

Diffusion Models as Plug-And-Play Priors

Sunday, November 13, 2022 3:42 AM

- This note is written as I read "Diffusion models and plug-and-play priors" by Graikos et al.
- Paper link: <https://arxiv.org/abs/2206.09012>

- We have a prior $p(x)$ on high-dimensional data such as images.
- We are given a constraint $c(x, y)$.
- We want to perform "inference" on a model that involve $p(x)$ and $c(x, y)$.
- That is, we want to find an approximation to $p(x|y) \propto p(x) c(x, y)$.
- In our case, the prior is a DDPM: $p(x^{(0)}, x^{(1)}, x^{(2)}, \dots, x^{(T)})$

pretrained and cannot be changed \nwarrow $x^{(1)}$ \nwarrow $x^{(2)}$ \nwarrow \dots \nwarrow $x^{(T)}$
treated as latent variables h

- What is $c(x, y)$? It can be:

$\Rightarrow c(x, y) = \text{probability that image } x \text{ has class } y.$

$\Rightarrow c(x, y) = \text{a constraint so that image } x \text{ matches a segmentation labeling } y$

Variation Inference

- We are given a posterior distribution

$$p(x|y) = \frac{p(x) c(x, y)}{Z(y)}$$

where $Z(y) = \int p(x) c(x, y) dx$ is a normalization constant,

- We want to approximate $p(x|y)$ with a tractable distribution $q(x)$
- So, we seek to minimize $D_{KL}(q(x) \parallel p(x|y))$, which is given by

$$D_{KL}(q(x) \parallel p(x|y))$$

$$= \int q(x) \log \frac{q(x)}{p(x, y)} dx$$

$$= E_{x \sim q(x)} [\log q(x) - \log p(x, y)]$$

constant \uparrow

$$\begin{aligned}
 & - \mathbb{E}_{x \sim q(x)} [\log p(x) + \log c(x, y) - \log Z(y) - \log q(x)] \\
 & = - \mathbb{E}_{x \sim q(x)} [\log p(x) + \log c(x, y) - \log q(x)] + C
 \end{aligned}$$

$F = \text{free energy}$

- When $q(x)$ is expressive enough to capture $p(x, y)$, we have that $q(x) = p(x|y)$ when F is optimized.
- Otherwise, $q(x)$ will capture a mode-seeking approximation to $p(x|y)$.
 \hookrightarrow If $q(x)$ is Dirac delta, then the optimized $q(x)$ will be located at the mode of $p(x|y)$.

Variational inference with latent variable model

- We consider the special case where $p(x)$ is a latent variable model $p(x, h)$ with $p(x) = \int p(x, h) dh = \int p(x|h) p(h) dh$.
- The problem now is that $p(x)$ becomes hard to approximate.
- The solution is to introduce another component to the tractable distribution.
- Let $q(h|x)$ be a tractable approximate to the posterior $p(h|x)$.
- In this way,

$$\begin{aligned}
 p(x) &= \int p(x|h) p(h) dh \\
 &= \int q(h|x) \frac{p(x|h) p(h)}{q(h|x)} dh \\
 &= \mathbb{E}_{h \sim q(h|x)} \left[\frac{p(x|h) p(h)}{q(h|x)} \right].
 \end{aligned}$$

- By Jensen's inequality,

$$\log p(x) = \log \mathbb{E}_{h \sim q(h|x)} \left[\frac{p(x|h) p(h)}{q(h|x)} \right] = \log \mathbb{E}_{h \sim q(h|x)} \left[\frac{p(x, h)}{q(h|x)} \right]$$

$$\begin{aligned}
\log p(x) &= \log E_{h \sim q(h|x)} \left[\frac{p(x|h) p(h)}{q(h|x)} \right] = \log E_{h \sim q(h|x)} \left[\frac{p(x,h)}{q(h|x)} \right] \\
&\geq E_{h \sim q(h|x)} \left[\log \frac{p(x,h)}{q(h|x)} \right] \\
&= E_{h \sim q(h|x)} \left[\log p(x,h) - \log q(h|x) \right]
\end{aligned}$$

