



SUPPORT VECTOR MACHINES

CSCI-B565

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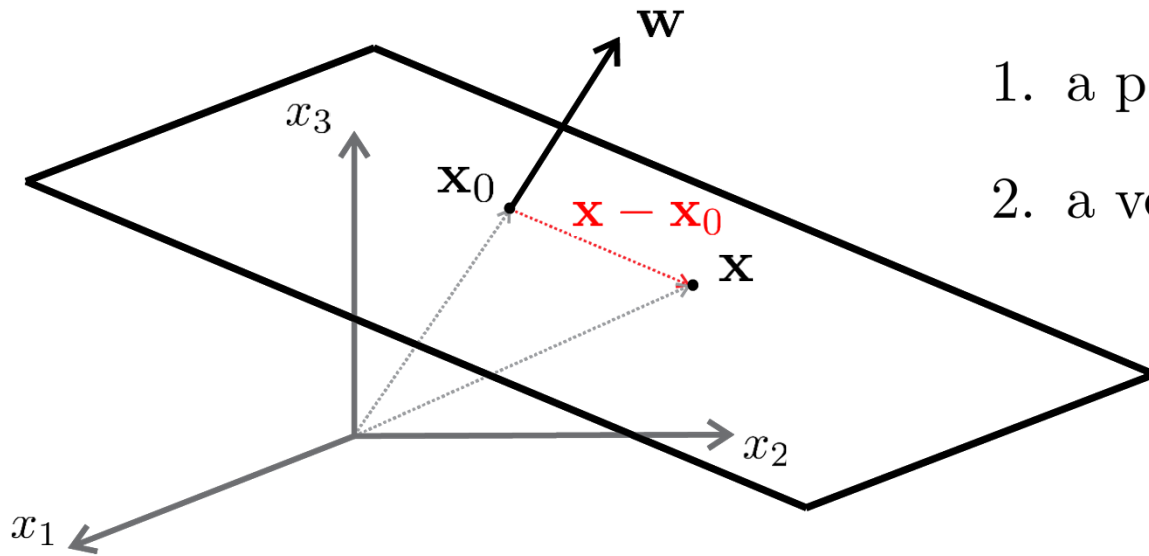
INDIANA UNIVERSITY BLOOMINGTON

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EQUATION OF THE PLANE

A plane is defined using:

1. a point \mathbf{x}_0 lying in the plane
2. a vector \mathbf{w} normal to the plane



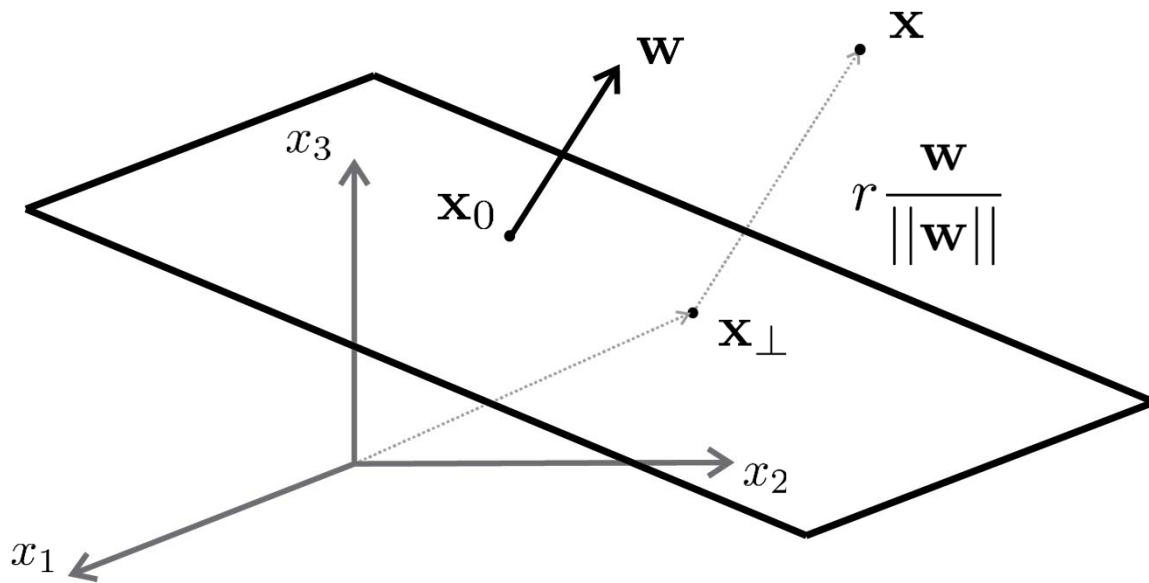
Let \mathbf{x} be on the plane defined by \mathbf{w} and \mathbf{x}_0 :

