Data Augmentation using GANs

Petros Kafkas

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Project Description

- The purpose of this project is to make use of generative AI in order to address the problem of class imbalance.
- To this end, we experiment using different generative Al architectures, from autoencodes to various GANs
- We extracted accuracy measurements for the various solutions tested and compared them against a baseline.

step 1: Create an imbalanced dataset (for this case, MNIST)

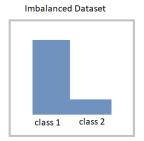


Figure: Project Pipeline

step 2: Feed the imbalanced class to a Generative Model

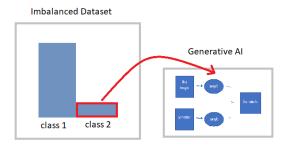


Figure: Project Pipeline

step 3: Generate Artificial data to correct the imbalance

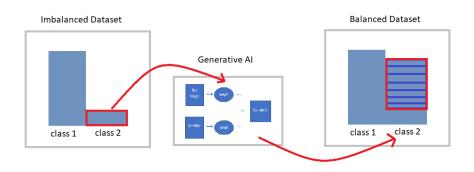


Figure: Project Pipeline

In more detail:

- We deleted $\sim 99\%$ of all the data corresponding to number 5.
- We used a standard CNN in order to measure the class accuracy (baseline measurement)
- Extra: We applied standard augmentations (crop, rotation etc.) and measured again in order to compare the Generative Methods to the classic data augmentation approach.

Data Visualization

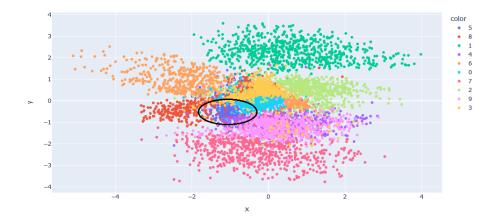


Figure: Dataset Visualization (Balanced)

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Data Visualization

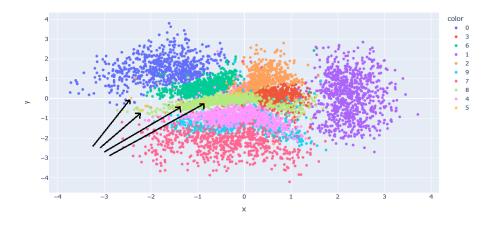


Figure: Dataset Visualization (Imbalanced)

Generative Models

- Autoencoders / VAEs
- GANs / WGANs
- ProGAN
- CGAN



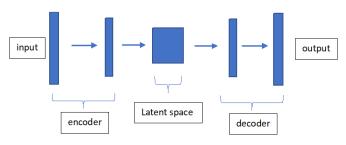


Figure: Basic Autoencoder

- An AE learns two functions, an encoding function that transforms the input data, and a decoding that recreates the input data from the encoded representation
- The latent space is rerpesented by a fixed vector



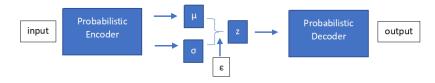


Figure: Variational Autoencoder

The *encoder* neural network maps the input variable to a latent space that corresponds to the parameters of a <u>variational distribution</u>. If the latent

space is regular enough (well "organized" by the encoder during the training process), we could take a point randomly from that latent space and decode it to get a new content

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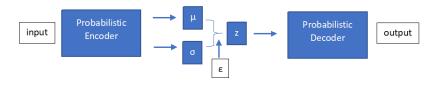


Figure: Variational Autoencoder

Loss L =
$$E_{q_{\phi}(x|z)}[\log p_{\theta}(x|z)] - D_{\mathsf{KL}}(q_{\phi}(z|x)||p(z))$$

Figure: Variational Autoencoder



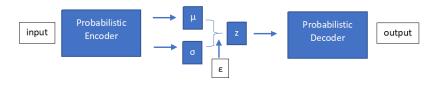


Figure: Variational Autoencoder

Loss L =
$$E_{q_{\phi}(x|z)}[\log p_{\theta}(x|z)] - D_{\mathsf{KL}}(q_{\phi}(z|x)||p(z))$$

