_{result_real} = D(x_)
D_real_score = D_result_real
    = torch.randn((mini_batch, noise_size))
z_{-} = Variable(z_{-})
if torch.cuda.is_available():
        z_{\perp} = z_{\perp}.cuda()
G_{result} = G(z_{result})
D_result_fake = D(G_result)
D_fake_score = D_result_fake
```

```
D_real_loss = BCE_loss(D_result_real, y_real_)
D_fake_loss = BCE_loss(D_result_fake, y_fake_)
D_train_loss = D_real_loss + D_fake_loss
```

Compute the non-saturated GAN loss for updating the discriminator

```
D_train_loss.backward()
D_optimizer.step()
D_losses.append(D_train_loss.data)
```

Generate the image from the random noise.

Remember to clear the gradient first after updating the discriminator

```
G. zero_grad()
         torch.randn((mini batch, noise size))
     = torch.ones((mini_batch, 1))
z_{-}, y_{-} = Variable(z_{-}), Variable(y_{-})
if torch.cuda.is_available():
          z_{\perp} = z_{\perp}. \operatorname{cuda}()
          y_{\perp} = y_{\perp}. \operatorname{cuda}()
G result = G(z)
D_result_fake = D(G_result)
```

```
D_fake_loss = BCE_loss(D_result_fake, y_real_)
G_train_loss = D_fake_loss
```

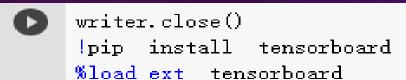
Compute the non-saturated GAN loss for updating the generator

```
G_train_loss.backward()
G_optimizer.step()

G_losses.append(G_train_loss.data)

