

### Safety Function File Settings-YRC1000

Robot Range Limit | Axis Range Limit | Axis Speed Monitor | Speed Limit | Tool Angle Monitor

File No. 1

Comment

File Valid Cond Valid

Alarm Set ON Stop Method Category0

Group R1

Out Signal Undefined

Monitor Target OutSide

CPU Load 6

Coord Robot

Shape Type Cuboid

Used Vertex Num 4

In Signal

bit	Input Signal	Set
bit0	Undefined	OFF
bit1	Undefined	OFF
bit2	Undefined	OFF
bit3	Undefined	OFF
bit4	Undefined	OFF

Vertex

Vertex	X (mm)	Y (mm)	Z
Vertex1	600	-250	2
Vertex2	680	-50	5

Z Upper (mm) 250

Z Lower (mm) 50

Add Model Delete Model

Model Settings

Inside

Color...

Opacity 0.50

OutSide/Plane

Color...

Opacity 0.50

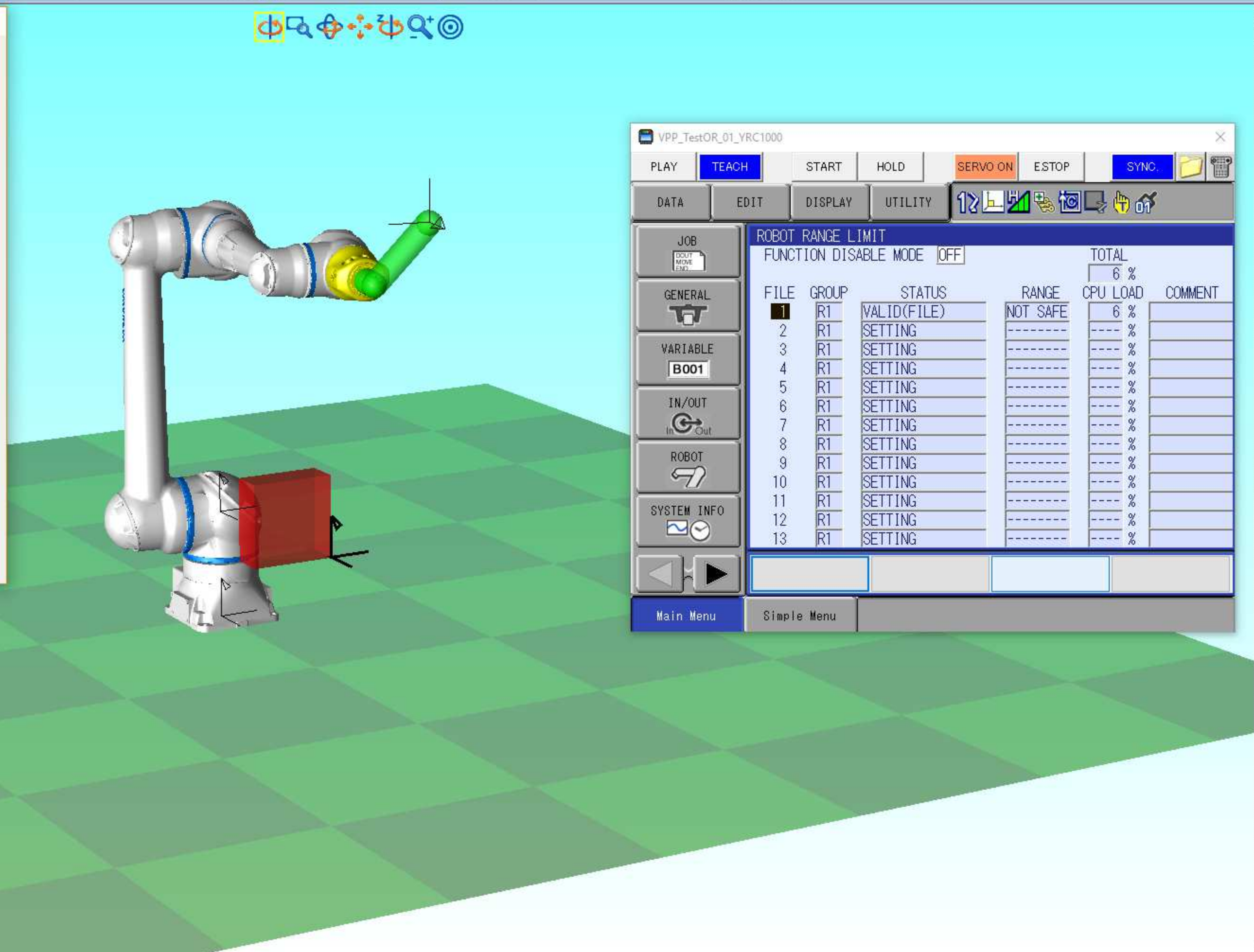
Add All Model

Delete All Model

Safety fence Utility

Delete Safety fence

Close



### VPP\_TestOR\_01\_YRC1000

PLAY TEACH START HOLD SERVO ON ESTOP SYNC

DATA EDIT DISPLAY UTILITY

JOB

GENERAL

VARIABLE B001

IN/OUT

ROBOT

SYSTEM INFO

#### ROBOT RANGE LIMIT

FUNCTION DISABLE MODE OFF

TOTAL 6 %

FILE	GROUP	STATUS	RANGE	CPU LOAD	COMMENT
1	R1	VALID(FILE)	NOT SAFE	6 %	
2	R1	SETTING	---	---	
3	R1	SETTING	---	---	
4	R1	SETTING	---	---	
5	R1	SETTING	---	---	
6	R1	SETTING	---	---	
7	R1	SETTING	---	---	
8	R1	SETTING	---	---	
9	R1	SETTING	---	---	
10	R1	SETTING	---	---	
11	R1	SETTING	---	---	
12	R1	SETTING	---	---	
13	R1	SETTING	---	---	

Main Menu Simple Menu