

Minimum Cost Spanning Trees: Prim's Algorithm

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Programming, Data Structures and Algorithms using Python
Week 5

Minimum cost spanning tree (MCST)

- Weighted undirected graph,
 $G = (V, E), W : E \rightarrow \mathbb{R}$
 - G assumed to be connected

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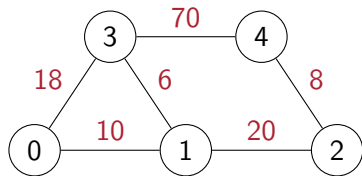
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 - Incrementally grow the minimum cost spanning tree
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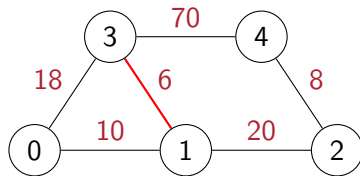
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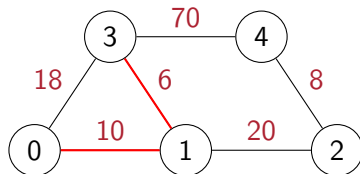


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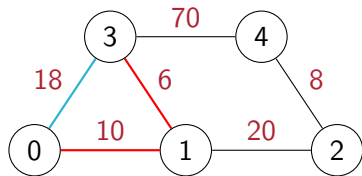


- Start with smallest edge, $(1, 3)$
- Extend the tree with $(1, 0)$

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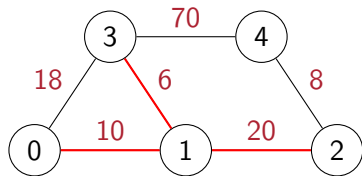


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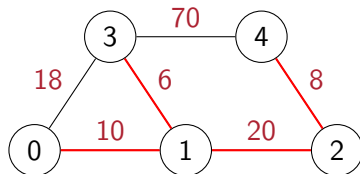


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- Start with smallest edge, $(1, 3)$
- Extend the tree with $(1, 0)$
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- Extend the tree with $(2, 4)$

Prim's algorithm

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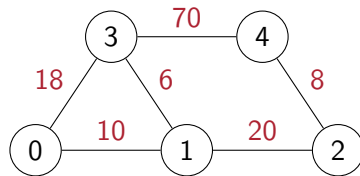
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- Repeat $n - 2$ times
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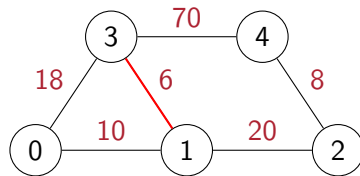
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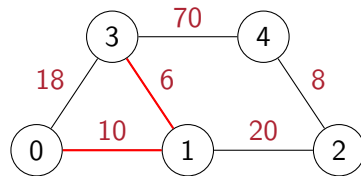
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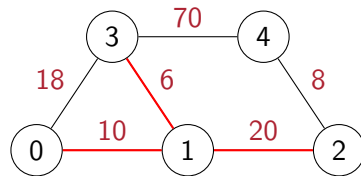
$$TV = \{1, 3, 0\}$$

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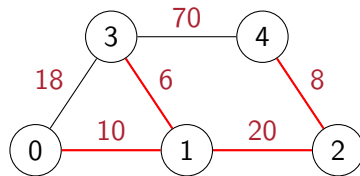
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$$TV = \{1, 3, 0, 2, 4\}$$
$$TE = \{(1, 3), (1, 0), (1, 2), (2, 4)\}$$

Correctness of Prim's algorithm

Minimum Separator Lemma

- Let V be partitioned into two non-empty sets U and $W = V \setminus U$
- Let $e = (u, w)$ be the minimum cost edge with $u \in U, w \in W$
- Every MCST must include e