$$\mathbf{w}^T (\mathbf{x} - \mathbf{x}_0) = 0$$

$$\mathbf{w}^T \mathbf{x} - \mathbf{w}^T \mathbf{x}_0 = 0$$

$$\mathbf{w}^T \mathbf{x} + w_0 = 0$$

DISTANCE FROM POINT TO THE PLANE



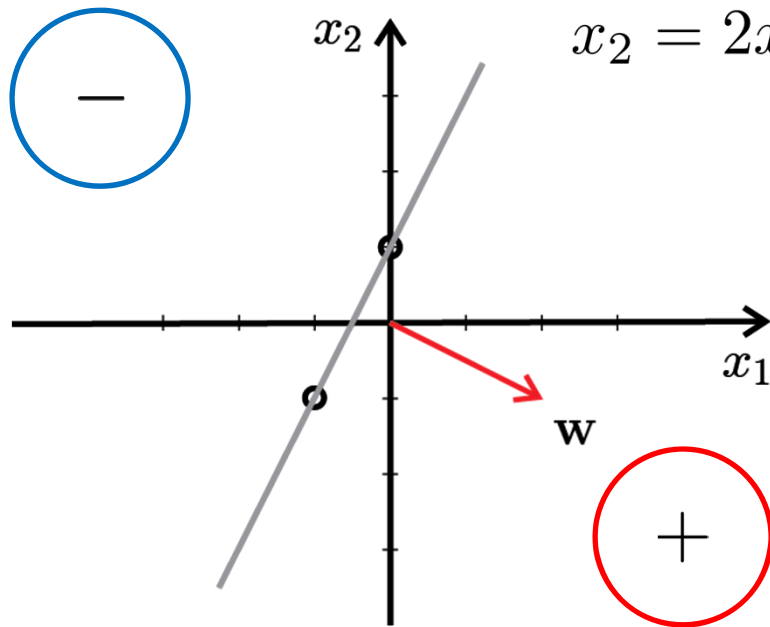
\mathbf{x} = outside the plane

$$\mathbf{x} = \mathbf{x}_\perp + r \frac{\mathbf{w}}{\|\mathbf{w}\|}$$

$$\mathbf{w}^T \mathbf{x} + w_0 = \underbrace{\mathbf{w}^T \mathbf{x}_\perp + w_0}_0 + r \|\mathbf{w}\|$$

$$r = \frac{\mathbf{w}^T \mathbf{x} + w_0}{\|\mathbf{w}\|}$$

EXAMPLE



$$x_2 = 2x_1 + 1 \quad \text{or} \quad 2x_1 - x_2 + 1 = 0$$

$$\mathbf{x}, \mathbf{w} \in \mathbb{R}^2$$

$$\mathbf{w}^T \mathbf{x} + w_0 = 0$$

where $\mathbf{w} = (2, -1)$ and $w_0 = 1$.

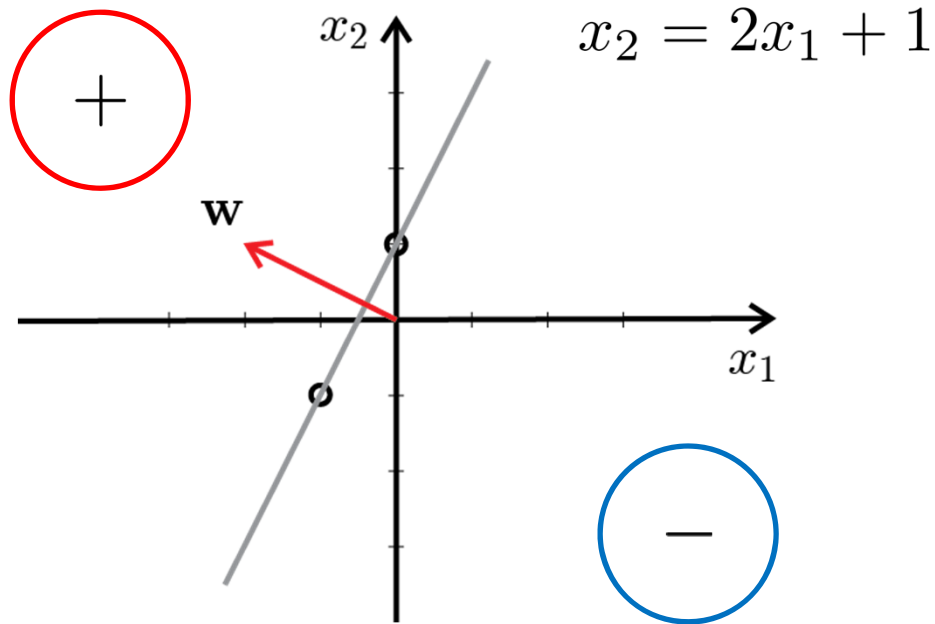
$$r = \frac{\mathbf{w}^T \mathbf{x} + w_0}{\|\mathbf{w}\|}$$

$$\mathbf{x} = (0, 0) \implies r = \frac{1}{\sqrt{5}}$$

$$\mathbf{x} = (-1, 1) \implies r = -\frac{2}{\sqrt{5}}$$

The vector \mathbf{w} defines what side of the plane is positive.