Reconstruction Loss

Figure: Variational Autoencoder

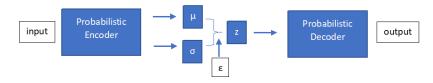


Figure: Variational Autoencoder

Loss L =
$$E_{q_{\phi}(x|z)}[\log p_{\theta}(x|z)] - D_{\mathsf{KL}}(q_{\phi}(z|x)||p(z))$$

Reconstruction Loss Approximate Normal(0,1)

Figure: Variational Autoencoder

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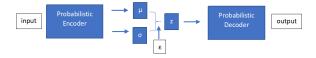


Figure: Variational Autoencoder

Cannot Back-propagate due to stochastic nature of sampling!

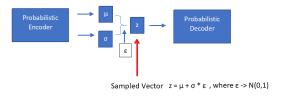
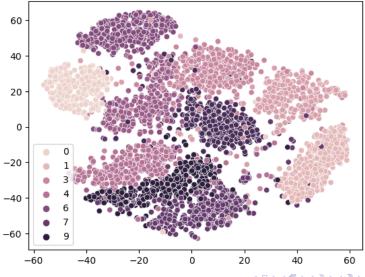


Figure: Latent Distribution Sampling

Reparametarization Trick: We sample ϵ from a normal distribution



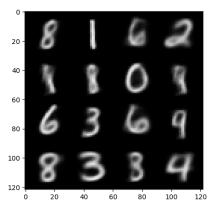


Figure: Data Generation using VAE



Basic Gan

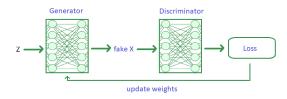


Figure: Generator Training

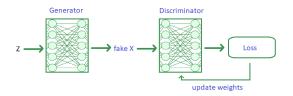


Figure: Discriminator Training



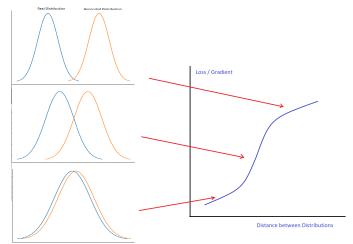
Basic Gan

Problems with the basic gan architecture:

- Mode Collapse: The generator gets stuck in a single mode
- Loss function (BCE) does not offer a good correlation between the loss value and the generated results
- Flat gradients during training:

Basic Gan

• Flat gradients during training:



Advanced Gan: WGAN

Solves the problems of the basic gan by introducing a new loss function: Wasserstein Loss.

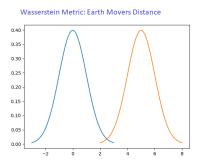
Critic:
$$min_d - [E(D(x)) - E(D(G(x)))]$$

Generator: $min_g - [-E(D(G(x)))]$
Sample Labels: $-\frac{1}{n}\sum_{n=1}^{\infty}y_n*pred_n$

MinMax Game: The critic tries to maximize the difference between its real and fake predictions, while the generator tries to minimize that difference. Important: gradient norm penalty to achieve Lipschitz continuity!

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Advanced Gan: WGAN



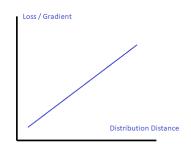


Figure: Earth's Mover Distance

Progressive Growing GAN

Key Idea: grow both the generator and discriminator progressively, starting from a low resolution, add new layers that model increasingly fine details as training progresses

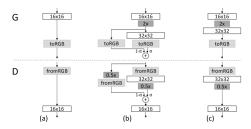


Figure: progan

Progressive Growing GAN

Key Idea: grow both the generator and discriminator progressively, starting from a low resolution, add new layers that model increasingly fine details as training progresses

