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Run Program Installation Move IO Log

PROGRAM <unnamed>  
INSTALLATION default

New... Open... Save...

C C  
C C

≡

Initialize

Robot Status

Power  
ON

Booting  
Complete

Robot  
Active

Brakes  
Released

Robot in  
Normal Mode

START

OFF

Payload

Robot

Active Payload is used to temporarily overwrite the Installation Payload.

Active Payload

Installation Payload

0 kg

0.00 kg

Exit

Speed 100%

8

4

7

5