EXAMPLE



What if $\mathbf{w} = (-2, 1)$?

$$\mathbf{x}, \mathbf{w} \in \mathbb{R}^2$$

$$\mathbf{w}^T \mathbf{x} + w_0 = 0$$

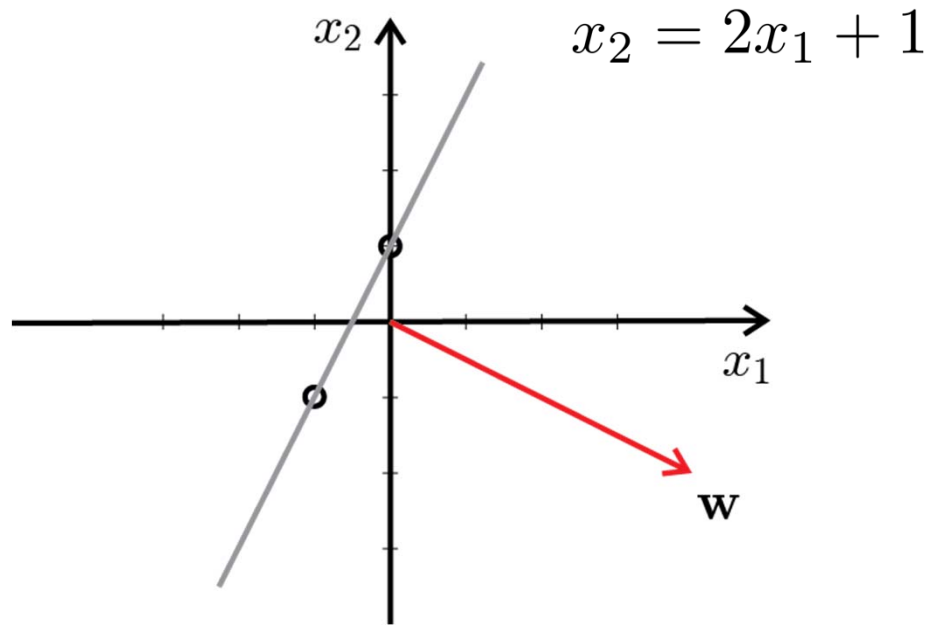
where $\mathbf{w} = (-2, 1)$ and $w_0 = -1$.

$$r = \frac{\mathbf{w}^T \mathbf{x} + w_0}{\|\mathbf{w}\|}$$

$$\mathbf{x} = (0, 0) \implies r = -\frac{1}{\sqrt{5}}$$

$$\mathbf{x} = (-1, 1) \implies r = \frac{2}{\sqrt{5}}$$

EXAMPLE



What if $\mathbf{w} = (4, -2)$
and $w_0 = 2$?

$$4x_1 - 2x_2 + 2 = 0$$

$\mathbf{w}^T \mathbf{x} + w_0$ is “bigger”!!!

$$r = \frac{\mathbf{w}^T \mathbf{x} + w_0}{\|\mathbf{w}\|}$$

$$\mathbf{x} = (0, 0) \implies r = \frac{1}{\sqrt{5}}$$

$$\mathbf{x} = (-1, 1) \implies r = -\frac{2}{\sqrt{5}}$$

Distances are unchanged when \mathbf{w} and w_0 are multiplied by a constant!

EXAMPLE OF CONSTRAINED OPTIMIZATION

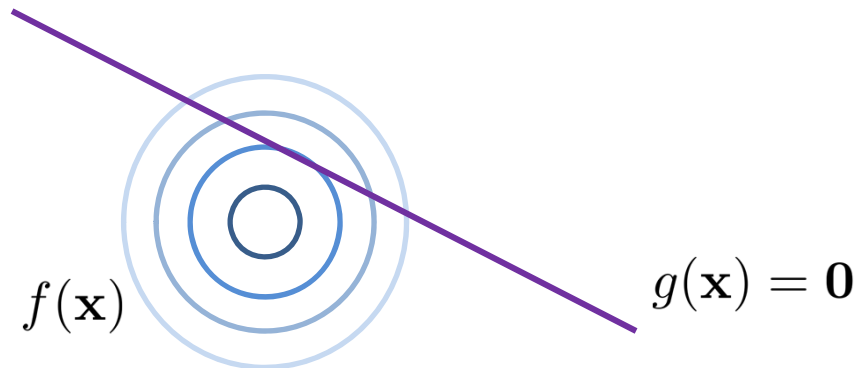
Objective: find optima with some restrictions

$$\mathbf{x}^* = \arg \min_{\mathbf{x}} \{x_1^2 + x_2^2\}$$

$$\mathbf{x} = (x_1, x_2)$$

Subject to:

$$3x_1 + x_2 + 5 = 0$$



CONSTRAINED OPTIMIZATION

Objective: solve the following optimization problem

$$\mathbf{x}^* = \arg \max_{\mathbf{x}} \{f(\mathbf{x})\}$$

Subject to:

$$g_i(\mathbf{x}) = 0 \quad \forall i \in \{1, 2, \dots, m\}$$

$$h_j(\mathbf{x}) \geq 0 \quad \forall j \in \{1, 2, \dots, n\}$$

Or, in a shorter notation, to:

$$\mathbf{g}(\mathbf{x}) = \mathbf{0}$$

$$\mathbf{h}(\mathbf{x}) \geq \mathbf{0}$$

LAGRANGE MULTIPLIERS

Taylor's expansion for $g(\mathbf{x})$, where $\mathbf{x} + \boldsymbol{\epsilon}$ is on the surface of $g(\mathbf{x})$

$$g(\mathbf{x} + \boldsymbol{\epsilon}) \approx g(\mathbf{x}) + \boldsymbol{\epsilon}^T \nabla g(\mathbf{x})$$

