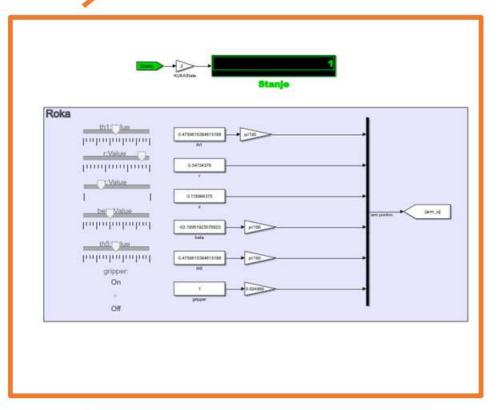
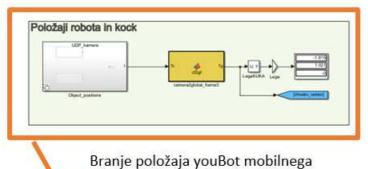
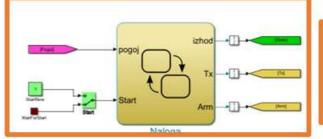
Virtualna kontrolna palica za premikanje roke robota.

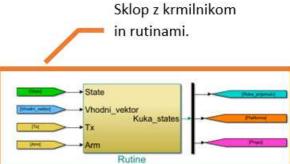


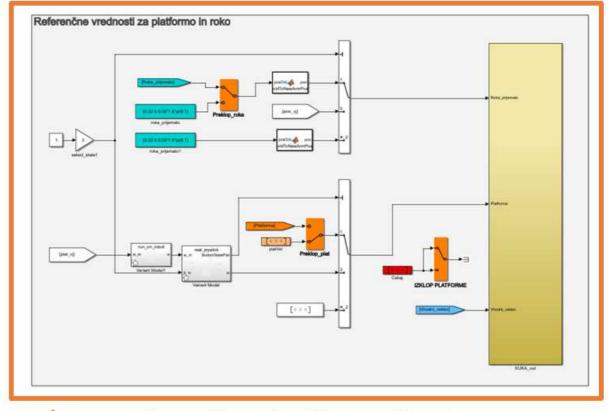


robota in kock.

Sklop Naloga v katerega boste
v pravem vrstnem redu v
diagram prehajanja stanj
razporedili rutine za reševanje
naloge Hanojski stolp.







Sklop za pošiljanje referenčnih vrednosti hitrosti platforme in položaja roke.