



# Principles of Parameter Estimation

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# PRELIMINARIES

**Given:** a set of observations  $\mathcal{D} = \{x_i\}_{i=1}^n$ ,  $x_i \in \mathcal{X}$

**Objective:** find a model  $\hat{f} \in \mathcal{F}$  that models the phenomenon well

**Requirements:**

- (i) the ability to generalize well
- (ii) the ability to incorporate prior knowledge and assumptions
- (iii) scalability

**Terminology through an example:**  $\mathcal{D} = \{3.1, 2.4, -1.1, 0.1\}$

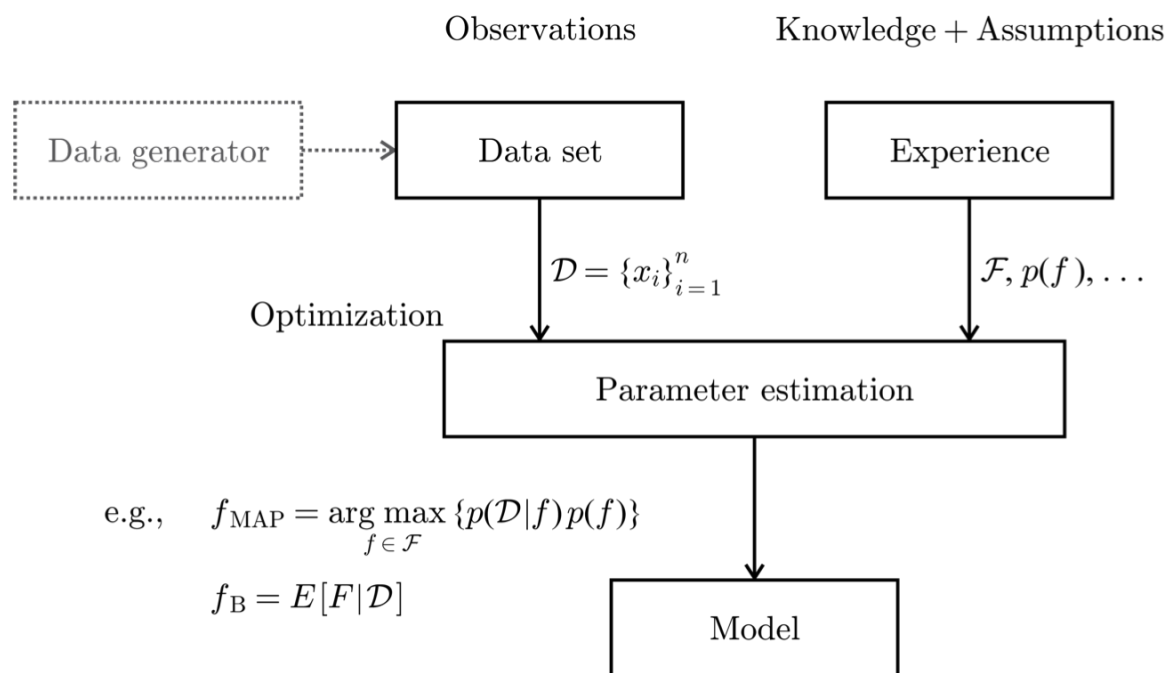
What is the data generator?

$\mathcal{F} = \text{Gaussian}(\mu, \sigma^2)$ ,  $\mu \in \mathbb{R}$ ,  $\sigma \in \mathbb{R}^+$

**Parameter  
estimation**



# STATISTICAL FRAMEWORK



*Model inference:* Observations + Knowledge and Assumptions + Optimization



# MAXIMUM A POSTERIORI INFERENCE

**Idea:**

$$f_{\text{MAP}} = \arg \max_{f \in \mathcal{F}} \{p(f|\mathcal{D})\},$$

where  $p(f|\mathcal{D})$  is called the posterior distribution.

**How do we calculate it?**

$$p(f|\mathcal{D}) = \frac{p(\mathcal{D}|f) \cdot p(f)}{p(\mathcal{D})}$$

where  $p(\mathcal{D}|f)$  = likelihood,  $p(f)$  = prior, and  $p(\mathcal{D})$  = data distribution.



