



Move

PROGRAM koncana aplikacija 14.11\*  
INSTALLATION kamera kalibrirana\*

New...

Open...

Save...

0 7  
C B

Run

Program

Installation

Move

I/O

Log

TCP Position

Robot

Tool Position

Feature

Active TCP

View

TCP

X 316.780 mm RX 0.411 rad

Y -487.550 mm RY -3.098 rad

Z 127.010 mm RZ 0.023 rad

TCP Orientation

Joint Position

Base 91.39 °

Shoulder -79.66 °

Elbow 73.03 °

Wrist 1 -83.97 °

Wrist 2 -91.10 °

Wrist 3 4.87 °



Home



Freedrive

Speed 100%

10:57:10  
November 23, 2018