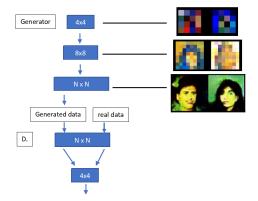


Figure: progan



Conditional WGAN

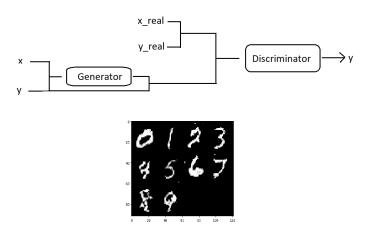


Figure: conditional gan



For our experiment we used the Wasserstein GAN for data generation, as it was the most "cost-effective" in terms of quality of data generated and of training time.

We repeated the experiment several times for different amount of data generated: 1) class imbalance 99.9% (baseline), 96%, 90%, 75%, 45%, and finally, 10%.

We measured the accuracy using a convolutional based classifier with two covolutional layers followed by a linear layer.

```
(cnn model): Sequential(
 (0): Sequential(
   (0): Conv2d(1, 8, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
   (1): BatchNorm2d(8, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
   (2): ReLU(inplace=True)
   (3): Dropout(p=0.2, inplace=False)
 (1): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1, ceil mode=False)
 (2): Sequential(
   (0): Conv2d(8, 32, kernel_size=(5, 5), stride=(1, 1), padding=(2, 2))
   (1): BatchNorm2d(32, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
   (2): ReLU(inplace=True)
   (3): Dropout(p=0.2, inplace=False)
 (3): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1, ceil mode=False)
(lin model): Sequential(
 (0): Sequential(
   (0): Linear(in features=1568, out features=600, bias=True)
   (1): ReLU(inplace=True)
   (2): Dropout(p=0.5, inplace=False)
 (1): Linear(in features=600, out features=10, bias=True)
```

Figure: classifier network

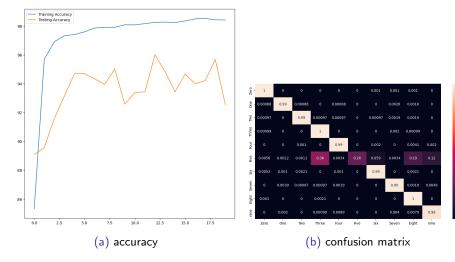


Figure: Baseline (99% imb.)

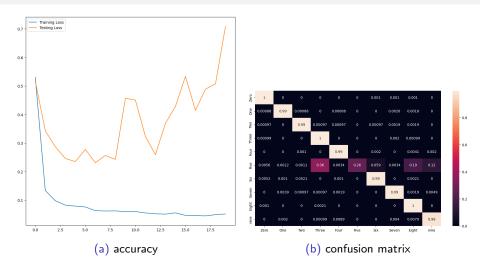
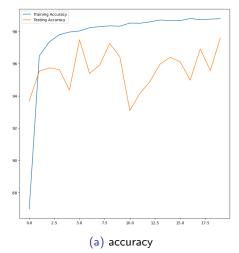


Figure: Baseline (99% imb.)





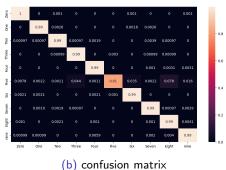


Figure: 75% imb.

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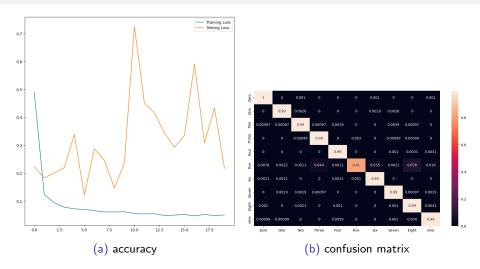


Figure: 75% imb.



