



Manual

14000-100151 (192.168.65.80)

Motors Off

Stopped (2 of 2) (Speed 100%)



Jogging

Tap a property to change it

Mechanical unit: ROB_R...

Absolute accuracy: On

Motion mode: Linear...

Coordinate system: Base...

Tool: GripperR...

Work object: wobj0...

Payload: load0...

Joystick lock: None...

Increment: None...

Position

Positions in coord: WorkObject

X: 82.44 mm

Y: -280.68 mm

Z: 211.52 mm

q1: 0.13256

q2: 0.74653

q3: 0.21155

q4: 0.61673

Position Format...

Joystick directions



X



Y



Z

Align...

Go To...

Activate...

Enable Lead-through

Program
Editor

Jogging

