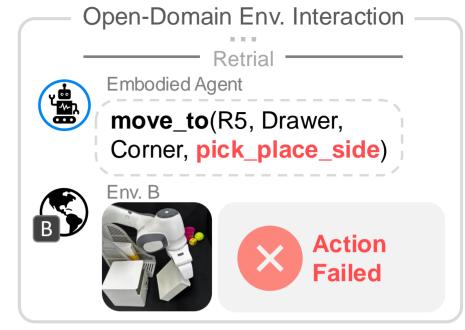
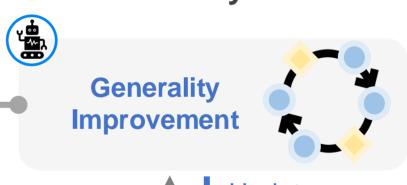


Case 1: Conventional Neuro-symbolic Framework





Case 2 : Neuro-symbolic Continual Learner (ours)



↑ Update
Actionable Knowledge

move to

move_to(Robot, Object, Destination, Method):not holding(Robot), gripper_size(Object),
pick_place(Method).

move_to(Robot, Object, Destination, Method):not holding(Robot), not gripper_size(Object),
push(Method).

