

RModelo - Robot Model Description Form

R. Manseur - Robot Modeling and Kinematics.

Robot DH-Parameters

i	d	a	θ	ϕ
1	0.2	0.2	90	0
2	0.2	0.2	90	0
3	0.2	0.2	90	0
4	0.2	0.2	90	0
5	0.2	0.2	90	0
6	0.2	0.2	90	0

Check for Link Frame

- Check if Prismatic
- ☐ Prismatic

☐ Frame 0
- ☐ Prismatic

☐ Frame 1
- ☐ Prismatic

☐ Frame 2
- ☐ Prismatic

☐ Frame 3
- ☐ Prismatic

☐ Frame 4
- ☐ Prismatic

☐ Frame 5
- ☐ Prismatic

☐ Frame 6

Save Robot

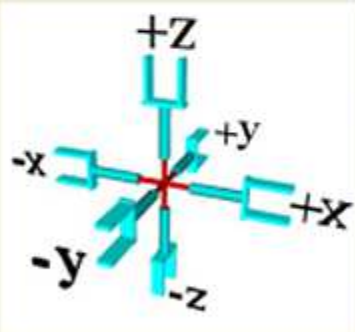
Model Robot

☐ Show Frames Only

Model With Trajectory

Number of points
50

Robot End-Effector Orientation Choices



- ☐ - X Direction
- ☒ + X Direction
- ☐ - Y Direction
- ☐ + Y Direction
- ☐ - Z Direction
- ☐ + Z Direction