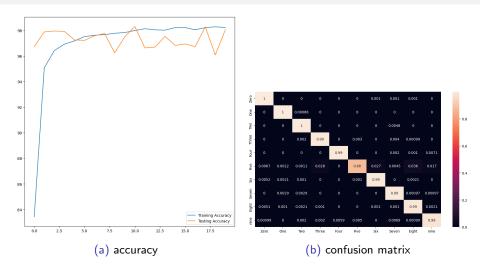


Figure: 50% imb.



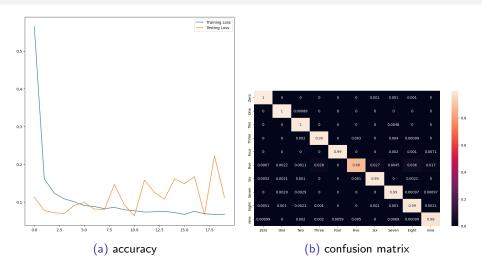


Figure: 50% imb.



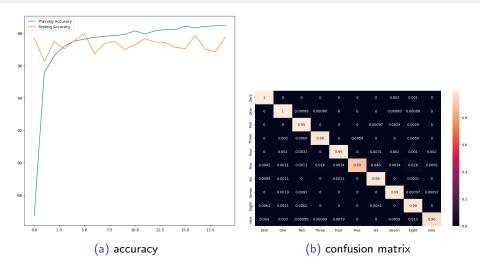


Figure: 10% imb.



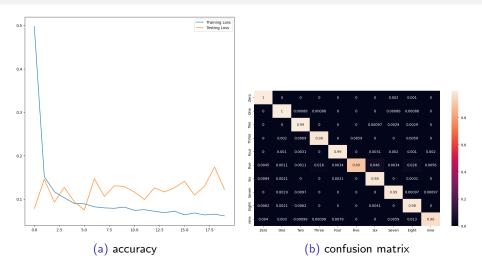


Figure: 10% imb.



Comparison with traditional data augm. techniques

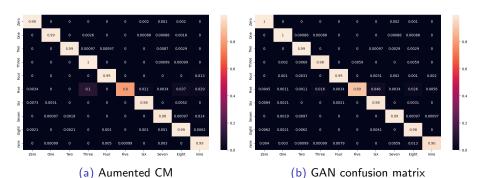


Figure: GAN vs (crop, rotation etc)

Comparison with traditional data augm. techniques

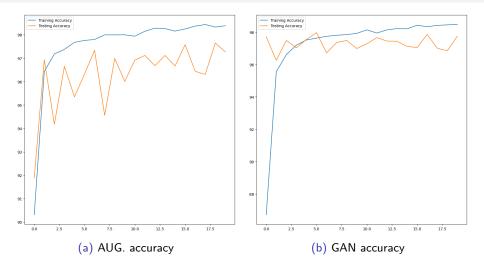


Figure: GAN vs (crop, rotation etc)

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Comparison with traditional data augm. techniques

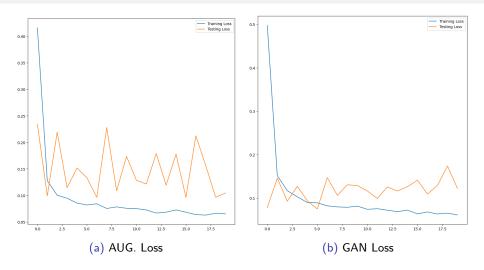


Figure: GAN vs (crop, rotation etc)



Conclusion

Comparison summing points:

- The ai generated data significantly improved the accuracy of the base classifier although the data did not capture all the statistical properties of the testing samples. However, this was also a problem when we used crop-rotation and other typical data aumentation techniques.
- The gans method offered better results compared to the traditional way of augmenting data, although it required significantly more time.
- Factrors to consider when deciding whether to use generative Ai for data aumentation:
 - problem and data complexity, availability of data data complexity ratio, time constraints.

Conclusion

Suggestions for further investigation:

- Combining VAEs with GANs for data aumentation
- Combining traditional aumentation techniques + generative AI methods

Thank you!