

Speed:

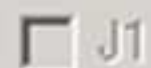
5

Motion Command:

Go

Execute

Free Joints



J1



J3



J2



J4

Free All

Lock All

Points

Point #:

0

Point Name:

X (mm)

4.726

Y (mm)

433.951

Z (mm)

-73.198

Local

0

0

999

U (deg)

94.379

V (deg)

W (deg)

J4Flag

Point File:

robot1.pnt

Hand

Righty

Elbow

Wrist

J6Flag

Teach P0

Delete P0