# MAXIMUM A POSTERIORI INFERENCE

Finding the data distribution:

$$p(\mathcal{D}) = \begin{cases} \sum_{f \in \mathcal{F}} p(\mathcal{D}|f)p(f) & f : \text{discrete} \\ \int_{\mathcal{F}} p(\mathcal{D}|f)p(f)df & f : \text{continuous} \end{cases}$$

We can now simplify the process if we observe that

$$\begin{aligned} p(f|\mathcal{D}) &= \frac{p(\mathcal{D}|f) \cdot p(f)}{p(\mathcal{D})} \\ &\propto p(\mathcal{D}|f) \cdot p(f) \end{aligned}$$



# MAXIMUM LIKELIHOOD INFERENCE

Express the posterior distribution as

$$\begin{aligned} p(f|\mathcal{D}) &= \frac{p(\mathcal{D}|f) \cdot p(f)}{p(\mathcal{D})} \\ &\propto p(\mathcal{D}|f) \cdot p(f) \end{aligned}$$

Now, ignore  $p(f)$  to get

$$f_{\text{ML}} = \arg \max_{f \in \mathcal{F}} \{p(\mathcal{D}|f)\}$$

There are technical problems with this approach.



## EXAMPLES OF MAXIMUM LIKELIHOOD INFERENCE

**Example:**  $\mathcal{D} = \{2, 5, 9, 5, 4, 8\}$  is an i.i.d. sample from  $\text{Poisson}(\lambda)$ ,  $\lambda \in \mathbb{R}^+$

Find  $\lambda$

**Solution:** Poisson probability mass function is  $p(x|\lambda) = \frac{\lambda^x e^{-\lambda}}{x!}$

$$\lambda_{\text{ML}} = \arg \max_{\lambda \in (0, \infty)} \{p(\mathcal{D}|\lambda)\}.$$

**Likelihood:**  $p(\mathcal{D}|\lambda) = p(\{x_i\}_{i=1}^n | \lambda)$

$$\begin{aligned} &= \prod_{i=1}^n p(x_i|\lambda) \\ &= \frac{\lambda^{\sum_{i=1}^n x_i} \cdot e^{-n\lambda}}{\prod_{i=1}^n x_i!}. \end{aligned}$$



## EXAMPLES OF MAXIMUM LIKELIHOOD INFERENCE

**Likelihood:** 
$$p(\mathcal{D}|\lambda) = \frac{\lambda^{\sum_{i=1}^n x_i} \cdot e^{-n\lambda}}{\prod_{i=1}^n x_i!}$$

**Log-likelihood:** 
$$ll(\mathcal{D}, \lambda) = \ln \lambda \sum_{i=1}^n x_i - n\lambda - \sum_{i=1}^n \ln(x_i!)$$

**Optimization:**

$$\begin{aligned} \frac{\partial ll(\mathcal{D}, \lambda)}{\partial \lambda} &= \frac{1}{\lambda} \sum_{i=1}^n x_i - n \\ &= 0 \end{aligned}$$

**Solution:**

$$\begin{aligned} \lambda_{\text{ML}} &= \frac{1}{n} \sum_{i=1}^n x_i \\ &= 5.5 \end{aligned}$$

MAP and ML estimates are called the point estimates.





## EXAMPLES OF MAP INFERENCE

**Example:**  $\mathcal{D} = \{2, 5, 9, 5, 4, 8\}$  is i.i.d. sample from  $\text{Poisson}(\lambda)$ ,  $\lambda \in \mathbb{R}^+$

Assume  $\lambda$  is taken from  $\Gamma(x|k, \theta)$  with parameters  $k = 3$  and  $\theta = 1$

Find  $\lambda$

**Solution:** Poisson:  $p(x|\lambda) = \frac{\lambda^x e^{-\lambda}}{x!}$

Gamma:  $\Gamma(x|k, \theta) = \frac{x^{k-1} e^{-\frac{x}{\theta}}}{\theta^k \Gamma(k)}$ , where  $x > 0$ ,  $k > 0$ , and  $\theta > 0$ .

