

Project Explorer

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Main.prg

```
Global String GReadString$
Global String GWriteString$
Global Integer TestNumber
```

Function main

```
Motor On
Power Low
```

```
Speed 10
SpeedS 10
```

```
Xqt EthernetControl
```

```
Integer i, StringToCut
```

```
i = 0
```

```
Do While i < 2
```

```
  If Len(GReadString$) > 0 Then
    Print GReadString$
    If Left$(GReadString$, 1) = "M" Then
```

```
      StringToCut = InStr(
        TestNumber = Val(Mid(
        Print TestNumber
```

```
Select TestNumber
```

```
  Case 0
    Call StartRobot
```

```
  Case 1
    Call FPoint1_x
```

Robot Manager

Control Panel

Jog & Teach

Points

Arch

Locals

Tools

Boxes

Planes

Weight

Inertia

XYZ Limits

Range

Home Config

Status

Emergency Stop: OFF

Safeguard: OFF

Motors: ON

Power: LOW

Motors

MOTOR OFF

MOTOR ON

Power

POWER LOW

POWER HIGH

Free Joints

☐ J1

☐ J2

☐ J3

☐ J4

Free All

Lock All

Reset

Home

Status

08:40:29 Sending files to controller...

08:40:29 Sending Points.pts

08:40:29 Sending tmp2.sprj

08:40:29 Loading project in controller...

08:40:29 Controller point files update complete