# Course 2: Supervised Learning



### **Summary**

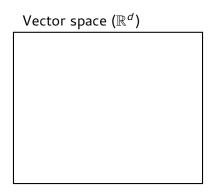
#### Last session

- What is not Al?
- Al definition
- 3 Applications
- Open issues

#### Today's session

- Learning from labeled examples
- Challenges of supervised learning

### **Notations**



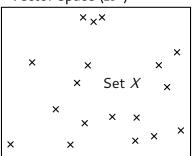
### **Notations**

Vector space 
$$(\mathbb{R}^d)$$

Vector  $\mathbf{x} \ (\in \mathbb{R}^d)$ 

### **Notations**

### Vector space ( $\mathbb{R}^d$ )



#### **Definition**

Supervised learning methods use **labels** y associated to examples  $x \in X$  to learn a function f such as y = f(X), with the aim of **generalizing** ( $\neq$  memorizing) to unlabeled examples.

- Regression (y is scalar)
- Classification (y is categorical)
- Tons of applications
  - recognition
    - Prediction...



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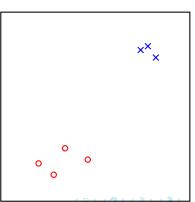
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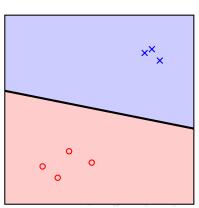
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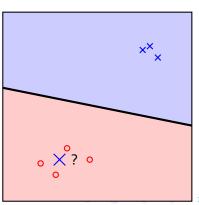
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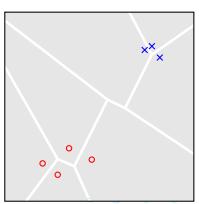
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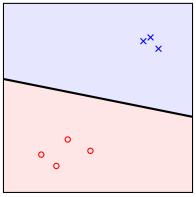
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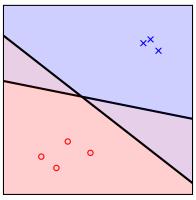
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- An infinity of potential solutions, one must be the "best one" but is unreachable,
- ⇒ requires a priori, constraints.



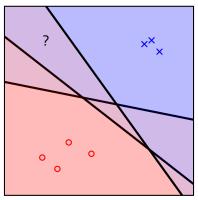
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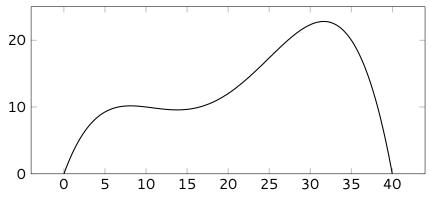


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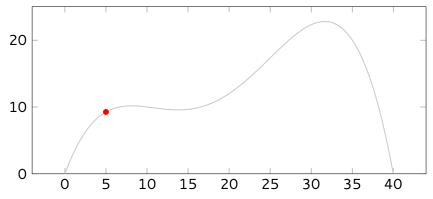
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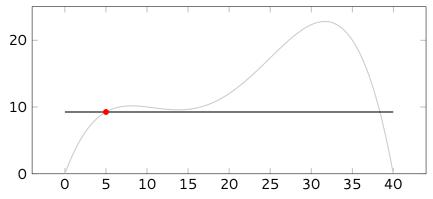
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- Mimicking is not learning: overfitting problem.