**Likelihood:**  $p(\mathcal{D}|\lambda) = \frac{\lambda^{\sum_{i=1}^n x_i} \cdot e^{-n\lambda}}{\prod_{i=1}^n x_i!}$

**Prior:**  $p(\lambda) = \frac{\lambda^{k-1} e^{-\frac{\lambda}{\theta}}}{\theta^k \Gamma(k)}$ .



## EXAMPLES OF MAP INFERENCE

**Log-likelihood:**

$$\begin{aligned}\ln p(\lambda|\mathcal{D}) &\propto \ln p(\mathcal{D}|\lambda) + \ln p(\lambda) \\ &= \ln \lambda(k-1 + \sum_{i=1}^n x_i) - \lambda(n + \frac{1}{\theta}) - \sum_{i=1}^n \ln x_i! - k \ln \theta - \ln \Gamma(k)\end{aligned}$$

We now obtain

$$\begin{aligned}\lambda_{\text{MAP}} &= \frac{k-1 + \sum_{i=1}^n x_i}{n + \frac{1}{\theta}} \\ &= 5\end{aligned}$$



## ANOTHER EXAMPLE

**Example:**  $\mathcal{D} = \{x_i\}_{i=1}^n$  is i.i.d. sample from  $\text{Gaussian}(\mu, \sigma^2)$

Find  $\mu$  and  $\sigma$

**Solution:** Gaussian:  $p(x|\mu, \sigma) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$

$$\mu_{\text{ML}} = \frac{1}{n} \sum_{i=1}^n x_i$$

$$\sigma_{\text{ML}}^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \mu_{\text{ML}})^2.$$



## RELATIONSHIP TO KULLBACK-LEIBLER (KL) DIVERGENCE

The KL divergence between two probability distributions  $p(x)$  and  $q(x)$  is

$$D_{\text{KL}}(p||q) = \int_{-\infty}^{\infty} p(x) \log \frac{p(x)}{q(x)} dx$$

Assume now the data is generated according to some  $p(x|\theta_t)$ . We estimated it as  $p(x|\theta)$ .

Let's look at the KL divergence

$$\begin{aligned} D_{\text{KL}}(p(x|\theta_t)||p(x|\theta)) &= \int_{-\infty}^{\infty} p(x|\theta_t) \log \frac{p(x|\theta_t)}{p(x|\theta)} dx - E[\log p(x|\theta)] \\ &= \int_{-\infty}^{\infty} p(x|\theta_t) \log \frac{1}{p(x|\theta)} dx - \int_{-\infty}^{\infty} p(x|\theta_t) \log \frac{1}{p(x|\theta_t)} dx. \end{aligned}$$



## RELATIONSHIP TO KULLBACK-LEIBLER (KL) DIVERGENCE

$$\frac{1}{n} \sum_{i=1}^n \log p(x_i|\theta) \xrightarrow{a.s.} E[\log p(x|\theta)]$$

when  $n \rightarrow \infty$ .

### Conclusion:

When  $n \rightarrow \infty$ , ML estimation implies  $p(x|\theta_{\text{ML}}) = p(x|\theta_t)$

This usually implies  $\theta_{\text{ML}} = \theta_t$



# PARAMETER ESTIMATION FOR MIXTURES OF DISTRIBUTIONS

**Given:** a set of observations  $\mathcal{D} = \{x_i\}_{i=1}^n$ ,  $x_i \in \mathcal{X}$

$$p(x|\theta) = \sum_{j=1}^m w_j p(x|\theta_j).$$

$$w_j \geq 0, \quad \sum_{j=1}^m w_j = 1.$$

where  $\theta = (w_1, w_2, \dots, w_m, \theta_1, \theta_2, \dots, \theta_m)$

**Example:** Consider a mixture of  $m = 2$  exponential distributions.

$$p(x|\theta_j) = \lambda_j e^{-\lambda_j x}, \text{ where } \lambda_j > 0$$

$$p(x|\lambda_1, \lambda_2, w_1, w_2) = w_1 \cdot \lambda_1 e^{-\lambda_1 x} + w_2 \cdot \lambda_2 e^{-\lambda_2 x}$$

