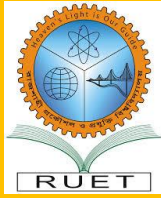
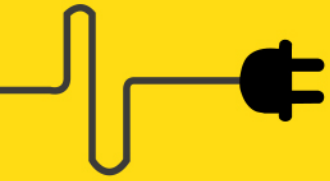


**WELCOME TO OUR PRESENTATION  
ON  
OUR PROJECT**

# **“Android Controlled Obstacle Avoiding Robot”**

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## **Project Supervisor:**

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# Features Of Our Robot



Senses any kinds of  
obstacle

Controlled by the pre-  
computation of Arduino

Controlled by Bluetooth  
devices through our  
Android app



# Hardware Required

- ☐ Arduino Board(Based On Atmega -328 Microcontroller)
- ☐ L298N H-Bridge Motor driver
- ☐ HC-SR04 Ultrasonic Sensor
- ☐ HC-05 Bluetooth Module
- ☐ SG90 Servo
- ☐ DC Motors and Wheel
- ☐ Chasis
- ☐ HC-SR04 Bracket
- ☐ Pololu Ball Caster (Model : ROB-00006)
- ☐ Mini Breadboard
- ☐ Jumper Wires(female-female, male-male, male-female)
- ☐ 9V Battery,11.1V Lipo Battery
- ☐ Android Device(BluControl App)



# Arduino Uno R3



- ❑ Arduino Uno is a microcontroller board based on the ATmega328 P (datasheet).
- ❑ It has 14 digital input/output pins (of which 6 can be used as PWM outputs)



# HC-SR04 Ultrasonic Sensor

- ☐ Uses sonar to determine distance to an object
- ☐ Non-contact range detection with high accuracy and stable readings



# L298N Motor driver



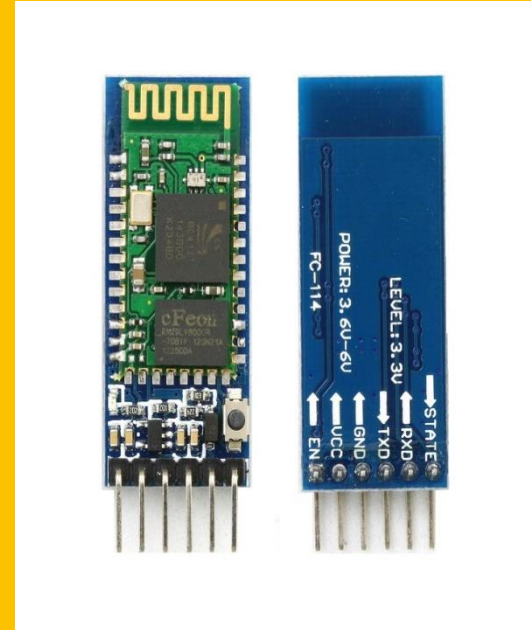
- ☐ **The L298N is an integrated circuit**
- ☐ **It is a high voltage, high current dual full-bridge driver**
- ☐ **Operating supply voltage up to 46V and Total DC current up to 4A.**