writer.add_scalar("D_Loss/train", D_train_loss, step)
writer.add_scalar("G_Loss/train", G_train_loss, step)
```

Use tensorboard to record the loss

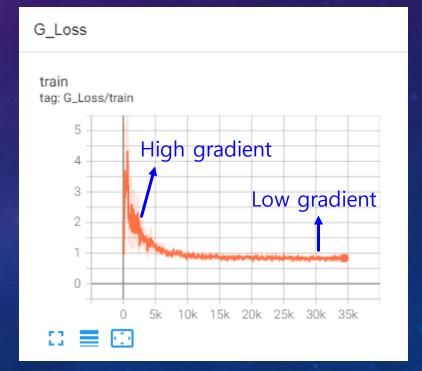


%tensorboard —logdir=runs

Show the tensorboard on the Colab.

#### Non-saturated loss trajectory





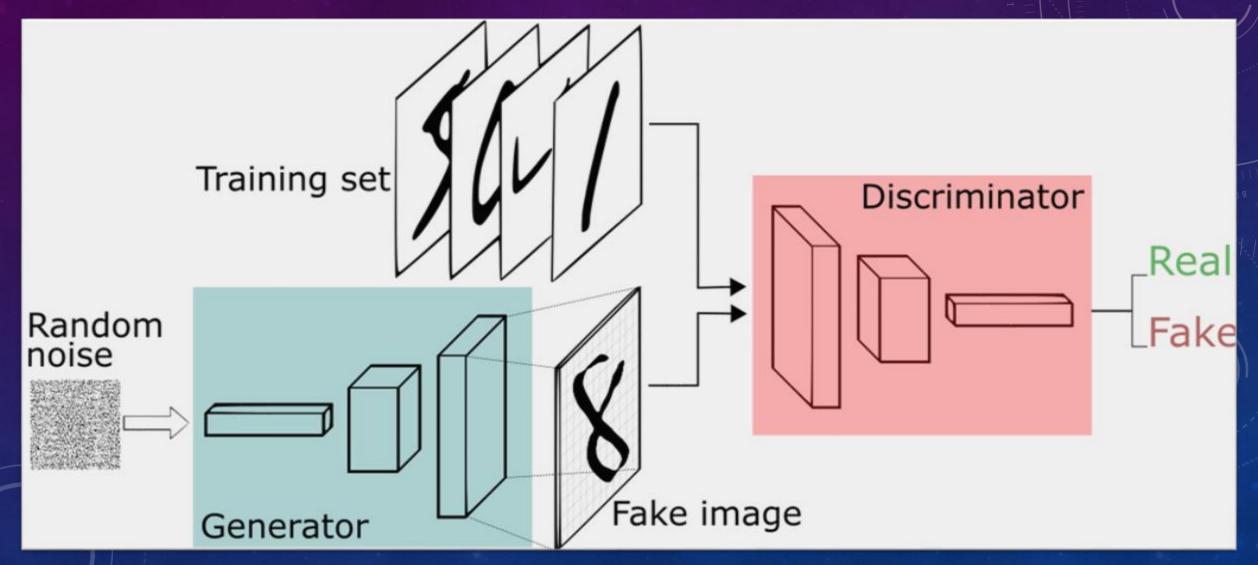
#### Exercise 4-3: Adversarial Loss Function

- Please download the "exercise4.3\_ GAN.ipynb" on Moodle.
- Upload the "exercise4.3\_ GAN.ipynb" to the Google Colab.
- Follow the sample code to understand the data flow of the generative adversarial network.
  - Compare the training results by using "wgan", "wgan-gp", "saturated loss", and "non-saturated loss".
  - Observe the trajectories of the generator loss and discriminator loss





# Let's Try DCGAN By Ourselves: Example 6 Simple GAN Training On Fashion-MNIST



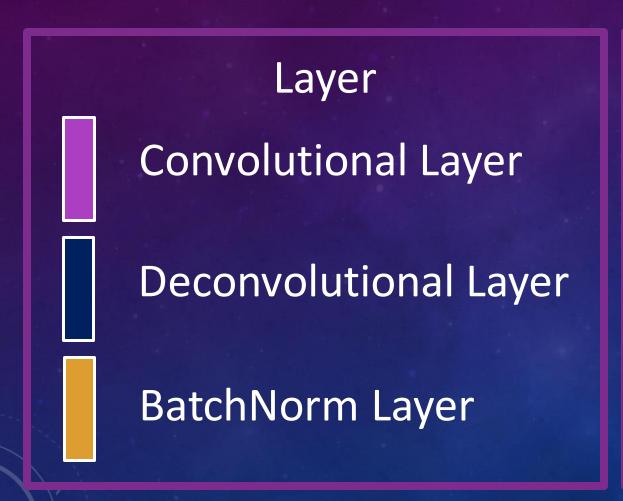
#### Hyper Parameters and training Data

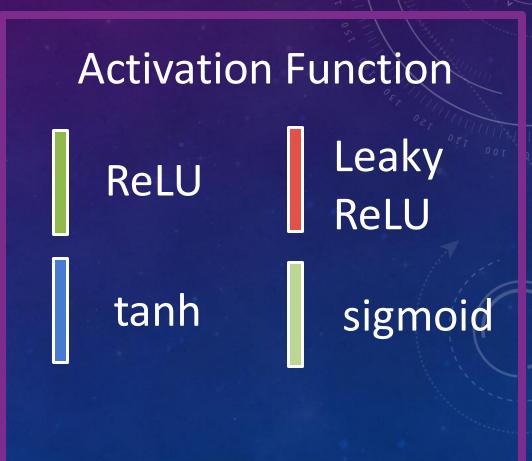
```
img size = 32
train epoch = 5
                            Define the hyperparameters
batch_size = 128
noise size = 100
Ir = 2e-4
experiment_name= 'KL_Loss_Batch_Norm' Give your experiment a describing name
experiment_path='./gan_img/{}'.format(experiment_name)
if not os.path.exists(experiment_path):
  os.mkdir(experiment path)
img transform = transforms.Compose([
transforms.Resize(img_size), transforms.ToTensor(), transforms.Normalize([0.5], [0.5])])
                                                     Download the Mnist dataset to the folder './data'
dataset = torchvision.datasets.FashionMNIST(root='./data', train=True, download=True,
transform=img transform)
dataloader = torch.utils.data.DataLoader(dataset, batch_size=batch_size, shuffle=False)
```

# Function for initialization of weights as a Gaussian distribution with mean and standard deviation

You can later change the mean and std to play around with the initialization of your weights

#### Color code for network architecture





#### DCGAN - Generator