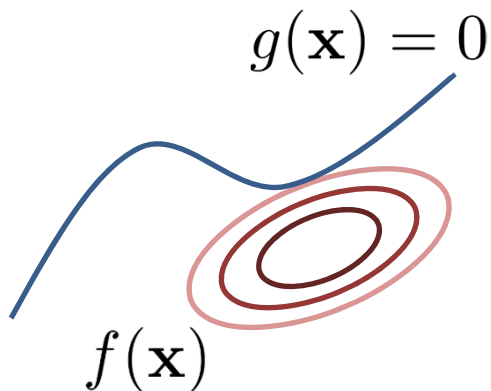
We know that $g(\mathbf{x}) = g(\mathbf{x} + \boldsymbol{\epsilon})$

$$\boldsymbol{\epsilon}^T \nabla g(\mathbf{x}) \approx 0$$

when $\boldsymbol{\epsilon} \rightarrow \mathbf{0}$

$$\boldsymbol{\epsilon}^T \nabla g(\mathbf{x}) = 0$$

$\implies \nabla g(\mathbf{x})$ is orthogonal
to the surface



$\nabla g(\mathbf{x})$ and $\nabla f(\mathbf{x})$ are parallel!

$$\nabla f(\mathbf{x}) + \alpha \nabla g(\mathbf{x}) = 0 \quad \alpha \neq 0$$

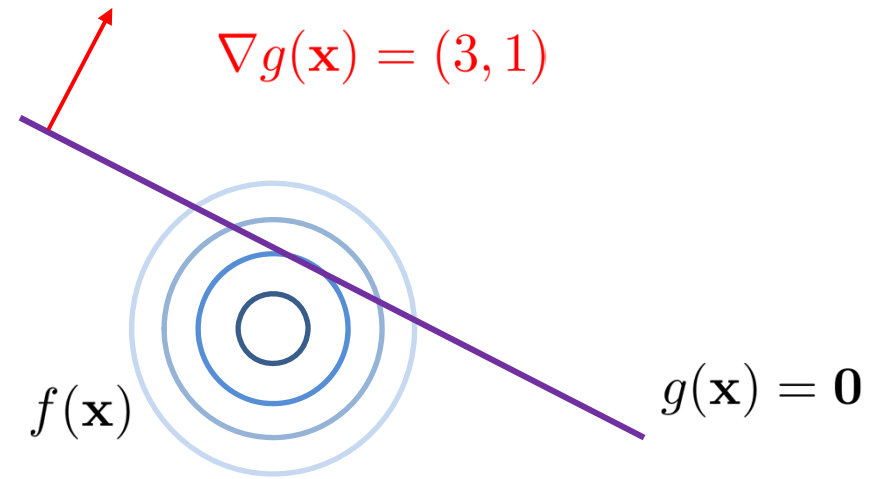
$$L(\mathbf{x}, \alpha) = f(\mathbf{x}) + \alpha g(\mathbf{x})$$

EXAMPLE OF CONSTRAINED OPTIMIZATION

$$\mathbf{x}^* = \arg \min_{\mathbf{x}} \{x_1^2 + x_2^2\}$$

Subject to:

$$3x_1 + x_2 + 5 = 0$$



$$L(\mathbf{x}, \alpha) = x_1^2 + x_2^2 + \alpha(3x_1 + x_2 + 5)$$

$$\frac{\partial L}{\partial x_1} = 2x_1 + 3\alpha = 0$$

$$\frac{\partial L}{\partial x_2} = 2x_2 + \alpha = 0$$

\Rightarrow

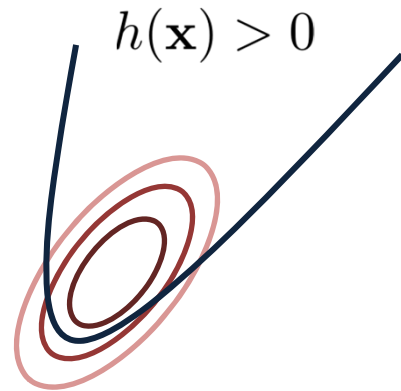
$$x_1 = -\frac{3}{2}$$

$$x_2 = -\frac{1}{2}$$

$$\alpha = 1$$

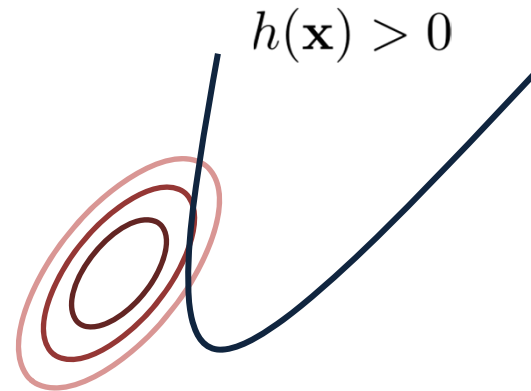
LAGRANGE MULTIPLIERS

Inactive constraint



$$\nabla f(\mathbf{x}) = 0$$

Active constraint



$$\nabla f(\mathbf{x}) = -\mu \nabla h(\mathbf{x}) \quad \mu > 0$$

It holds that:

$$\begin{aligned} h(\mathbf{x}) &\geq 0 \\ \mu &\geq 0 \\ \mu \cdot h(\mathbf{x}) &= 0 \end{aligned}$$

Karush-Kuhn-Tucker (KKT)
conditions

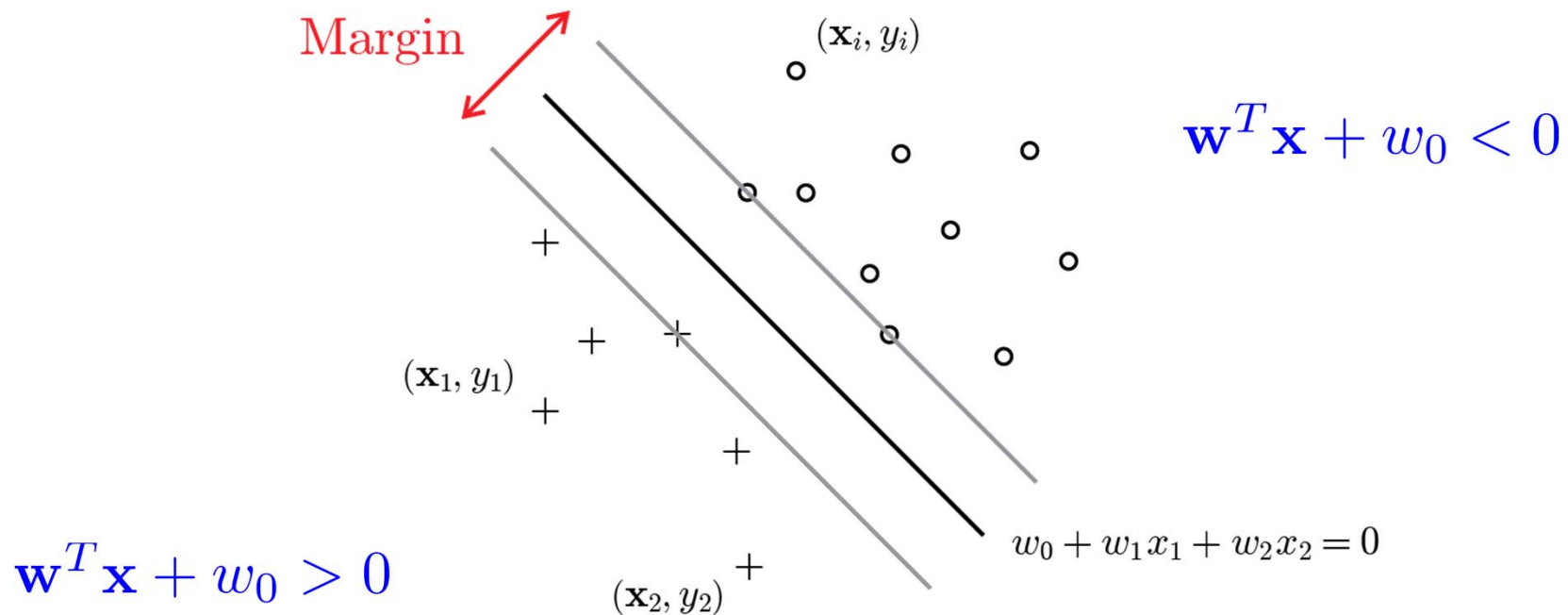
$$L(\mathbf{x}, \boldsymbol{\alpha}, \boldsymbol{\mu}) = f(\mathbf{x}) + \boldsymbol{\alpha}^T \mathbf{g}(\mathbf{x}) + \boldsymbol{\mu}^T \mathbf{h}(\mathbf{x})$$