where  $\lambda_1, \lambda_2 > 0$ ,  $w_1, w_2 \geq 0$ , and  $w_1 = 1 - w_2$



# PARAMETER ESTIMATION FOR MIXTURES OF DISTRIBUTIONS

**Likelihood:**

$$\begin{aligned} p(\mathcal{D}|\theta) &= \prod_{i=1}^n p(x_i|\theta) \\ &= \prod_{i=1}^n \left( \sum_{j=1}^m w_j p(x_i|\theta_j) \right) \end{aligned}$$

$p(\mathcal{D}|\theta)$  has  $O(m^n)$  terms. It can be calculated in  $O(mn)$  time as a log-likelihood.

How can we find  $\theta$ ? Is there a closed-form solution?



## IDEA #1

Suppose we know what data point is generated by what mixing component.

That is,  $\mathcal{D}_{xy} = \{(x_i, y_i)\}_{i=1}^n$  is an i.i.d. sample from some distribution  $p(x, y)$ , where  $y \in \mathcal{Y} = \{1, 2, \dots, m\}$  specifies the mixing component.

$$\begin{aligned} p(\mathcal{D}_{xy}|\theta) &= \prod_{i=1}^n p(x_i, y_i|\theta) \\ &= \prod_{i=1}^n p(x_i|y_i, \theta)p(y_i|\theta) \\ &= \prod_{i=1}^n w_{y_i} p(x_i|\theta_{y_i}), \end{aligned}$$

where  $w_j = P(y = j)$ .





## IDEA #1

**Log-likelihood:**

$$\begin{aligned}\log p(\mathcal{D}_{xy}|\theta) &= \sum_{i=1}^n (\log w_{y_i} + \log p(x_i|\theta_{y_i})) \\ &= \sum_{j=1}^m n_j \log w_j + \sum_{i=1}^n \log p(x_i|\theta_{y_i}),\end{aligned}$$

where  $n_j$  is the number of data points in  $\mathcal{D}_{xy}$  generated by the  $j$ -th mixing component.

**Constrained optimization:** Let's first find  $\mathbf{w}$

$$L(\mathbf{w}, \alpha) = \sum_{j=1}^m n_j \log w_j + \alpha \left( \sum_{j=1}^m w_j - 1 \right)$$

where  $\alpha$  is the Lagrange multiplier.



## IDEA #1

Set  $\frac{\partial}{\partial w_k} L(\mathbf{w}, \alpha) = 0$  for every  $k \in \mathcal{Y}$  and  $\frac{\partial}{\partial \alpha} L(\mathbf{w}, \alpha) = 0$ . Solve it.

It follows that  $w_k = -\frac{n_k}{\alpha}$  and  $\alpha = -n$ .

$$w_k = \frac{1}{n} \sum_{i=1}^n I(y_i = k),$$

where  $I(\cdot)$  is the indicator function.

To find all  $\theta_j$ , we need to get concrete.

$$\frac{\partial}{\partial \lambda_k} \sum_{i=1}^n \log p(x_i | \lambda_{y_i}) = 0,$$

for each  $k \in \mathcal{Y}$ .



## IDEA #1

We obtain that

$$\lambda_k = \frac{n_k}{\sum_{i=1}^n I(y_i = k) \cdot x_i},$$

for each  $k \in \mathcal{Y}$ .

Recall that

$$w_k = \frac{1}{n} \sum_{i=1}^n I(y_i = k)$$

If the mixing component designations  $\mathbf{y}$  are known,  
the parameter estimation is greatly simplified.



## IDEA #2

Suppose we know the  $\theta$  but not the mixing component designations..