```
class generator(nn.Module):
    # initializers
    def __init__(self, input_size = 100, d=64):
        super(generator, self).__init__()
        self.deconv1 = nn.ConvTranspose2d(input_size, d*4,
4, 1, 0)
        self.deconv2_bn = nn.BatchNorm2d(d*4)
        self.deconv2_bn = nn.BatchNorm2d(d*2)
        self.deconv3 = nn.ConvTranspose2d(d*2, d, 4, 2, 1)
        self.deconv3_bn = nn.BatchNorm2d(d)
        self.deconv4 = nn.ConvTranspose2d(d, 1, 4, 2, 1)
```

#### Define the architecture with nn.ConvTranspose2d

```
torch.nn.Conv<mark>Transpose</mark>2d(in_channels, out_channels, kernel_size, stride=1, padding=0, output_padding=0, groups=1, bias=True, dilation=1, padding_mode='zeros')
```

```
# weight_init
def weight_init(self, mean, std):
    for m in self._modules:
        normal_init(self._modules[m], mean, std)
```

```
# forward method Forward pass

def forward(self, input):
    x = F.relu(self.deconv1_bn(self.deconv1(input)))
    x = F.relu(self.deconv2_bn(self.deconv2(x)))
    x = F.relu(self.deconv3_bn(self.deconv3(x)))
```

x = F.tanh(self.deconv4(x))

return x

torch.nn.ReLU(inplace=False)

Applies the rectified linear unit function element-wise:

ReLU(x) = max(0, x)

### DCGAN - Discriminator



```
class discriminator(nn.Module):
# initializers

def __init__(self, d=64):
super(discriminator, self).__init__()

self.conv1 = nn.Conv2d(1, d, 4, 2, 1)
self.conv1_bn = nn.BatchNorm2d(d)
self.conv2 = nn.Conv2d(d, d*2, 4, 2, 1)
self.conv2_bn = nn.BatchNorm2d(d*2)
self.conv3 = nn.Conv2d(d*2, d*4, 4, 2, 1)
self.conv3_bn = nn.BatchNorm2d(d*4)
self.conv4 = nn.Conv2d(d*4, 1, 4, 1, 0)
```

```
# weight_init
def weight_init(self, mean, std):
    for m in self._modules:
        normal_init(self._modules[m], mean, std)

# forward method
def forward(self, input):
    x = F.leaky_relu(self.conv1_bn(self.conv1(input)), 0.2)
    x = F.leaky_relu(self.conv2_bn(self.conv2(x)), 0.2)
    x = F.leaky_relu(self.conv3_bn(self.conv3(x)), 0.2)
    x = F.sigmoid(self.conv4(x))
```

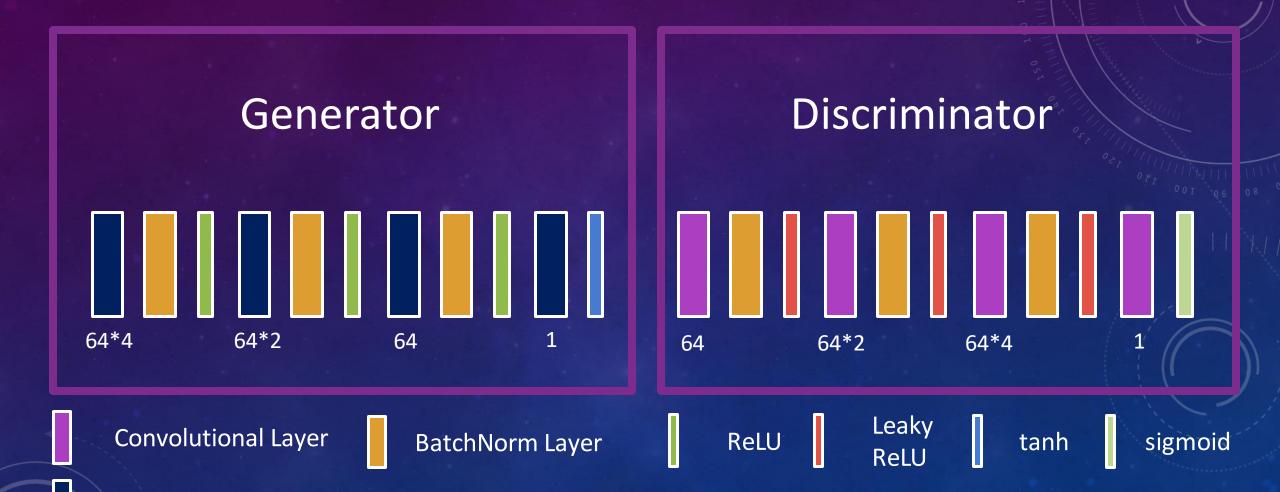
Define the discriminator with nn.Conv2d

return x