PROBLEM FORMULATION

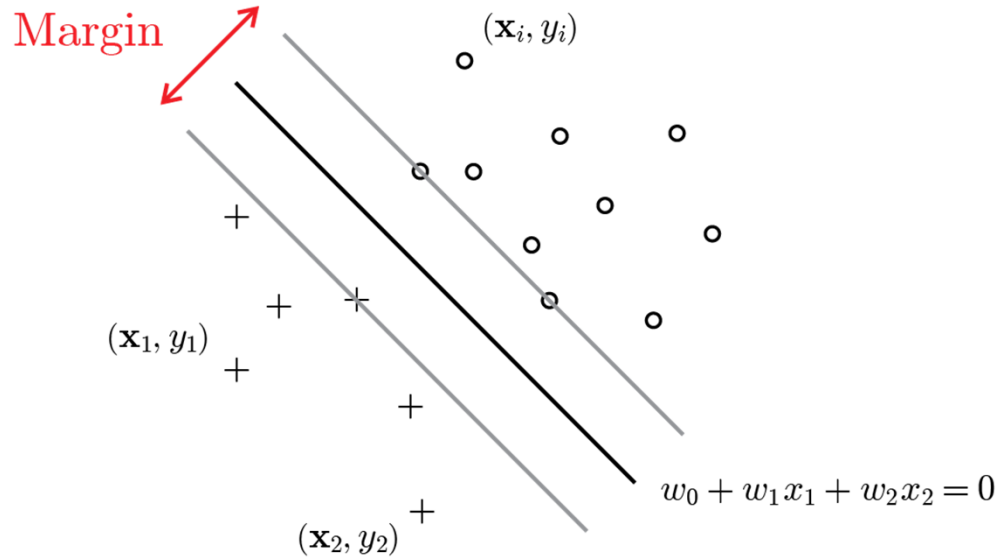
Given: $\mathcal{D} = \{(\mathbf{x}_i, y_i)\}_{i=1}^n$, where $\mathbf{x}_i \in \mathbb{R}^k$ and $y_i \in \{-1, +1\}$.

Data is linearly separable.

Objective: Find hyperplane such that the minimum distance from any data point to the hyperplane is maximized.



MAXIMIZING MARGIN



$$\mathbf{w}^T \mathbf{x}_i + w_0 > 0 \implies y_i = +1$$

$$\mathbf{w}^T \mathbf{x}_i + w_0 < 0 \implies y_i = -1$$

$$y_i(\mathbf{w}^T \mathbf{x}_i + w_0) > 0$$

$$i \in \{1, 2, \dots, n\}$$

Idea: find \mathbf{w} to maximize unsigned distance $d_i = \frac{y_i(\mathbf{w}^T \mathbf{x} + w_0)}{\|\mathbf{w}\|}$

$$(\mathbf{w}^*, w_0^*) = \arg \max_{\mathbf{w}, w_0} \left\{ \frac{1}{\|\mathbf{w}\|} \min_i (y_i(\mathbf{w}^T \mathbf{x}_i + w_0)) \right\}$$

REFORMULATING THE PROBLEM

$$(\mathbf{w}^*, w_0^*) = \arg \max_{\mathbf{w}, w_0} \left\{ \frac{1}{\|\mathbf{w}\|} \min_i (y_i(\mathbf{w}^T \mathbf{x}_i + w_0)) \right\}$$

Scale \mathbf{w} and w_0 such that $\min_i \{ \mathbf{w}^T \mathbf{x}_i + w_0 \} = 1$