Looks like clustering, right? Let's see. Express

$$\begin{aligned} p(\mathbf{y}|\mathcal{D}, \theta) &= \prod_{i=1}^n p(y_i|x_i, \theta) \\ &= \prod_{i=1}^n \frac{w_{y_i} p(x_i|\theta_{y_i})}{\sum_{j=1}^m w_j p(x_i|\theta_j)} \end{aligned}$$

and subsequently find the best configuration out of  $m^n$  possibilities.

Data is i.i.d. so  $y_i$  can be estimated separately. The MAP estimate for  $y_i$

$$\hat{y}_i = \arg \max_{k \in \mathcal{Y}} \{p(y_i|x_i, \theta)\} \qquad p(y_i|x_i, \theta) = \frac{w_{y_i} p(x_i|\theta_{y_i})}{\sum_{j=1}^m w_j p(x_i|\theta_j)}$$



# CLASSIFICATION EXPECTATION MAXIMIZATION (CEM)

1. Initialize  $\lambda_k^{(0)}$  and  $w_k^{(0)}$  for  $\forall k \in \mathcal{Y}$

2. Set  $t = 0$

3. Repeat until convergence

$$(a) \hat{y}_i^{(t)} = \arg \max_{k \in \mathcal{Y}} \{p(y_i = k | x_i, \mathbf{w}^{(t)}, \boldsymbol{\lambda}^{(t)})\}$$

for  $\forall i \in \{1, 2, \dots, n\}$

$$(b) w_k^{(t+1)} = \frac{1}{n} \sum_{i=1}^n I(\hat{y}_i^{(t)} = k)$$

$$(c) \lambda_k^{(t+1)} = \frac{\sum_{i=1}^n I(\hat{y}_i^{(t)} = k)}{\sum_{i=1}^n I(\hat{y}_i^{(t)} = k) \cdot x_i}$$

$$(d) t = t + 1$$

4. Report  $\lambda_k^{(t)}$  and  $w_k^{(t)}$  for  $\forall k \in \mathcal{Y}$

Contains all  $w_k$       Contains all  $\lambda_k$

$$p(y_i = k | x_i, \mathbf{w}, \boldsymbol{\lambda}) = \frac{p(y_i = k | w_k) \cdot p(x_i | \lambda_k)}{\sum_{j=1}^m p(y_i = j | w_j) \cdot p(x_i | \lambda_j)}$$
$$= \frac{w_k p(x_i | \lambda_k)}{\sum_{j=1}^m w_j p(x_i | \lambda_j)}$$



# EXPECTATION MAXIMIZATION

## EM

1. Initialize  $\lambda_k^{(0)}$  and  $w_k^{(0)}$  for  $\forall k \in \mathcal{Y}$
2. Set  $t = 0$
3. Repeat until convergence
  - (a)  $r_{ik}^{(t)} = p(y_i = k | x_i, \mathbf{w}^{(t)}, \boldsymbol{\lambda}^{(t)})$   
for  $\forall i \in \{1, 2, \dots, n\}$  and  $\forall k \in \mathcal{Y}$
  - (b)  $w_k^{(t+1)} = \frac{1}{n} \sum_{i=1}^n r_{ik}^{(t)}$
  - (c)  $\lambda_k^{(t+1)} = \frac{\sum_{i=1}^n r_{ik}^{(t)}}{\sum_{i=1}^n r_{ik}^{(t)} \cdot x_i}$
  - (d)  $t = t + 1$
4. Report  $\lambda_k^{(t)}$  and  $w_k^{(t)}$  for  $\forall k \in \mathcal{Y}$