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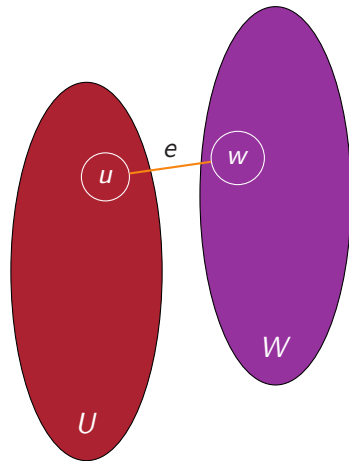
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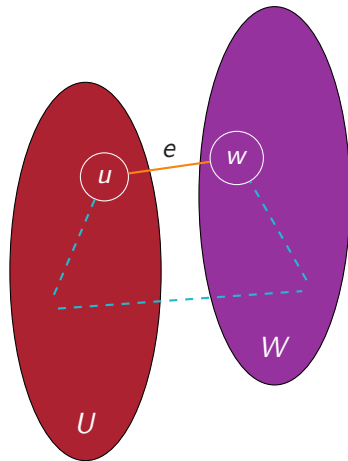
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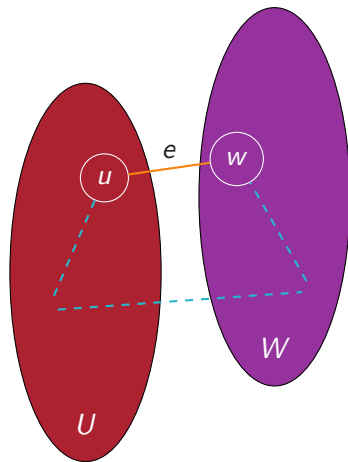
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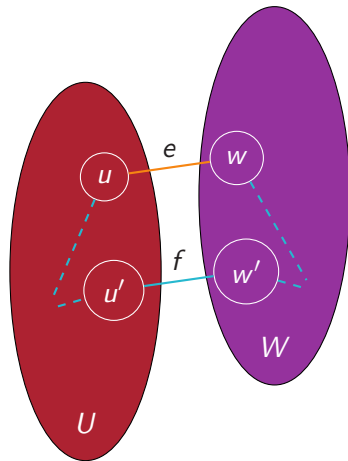
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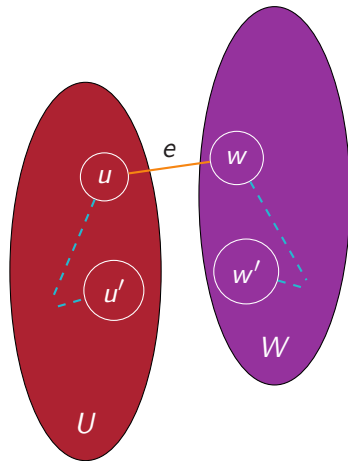
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 - Let $f = (u', w')$ be the first edge on p crossing from U to W



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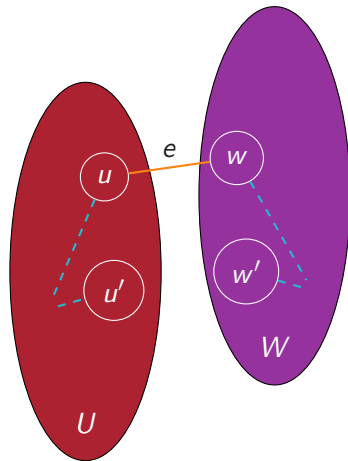
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 - Drop f , add e to get a cheaper spanning tree



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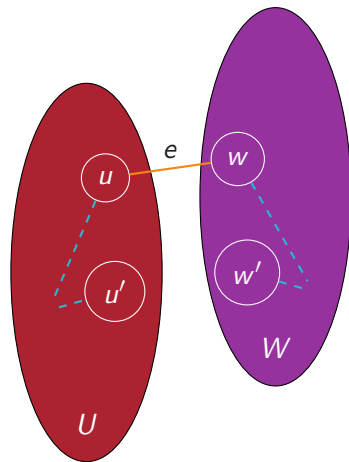
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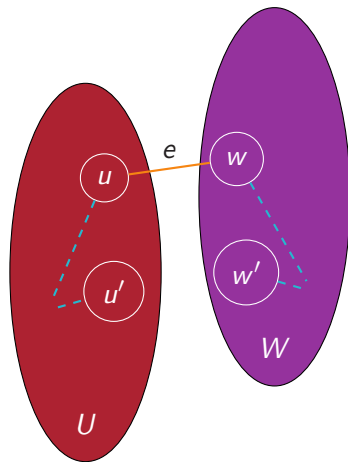
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 - Define $(e, i) < (f, j)$ if $W(e) < W(f)$ or $W(e) = W(f)$ and $i < j$



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- Instead, can start at any vertex v , with $TV = \{v\}$ and $TE = \emptyset$
- First iteration will pick minimum cost edge from v

