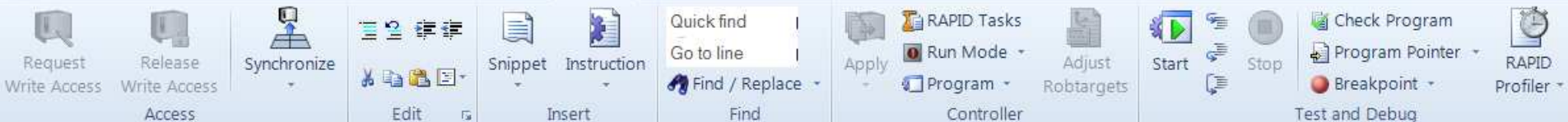


File Home Modeling Simulation Controller RAPID Add-Ins



Controller

Files

Current Station

- IRB1600\_6kg\_1.45m
  - Configuration
  - Event Log
  - I/O System
  - RAPID
    - T\_ROB1 (Program 'alu\_blok')
      - Program Modules
        - CalibData
        - Module1
          - main
          - Path\_10
          - Path\_20
          - Path\_30
          - Path\_40
      - System Modules
        - BASE
        - user

test\_alu\_block5:View1

IRB1600\_6kg\_1.45m (Station) x

T\_ROB1/Module1 x

```

205 CONST robtarget Target_2030:=[[-21.235118168,174.799154351,-9.501515804],[0.4
206 CONST robtarget TockPredObd:=[[108.663654353,-110.259819587,28.750126047],[0.
207 PROC main()
208   Path_10;
209   Path_20;
210   Path_30;
211   Path_40;
212
213   ENDPROC
214 PROC Path_10()
215   MoveJ Target_10,v1000,z100,MyNewTool\WObj:=wobj0;
216   MoveJ Target_20,v1000,z100,MyNewTool\WObj:=wobj0;
217   MoveJ Target_30,v1000,z100,MyNewTool\WObj:=Workobject_1;
218   MoveL Target_40,v1000,z100,MyNewTool\WObj:=Workobject_1;
219   MoveL Target_50,v1000,z100,MyNewTool\WObj:=Workobject_1;
220   MoveL Target_60,v1000,z100,MyNewTool\WObj:=Workobject_1;
221   MoveL Target_70,v1000,z100,MyNewTool\WObj:=Workobject_1;
222   MoveL Target_80,v1000,z100,MyNewTool\WObj:=Workobject_1;
223   MoveL Target_90,v1000,z100,MyNewTool\WObj:=Workobject_1;
224   MoveL Target_100,v1000,z100,MyNewTool\WObj:=Workobject_1;
225   MoveL Target_110,v1000,z100,MyNewTool\WObj:=Workobject_1;
226   MoveL Target_120,v1000,z100,MyNewTool\WObj:=Workobject_1;
227   MoveL Target_130,v1000,z100,MyNewTool\WObj:=Workobject_1;
228   MoveL Target_140,v1000,z100,MyNewTool\WObj:=Workobject_1;
229   MoveL Target_150,v1000,z100,
230   MoveL Target_160,v1000,z100,
231   MoveL Target_170,v1000,z100,
232   MoveL Target_180,v1000,z100,MyNewTool\WObj:=Workobject_1;
233   MoveL Target_190,v1000,z100,MyNewTool\WObj:=Workobject_1;
234   MoveL Target_200,v1000,z100,MyNewTool\WObj:=Workobject_1;
235   MoveL Target_210,v1000,z100,MyNewTool\WObj:=Workobject_1;
236   MoveL Target_220,v1000,z100,MyNewTool\WObj:=Workobject_1;
237   MoveL Target_230,v1000,z100,MyNewTool\WObj:=Workobject_1;

```

PERS tooldata MyNewTool  
Module: CalibData  
Current Value: [TRUE,[[55.53,0,116.21],[0.906308,0,0.0]]]

Controller Status

Output

Search Results

RAPID Watch

Simulation Watch

Show messages from All messages

Time

Category

IRB1600_6kg_1.45m (Station): 10002 - Program pointer has been reset	23.9.2014 14:55:42	Event Log
IRB1600_6kg_1.45m (Station): 10011 - Motors ON state	23.9.2014 14:55:43	Event Log
IRB1600_6kg_1.45m (Station): 10052 - Regain start	23.9.2014 14:55:43	Event Log
IRB1600_6kg_1.45m (Station): 10053 - Regain ready	23.9.2014 14:55:43	Event Log
IRB1600_6kg_1.45m (Station): 10151 - Program started	23.9.2014 14:55:43	Event Log
IRB1600_6kg_1.45m (Station): 10125 - Program stopped	23.9.2014 14:55:46	Event Log