## CEM

1. Initialize  $\lambda_k^{(0)}$  and  $w_k^{(0)}$  for  $\forall k \in \mathcal{Y}$
2. Set  $t = 0$
3. Repeat until convergence
  - (a)  $\hat{y}_i^{(t)} = \arg \max_{k \in \mathcal{Y}} \{p(y_i = k | x_i, \mathbf{w}^{(t)}, \boldsymbol{\lambda}^{(t)})\}$   
for  $\forall i \in \{1, 2, \dots, n\}$
  - (b)  $w_k^{(t+1)} = \frac{1}{n} \sum_{i=1}^n I(\hat{y}_i^{(t)} = k)$
  - (c)  $\lambda_k^{(t+1)} = \frac{\sum_{i=1}^n I(\hat{y}_i^{(t)} = k)}{\sum_{i=1}^n I(\hat{y}_i^{(t)} = k) \cdot x_i}$
  - (d)  $t = t + 1$
4. Report  $\lambda_k^{(t)}$  and  $w_k^{(t)}$  for  $\forall k \in \mathcal{Y}$

$$p(y_i = k | x_i, \mathbf{w}, \boldsymbol{\lambda}) = \frac{w_k p(x_i | \lambda_k)}{\sum_{j=1}^m w_j p(x_i | \lambda_j)}$$



## EM APPROACH

Observable data

$$\mathcal{D}_x = \{x_i\}_{i=1}^n.$$

Goal: maximize  $ll(\mathcal{D}_x, \theta)$

Partially observable data

$$\mathcal{D}_{xy} = \{(x_i, y_i)\}_{i=1}^n$$

Consider complete  
data log-likelihood  $ll(\mathcal{D}_{xy}, \theta)$

Current Estimate

$$\theta^{(t)}$$

E-Step

$$Q(\theta|\theta^{(t)}) = \mathbb{E}_{\mathbf{y}} [ll(\mathcal{D}_{xy}, \theta) | \mathcal{D}_x, \theta^{(t)}]$$

Expectation is taken over the distribution of random vector  $\mathbf{y}$  (containing  $y_i$  as entries) given the observable data  $\mathcal{D}_x$  and the current estimate  $\theta^{(t)}$ .

M-Step

$$\theta^{(t+1)} = \arg \max_{\theta} Q(\theta|\theta^{(t)})$$

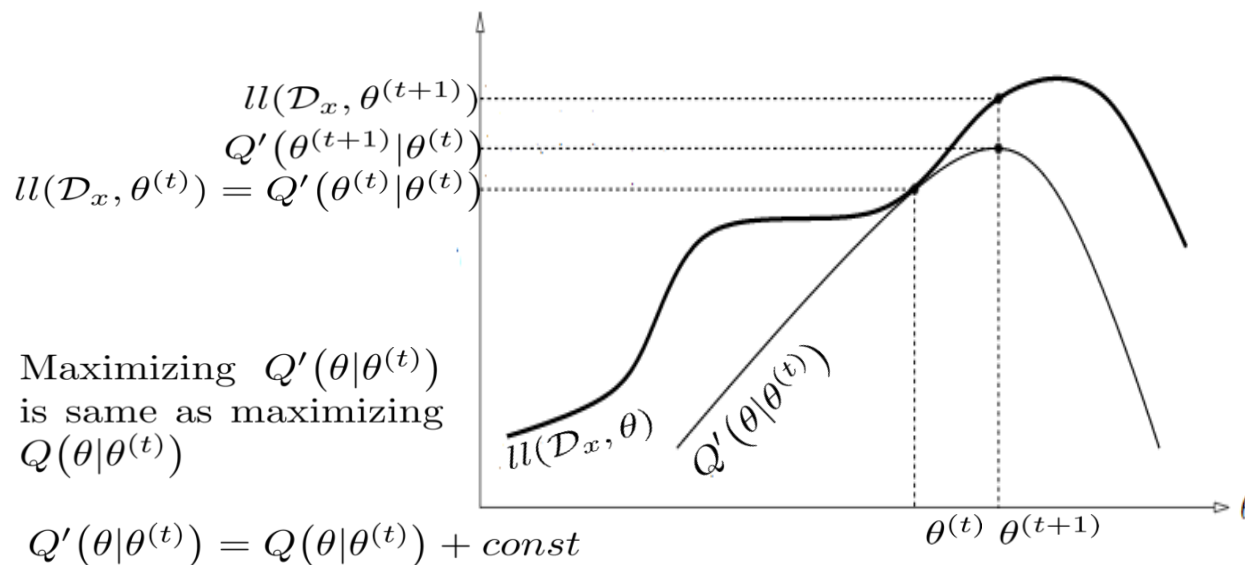
EM framework is much more general and has many applications beyond mixture models. Hidden markov models, handling missing data, correcting sample selection bias to name a few.