$$\mathbf{w} \leftarrow k \cdot \mathbf{w}$$

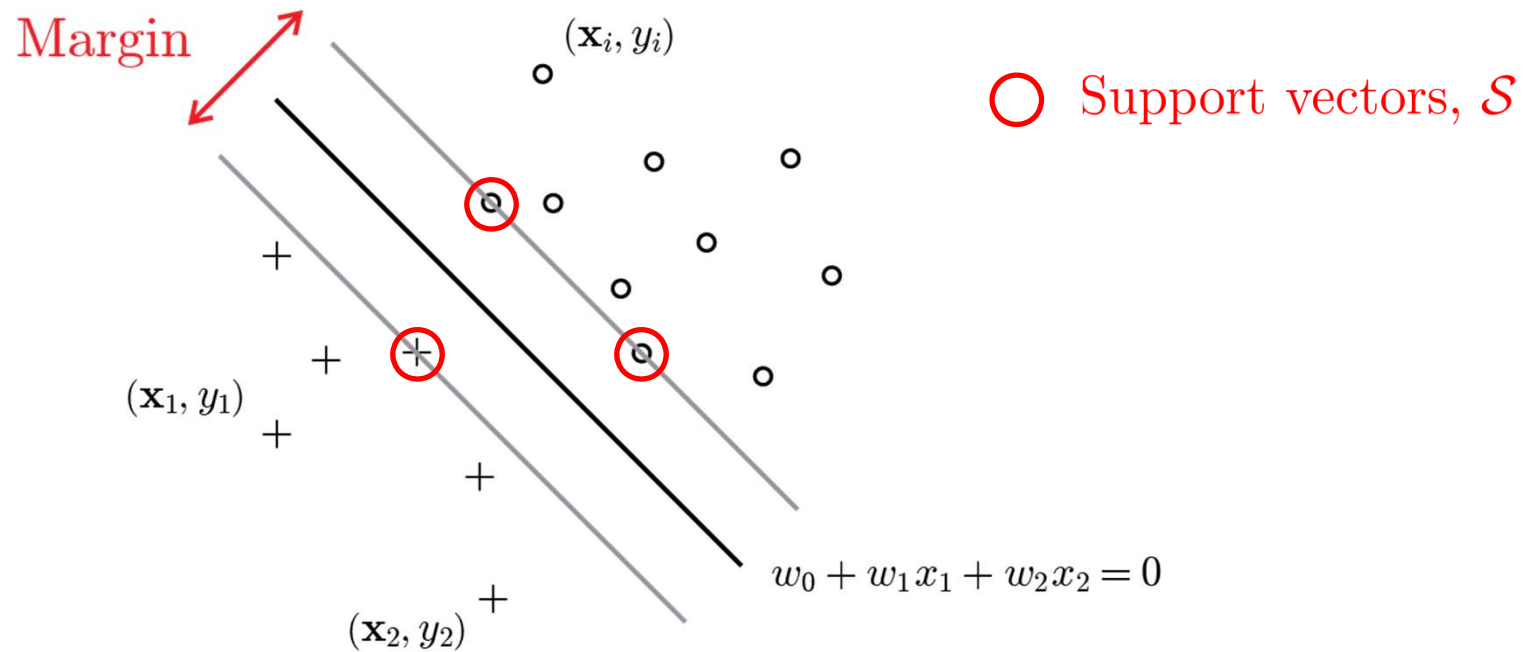
$$w_0 \leftarrow k \cdot w_0$$

$$(\mathbf{w}^*, w_0^*) = \arg \min_{\mathbf{w}} \{ \|\mathbf{w}\| \}$$

Subject to:

$$y_i(\mathbf{w}^T \mathbf{x}_i + w_0) \geq 1 \quad \forall i \in \{1, 2, \dots, n\}$$

FINAL PROBLEM FORMULATION



$$(\mathbf{w}^*, w_0^*) = \arg \min_{\mathbf{w}} \left\{ \frac{1}{2} \mathbf{w}^T \mathbf{w} \right\}$$

← Convex function!

Subject to:

$$y_i(\mathbf{w}^T \mathbf{x}_i + w_0) \geq 1 \quad \forall i \in \{1, 2, \dots, n\}$$

← Linear constraints!

HOW CAN WE SOLVE IT?

$$(\mathbf{w}^*, w_0^*) = \arg \min_{\mathbf{w}} \left\{ \frac{1}{2} \mathbf{w}^T \mathbf{w} \right\}$$

Subject to:

$$y_i(\mathbf{w}^T \mathbf{x}_i + w_0) \geq 1 \quad \forall i \in \{1, 2, \dots, n\}$$

Solution: use Lagrangian multipliers!

$$L(\mathbf{w}, w_0, \boldsymbol{\alpha}) = \frac{1}{2} \mathbf{w}^T \mathbf{w} - \sum_{i=1}^n \alpha_i (y_i (\mathbf{w}^T \mathbf{x}_i + w_0) - 1)$$

SOLVING IT

$$\frac{\partial}{\partial w_j} L(\mathbf{w}, w_0, \boldsymbol{\alpha}) = 0 \quad \Rightarrow \quad w_j = \sum_{i=1}^n \alpha_i y_i x_{ij}$$

$$\Rightarrow \quad \mathbf{w} = \sum_{i=1}^n \alpha_i y_i \mathbf{x}_i$$

$$\frac{\partial}{\partial w_0} L(\mathbf{w}, w_0, \boldsymbol{\alpha}) = 0 \quad \Rightarrow \quad \sum_{i=1}^n \alpha_i y_i = 0$$

DUAL PROBLEM

$$\begin{aligned} L(\mathbf{w}, w_0, \boldsymbol{\alpha}) &= \frac{1}{2} \mathbf{w}^T \mathbf{w} - \sum_{i=1}^n \alpha_i y_i \mathbf{w}^T \mathbf{x}_i - \sum_{i=1}^n \alpha_i y_i w_0 + \sum_{i=1}^n \alpha_i \\ &= \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j \mathbf{x}_i^T \mathbf{x}_j - \sum_{i=1}^n \alpha_i y_i \left(\sum_{j=1}^n \alpha_j y_j \mathbf{x}_j \right)^T \mathbf{x}_i + \sum_{i=1}^n \alpha_i \\ &= \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j \mathbf{x}_i^T \mathbf{x}_j \\ &= \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j k(\mathbf{x}_i, \mathbf{x}_j) \end{aligned}$$

Subject to:

$$\alpha_i \geq 0 \quad \forall i \in \{1, 2, \dots, n\}$$

$$\sum_{i=1}^n \alpha_i y_i = 0$$

SOLVING THE DUAL PROBLEM

Use quadratic programming to solve for α

$$\implies \mathbf{w} = \sum_{i=1}^n \alpha_i y_i \mathbf{x}_i$$

$$\begin{aligned} \implies f(\mathbf{x}) &= \mathbf{w}^T \mathbf{x} + w_0 \\ &= \frac{1}{2} \sum_{i=1}^n \alpha_i y_i k(\mathbf{x}, \mathbf{x}_i) + w_0 \end{aligned}$$