Implementation

- Keep track of
 - `visited[v]` – is `v` in the spanning tree?
 - `distance[v]` – shortest distance from `v` to the tree
 - `TreeEdges` – edges in the current spanning tree

```
def primlist(WList):  
    infinity = 1 + max([d for u in WList.keys()  
                       for (v,d) in WList[u]])  
    (visited,distance,TreeEdges) = ({},{},[])  
    for v in WList.keys():  
        (visited[v],distance[v]) = (False,infinity)  
    visited[0] = True  
    for (v,d) in WList[0]:  
        distance[v] = d  
    for i in WList.keys():  
        (mindist,nextv) = (infinity,None)  
        for u in WList.keys():  
            for (v,d) in WList[u]:  
                if visited[u] and (not visited[v]) and d < mindist:  
                    (mindist,nextv,nexte) = (d,v,(u,v))  
        if nextv is None:  
            break  
        visited[nextv] = True  
        TreeEdges.append(nexte)  
        for (v,d) in WList[nextv]:  
            if not visited[v]:  
                distance[v] = min(distance[v],d)  
    return(TreeEdges)
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- First add vertex `0` to tree
- Find edge `(u,v)` leaving the tree where `distance[v]` is minimum, add it to the tree, update `distance[w]` of neighbours

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    for (v,d) in WList[0]:  
        distance[v] = d  
    for i in WList.keys():  
        (mindist,nexttv) = (infinity,None)  
        for u in WList.keys():  
            for (v,d) in WList[u]:  
                if visited[u] and (not visited[v]) and d < mindist:  
                    (mindist,nexttv,nexte) = (d,v,(u,v))  
        if nexttv is None:  
            break  
        visited[nexttv] = True  
        TreeEdges.append(nexte)  
        for (v,d) in WList[nexttv]:  
            if not visited[v]:  
                distance[v] = min(distance[v],d)  
    return(TreeEdges)
```

Complexity

- Initialization takes ($O(n)$)

```
def primlist(WList):
    infinity = 1 + max([d for u in WList.keys()
                       for (v,d) in WList[u]])
    (visited,distance,TreeEdges) = ({},{},[])
    for v in WList.keys():
        (visited[v],distance[v]) = (False,infinity)
    visited[0] = True
    for (v,d) in WList[0]:
        distance[v] = d
    for i in WList.keys():
        (mindist,nextv) = (infinity,None)
        for u in WList.keys():
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Complexity

- Initialization takes $O(n)$
- Loop to add nodes to the tree runs $O(n)$ times
- Each iteration takes $O(m)$ time to find a node to add

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Complexity

- Initialization takes $O(n)$
- Loop to add nodes to the tree runs $O(n)$ times
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- Overall time is $O(mn)$, which could be $O(n^3)$!

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Complexity

- Initialization takes $O(n)$
- Loop to add nodes to the tree runs $O(n)$ times
- Each iteration takes $O(m)$ time to find a node to add
- Overall time is $O(mn)$, which could be $O(n^3)$!
- Can we do better?

```
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```

Improved implementation

- For each v , keep track of its nearest neighbour in the tree
 - $visited[v]$ – is v in the spanning tree?
 - $distance[v]$ – shortest distance from v to the tree
 - $nbr[v]$ – nearest neighbour of v in tree

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def primlist2(WList):
    infinity = 1 + max([d for u in WList.keys()
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 - $visited[v]$ – is v in the spanning tree?
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- Scan all non-tree vertices to find $nextv$ with minimum distance

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- Then $(nbr[nextv], nextv)$ is the tree edge to add

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- Scan all non-tree vertices to find $nextv$ with minimum distance
- Then $(nbr[nextv], nextv)$ is the tree edge to add
- Update $distance[v]$ and $nbr[v]$ for all neighbours of $nextv$

```
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```

Improved implementation — complexity

- Now the scan to find the next vertex to add is $O(n)$

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- Now the scan to find the next vertex to add is $O(n)$
- Very similar to Dijkstra's algorithm, except for the update rule for distance

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Improved implementation — complexity

- Now the scan to find the next vertex to add is $O(n)$
- Very similar to Dijkstra's algorithm, except for the update rule for distance
- Like Dijkstra's algorithm, this is still $O(n^2)$ even for adjacency lists

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Improved implementation — complexity

- Now the scan to find the next vertex to add is $O(n)$
- Very similar to Dijkstra's algorithm, except for the update rule for distance
- Like Dijkstra's algorithm, this is still $O(n^2)$ even for adjacency lists
- With a more clever data structure to extract the minimum, we can do better

```
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```

Summary

- Prim's algorithm grows an MCST starting with any vertex
- At each step, connect one more vertex to the tree using minimum cost edge from inside the tree to outside the tree
- Correctness follows from Minimum Separator Lemma
- Implementation similar to Dijkstra's algorithms
 - Update rule for distance is different
- Complexity is $O(n^2)$
 - Even with adjacency lists
 - Bottleneck is identifying unvisited vertex with minimum distance
 - Need a better data structure to identify and remove minimum (or maximum) from a collection