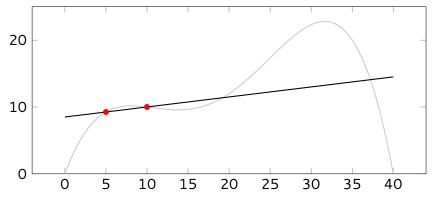
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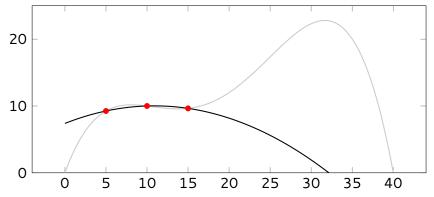
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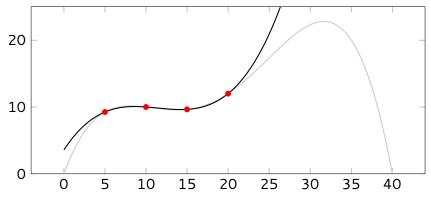
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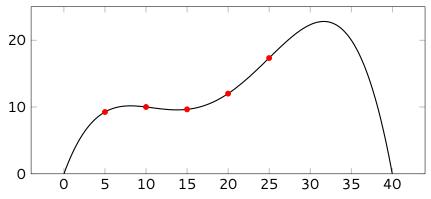
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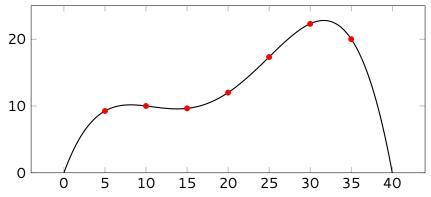
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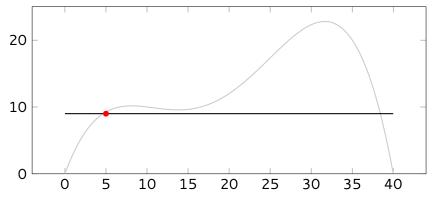
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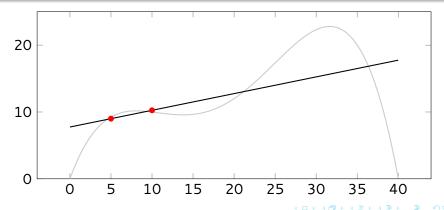
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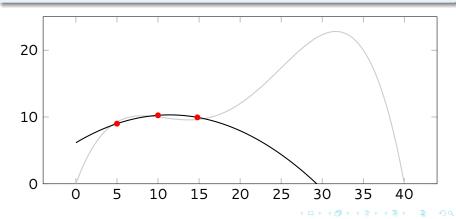
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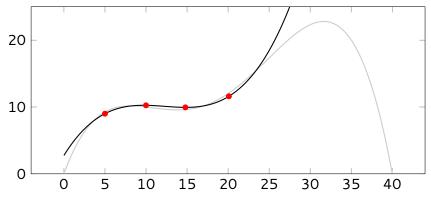
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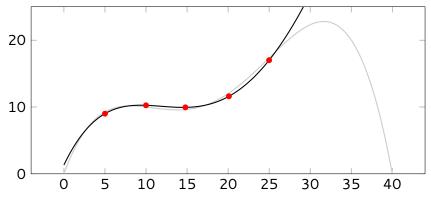
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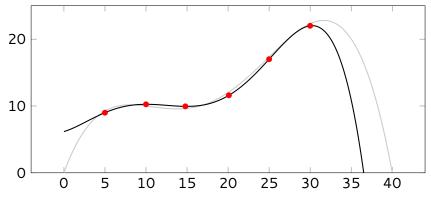
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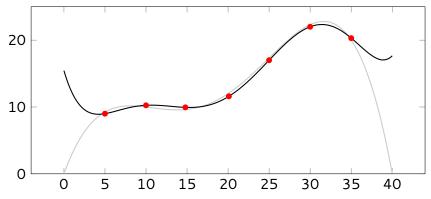
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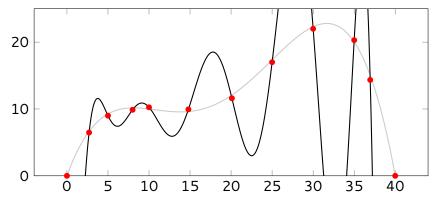
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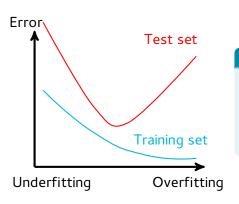


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#### Bias/variance trade-off

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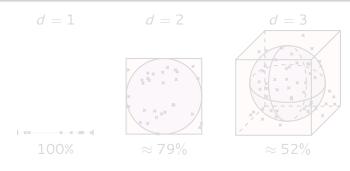


#### Crossvalidation

- To quantify overfitting, split training dataset in two parts:
  - A first part is used to train,
  - 2 A second part is used to validate,

### Curse of dimensionality

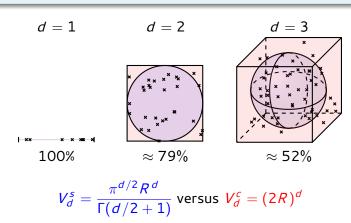
- Geometry is not intuitive in high dimension,
- Efficient methods in 2D are not necessarily still valid.



$$V_d^s = \frac{\pi^{d/2} R^d}{\Gamma(d/2 + 1)}$$
 versus  $V_d^c = (2R)^d$ 

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See http://www.maths.manchester.ac.uk/~mlotz/teaching/suprises.pdf 4 🗇 > 4 🗇 > 4 💆 > 4 💆 > 5 💆

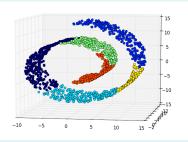












### Linear separability and need for embedding











### Computation time

Example on ImageNet, simply going through all images:

- $n = 10.000.000, d \approx 1.000.000,$
- ho pprox pprox pprox pprox elementary operations,
- ho  $\approx$  2h45 on a modern processor.

#### Scalability

- Finding the best solution to a problem would be feasible with unlimited computation time,
- But searching through the space of possible functions is often untractable,
- Solutions must be computationally reasonable, which is the true challenge today.

# Challenges of supervised learning (5/5)

#### Computation time

Example on ImageNet, simply going through all images:

- $n = 10.000.000, d \approx 1.000.000,$
- $ho pprox 10^{13}$  elementary operations,
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#### **Definition**

- Let us fix d,
- The VC dimension is a measure of the genericity of a method,
- It is the maximum cardinality of a set of vectors that the method is able to shatter in any possible way.

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Consider for example lines to shatter set of points with d = 2.

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### Non-symmetric PyRat without walls / mud



Both players follow a deterministic greedy algorithm. Supervised learning - Two tasks

- Predict the outcome of a game from the start configuration.
- Learn the next move using a dataset of winners

# Lab Session 2 and assignments for Session 3

#### TP Supervised Learning (TP1)

- Basics of machine learning using sklearn (including new definitions / concepts)
- Tests on PyRat datasets using the two tasks (predicting winner and predicting moves to play)

#### Project 1 (P1)

You will be choose a supervised learning method. You have to prepare a Jupyter Notebook on this method, including:

- A brief description of the theory behind the method,
- Basic tests on simulated data to show the influence of parameters and hyperparameters
- Tests on PyRat Datasets on at least ONE of the two tasks (predicting winner or playing)

During Session 3 you will have 7 minutes to present your notebook.