```
torch.nn.Conv2d(in_channels, out_channels, kernel_size, stride=1, padding=0,
dilation=1, groups=1, bias=True, padding_mode='zeros')
```

# Comparison generator and discriminator

Deconvolutional Layer



# DCGAN- Weight initialization, loss and optimizer

```
G = generator(input_size = noise_size)
D = discriminator()
```

Build the instance of our classes generator and discriminator model

```
G.weight_init(mean=0.0, std=0.02)
D.weight_init(mean=0.0, std=0.02)
```

Weight initialization

```
if torch.cuda.is_available():
    G.cuda()
    D.cuda()

print(G)
print(D)
```

```
BCE loss = nn.BCELoss()
```

```
# D_optimizer = torch.optim.Adagrad(D.parameters(), Ir=Ir)
# G_optimizer = torch.optim.Adagrad(G.parameters(), Ir=Ir)
# D_optimizer = torch.optim.SGD(D.parameters(), Ir=Ir,
momentum=0.9)
# G_optimizer = torch.optim.SGD(G.parameters(), Ir=Ir,
momentum=0.9)

D_optimizer = torch.optim.Adam(D.parameters(), Ir=Ir,
betas=(0.5, 0.999))
G_optimizer = torch.optim.Adam(G.parameters(), Ir=Ir,
betas=(0.5, 0.999))
```

Above are 3 choices for the optimizer, default is Adam

### DCGAN – Train the "discriminator D"

#### Start to training the "discriminator" D

```
# train discriminator D
     D.zero grad()
    mini batch = x .size()[0]
    y real = torch.ones(mini batch)
    y fake = torch.zeros(mini batch)
    x, y real, y fake = Variable(x),
     Variable(y real ), Variable(y fake )
    if torch.cuda.is available():
      x = x .cuda()
      y_real_ = y_real_.cuda()
      y_fake_ = y_fake_.cuda()
       Discriminate if real images are real or fake
    D_{result} = D(x_{squeeze})
    D_real_loss = BCE_loss(D_result, y_real_)
    D real score = D result
```

```
z = torch.randn((mini batch, noise size)).view(-
            1, noise size, 1, 1)
z = Variable(z )
                                Generate the noises
if torch.cuda.is available():
  z = z .cuda()
G result = G(z)
              Generate the images from the noises
D result = D(G result).squeeze()
D fake loss = BCE loss(D result, y fake )
D fake score = D result.data.mean()
D_train_loss = D_real_loss + D_fake_loss
D_train_loss.backward()
D optimizer.step()
```

### DCGAN Train the Generator