# EM CONVERGENCE

Convergence follows because the inequality below is true for all  $\theta$ . Finding a  $\theta$  that increases the  $Q$  function from  $Q(\theta^{(t)}|\theta^{(t)})$  makes the RHS positive which ensures that the LHS is also positive and consequently that  $\theta$  also increases the log-likelihood from  $ll(\mathcal{D}_x, \theta^{(t)})$ .

$$ll(\mathcal{D}_x, \theta) - ll(\mathcal{D}_x, \theta^{(t)}) \geq Q(\theta|\theta^{(t)}) - Q(\theta^{(t)}|\theta^{(t)})$$



Graphical interpretation of a single iteration of the EM: The function  $Q'(\theta|\theta^{(t)})$  is upper-bounded by  $ll(\mathcal{D}_x, \theta)$ . The functions are equal at  $\theta = \theta^{(t)}$ . The EM algorithm chooses  $\theta^{(t+1)}$  as the value of  $\theta$  for which  $Q'(\theta|\theta^{(t)})$  is maximum. Since  $ll(\mathcal{D}_{xy}, \theta) = Q'(\theta|\theta^{(t)}) + \text{const}$ , increasing  $Q'(\theta|\theta^{(t)})$  ensures that the value of the likelihood function  $ll(\mathcal{D}_{xy}, \theta)$  is increased at each step.





## EM CONVERGENCE (PROOF)

$$\begin{aligned}
 ll(\mathcal{D}_x, \theta) &= \log p(\mathcal{D}_x | \theta) \\
 &= \log \frac{p(\mathcal{D}_x, \mathbf{y} | \theta)}{p(\mathbf{y} | \mathcal{D}_x, \theta)} \\
 &= \log p(\mathcal{D}_{xy} | \theta) - \log p(\mathbf{y} | \mathcal{D}_x, \theta) \\
 &= ll(\mathcal{D}_{xy}, \theta) - \log p(\mathbf{y} | \mathcal{D}_x, \theta) \\
 &= \mathbb{E}_{\mathbf{y}} [ll(\mathcal{D}_{xy}, \theta) | \mathcal{D}_x, \theta^{(t)}] - \mathbb{E}_{\mathbf{y}} [\log p(\mathbf{y} | \mathcal{D}_x, \theta) | \mathcal{D}_x, \theta^{(t)}] \\
 &= \underbrace{Q(\theta | \theta^{(t)}) + H(\theta^{(t)})}_{Q'(\theta | \theta^{(t)})} + \underbrace{KL(\theta^{(t)} || \theta)}_{\text{Constant w.r.t. } \theta} \quad (1)
 \end{aligned}$$

$H(\theta^{(t)})$  is short for the entropy of  $p(\mathbf{y} | \mathcal{D}_x, \theta^{(t)})$  given by  $\mathbb{E}_{\mathbf{y}} [-\log p(\mathbf{y} | \mathcal{D}_x, \theta^{(t)}) | \mathcal{D}_x, \theta^{(t)}]$

$KL(\theta^{(t)} || \theta)$  is short for the KL divergence between  $p(\mathbf{y} | \mathcal{D}_x, \theta^{(t)})$  and  $p(\mathbf{y} | \mathcal{D}_x, \theta)$

Note  $KL(\theta^{(t)} || \theta^{(t)}) = 0$

Thus, from (1)

$$\begin{aligned}
 ll(\mathcal{D}_x, \theta) - ll(\mathcal{D}_x, \theta^{(t)}) &= Q(\theta | \theta^{(t)}) - Q(\theta^{(t)} | \theta^{(t)}) \\
 &\quad + KL(\theta^{(t)} || \theta) \\
 &\geq Q(\theta | \theta^{(t)}) - Q(\theta^{(t)} | \theta^{(t)}) \\
 &\quad \text{since } KL(\theta^{(t)} || \theta) \geq 0
 \end{aligned}$$

