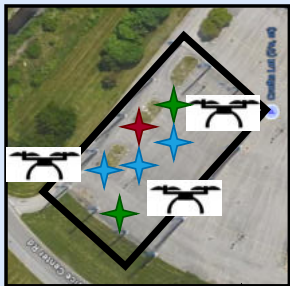





Environment



-  Incomplete
-  Completed
-  In-progress

Decision Making



Task Graph



Peer Robot
Information

Assign Bigraph
Weights

Weight Matching

Idle Robot
&
Feasible
Tasks

Task for Idle Robot