



Auto

14000-100151 (SKELETOR)

Motors On

Stopped (2 of 2) (Speed 100%)



NewProgramName in T_ROB_L/MainModule

Tasks and Programs

Modules

Routines

PROC main()

MoveJ homeL,v1000,fine,Camera\WObj:=wobj0;

MoveJ Target_10,v1000,fine,Camera\WObj:=wobj0

Hand_GripOutward;

MoveL Target_20,v1000,fine,Camera\WObj:=wobj0

Hand_MoveTo 10;

MoveL Target_30,v1000,fine,Camera\WObj:=wobj0

MoveL Target_40,v1000,fine,Camera\WObj:=wobj0

ENDPROC

ENDMODULE

Add
Instruction

Edit

Debug

Modify
PositionHide
DeclarationsT_ROB_L
MainMod...