```
# train generator G
    G.zero_grad()
                      Generate the noises
   z_ = torch.randn((mini_batch, noise_size)).view(-
    1, noise_size, 1, 1)
   z = Variable(z )
   if torch.cuda.is_available():
     z_{-} = z_{-}.cuda()
                    Generate the images from the noises
   G result = G(z)
   G_train_loss = BCE_loss(D_result, y_real_)
   G_train_loss.backward()
   G_optimizer.step()
```

### **DCGAN** Results

Resuit:

#### Epoch 1:



#### Epoch 10:



#### Epoch 30:



~20 mins

### Exercise 4-4: DC-GAN

- Please download the "exercise4.4\_ DCGAN.ipynb" on Moodle.
- Upload the "exercise4.4\_ DCGAN.ipynb" to the Google Colab.
- Follow the sample code to understand the data flow of the generative adversarial network.
  - Compare the architecture and results with the exercise4-2.
  - > Try to implement the gan loss function from exercise4-3.
  - > Compare the training results by using "wgan-gp".
  - given the trajectories of the generator loss and discriminator loss, please write down your description

### Face Dataset - CelebA

 CelebA is a dataset of 202,599 face images with 10,177 celebrity identities, which provides 5 face key points (facial landmarks) coordinates and 40 facial attributes



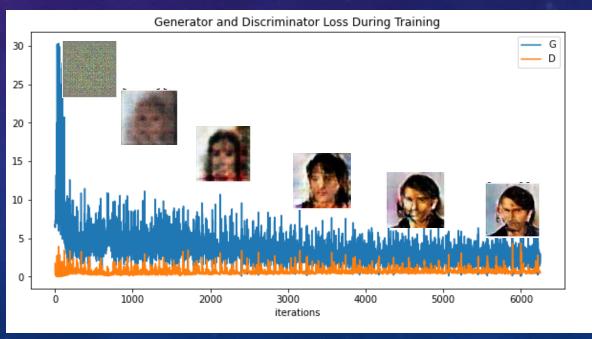
### Bedroom Dataset - LSUN

• It contains around one million labeled images for each of 10 scene categories and 20 object categories

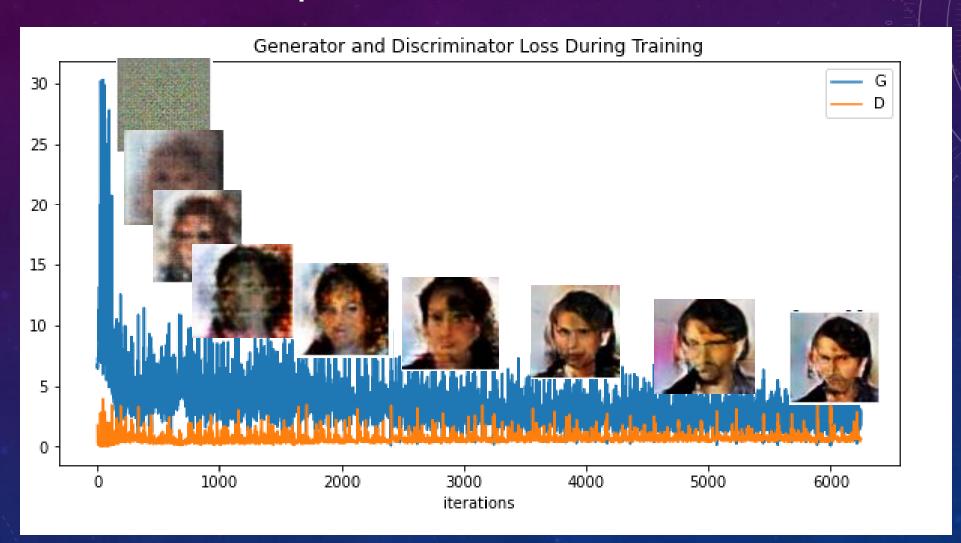


