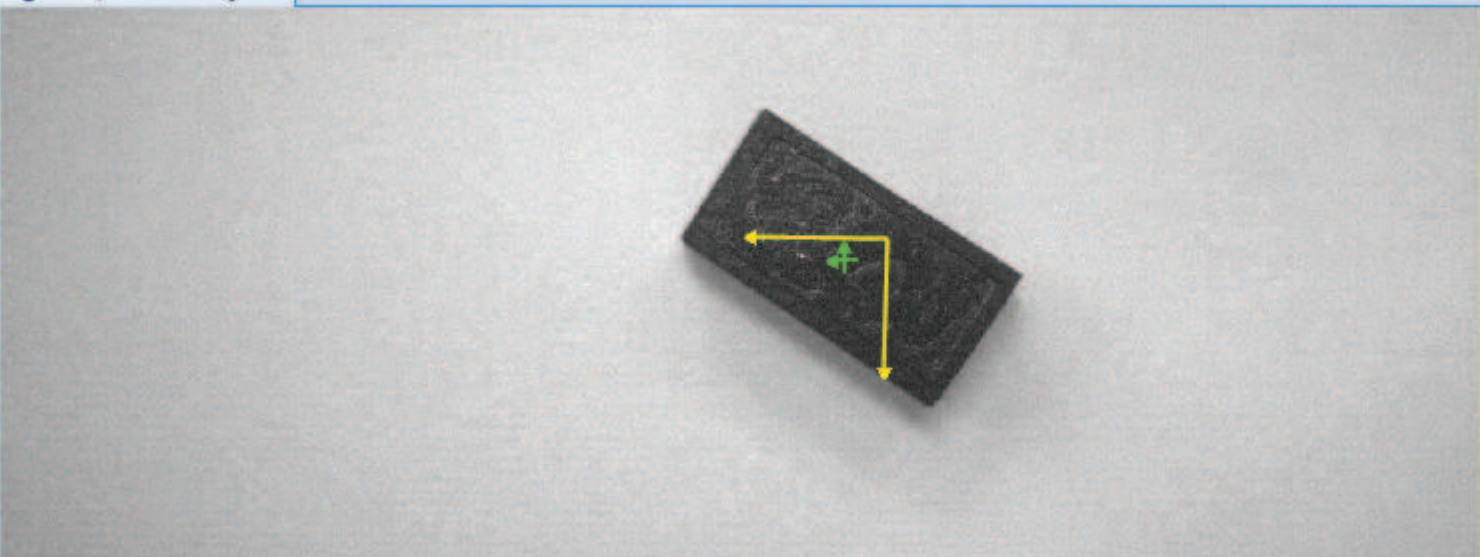


Yumi_Vision/vidRobTest.job



ResultsI/OHelp

	Name	Result
	kvader	(5.7,3.1) -180.1° soc

Rate: 100,0% (21/21)
Time: 0,0ms

OutputContext - Setup communication

Item types

objekt1

AddDeleteRename

Camera target inputs for selected item type

Component	Data type	Group	Result	Value
Position x	num	kvader	Fixture.X	5,673
Position y	num	kvader	Fixture.Y	3,116
Rotation z	num	kvader	Fixture.Angle	-180,116
Value 1	num	Constant	0	0
Value 2	num	Constant	0	0
Value 3	num	Constant	0	0
Value 4	num	Constant	0	0

Resulting camera target

Component	Value
x	5,673
y	3,116
z	0
anglex	0
angley	0
anglez	-180,116
val1	0

Revert