# HC-05 Bluetooth Module

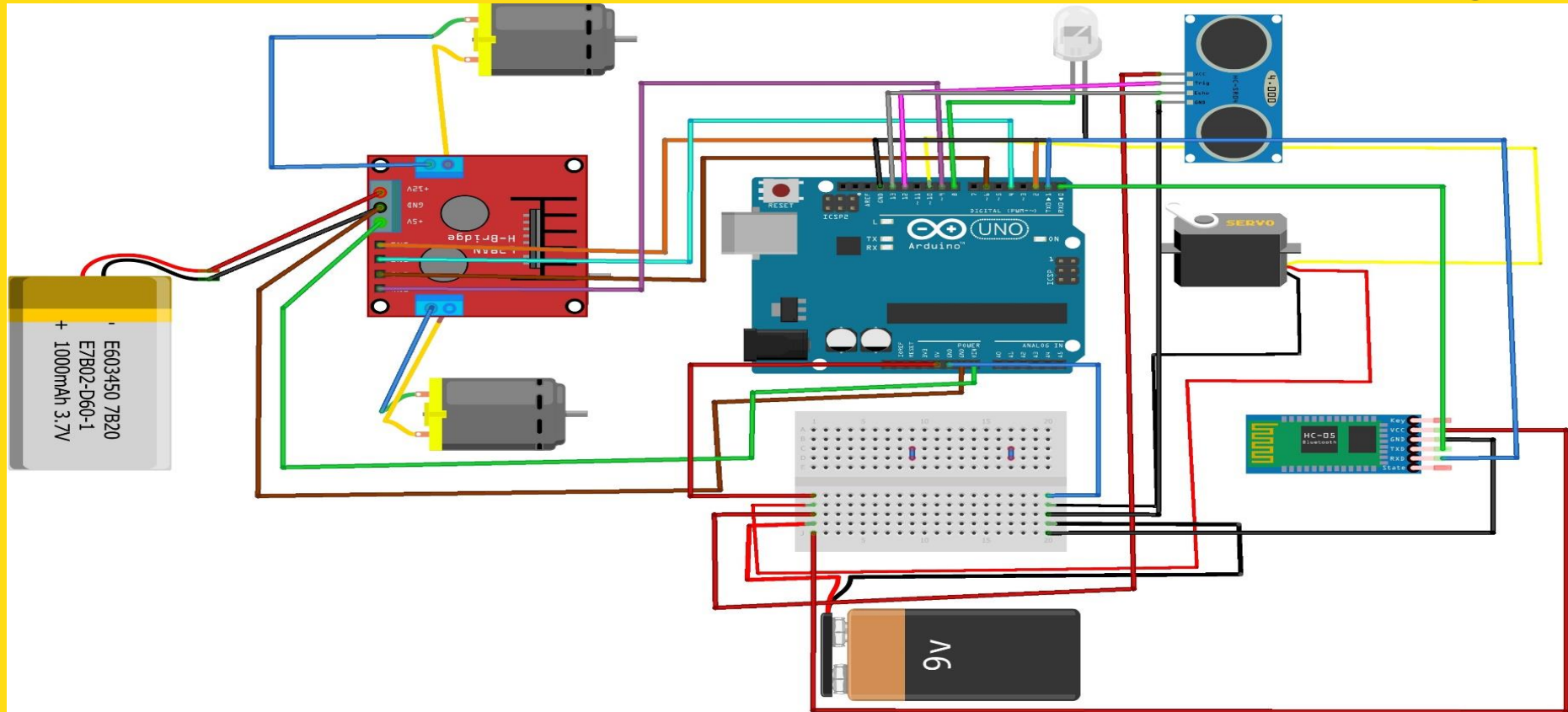


- ❑ An easy to use Bluetooth SPP(Serial Port Protocol) module
- ❑ Designed for transparent wireless serial connection setup
- ❑ Bluetooth V2.0+EDR (Enhanced Data Rate)