# Example 4-5: DC-GAN - Face

- Please download the "exercise4.5\_CelebA\_DCGAN.ipynb" on Moodle.
- Upload the "exercise4.5\_CelebA\_DCGAN.ipynb" to the Google Colab.
- Follow the sample code to understand the data flow of the generative adversarial network.
  - Download the CelebA dataset given the code on the Colab.
  - Define the structure of generator and discriminator
  - Define the loss and optimizer
  - Train the DC-GAN model for celebA
  - Use the fixed noise to observe each generated image during training process

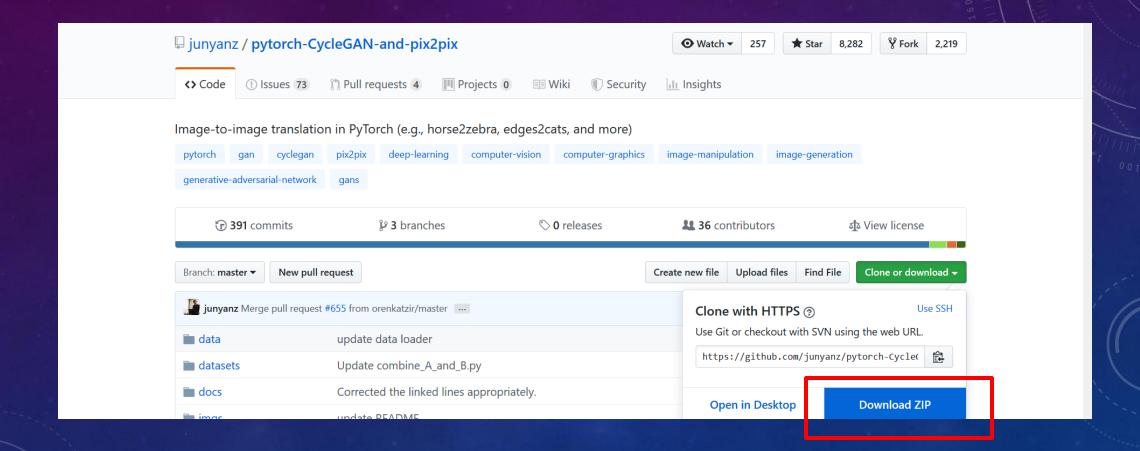


# Example 4-5: DC-GAN - Face



# Example 4-5: DC-GAN - Face



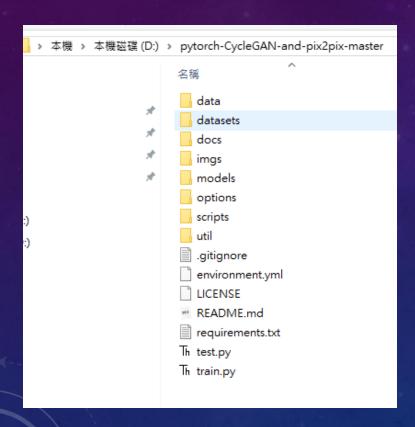


- 1. Please visit <a href="https://github.com/junyanz/pytorch-CycleGAN-and-pix2pix">https://github.com/junyanz/pytorch-CycleGAN-and-pix2pix</a>
- 2. Download the zip file of the codes

### Exercise 4-5: DC-GAN - LSUN

- Please download the "exercise4.5\_DCGAN.ipynb" on Moodle.
- Upload the "exercise4.5\_DCGAN.ipynb" to the Google Colab.
- Follow the sample code to understand the data flow of the generative adversarial network.
  - Download the LSUN dataset given the code on the Colab.
  - Define the structure of generator and discriminator which are same as exercise 4-4.
  - ➤ Define the loss and optimizer which are same as exercise 4-4.
  - > Train the DC-GAN model on LSUN dataset.
  - Use the fixed noise to observe each generated image during training process.

3.Unzip your code and put it in the directory desired.