ANALYSIS OF THE SOLUTION

Karush-Kuhn-Tucker (KKT) conditions:

$$\alpha_i \geq 0$$

$$y_i(\mathbf{w}^T \mathbf{x}_i + w_0) - 1 \geq 0 \quad \forall i \in \{1, 2, \dots, n\}$$

$$\alpha_i (y_i (\mathbf{w}^T \mathbf{x}_i + w_0) - 1) = 0$$

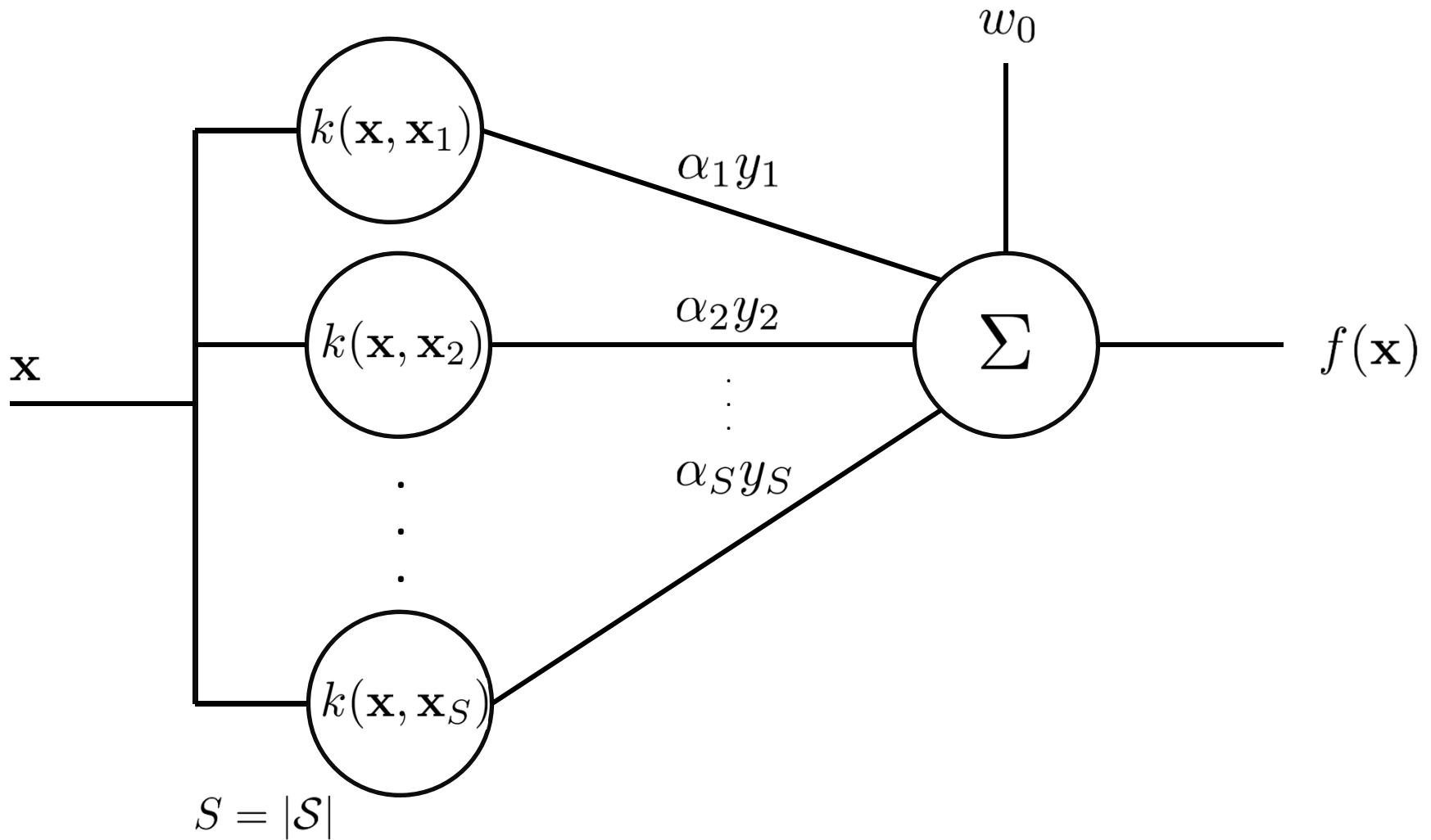
This means that for $\forall i$, either $\alpha_i = 0$ or $y_i (\mathbf{w}^T \mathbf{x}_i + w_0) = 1$

$\Rightarrow \alpha_i = 0$ for all vectors that are not support vectors

$$f(\mathbf{x}) = \sum_{\mathbf{x}_i \in \mathcal{S}} \alpha_i y_i k(\mathbf{x}, \mathbf{x}_i) + w_0$$

$$w_0 = 1 - \mathbf{w}^T \mathbf{x}_s, \text{ where } \mathbf{x}_s \in \mathcal{S}$$

A SUPPORT VECTOR MACHINE



A support vector machine is a neural network.