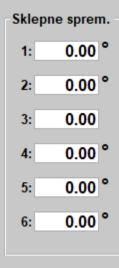
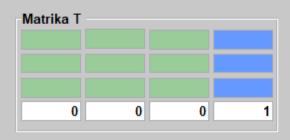
Х

## Direktni kinematični model robota UR5e.







Izračun modela robota z vektorskimi parametri