

Robot Manager

Control Panel

Jog & Teach

Points

Arch

Locals

Tools

Boxes

Planes

Weight

Inertia

XYZ Limits

Range

Home Config

Jogging

Mode: World

Speed: High

←
+X

↑
-Y

→
-X

↑
+Z

↓
+Y

↓
-Z

↶
-U

↶
-V

↶
-W

↷
+U

↷
+V

↷
+W

Execute Motion Command

Command: Go

Execute

Local: 0

Tool: 0

Arm:

Current Position

X (mm)	Y (mm)	Z (mm)	<input checked="" type="radio"/> World
-29.444	682.140	608.550	<input type="radio"/> Joint
U (deg)	V (deg)	W (deg)	<input type="radio"/> Pulse
160.929	-86.860	112.428	

Current Arm Orientation

Hand	Elbow	Wrist	J4Flag	0
Righty	Above	NoFlip	J6Flag	0

Jog Distance

X (mm)	Y (mm)	Z (mm)	<input checked="" type="radio"/> Continuous
			<input type="radio"/> Long
U (deg)	V (deg)	W (deg)	<input type="radio"/> Medium
			<input type="radio"/> Short

Teach Points

Point File: Points.pts

Teach

Point: P0 - Start

Edit