- Now, consider the free energy F

$$\begin{aligned}
F &= - E_{x \sim q(x)} \left[\log p(x) + \log c(x,y) - \log q(x) \right] \\
&= - E_{x \sim q(x)} \left[\log p(x) - \log q(x) \right] - E_{x \sim q(x)} \left[\log c(x,y) \right] \\
&\leq - E_{x \sim q(x)} \left[E_{h \sim q(h|x)} \left[\log p(x,h) - \log q(h|x) \right] - \log q(x) \right] \\
&\quad - E_{x \sim q(x)} \left[\log c(x,y) \right] \\
&= - E_{x \sim q(x)} \left[E_{h \sim q(h|x)} \left[\log p(x,h) - \log q(h|x) \right] - E_{h \sim q(h|x)} \left[\log q(x) \right] \right] \\
&\quad - E_{x \sim q(x)} \left[\log c(x,y) \right] \\
&= - E_{x \sim q(x), h \sim q(h|x)} \left[\log p(x,h) - \log q(h|x) - \log q(x) \right] - E_{x \sim q(x)} \left[\log c(x,y) \right] \\
&= - E_{x \sim q(x), h \sim q(h|x)} \left[\log p(x,h) - \log q(h|x) q(x) \right] - E_{x \sim q(x)} \left[\log c(x,y) \right]
\end{aligned}$$

- Equation (2) of the paper says that $F = \text{RHS above}$.

However, this is not the case!!! The paper was sloppy.

It should be

$$F \leq - \underbrace{E_{x \sim q(x), h \sim q(h|x)} \left[\log p(x,h) - \log q(x) q(h|x) \right]}_{\substack{\text{ELBO}(x) \text{ or } \text{VLB}(x) \\ \text{"evidence lower bound"} \\ \text{"variational lower bound"}}}} - E_{x \sim q(x)} \left[\log c(x,y) \right]$$

Application to DDPM

- For a DDPM, we have that

$$p(x^{(T)}, x^{(T-1)}, \dots, x^{(0)}) = p(x^{(T)}) \prod_{t=1}^T p(x^{(t-1)} | x^{(t)})$$

where

$$p(x^{(t-1)} | x^{(t)}) = N(x^{(t-1)}; \underbrace{\mu_\theta(x^{(t)}, t)}_{\text{neural network}}, \underbrace{\Sigma_\theta(x^{(t)}, t)}_{\sigma_t^2 I \text{ fixed function of } t}),$$

$$p(x^{(t)}) = N(x^{(t)}; 0, I)$$

- The DDPM is trained so that

$$q(x^{(t)} | x^{(t-1)}) = N(x^{(t)}; \sqrt{1-\beta_t} x^{(t-1)}, \beta_t I).$$

So, we should use

$$q(h = (x^{(T)}, x^{(T-1)}, \dots, x^{(1)}) | x) = \prod_{t=1}^T q(x^{(t)} | x^{(t-1)}).$$

- The simplest approximation $q(x)$ that we can use is the Dirac delta

$$q(x) = \delta(x - \eta).$$

which simply sets $x^{(0)} = \eta$.

- So, with $q(x) = \delta(x - \eta)$

$$\begin{aligned} & - E_{x \sim q(x), h \sim q(x)} [\log p(x, h) - \log q(x) q(h | x)] = E_{x \sim q(x)} [\log c(x, y)] \\ & = - E_{h \sim q(\eta)} [\log p(\eta, h) - \log q(h | \eta)] \} L = \log c(\eta, y) \end{aligned}$$

- We now must optimize η so that $L = \log c(\eta, y)$ is minimized.