Also from (1)

$$\begin{aligned}
 ll(\mathcal{D}_x, \theta) &\geq Q'(\theta | \theta^{(t)}) \\
 &\quad \text{since } KL(\theta^{(t)} || \theta) \geq 0 \\
 ll(\mathcal{D}_x, \theta^{(t)}) &= Q'(\theta^{(t)} | \theta^{(t)}) \\
 &\quad \text{since } KL(\theta^{(t)} || \theta^{(t)}) = 0
 \end{aligned}$$



## EM FOR EXPONENTIAL MIXTURE

$$\begin{aligned} ll(\mathcal{D}_{xy}, \theta) &= \sum_{i=1}^n \log\{w_{y_i} p(x_i | \lambda_{y_i})\} \\ &= \sum_{i=1}^n \log \left\{ \prod_{j=1}^m (w_j p(x_i | \lambda_j))^{I(y_i=j)} \right\} \\ &= \sum_{i=1}^n \sum_{j=1}^m I(y_i = j) (\log w_j + \log p(x_i | \lambda_j)) \\ &= \sum_{i=1}^n \sum_{j=1}^m I(y_i = j) (\log w_j + \log \lambda_j - \lambda_j x_i) \end{aligned}$$

For exponential  
distribution

$$p(x | \lambda_j) = \lambda_j e^{-\lambda_j x}$$



## EM FOR EXPONENTIAL MIXTURE: E-STEP

$$\begin{aligned}
 Q(\theta|\theta^{(t)}) &= \mathbb{E}_{\mathbf{y}} \left[ ll(D_{xy}, \theta) | \mathcal{D}_x, \theta^{(t)} \right] \\
 &= \mathbb{E}_{\mathbf{y}} \left[ \sum_{i=1}^n \sum_{j=1}^m I(y_i = j) (\log w_j + \log \lambda_j - \lambda_j x_i) \middle| \mathcal{D}_x, \theta^{(t)} \right] \\
 &= \sum_{i=1}^n \sum_{j=1}^m \mathbb{E}_{\mathbf{y}} \left[ I(y_i = j) | \mathcal{D}_x, \theta^{(t)} \right] (\log w_j + \log \lambda_j - \lambda_j x_i) \quad \text{because of linearity of expectation} \\
 &= \sum_{i=1}^n \sum_{j=1}^m \mathbb{E}_{y_i} \left[ I(y_i = j) | x_i, \theta^{(t)} \right] (\log w_j + \log \lambda_j - \lambda_j x_i) \quad \begin{array}{l} \text{Since the distribution } y_i \text{ is only depen-} \\ \text{dent on } x_i \text{ and independent of } y_j \text{ and} \\ x_j \text{ for } i \neq j \end{array} \\
 &= \sum_{i=1}^n \sum_{j=1}^m p(y_i = j | x_i, \theta^{(t)}) (\log w_j + \log \lambda_j - \lambda_j x_i) \quad \text{Expectation of the indicator function of} \\
 &\quad \text{an event gives probability of that event.} \\
 &= \sum_{i=1}^n \sum_{j=1}^m r_{ij}^{(t)} (\log w_j + \log \lambda_j - \lambda_j x_i)
 \end{aligned}$$



## EM FOR EXPONENTIAL MIXTURE: M-STEP

Find  $\theta^{(t+1)} = \arg \max_{\theta} Q(\theta | \theta^{(t)})$  by

$$\frac{\partial}{\partial w_j} Q(\theta | \theta^{(t)}) = 0 \Rightarrow w_j = \frac{1}{n} \sum_{i=1}^n r_{ij}^{(t)}$$

$$\frac{\partial}{\partial \lambda_j} Q(\theta | \theta^{(t)}) = 0 \Rightarrow \lambda_j = \frac{\sum_{i=1}^n r_{ij}^{(t)}}{\sum_{i=1}^n r_{ij}^{(t)} \cdot x_i}$$