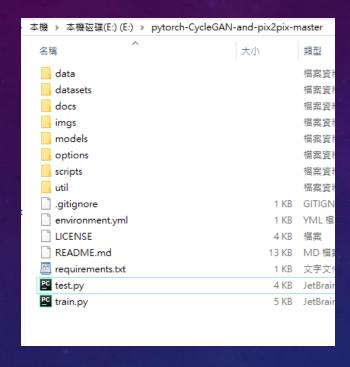


4. Visit <a href="http://efrosgans.eecs.berkeley.edu/cyclegan/pretrained\_models/">http://efrosgans.eecs.berkeley.edu/cyclegan/pretrained\_models/</a>
for pretrained models

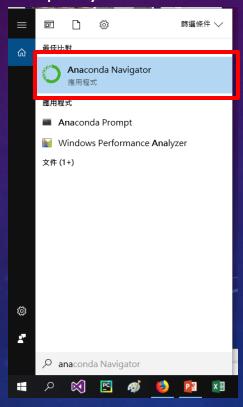
← → C ① 不安全   efrosgans.eecs.berkeley.edu/cyclegan/pretrained_models/			
Index of /cyclegan/pretrained_models			
<b></b> [ICO]	<u>Name</u>	Last modified	Size Description
PARENTDIR] Parent Directory -			
<b>2</b> []	apple2orange.pth	2018-07-24 16:47	43M
<b>]</b> []	cityscapes_label2pho>	2018-07-24 16:48	43M
<b>&gt;</b> []	cityscapes_photo2lab>	2018-07-24 16:47	43M
<b>&gt;</b> []	facades_label2photo.pth	2018-07-24 16:48	43M
<u> </u>	Consider of the Analysis	2019 07 24 16:49	4214

Let's take appe2orange for example.

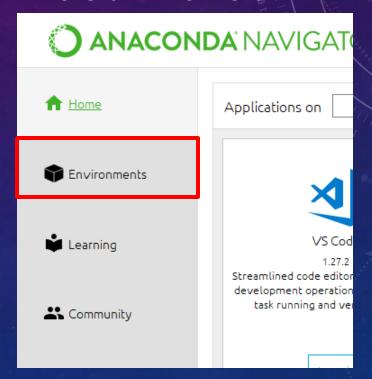
1. Extract your files to D:/



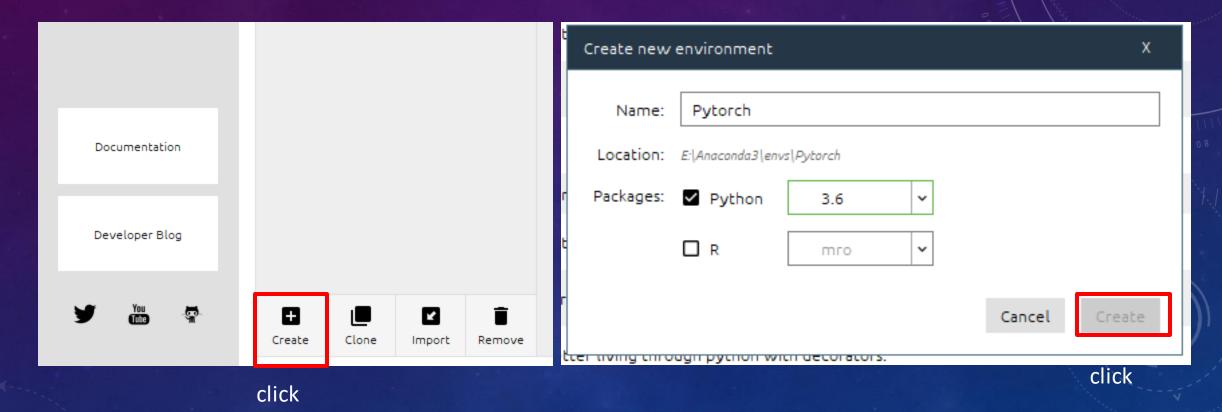
2. Open your Anaconda



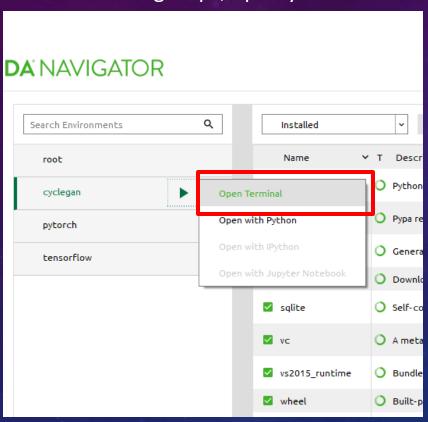
3. Click Environment



4. Create a new environment.



5. After building steps, open your terminal.



6. Enter the folder where you put the codes

(C:\Anaconda3\envs\cyclegan) C:\Users\c\_user>D: (C:\Anaconda3\envs\cyclegan) D:\>cd pytorch-CycleGAN-and-pix2pix-master

(C:\Anaconda3\envs\cyclegan) D:\pytorch-CycleGAN-and-pix2pix-master>

- 7. Enter the command
- "conda install pytorch=0.4.1 cuda80 -c pytorch"

8. Enter "y" for the permission

Proceed ([y]/n)? y

Scipy: Please install the version of 1.2.1