- From the standard derivation of the ELBO of a DDPM, we have that

$$\begin{aligned} L &= - E_{x^{(T)} \sim q(x^{(T)} | \eta)} \left[\log \frac{p(x^{(T)})}{q(x^{(T)} | \eta)} \right] \} L_T \\ & - E_{x^{(1)} \sim q(x^{(1)} | \eta)} \left[\log p(\eta | x^{(1)}) \right] \} L_0 \\ & - \sum_{t=2}^T E_{x^{(t)} \sim q(x^{(t)} | \eta)} \left[D_{KL}(q(x^{(t-1)} | x^{(t)}, \eta) \| p(x^{(t-1)} | x^{(t)})) \right] \} L_{t-1} \end{aligned}$$

- Now, following the (non-standard) derivation in my note

- Now, following the (non-standard) derivation in my note ^{L_{T-1}} (<https://pkhungurn.github.io/notes/notes/ml/ddpm/ddpm.pdf>), we have that

$$L_0 + \sum_{t=2}^T L_{t-1} = \sum_t w(t) E_{\xi \sim N(0, I)} [\|\xi - \xi_\theta(x^{(t)}, t)\|^2]$$

Where $x^{(t)} = \sqrt{\alpha_t} \eta + \sqrt{1 - \alpha_t} \xi$, $\alpha_t = 1 - \beta_t$, $\bar{\alpha}_t = \prod_{s=1}^t \alpha_s$, and $w(t)$ is a weight function.

- The paper then makes more simplifications

- ① It drops the L_T term even though it has dependency on η
- ② It drops the $w(t)$ term to simplify the loss as Ho et al. does in their famous DDPM paper.

$$\text{So, } L - \log c(\eta, y) \approx \underbrace{\left(\sum_{t=1}^T E_{\xi \sim N(0, I)} [\|\xi - \xi_\theta(x^{(t)}, t)\|^2] \right)}_{L_{\text{simple}}} - \log c(\eta, y)$$

- To repeat, we perform inference by optimizing ^{L_{simple}} with respect to η .
- The paper gives a sample optimization algorithm.

Input: pretrained $\xi_\theta(\cdot, \cdot)$, data y , constraint $c(\cdot, \cdot)$, learning rate λ

Initialized $x \sim N(0, I)$

for $i = T$ downto 1

Sample $\xi \sim N(0, I)$

$$x_{t_i} \leftarrow \sqrt{\alpha_{t_i}} x + \sqrt{1 - \alpha_{t_i}} \xi$$

$$x \leftarrow \lambda \nabla_x (\|\xi - \xi_\theta(x^{(t_i)}, t_i)\|^2 - \log c(x, y))$$

end for

output $\eta = x$

Not that the timestep is not simple $t = T, T-1, \dots, 1$, but

$$t = t_T, t_{T-1}, \dots, t_1$$

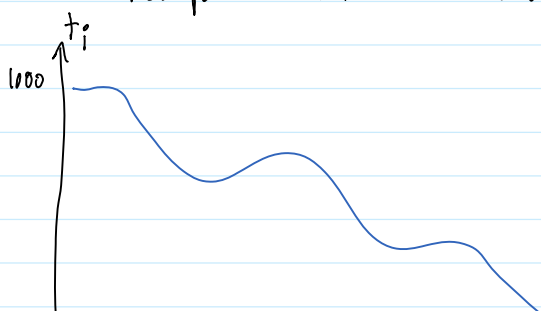
So, there's a flexibility in choosing the timestep.

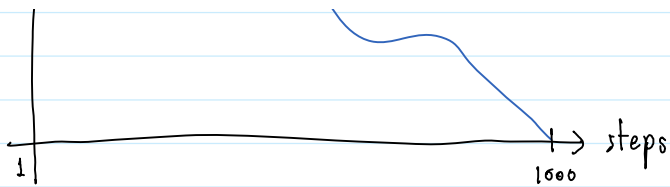
- The above algorithm can be changed in various ways.
 - \Rightarrow How to initialize x
 - \Rightarrow The number of time steps T
 - \Rightarrow The timesteps used $t_T, t_{T-1}, t_{T-2}, \dots, t_1$
 - \Rightarrow How x is accumulated.
 - \hookrightarrow The above is based on SDD, but we may do something else.
- Note that the optimization is stochastic. Each time it is run it produces a different output.
- On the timestep used.
 - \Rightarrow The paper observed that, when optimizing for all timestep at once, it is hard for the sample to reach a mode.
 - \Rightarrow So, they suggest annealing: t_i should generally be decreasing.
 - \hookrightarrow First few iterations should coarsely explore the search space.
 - \hookrightarrow Later iterations should be at lower temperature to home in on a local minimum.

