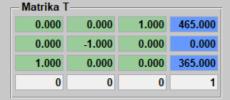
## Direktni kinematični model robota Fanuc CR7i



- 1: 0.00 ° 2: 0.00 °
- 2. 0.00
- 3: 0.00
- 4: 0.00 °
- 5: 0.00 °
- 6: 0.00 °





Izračun modela robota z vektorskimi parametri