pytorch-CycleGAN-and-pix2pix-master>pip install scipy=1.2.1

And other packages

(C:\Anaconda3\envs\cyclegan) D:\pytorch-CycleGAN-and-pix2pix-master>pip install dominate pillow

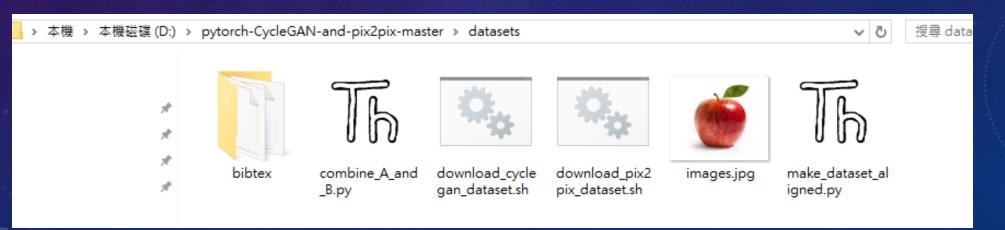
(C:\Anaconda3\envs\cyclegan) D:\pytorch-CycleGAN-and-pix2pix-master>pip install torchvision

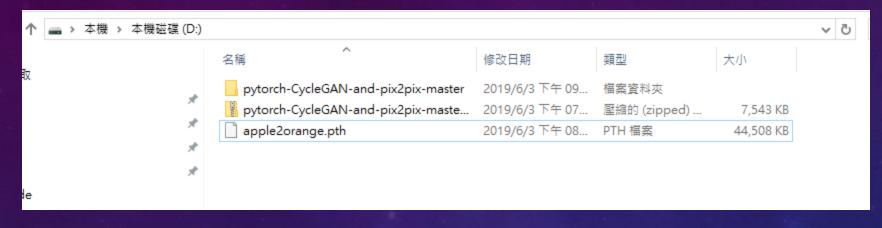
We will take "apple2orange" for example.

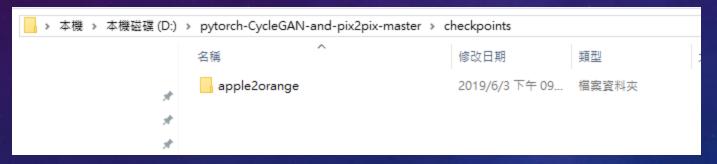




#### Please put your picture here







- 1. Make the directory in <CycleGAN dir>/checkpoints/apple2orange
- 2. Copy it and paste it to <CycleGAN dir>/checkpoints/apple2orange/



 Enter the command <python test.py --dataroot datasets --model test --name apple2orange --no\_dropout>

python test.py --dataroot datasets --model test --name apple2orange --no\_dropout --gpu\_ids -1-

And you will get your results in the folder (pytorch-CycleGAN-and-pix2pix-master\results\apple2orange\test\_latest\images)





# Exercise 4-6: CycleGAN

- Please download the pre-trained model from the following link http://efrosgans.eecs.berkeley.edu/cyclegan/pretrained\_models/
- Take arbitrary face image as input, please use the monet2photo.pth, style vangogh.pth and stytle cezanne.pth pretrained models, and add Monet/Vangogh/Cezanne-style to the input image.
- Utilize the same image as input, and use <u>orange2apple.pth</u> as the pretrained model to transfer the style of the input image.
- Write down what you observe in the docx file.



CycleGAN