Conditional image generation ①: MNIST

\rightarrow the "DDPM beats GAN" paper

- The paper trains Dhariwal and Nichol (2021) on MNIST.
- They experimented with a number of constraints $c(x, y)$
 - \Rightarrow "thin digit" = negative of average density of image
 - \Rightarrow "thick digit" = average intensity.
 - \Rightarrow "vertical symmetry", "horizontal symmetry" = negative distance between two halves
 - \Rightarrow "class" = "generate digit 3"
- Inference was performed with the ADAM optimizer with learning rate 10^{-2}
- The timesteps is cosine-modulated linearly decreasing.





- It is also important to reduce the weight of the constraint $\log C(x, y)$ as we progress through the algorithm. So, they set the weight for that term to linearly decrease from $w_T = 10^{-2}$ to $w_L = 0$.
Not doing so results in poor sample quality.

Conditional image generation ②: FFHQ

- Use ① DDPM for 256×256 FFHQ from Baranchuk et al. (<https://arxiv.org/abs/2112.03126>)

② pretrained ResNet-18 face attribute classifier on CelebA
(<https://arxiv.org/abs/1411.7766>)

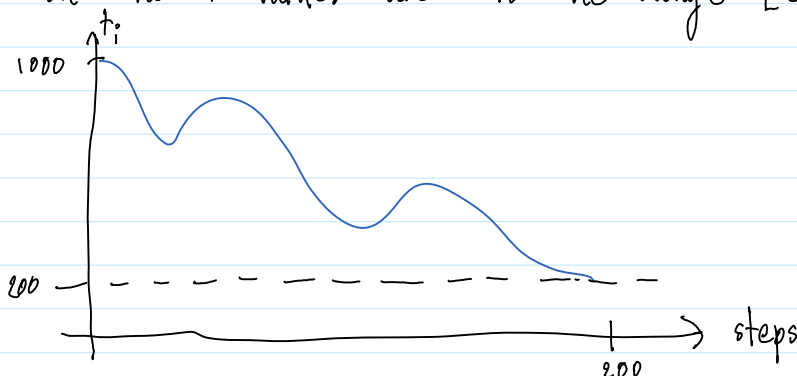
- Attributes classified included "no beard", "smiling", "blonde hair", "male"
- The paper select a collection of attributes $y = \{y_1, y_2, \dots, y_k\}$ and enforce the attributes with constraint

$$C(x, y) = \prod_{i=1}^k \log p(y_i | x)$$

→ classifier for attribute y_i

Inference algorithm

- ⇒ Run optimization with Adamax with $\beta_1 = 0.9$, $\beta_2 = 0.999$ for 200 steps
- ⇒ Decrease learning rate from 1 to 0.5
- ⇒ Timestep schedule is again cosine modulated linearly decreasing but the t values are in the range $[200, 1000]$.



- ⇒ Balancing diffusion loss (L) with $\log C(x, y)$ was difficult.

⇒ Balancing diffusion loss (L) with $\log c(x, y)$ was difficult.

⇒ So, clip the gradient norm of $\log c(x, y)$ to half of diffusion loss's gradient norm.

⇒ After the 200 Adamax step, the image is still noisy,
so the paper just run the DDPM from $t=200$ to denoise
the sample.

Comments

- The paper also provides experiments on semantic segmentation and solving TSP. However, I did not read them in details.
- The framework introduced by the paper is versatile
 - ↳ Can use off-the-shelf DDPM.
 - ↳ Constraints can be anything including off-the-shelf classifiers
 - ↳ as long as it is differentiable
- However, it is hard to apply.
 - ↳ Need to finetune algorithm for each problem instance.
- No guarantees on generated sample quality.