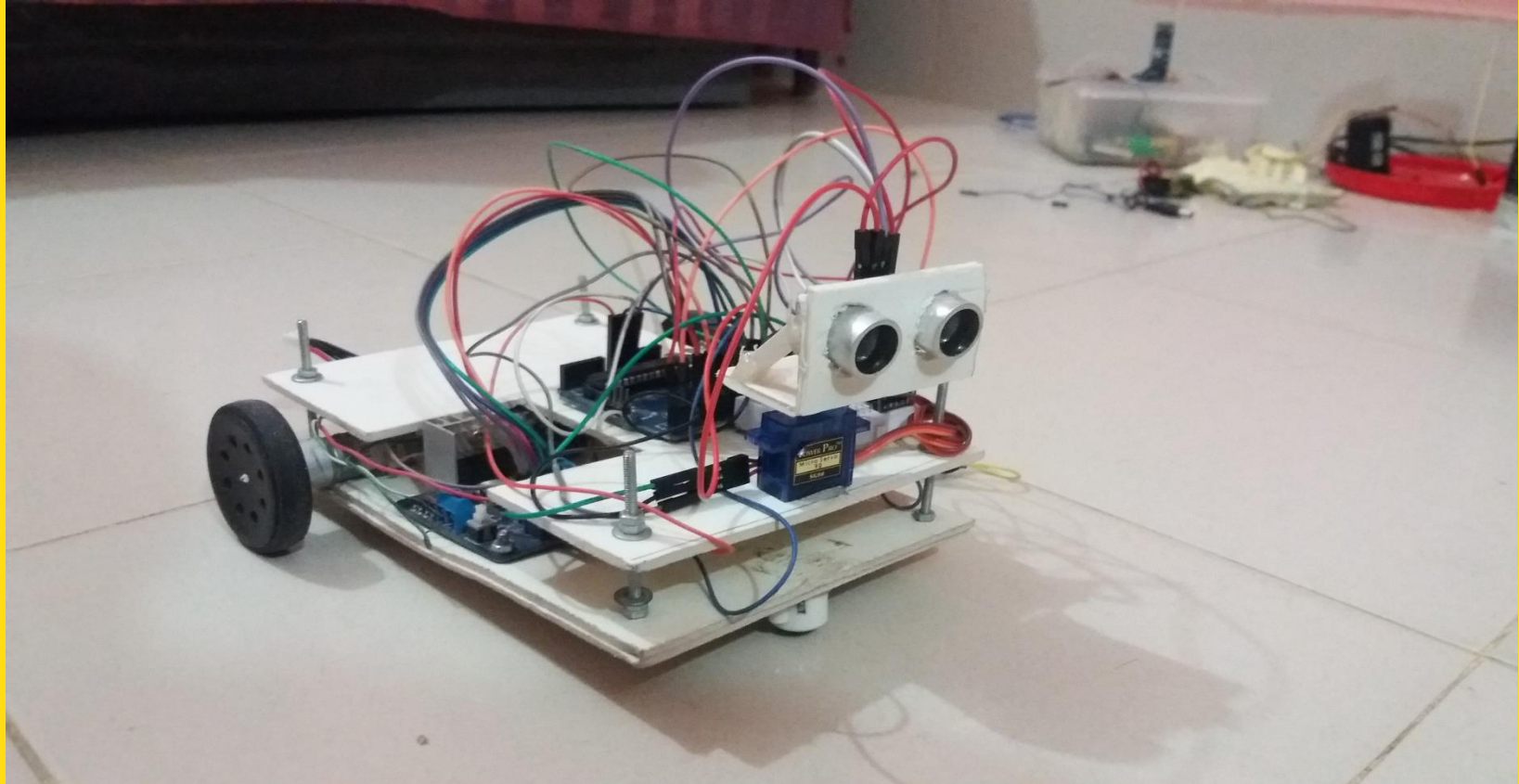




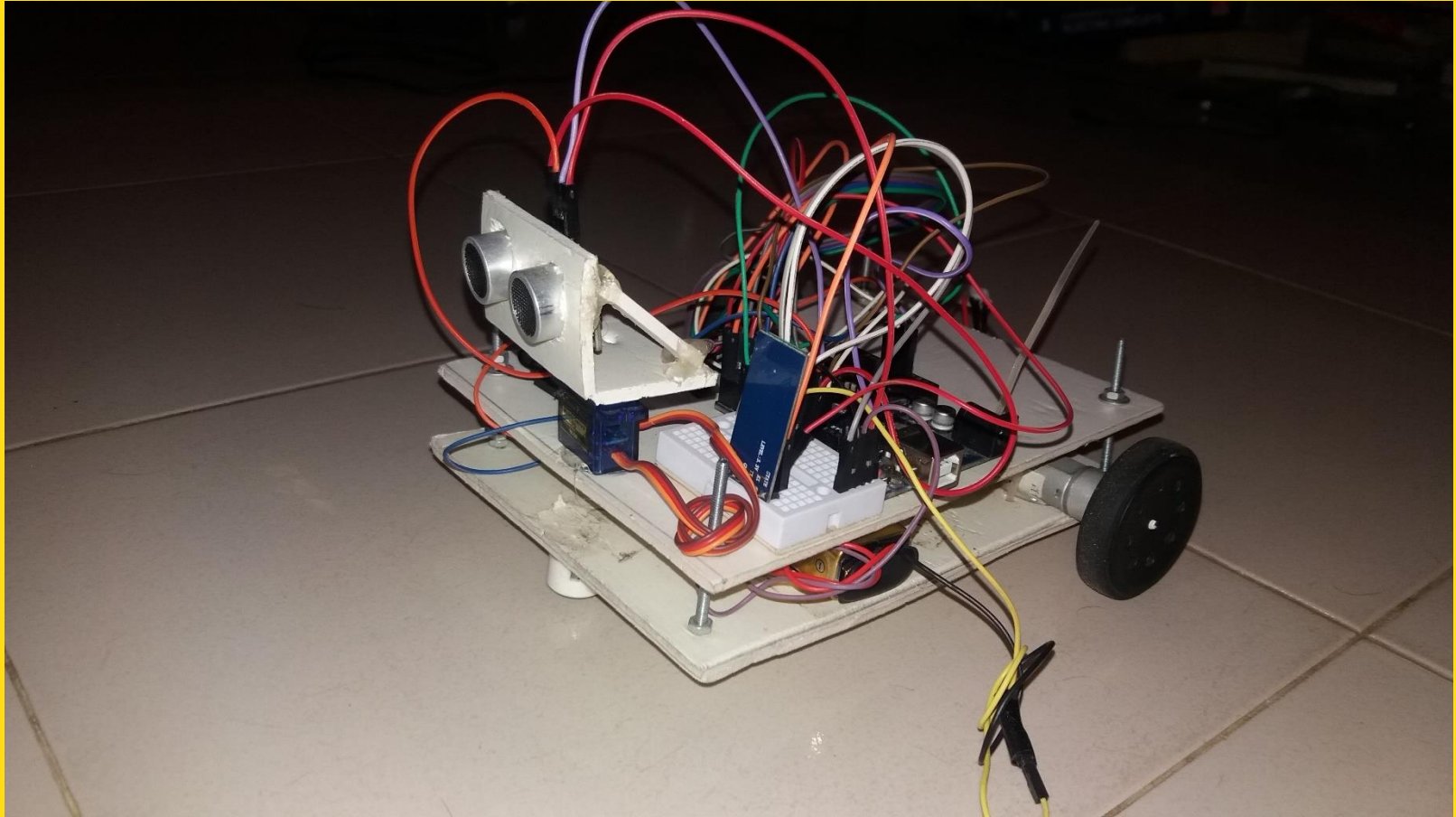
# Circuit Program Fritzing



# FRONT VIEW



# SIDE VIEW

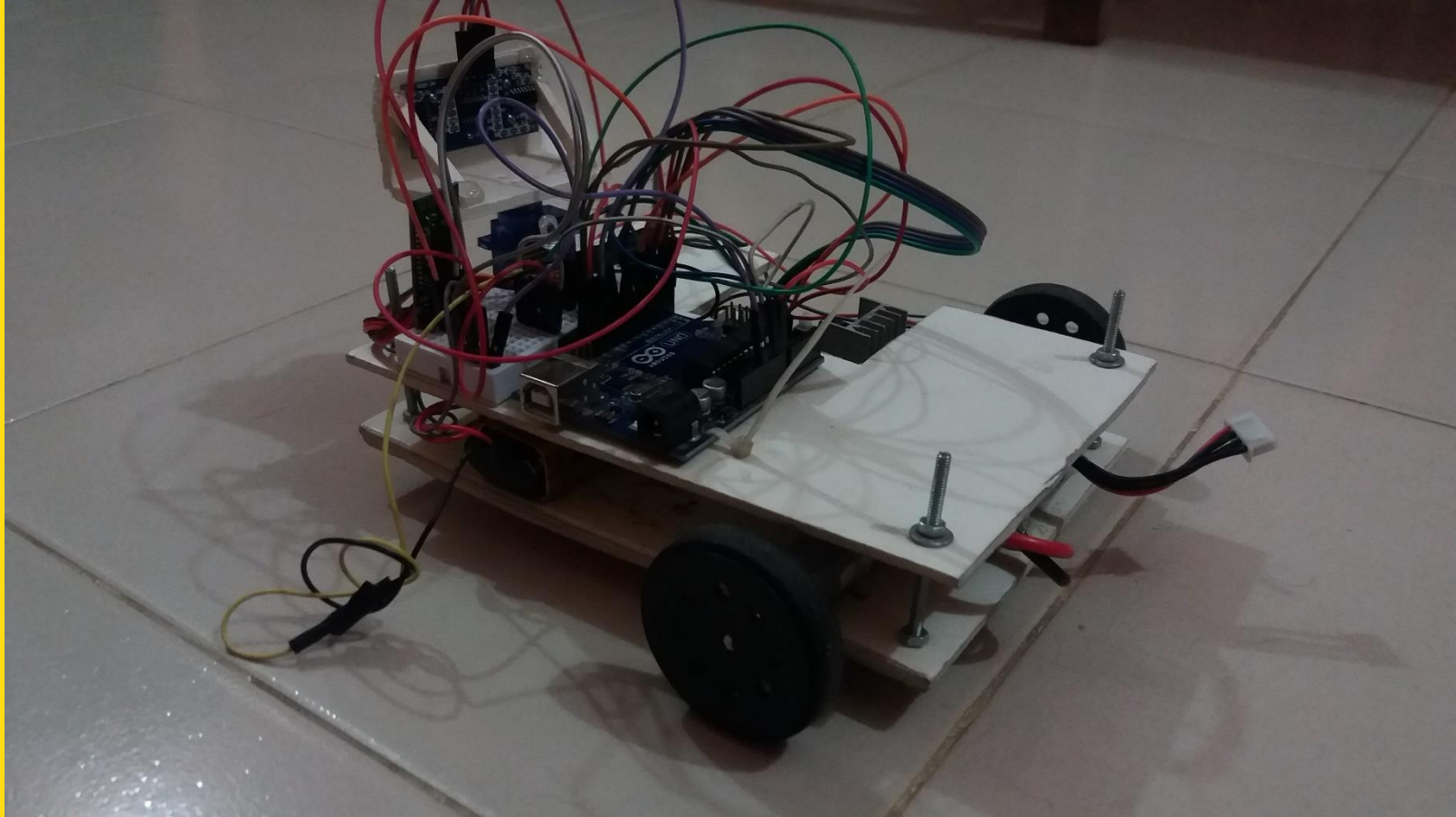


# DRONE VIEW

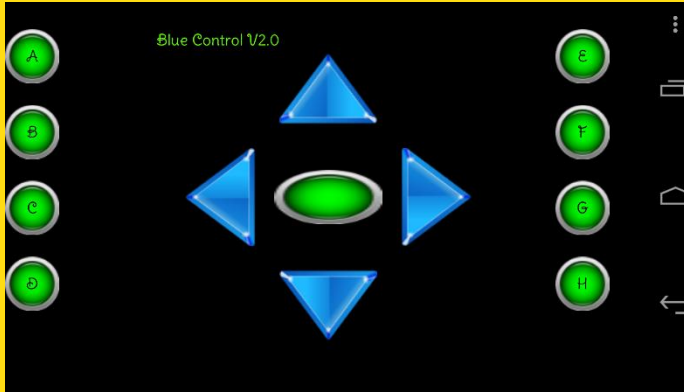




# REAR VIEW

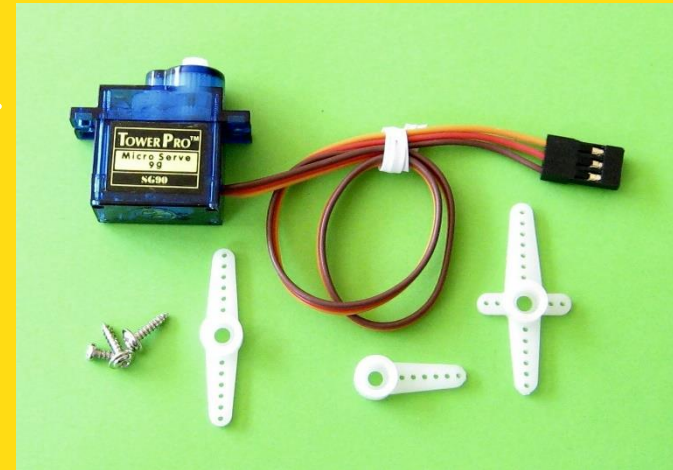


# Special Feature



Android  
Control  
Through  
Bluetooth By  
Our Android  
App

Servo Motor Detecting  
Obstacles At Every  
Direction(180 Degree)



# Advantages & Disadvantages

## **ADVANTAGES**

Senses  
obstacles  
Automatically

Low cost &  
simple  
programing

## **DISADVANTAGES**

Works only  
for short  
distance

Time  
consuming  
project



# Future Development

## **ARTIFICIAL INTELLIGENCE**

- Machine learning
- Voice & Image recognition

## **DIFFERENT ALGORITHMS**

- Color Image Domain
- Detect & Track Object

## **SENSORS**

- Accelerometer, GPS
- Pattern Recognition





THANK YOU EVERYONE!

Any Question?

